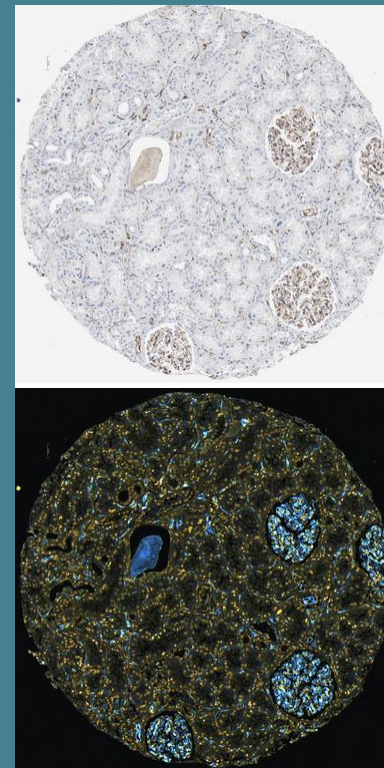


SegMed : Analysis on Automated Nuclei Segmentation Methods

— A Presentation by :
Akhil Mokkapati
Naga Anjaneyulu Kopalle
Sai Sugeeth Kamineni
Vijay Sai Kondamadugu

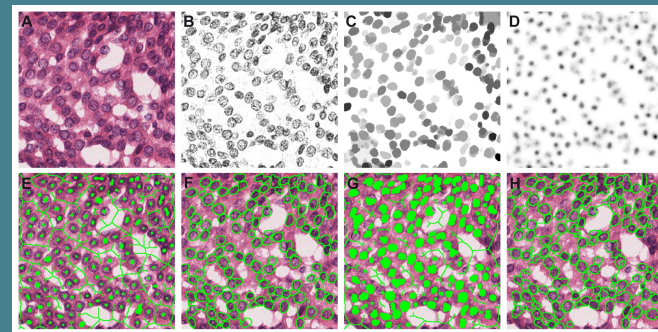
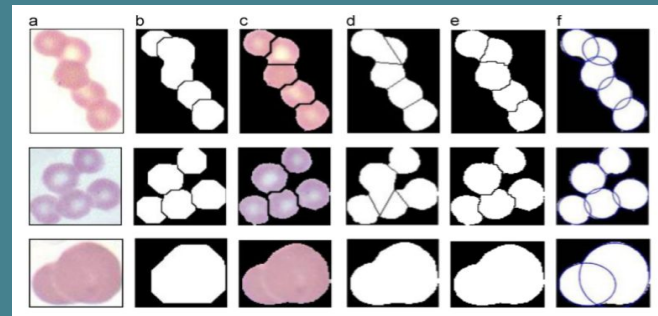
Project Proposal

- Nuclei segmentation in high-resolution histopathological images.
- Nuclear segmentation is an important step in the pipeline of many cytometric analyses. Helps in obtaining the detailed information of each nucleus.
- Variation in appearance such as color, shape, and texture, makes nuclei segmentation from histopathological images very challenging.
- Contribute to the Human Biomolecular Atlas Program (HuBMAP). HuBMAP is to develop an open and global platform to map healthy cells in the human body.



Prior

- Conventional - Otsu's method detects nuclei through intensity thresholding, filtering by utilizing the features of the nuclei, k-means.
- Limitations - they are only effective for one or a few specific types of nuclei or images and are highly sensitive to manually set parameters .
- Supervised Learning - Pixel level classification, splitting overlapped nuclei areas through bottleneck detection and ellipse fitting.
- Deep learning - Advancements in object classification, object detection and segmentation.





