

INTRODUCTION TO RASPBERRY PI BOARD

- The Raspberry Pi is a tiny and affordable computer that you can use to learn programming through fun practical project.
- Raspberry Pi is the name of a series of a single-board computers made by Raspberry Pi Foundation.
- Raspberry Pi is used to learn programming skills, build hardware projects, do home automation, edge computing.
- Several generations of Raspberry Pi have been released.

All model of Raspberry Pi has feature a Broadcom system-on-a-chip (SoC) with an integrated ARM compatible central processing unit (CPU) and on-chip GPU.

- Processor speed ranges from 700MHz to 1.2GHz for RPi 3 and on-board memory range from 256MB to 1GB RAM.
- SD cards are used to store OS and program memory in either SDHC or MicroSDHC sizes.
- Depending on model, the boards have either a single USB port or upto four USB ports.
- For video output, HDMI and composite video are supported.

- Lower level output is provided by a number of GPIO pins which support common protocols like I²C.
- The Raspberry Pi Pin Configuration is as follows:

Raspberry Pi Pinout

Alternate 0 to 10 enables to switch between a peripheral function.

Alternate function

3.3V PWR	1	2	5V PWR	
I2C1 SDA	3	4	5V PWR	
I2C1 SCL	5	6	GND (Switches off prescaler)	
GPIO3	7	8	UART0 TX	
GPIO4	9	10	UART0 RX	
GPIO5	11	12	GPIO 18	
GPIO6	13	14	GND	
GPIO27	15	16	GPIO 23	
GPIO22	17	18	GPIO 24	
3.3V PWR	19	20	GND (Switches off I2C)	
SPI0 MOSI	GPIO10	21	22	GPIO 25
SPI0 MISO	GPIO9	23	24	GPIO 8 (also SPI0 CS0)
SPI0 SCLK	GPIO11	25	26	GPIO 7 (also SPI0 CS1)
GPIO 9 GND	Reserved	27	28	Reserved (processing tasks)
GPIO5	29	30	GND	
SPI0 MOSI	GPIO6	31	32	GPIO12 (usage pending)
SPI0 MISO	GPIO13	33	34	GND
SPI0 SCLK	GPIO19	35	36	GPIO16 (switches off I2C)
GPIO26	37	38	GPIO20 (SPI1 CS0)	
GND	39	40	GPIO21 (SPI1 MOSI)	
			GPIO2 (SPI1 SCLK)	

Logic 1 indicates M0 or M1 or H or L or 1 or 0

Fig: Raspberry Pi Pin Configuration

Pinouts on the right side of board with below no peripherals.

Pinouts on the left side of board with above no logic 0 or 1.

Pinouts shown in the middle of board with logic 0 or 1.

Logic 0

Experiment - 1

PROCEDURE TO LOAD OS ON RASPBERRY PI

Aim: To install / load operating system on Raspberry Pi.

Apparatus:

- 1) Raspberry Pi board (you may or may not have)
- 2) SD card
- 3) SD card reader
- 4) PC having no floppy disk drive with atleast 1G

Procedure:

1. Download the Raspberry Pi operating system from its official website.
- a. The recommended OS is called Raspbian.
2. Unzip the file that you just downloaded.
- a) Right click on the file and choose "Extract all".
- b) Follow the instructions - you will end up with a file ending in .img.

This .img file can only be written to your SD card by special disk imaging software, so...

- 3) Download the Win32DiskImager software from here.
- a. Unzip it in the same way you did the Raspbian.zip file.
- b. You now have a new folder called win32diskimager-binary

You are now ready to write the Raspbian image to your SD card.

4. Writing Raspbian to the SD card

- a) Plug your SD card into your PC.
- b) Run the file named Win32DiskImager.exe
- c) If the SD card you are using isn't found automatically then click on the drop down box and select it.

d) In the Image File box, choose the Raspberry img file that you downloaded.

e) click Write.

f) After a few minutes you will have an SD card that you can use in your Raspberry Pi.

5) Booting your Raspberry Pi for the first time

a) Follow the Quick start guide on page 1.

b) On first boot you will come to the Raspi-config window.

c) Change settings such as timezone and locale if you want.

d) Finally, select the second choice:

expand-rootfs

and say 'yes' to a reboot when it is finished.

e) The Raspberry Pi will reboot and you will see:

raspberrypi login:

f) Type:

Pi

g) You will be asked for your password.

h) Type: (it will ask you press some buttons to activate raspberry pi)

i) You will then see the prompt:

Pi@raspberrypi ~ \$

j) Start the desktop by typing: startx

k) You will find yourself in a familiar-but-different desktop environment.

l) Experiment, explore and verify.

