Assignment 1 - part 2

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```
In [15]: import matplotlib.pyplot as plt
import numpy as np

from models.neural_net import NeuralNetwork
from utils.data_process import get_CIFAR10_data

%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 10.0) # set default size of pl
ots

# For auto-reloading external modules
# See http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2
```

The autoreload extension is already loaded. To reload it, use: %reload_ext autoreload

Loading CIFAR-10

Now that you have implemented a neural network that passes gradient checks and works on toy data, you will test your network on the CIFAR-10 dataset.

```
In [16]: # You can change these numbers for experimentation
# For submission be sure they are set to the default values
TRAIN_IMAGES = 49000
VAL_IMAGES = 1000

TEST_IMAGES = 10000

data = get_CIFAR10_data(TRAIN_IMAGES, VAL_IMAGES, TEST_IMAGES)
X_train, y_train = data['X_train'], data['y_train']
X_val, y_val = data['X_val'], data['y_val']
X_test, y_test = data['X_test'], data['y_test']
```

```
In [17]: def get_acc(pred, y_test):
    return np.sum(y_test==pred)/len(y_test)*100
```

Train using SGD

To train our network we will use SGD. In addition, we will adjust the learning rate with an exponential learning rate schedule as optimization proceeds; after each epoch, we will reduce the learning rate by multiplying it by a decay rate.

You can try different numbers of layers and other hyperparameters on the CIFAR-10 dataset below.

```
In [18]: # Hyperparameters

input_size = 32 * 32 * 3
num_layers = 2
hidden_size = 110
hidden_sizes = [hidden_size] * (num_layers - 1)
num_classes = 10
epochs = 4000
batch_size = 200
learning_rate = 7e-2
```

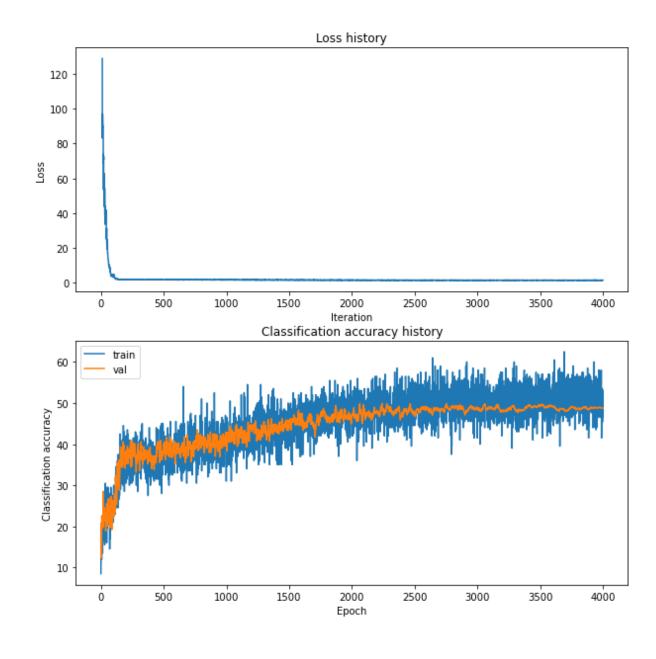
```
learning rate decay = 0.9
regularization = 1e-2
def train(hidden sizes, num layers, learning rate, learning rate decay,
regularization, optimizer = "SGD"):
    # Initialize a new neural network model
    net = NeuralNetwork(input size, hidden sizes, num classes, num laye
rs)
   # Variables to store performance for each epoch
   train loss = np.zeros(epochs)
   train accuracy = np.zeros(epochs)
   val accuracy = np.zeros(epochs)
   # For each epoch...
   for epoch in tqdm(range(epochs)):
       batch idx = np.random.choice(TRAIN IMAGES, batch size, replace=
True)
       X batch = X train[batch idx]
       y batch = y train[batch idx]
       y pred = np.argmax(net.forward(X batch), axis = 1)
       train accuracy[epoch] = get acc(y pred, y batch)
       train loss[epoch] = net.backward(X batch, y batch, learning rat
e, regularization, mode = optimizer)
       # Validation
       # No need to run the backward pass here, just run the forward p
ass to compute accuracy
       y val pred = np.argmax(net.forward(X val), axis = 1)
       val accuracy[epoch] = get acc(y val pred, y val)
       if epoch % 50 == 0:
             learning rate *= learning rate decay
    return net, train loss, train accuracy, val accuracy
```

Graph loss and train/val accuracies

Examining the loss graph along with the train and val accuracy graphs should help you gain some intuition for the hyperparameters you should try in the hyperparameter tuning below. It should also help with debugging any issues you might have with your network.