Models

- Nuclei-boundary model
- Unsupervised SegMed Model
- Mask R-CNN
- UNet2

Data Analysis



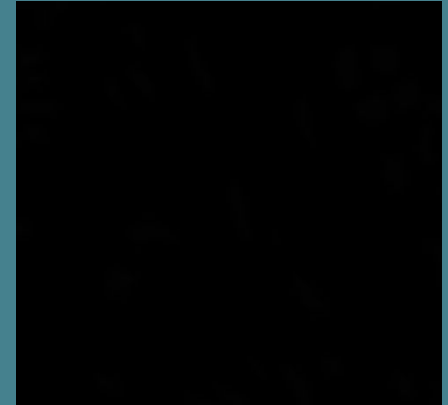
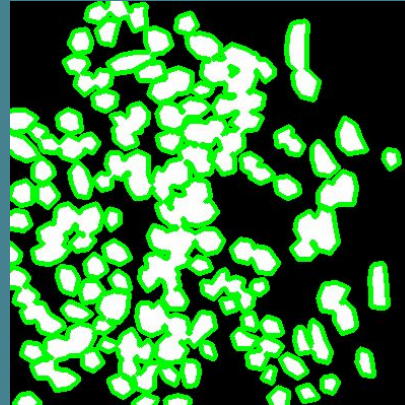
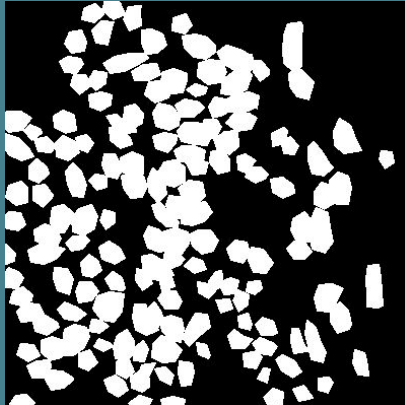
Datasets from multiple sources :

- MonuSeg - A Multi-Organ Nucleus Segmentation Challenge 2018 .
 - Training data of MoNuSeg contains 30 images and around 22000 nuclear boundary annotations and the test set has 14 images with 70000 nuclear boundary annotations.
- PSB Crowdsource
 - It has crowdsourcing image annotations for nucleus detection and segmentation that includes annotations from experts, automated methods and the crowd.
- TNBC
 - This dataset consists of H&E stained, triple negative breast cancer (TNBC) tissue slide images of 11 different patients.

Data Preprocessing

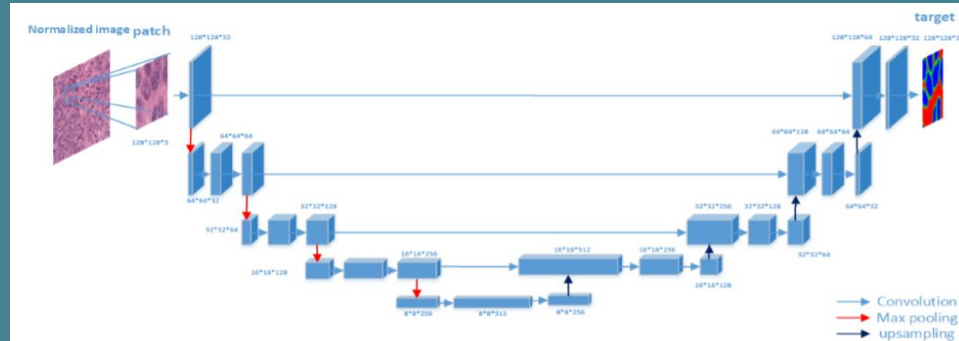
- H&E stain is the most widely used stain protocol in medical diagnosis.
- The nuclei of cells are stained to blue by Haematoxylin while cytoplasm is colored to pink by Eosin.
- Each of these models have used colour normalization techniques to eliminate the negative interference caused by color variation.
- Some models required for modifying the ground truth images and pixel level classification .
- Manual Annotations for nuclei .

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Unet2

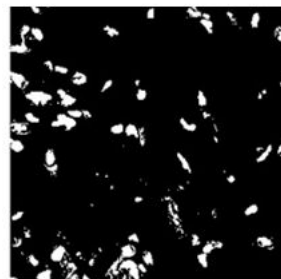
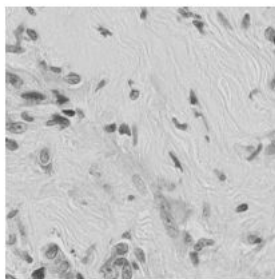
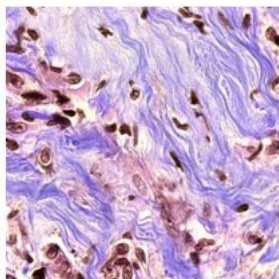
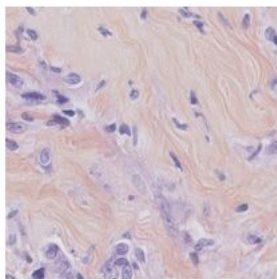
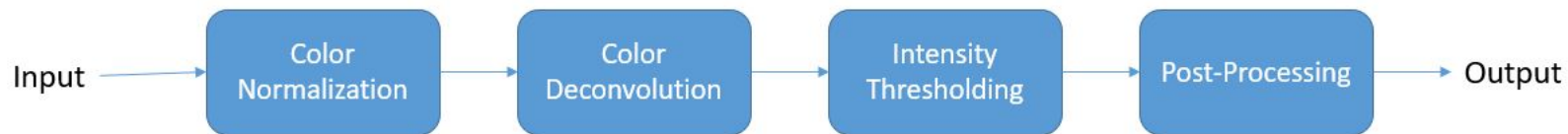
- Unet and Mask-RCNN are some of the highly successful architectures for instance based segmentation problems .
- This model uses the UNET architecture to classify the foreground and backgrounds of medical images .



