

## Minimal Sufficient Statistic

- \* Among all sufficient statistics, a minimal sufficient statistic reduces the data as much as possible while retaining sufficiency.
- \* Minimal sufficient statistics are not unique but are equivalent up to a one-to-one transformation.
- \* The partition of the sample space induced by a minimum sufficient statistic is the coarsest possible among sufficient statistics.

$T(X) = X$  is always a sufficient statistic, with  $h(x) = 1$

$$\begin{aligned}\Rightarrow f(x|\theta) &= g(T(x)|\theta) h(x) \\ &= g(x|\theta) \cdot 1 \\ &= f(x|\theta)\end{aligned}$$

and every one-to-one function  
of sufficient statistic is also  
a sufficient statistic.

let  $T(x)$  is a sufficient statistic  
and  $\alpha$  is a one-to-one function  
 $\Rightarrow \alpha^{-1}$  exists.

Then  $T^*(x) = \alpha(T(x)) \quad \forall x$   
is also sufficient statistic.

$$\begin{aligned} f(x|\theta) &= g(T(x)|\theta) h(x) \\ &= g(\alpha^{-1}(T^*(x))|\theta) h(x) \end{aligned}$$

Define

$$\begin{aligned} g^*(t|\theta) \\ &= g(\alpha^{-1}(t)|\theta) \end{aligned}$$

$$\Rightarrow f(x|\theta) = g^*(T^*(x)|\theta) h(x)$$

$\Rightarrow T^*(x)$  is also a sufficient statistic

$\Rightarrow$  There are many sufficient statistics.

$\Rightarrow$  The purpose of a sufficient statistic is to achieve data reduction without loss of information about the parameter  $\theta$ .

$\Rightarrow$  Thus, a statistic that achieves the most data reduction while still retaining all the information about  $\theta$  might be considered preferable.

Def: 6.2.11 :

A sufficient statistic  $T(x)$  is called a minimal sufficient statistic if, for any other sufficient statistic  $T'(x)$ ,  $T(x)$  is a function of  $T'(x)$ .

$T(x)$  must be derivable from  $T'(x)$

\* This makes  $T(x)$  a "minimal" way of summarizing the data, and no other sufficient statistic is more concise than  $T(x)$

$\Rightarrow$  The minimal sufficient statistic is the most efficient summary of the data, meaning it cannot be reduced further without losing information about  $\theta$ .

