**Development**

2.1 Code: Si Han, Report: Both

2.2 Code: Si Han, Report: Saivydas

3.1 Code: Both, Report: Saivydas

3.2 Code: Both, Report: Saivydas

*GitHub:* [*https://github.com/SaiVillani/IVR*](https://github.com/SaiVillani/IVR)

**Robot Vision**

2.1: Joint state estimation

The algorithm uses…

2.2: Joint state estimation

The algorithm uses…

**Robot Control**

*3.1: Forward Kinematics*

The algorithm uses…

*3.2: Inverse Kinematics*

The algorithm uses…