Result:

Installed Raspberry Pi OS for Raspberry Pi board using SD

card. This lesson is now available at www.english-test.net

29 (1) Abuse

b660d Flora of Quebec 163

(e) Best square code

Language

• Global wire彙報與各國政府對該事件的反應。

Monatst. 10 (1986) (Edizioni testi univ.) Bogni) $m = \text{long}$
"Grenzschwelle" (Edizioni testi univ.) Bogni) $m = \text{short}$

grown to know - the

Central American Wing

formal form = vib

Fontanella Indiana = 470-10017

6msec per mm = 1900 ft

form of form = whether

(*Abba hilf uns Christ unser Herr sei uns'*) 339

($\text{Pb}_2\text{Zr}_2\text{O}_5$, molar 10 mol) 200-2

Experiment-2

BASIC ARITHMETIC OPERATIONS

Ge given board Python int 3.0 & program below

Aim: To perform basic arithmetic operations using
Raspberry Pi

Apparatus: (1) PC

(2) Raspberry Pi board

(3) Power supply cable

Procedure:

- Using the Python programming language for writing the code for arithmetic operations is simple and easy.
- Open the Raspberry Pi Software and write code in Thonny.

Boot Pi \rightarrow Go to main menu \rightarrow Programming \rightarrow Select Thonny.

Program:

```
num1 = int(input('Enter First number:'))
```

```
num2 = int(input('Enter Second number:'))
```

```
add = num1 + num2
```

```
diff = num1 - num2
```

```
mul = num1 * num2
```

```
div = num1 / num2
```

```
floor-div = num1 // num2
```

```
Power = num1 ** num2
```

```
modulus = num1 % num2
```

```
Print ('Sum of ', num1, 'and', num2, 'is:', add)
```

```
Print ('Diff of ', num1, 'and', num2, 'is:', diff)
```

```
print ('Product of', num1, 'and', num2, 'is:', mul)
print ('Division of', num1, 'and', num2, 'is:', Div)
print ('Floor Division of', num1, 'and', num2, 'is:', floor_div)
print ('Exponent of', num1, 'and', num2, 'is:', power)
print ('Modulus of', num1, 'and', num2, 'is:', modulus)
```

Output:

Enter First number: 4

Enter Second number: 2

Sum of 4 and 2 is: 6

Difference of 4 and 2 is: 2

Product of 4 and 2 is: 8

Division of 4 and 2 is: 2

Floor Division of 4 and 2 is: 2

Exponent of 4 and 2 is: 16

Modulus of 4 and 2 is: 0

(Remainder)

Result:

Verified the arithmetic operators output with theoretical values.

Experiment-3

(Lum. of LED using Thonny) by

BLINKING OF LED

Aim: To perform blinking of LED operation using Raspberry Pi board and to verify practically

Apparatus: 1) PC or desktop

2) Raspberry Pi board

3) LED (P10)

4) Jumping wires

5) Mouse for working

6) Web browser

Procedure:

- Open the Raspberry Pi software and follow the below steps.
Boot Pi → Go to main menu → Programming → select Thonny.
- Write the program for blinking of led in thonny.

Program:

```
import RPi.GPIO as G
```

```
import time
```

```
G.setmode(G.BOARD)
```

```
G.setup(7,G.OUT)
```

for i in range(2):

```
while True:
```

```
G.output(7,True)
```

```
print("Led is On")
```

```
time.sleep(1)
```

```
G.output(7,False)
```

```
print("Led is Off")
```

```
time.sleep(1)
```

Experiment

Result:

DISCUSSION AND HTM OUTPUTS

Blinking of LED operation is performed and observed naturally along after (2) pinPad(2) on/off at 0.1s practically.

all types of two blood required given nothing

Experiment-4

CONTROLLING LED WITH PUSH BUTTON

Aim: To perform controlling LED with push button operation using RaspberryPi board and to verify the output.

Apparatus: (1) PC or desktop

(2) Push button

(3) LED

(4) Jumping wires

(5) RaspberryPi board

Procedure:

- Open the Raspberry Pi Software and follow the below steps
Boot Pi → Go to main menu → Programming → select Thonny
- Connect the LED and Push button to the Raspberry Pi board according the circuit requirements.