- The encoding layers are used to extract different levels of contextual feature maps.
 - The decoding layers are designed to combine these feature maps produced by the encoding layers to generate the desired segmentation maps.
 - Loss Function : Binary Cross Entropy
- Evaluation Metrics : Mean IOU

Unsupervised-SegMed Model

- This unsupervised method is done using the library HistomicsTK.
- This Model consists of four stages:



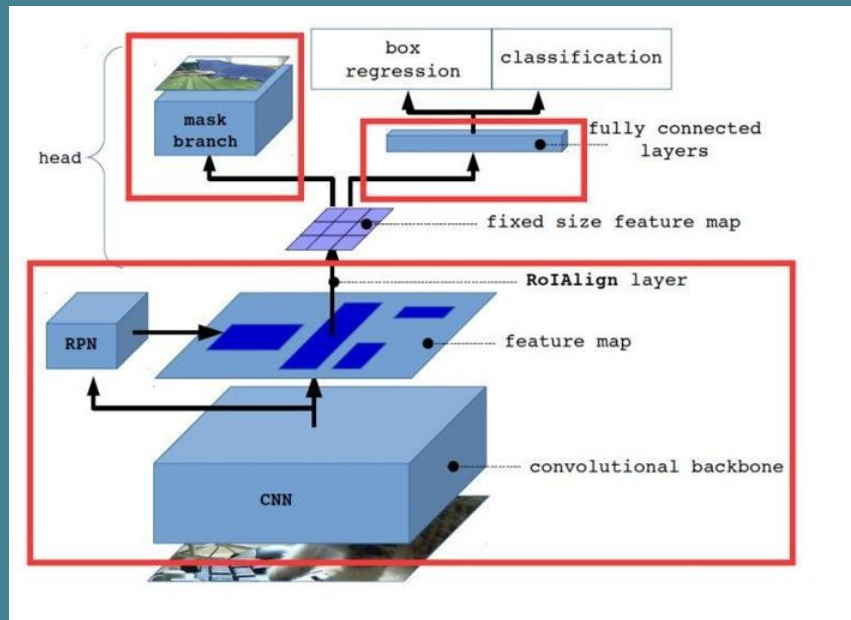


Limitations

- It is specific to H&E stained images.
- Params in post-processing such as minimum nuclei area, foreground intensity threshold should be provided to modulate it for multiorgan histology images.

Mask R-CNN

- backbone+RPN
- Parallel heads for box regression and classification
- RoIAlign



Loss Functions

$$\mathcal{L} = \mathcal{L}_{\text{cls}} + \mathcal{L}_{\text{box}} + \mathcal{L}_{\text{mask}}$$

Classification Loss

- Multiclass cross-entropy loss

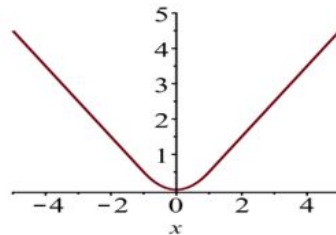
$$\mathcal{L}_{\text{cls}}(p_i, p_i^*) = -p_i^* \log p_i - (1 - p_i^*) \log(1 - p_i)$$

Bounding Box Loss (Top (x,y), Width and Height)

- Smooth L1 loss between ground-truth bounding boxes and predicted bounding boxes
- Smooth L1 loss is a robust L1 loss that is less sensitive to outliers than the L2 loss
 - Prevent gradient explosion