we know that

$$A_t = \{x: T(x) = t\}$$

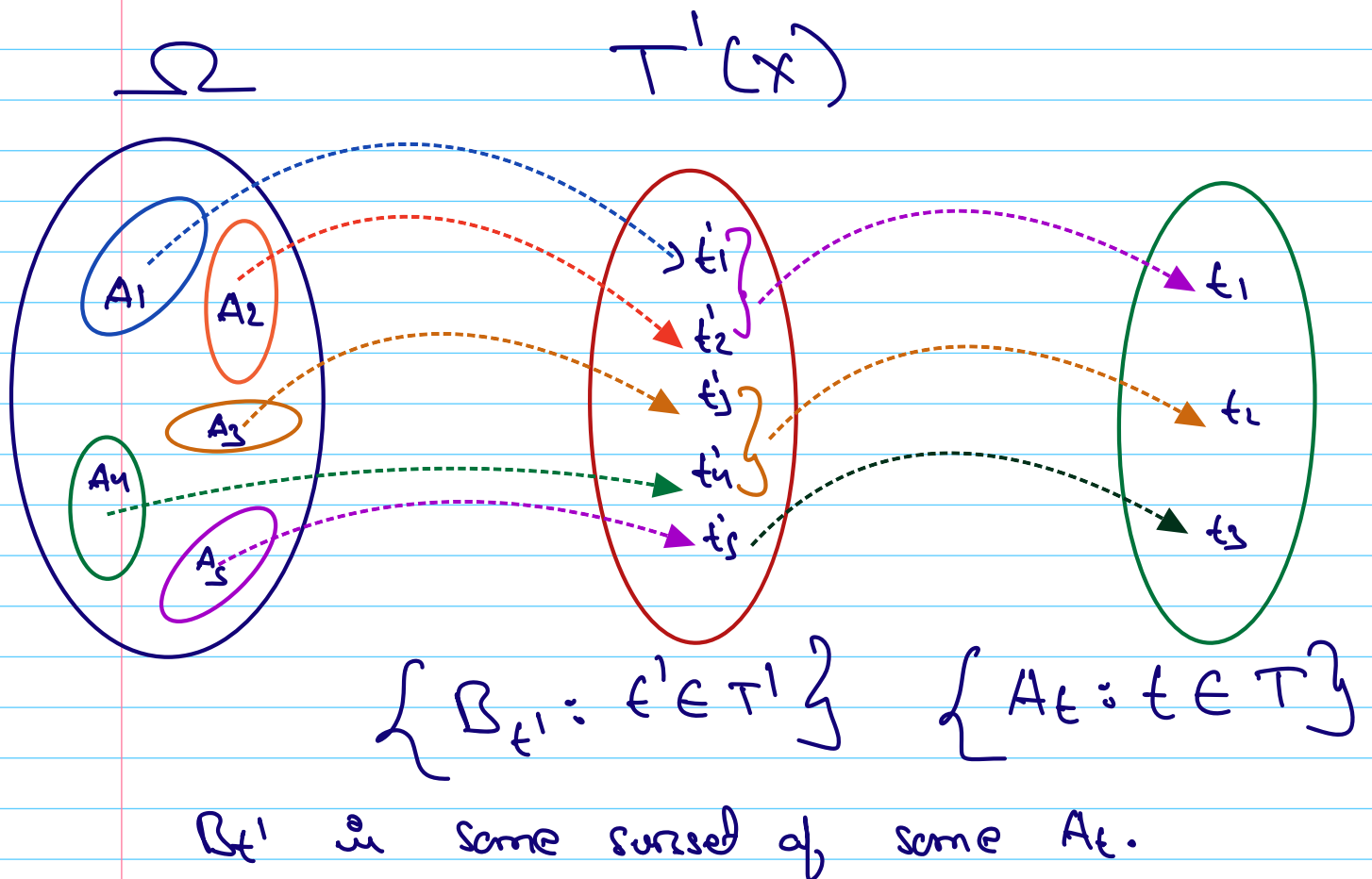
To say  $T(x)$  is a function of  $T'(x)$  simply means

$$\text{if } T'(x) = T'(y) \Rightarrow T(x) = T(y)$$

Understanding:

$$T(x) = c(T'(x))$$

where the function  $c$  does  
not need to be one-to-one.  
(can be many-to-one)



### Theorem 6.2.13:

Let  $f(x|\theta)$  be the pmf or pdf of a sample  $X$ . Suppose there exists a function  $T(x)$  such that, for every two sample points  $x$  and  $y$ , the ratio  $\frac{f(x|\theta)}{f(y|\theta)}$  is constant as a function of  $\theta \iff T(x) = T(y)$ . Then  $T(x)$  is a minimal sufficient statistic for  $\theta$ .

Proof: The sample space  $\Omega = \mathcal{X}$

$$x \in \mathcal{X}.$$

$$\text{let } \mathcal{T} = \{t: t = T(x) \text{ for some } x \in \mathcal{X}\}$$

$$\Rightarrow T(x): \mathcal{X} \longrightarrow \mathcal{T}$$

The partition sets induced by  $T(x)$  on  $\mathcal{X}$  are  $A_t = \{x: T(x) = t\}$

let's take  $x \in A_t \subseteq X$

let's take one element for each partition.

$x_{T(x)}$  is the fixed element for each set.