Program:

```
import RPi.GPIO as GPIO
import time
GPIO.setmode(GPIO.BCM)
GPIO.setup(23, GPIO.IN, pull_up_down=GPIO.PUD_UP)
GPIO.setup(24, GPIO.OUT)
try:
    while True:
        button_state = GPIO.input(23)
```

```
if button_state == False:  
    GPIO.output(24, True) # Turn LED ON  
    print('Button Pressed...')  
    time.sleep(0.2)  
  
else:  
    GPIO.output(24, False)  
  
except:  
    GPIO.cleanup()
```

Output:

Button Pressed...

Result:

verified the output for controlling LED with Push Button.

Experiment-5

DHT11 SENSOR TEMPERATURE AND HUMIDITY

Aim: To measure the temperature and humidity using DHT11 sensor.

Apparatus: 1) DHT11 sensor (Model No. DHT11-A19)

2) PC/Desktop

3) Jumping wires

4) Raspberry Pi board.

Procedure:

To install DHT11 sensor library

1. To download module from Git, Install Git

"sudo apt-get install git-core"

2. Download Adafruit-DHT library

"git clone https://github.com/adafruit/Adafruit-Python-DHT"

3. Navigate to Adafruit-Python-DHT directory

"cd Adafruit-Python-DHT"

4. For Python3

"sudo apt-get install build-essential python3-dev"

5. Install DHT Module

For Python3

"sudo python3 setup.py install"

Program:

```
# Import Sensor Module
import Adafruit_DHT
```

import Adafruit-DHT
import DHT11 sensor with autoreset off measure of temp
try:
 while True:
 humidity, temperature = Adafruit-DHT.read_retry
 print("Humidity={}% ; Temperature={}C".format(humidity, temperature))
except KeyboardInterrupt:
 print("Aborted by user")

Result:

Observe different results for temperature and humidity
based on the room conditions using DHT11 sensor

Observation of humidity varies from 60% to 80%
based on the room conditions

Observation of temperature varies from 19A to 22A
based on the room conditions

Observation of temperature varies from 19A to 22A
based on the room conditions

Experiment - 6

DHT11 SENSOR WITH THINGSPEAK

Aim: To measure the temperature and humidity values

using DHT11 sensor with thingspeak cloud platform.

Apparatus: (i) PC or desktop

(ii) thingspeak IoT cloud platform

(iii) DHT11 sensor (smart terminal)

(iv) Jumping wires

(v) Raspberry Pi board

Procedure:

Thingspeak setup for Pi weather station.

Step 1: Thingspeak Account Setup

- For creating your channel on Thingspeak you first need to sign up on Thingspeak.

Step 2: Create a channel for your data

- Once you sign in, create a new channel by clicking "New Channel" button.

Step 3: API Key

- Click on "API Keys" button to get your unique API key for uploading your sensor data.
- Copy your "API key".

• Install following in the terminal

sudo pip install thingspeak

sudo pip3 install thingspeak

program:

```
import thingspeak
```

```
import time
```

```
import Adafruit-DHT
```

```
channel_id = XXXXXX
```

```
write_key = 'XXXXXX'
```

```
pin = 3
```

```
sensor = 11
```

```
def measure(channel):
```

```
try:
```

```
    humidity, temperature = Adafruit-DHT.read_retry  
        (sensor, pin)
```

```
    response = channel.update({'field1': temperature,  
        'field2': humidity})
```

```
    print("Humidity = {}%; Temperature = {}C".format  
        (humidity, temperature))
```

except:

```
    print("connection failed")
```

```
if __name__ == "__main__":
```

```
    channel = thingspeak.Channel(id=channel_id, api_key  
        = write_key) .
```

```
while True:
```

```
    measure(channel)
```

```
    time.sleep(15)
```

Result:

The room temperature and humidity value are observed using the DHT11 sensor with thingspeak platform.

Platform:

thingspeak

Use thingspeak API through THD - turbola trigger

(A) Room's current

XXXXXX = 67.500000

(B) Room's current

XXXXXX = 40.900000

(C) Room's current

E = 0.01

Thingspeak

H = 10.0000

Therefore, step 3 is complete (temperature minimum for

using "if (THD - turbola = minTemperature, tibimurid (min, 0.01)) { // minimum on thingspeak, so first read the

key, autoconnect("tibia1") // key, tibia1 = connect

{ tibimurid("tibia1")

for (int i = 0; i < 100; i++)

Serial.print("5f"); autoconnect("tibia1"); tibimurid("tibia1")

else if (THD - turbola >= 67.5)

Serial.println("OK");

else if (THD - turbola <= 40.9)

Serial.println("OK");

public void b1_turbo() { tibimurid("tibia1"); tibimurid("tibia1") = 67.5;

else if (THD - turbola <= 40.9)

Serial.println("OK");

else if (THD - turbola >= 67.5)

Serial.println("OK");

Experiment - 7

CAMERA INTERFACING

Aim: To perform camera interfacing using Raspberry Pi board.