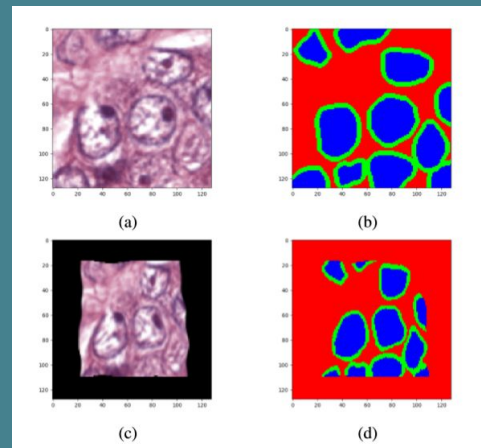
$$L_1^{\text{smooth}}(x) = \begin{cases} 0.5x^2 & \text{if } |x| < 1 \\ |x| - 0.5 & \text{otherwise} \end{cases}$$

$$\mathcal{L}_{\text{box}}(t^u, v) = \sum_{i \in \{x, y, w, h\}} L_1^{\text{smooth}}(t_i^u - v_i)$$



Nuclei-Boundary Model

- This model predicts the category of all the pixels of an image with only one pass.
- This model merges these two stage of extracting the nuclei and their edges at the same time.
- The output of the NB model has three channels, each has the same height and width with of the input image.
- Its values represent the probabilities of each pixel being background, boundary or inside class, respectively.
- Augmentation techniques used random elastic transformation, rescale, affine transformation, shift, flip and rotate.



Weighted loss

- This model has a weighted loss and a scheme for patch extraction and assembling.
- This allows the neural network to predict a segmentation map of equal size without concerning the lack of context issue in the border area.
- The model is trained by minimizing the categorical softmax cross-entropy loss between predictions and target.

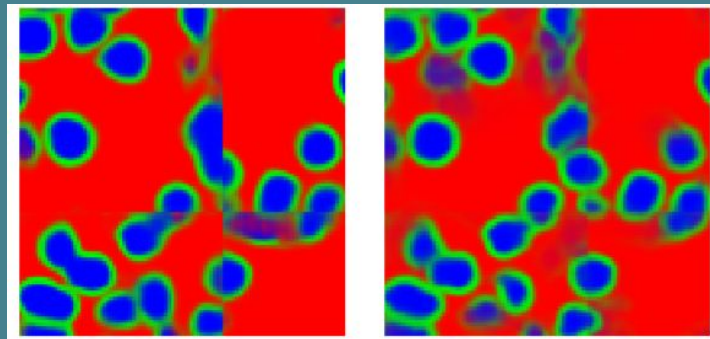
$$L = \sum_i \sum_j W_{i,j} \log(p_{t(i,j)}(i,j))$$

$$W_{i,j} = \alpha \frac{D_{i,j}^e}{(D_{i,j}^c + D_{i,j}^e)}$$
$$\alpha = \frac{h \cdot w}{\sum_{i=1}^h \sum_{j=1}^w \frac{D_{i,j}^e}{D_{i,j}^c + D_{i,j}^e}}$$

Overlapped Patches and Post Processing

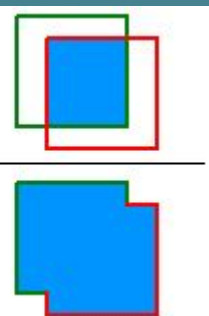
- Memory constraints and poor border area accuracy in UNET.
- The patches are extracted by sliding window with a stride. For assembling, a vote mechanism is applied to predict each pixel using $P(i,j)$.
- NB model detects both inside and boundary classes, all we need is the inside class map.
- Inside class map is transformed to a binary map using a constant threshold 0.5.
- In this way, each connected component in the binary image indicates the inside area of one nucleus.