$\Rightarrow$  for any  $x \in X$  chosen randomly  
 $x_{T(x)}$  is the fixed element in  
that partition

$$\Rightarrow T(x) = T(x_{T(x)})$$

$$f(x|\theta) = g(T(x)|\theta) h(x)$$

$$\begin{aligned}\Rightarrow \frac{f(x|\theta)}{f(x_{T(x)}|\theta)} &= \frac{g(\cancel{T(x)}|\theta) h(x)}{g(\cancel{T(x_{T(x)})}|\theta) h(x_{T(x)})} \\ &= \frac{h(x)}{h(x_{T(x)})}\end{aligned}$$

independent of  $\theta$ .

\* define a function on  $\mathcal{X}$  by

$$h(x) = \frac{f(x|\theta)}{f(T(x)|\theta)}$$

(independent of  $\theta$ )

(this is not similar to previous  $h(x)$ )

\* define a function on  $\mathcal{T}$  by

$$g(t|\theta) = f(x_t|\theta)$$

$$\Rightarrow f(x|\theta) = \frac{f(T(x)|\theta)}{f(T(x)|\theta)} \cdot f(x|\theta)$$

$$= f(T(x)|\theta) \cdot h(x)$$

$$= g(T(x)|\theta) \cdot h(x)$$

$\Rightarrow T(x)$  is sufficient statistic

Now we need to show  $T(x)$  is minimal.



let's take  $T'(x)$  is another  
sufficient statistic

$$\Rightarrow f(x|\theta) = g(T(x)|\theta) h(x) \\ = g'(T'(x)|\theta) h'(x)$$

Let  $x$  and  $y$  be any two sample  
points with  $T'(x) = T'(y)$ . Then

$$\frac{f(x|\theta)}{f(y|\theta)} = \frac{g'(T'(x)|\theta) h'(x)}{g'(T'(y)|\theta) h'(y)} \\ = \frac{h'(x)}{h'(y)}$$

Ex: 6.2.14 (Normal minimal sufficient statistic)

$$X_1, X_2, \dots, X_n \stackrel{\text{i.i.d.}}{\sim} N(\mu, \sigma^2)$$

Both  $\mu, \sigma^2$  are unknown.

let  $x_1, y$  are two data points, and

let  $(\bar{x}, s_x^2), (\bar{y}, s_y^2)$  be the

sample mean, sample variances.

$$\frac{f(x | \mu, \sigma^2)}{f(y | \mu, \sigma^2)} = \frac{\frac{1}{(2\pi\sigma^2)^{n/2}} \exp\left(-\frac{1}{2\sigma^2} (n(\bar{x} - \mu)^2 + (n-1)s_x^2)\right)}{\frac{1}{(2\pi\sigma^2)^{n/2}} \exp\left(-\frac{1}{2\sigma^2} (n(\bar{y} - \mu)^2 + (n-1)s_y^2)\right)}$$

$$= \exp\left(-\frac{1}{2\sigma^2} \left( n[(\bar{x} - \mu)^2 - (\bar{y} - \mu)^2] + (n-1)(s_x^2 - s_y^2) \right)\right)$$

$$\text{if } \bar{x} = \bar{y} \text{ \& } S_x^2 = S_y^2$$

$$= \exp \left( -\frac{1}{2\sigma^2} \left( n \cdot 0 + (n-1) \cdot 0 \right) \right)$$

$= 1$

$$\Rightarrow \frac{f(x|\mu, \sigma^2)}{f(y|\mu, \sigma^2)} \text{ is constant if } \bar{x} = \bar{y}, S_x^2 = S_y^2$$

$\Rightarrow (\bar{x}, s^2)$  is minimal sufficient statistic.

Example 6.2.15 (Uniform minimal sufficient statistic)

$X_1, X_2, \dots, X_n$  iid  $\text{Unif}(0, \theta+1)$

$$\text{then } f(x|\theta) = \begin{cases} 1 & 0 < x_i < \theta+1, i=1,2,\dots,n \\ 0 & \text{o.w} \end{cases}$$

we can write

$$f(x|\theta) = \begin{cases} 1 & \max x_i - 1 < \theta < \min x_i \\ 0 & \text{otherwise} \end{cases}$$

$\Rightarrow$  for two random samples  $x, y$

$$\frac{f(x|\theta)}{f(y|\theta)}$$