Apparatus:

- (1) PC or desktop
- (2) Raspberry Pi board
- (3) Camera Module
- (4) Power cable.

Procedure:

- Connect the camera module to the Raspberry Pi board.
- Enabling the camera
 - Open Raspberry Pi configuration tool from the main menu
 - Open preferences
 - Raspberry Pi configuration
 - Interfaces \Rightarrow Camera Enabled
- Taking a picture in terminal.
 - 1. raspistill -o pic.jpg (Image captured after 5 seconds)
 - 2. raspivid -o video.h264
- Recording a video with Raspberry pi camera module

Python code to capture the image

To install library for the camera module

```
sudo apt-get install python-picamera
```

Program:

```
from time import sleep
from picamera import PiCamera
camera = PiCamera()
camera.resolution = (1024, 768)
camera.start_preview()
sleep(2)
camera.capture('picture1.jpg')

# Take a picture including the annotations
camera.annotate_text = "Hello world!"
camera.start_preview()
sleep(1)
camera.capture('picture2.jpg')

# Capture and crop the picture
camera.start_preview()
sleep(2)
camera.capture('picture3.jpg', resize=(320, 240))
camera.stop_preview()

# Recording Video using Pi Camera
camera.resolution = (640, 480)
camera.start_recording('my_video.h264')
camera.wait_recording(30)
camera.stop_recording()
```

2 - from 1907 (r)

Result:

Result: Observed the Camera interfacing and captured images.

and recorded video using the Pi camera.

1999-2000 left at bed base when stems left ground.

Experiment-8

MOTION DETECTION PIR USING LED AND CAMERA

Aim: To perform motion detection PIR using LED and camera

Apparatus: (1) PC or desktop

(2) PIR Sensor

(3) LED

(4) Jumping wires

(5) Raspberry Pi board

(6) Camera Module.

Procedure:

- Connect the camera module and Led to the raspberryPi board.
- Write the program code in thonny.

Program:

```
import RPi.GPIO as GPIO  
import time  
from picamera import PiCamera  
GPIO.setmode(GPIO.BCM)  
pir = 8  
led = 10  
GPIO.setup(pir, GPIO.IN)  
GPIO.setup(led, GPIO.OUT)  
print (" Sensor initializing....")  
time.sleep(2)  
print (" Active")
```

```
print("Press Ctrl+C to end program")
camera = PiCamera()
camera.resolution = (1024, 768)
try:
    while True:
        if GPIO.input(pi) == True:
            print("Motion Detected!")
            GPIO.output(led, True)
            camera.start_preview()
            camera.annotate_text = 'Intruder!'
            time.sleep(2)
            camera.capture('foo1.jpg', resize=(320, 240))
            camera.start_preview()
            time.sleep(4)
            GPIO.output(led, False)
            time.sleep(2)
except KeyboardInterrupt:
    pass
finally:
    GPIO.output(led, False)
    GPIO.cleanup()
    print("Program ended")
```

Output:

Sensor initializing---

Active

Press Ctrl+C to end program

Motion Detected

Program ended

Result:

The functionality of PIR sensor along with camera module is observed practically for intruder detection and verified.

Experiment - 9

Do you want to control the door lock on your Node-RED

Aim: To write a program that sends sensor data to Cloud using Node-RED service to perform Data Analytics using Rpi3.

using Node-RED service to perform Data Analytics using Rpi3.
and also web interface will be provided.

Apparatus: (1) PC or Monitor

(2) Raspberry Pi board.

Procedure: After connecting Raspberry Pi with monitor

- Start up your Raspberry Pi.
- Click on the Raspberry Pi icon, then the Programming menu to open Node-RED.
- You should see a window displaying information about Node-RED starting up.
- Now go to the internet menu and open chromium web browser.
- In chromium, locate the address bar at the top and type in localhost:1880, then press enter. This will display the Node-RED interface.
- Programs in Node-RED are called flows.
- The coloured blocks on the left side are nodes.
- Scroll down to bottom to see nodes labelled Raspberry Pi.
- You will see two nodes with label "rpi gpio":
 - Raspberry icon on left is used for input
 - Raspberry icon on right is used for output (Ex: LED)

- Drag an output node onto the blank page in middle.
- Double-click on the node, box appears to let you configue the node.
- After configuration is done. Click Done.

Result:

Performed data analytics using NodeRed service with RPi 3 board is verified.