$$P(i,j) = \frac{\sum_k W_{k(i,j)} p(k(i,j))}{\sum_k W_{k(i,j)}}$$



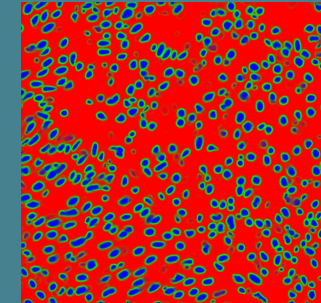
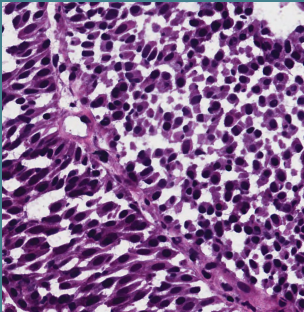
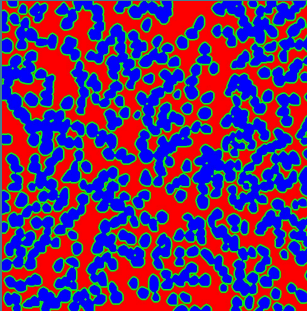
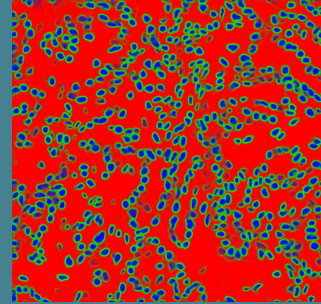
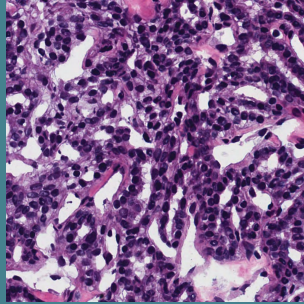
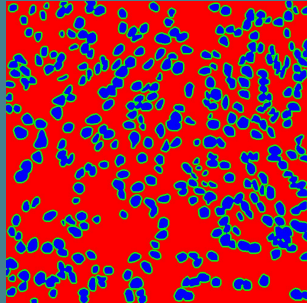
Evaluation

- Evaluation across models, datasets is pretty challenging .
- We used meanIOU - is the area of overlap between the predicted segmentation and the ground truth divided by the area of union between the predicted segmentation and the ground truth.

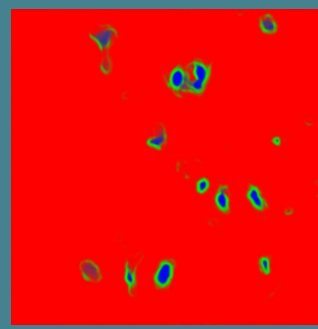
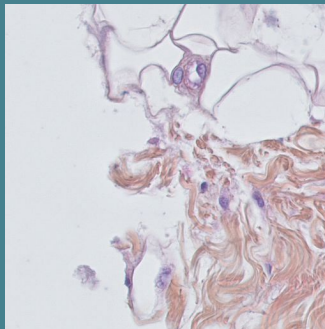
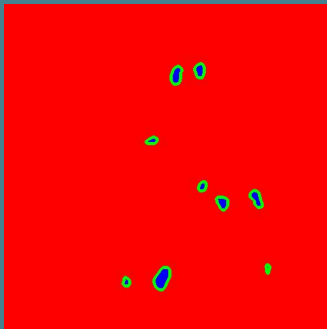
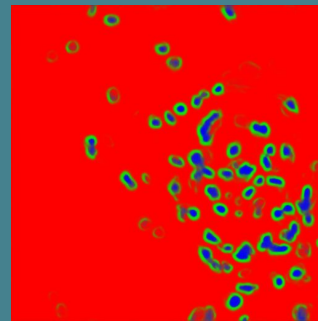
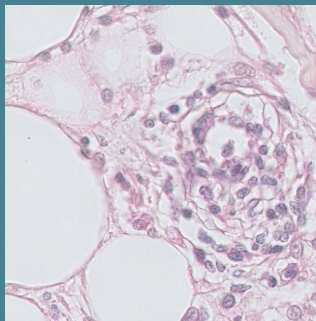
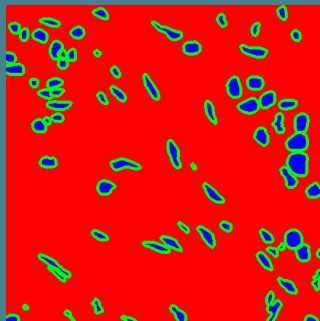
$$IOU = \frac{\text{area of overlap}}{\text{area of union}} = \frac{\text{area of overlap}}{\text{area of union}}$$


Segmentation Results

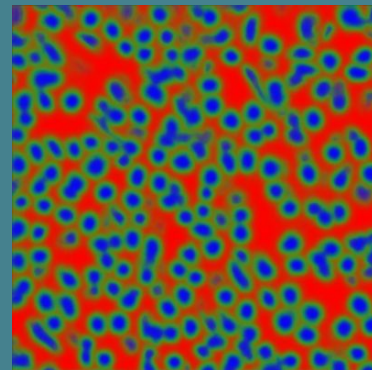
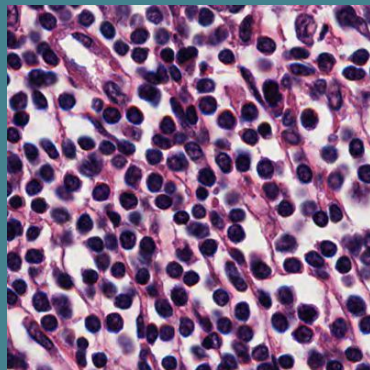
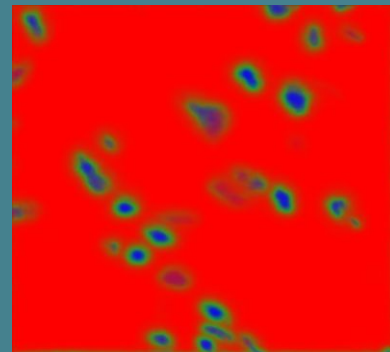
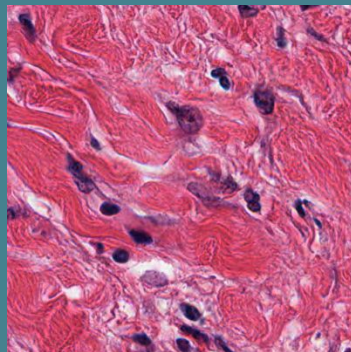
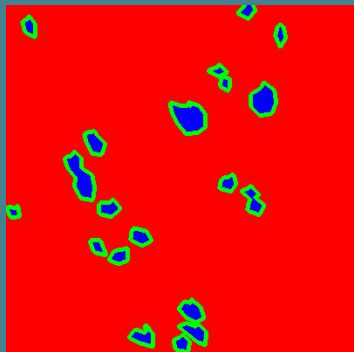
Nuclei Boundary Model - MonuSeg



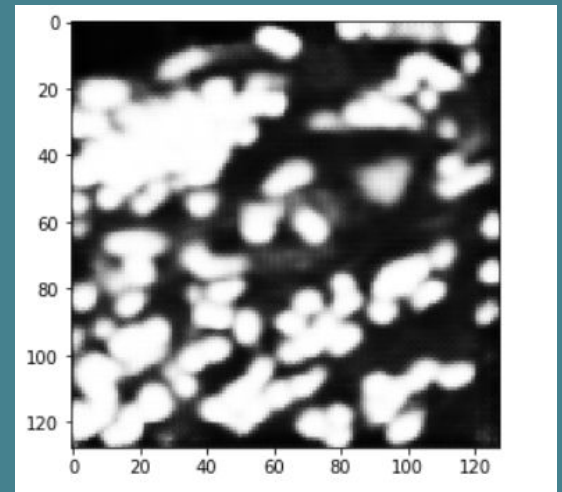
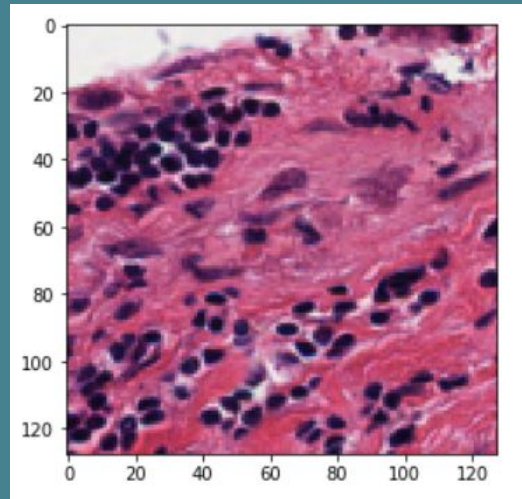
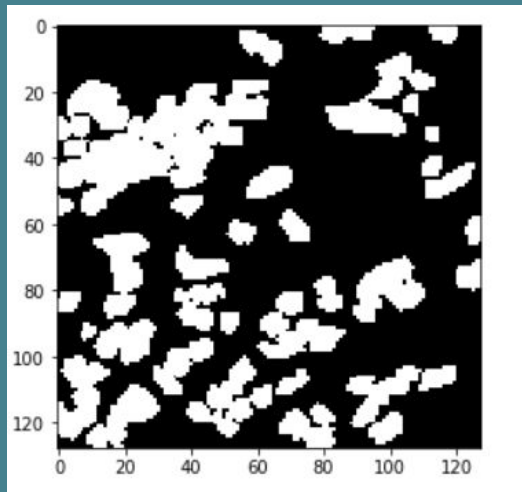
Nuclei Boundary Model - TNBC



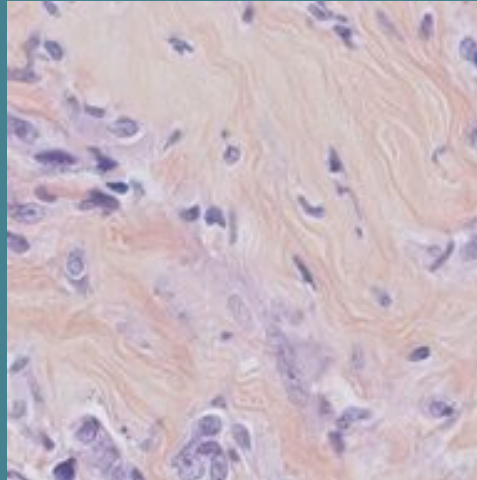
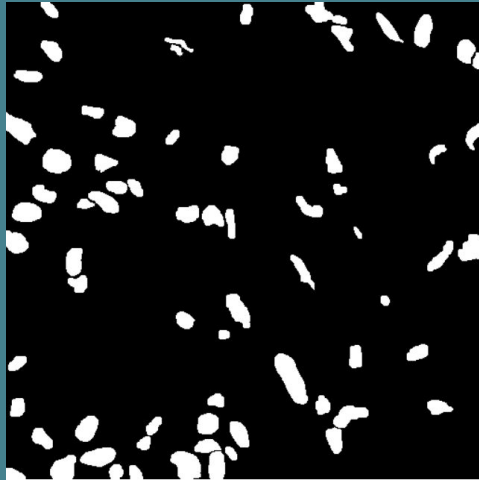
Nuclei Boundary Model - PSB



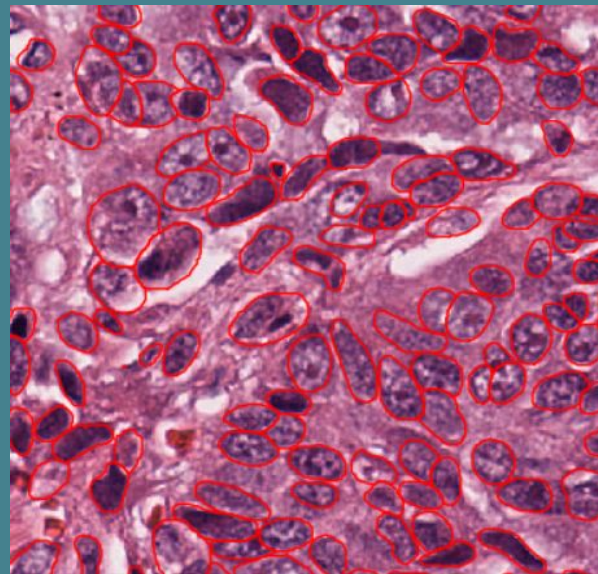
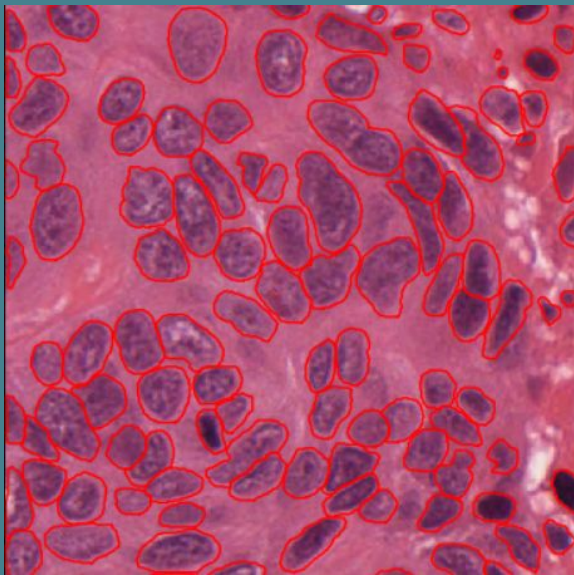
Unet2 - PSB



Unsupervised - SegMed Model



Mask R-CNN





Thank you!