```
In [20]: # Plot the loss function and train / validation accuracies
plt.subplot(2, 1, 1)
plt.plot(train_loss)
plt.title('Loss history')
plt.xlabel('Iteration')
plt.ylabel('Loss')

plt.subplot(2, 1, 2)
plt.plot(train_accuracy, label='train')
plt.plot(val_accuracy, label='val')
plt.title('Classification accuracy history')
plt.xlabel('Epoch')
plt.ylabel('Classification accuracy')
plt.legend()
plt.show()
```



Train using Adam

Next we will train the same model using the Adam optimizer. You should take the above code for SGD and modify it to use Adam instead. For implementation details, see the lecture slides. The original paper that introduced Adam is also a good reference, and contains suggestions for default values: https://arxiv.org/pdf/1412.6980.pdf

In [21]: # TODO: implement me

Hyperparameter tuning

Once you have successfully trained a network you can tune your hyparameters to increase your accuracy.

Based on the graphs of the loss function above you should be able to develop some intuition about what hyperparameter adjustments may be necessary. A very noisy loss implies that the learning rate might be too high, while a linearly decreasing loss would suggest that the learning rate may be too low. A large gap between training and validation accuracy would suggest overfitting due to large model without much regularization. No gap between training and validation accuracy would indicate low model capacity.

You will compare networks of two and three layers using the different optimization methods you implemented.

The different hyperparameters you can experiment with are:

- Batch size: We recommend you leave this at 200 initially which is the batch size we used.
- **Number of iterations**: You can gain an intuition for how many iterations to run by checking when the validation accuracy plateaus in your train/val accuracy graph.
- Initialization Weight initialization is very important for neural networks. We used the initialization W = np.random.randn(n) / sqrt(n) where n is the input dimension for layer corresponding to W. We recommend you stick with the given initializations, but you may explore modifying these. Typical initialization practices: http://cs231n.github.io/neural-networks-2/#init
- Learning rate: Generally from around 1e-4 to 1e-1 is a good range to explore according to our implementation.

- Learning rate decay: We recommend a 0.95 decay to start.
- **Hidden layer size**: You should explore up to around 120 units per layer. For three-layer network, we fixed the two hidden layers to be the same size when obtaining the target numbers. However, you may experiment with having different size hidden layers.
- Regularization coefficient: We recommend trying values in the range 0 to 0.1.

Hints:

- After getting a sense of the parameters by trying a few values yourself, you will likely want to write a few for-loops to traverse over a set of hyperparameters.
- If you find that your train loss is decreasing, but your train and val accuracy start to decrease
 rather than increase, your model likely started minimizing the regularization term. To prevent
 this you will need to decrease the regularization coefficient.

```
In [22]: input size = 32 * 32 * 3
         num layers = 2
         num classes = 10
         epochs = 2000
         batch size = 200
         # lrs= [1e-3]
         lrs = [7e-2]
         # hidden size = [100, 110]
         hidden size = [200]
         lrds = [0.9]
         \# lrds = [0.95, 0.9, 0.94]
         regs = [1e-2]
         \# regs = [3e-2, 1e-1, 5e-2]
         best acc = 0
         best net = None
         results = {}
         for in range(3):
             for hs in hidden size:
                 for lr in lrs:
                     for lrd in lrds:
```

```
for req in reqs:
                    hidden sizes = [hs] * (num layers - 1)
                    net, _, _, _ = train(hidden_sizes, num layers, lr,
lrd, reg, optimizer="Adam")
                    y val pred = np.argmax(net.forward(X val), axis = 1
                    val acc= get acc(y val pred, y val)
                    if val acc > best acc:
                        best net = net
                        best acc = val acc
                    results[(hs, lr, lrd, reg)] = val acc
                    print('hs %d, lr %e, lrd %f, reg %e, val accuracy:
%f' % (hs, lr, lrd, reg, val acc))
    for r in results:
          (hs, lr, lrd, reg) = r
         val acc = results[r]
         print('hs %d, lr %e, lrd %f, reg %e, val accuracy: %f' % (hs,
lr, lrd, req, val acc))
print("Best accuracy:", best acc)
               | 0/2000 [00:00<?, ?it/s]C:\Users\MYPC\Documents\Bachelo
  0%|
rs\sem6\DL\assignment1-part2\models\neural net.py:158: RuntimeWarning:
divide by zero encountered in log
 Total loss for this batch of training samples
               | 2000/2000 [03:21<00:00, 9.93it/s]
100%|
               | 2/2000 [00:00<02:20, 14.22it/s]
  0%|
hs 200, lr 7.000000e-02, lrd 0.900000, reg 1.000000e-02, val accuracy:
47.000000
100%|
                2000/2000 [03:24<00:00, 9.77it/s]
  0%|
               | 1/2000 [00:00<04:03, 8.22it/s]
hs 200, lr 7.000000e-02, lrd 0.900000, reg 1.000000e-02, val accuracy:
47.700000
               | 2000/2000 [03:12<00:00, 10.37it/s]
hs 200, lr 7.000000e-02, lrd 0.900000, reg 1.000000e-02, val accuracy:
47.700000
Best accuracy: 47.69999999999996
```

```
In [23]: y_test_pred = np.argmax(best_net.forward(X_test), axis = 1)
    test_acc= get_acc(y_test_pred, y_test)
    print(test_acc)
47.64
```

Run on the test set

When you are done experimenting, you should evaluate your final trained networks on the test set.

```
In [24]: best_2layer_sgd_prediction = None
    best_3layer_sgd_prediction = None
    best_2layer_adam_prediction = None
    best_3layer_adam_prediction = None
```

Compare SGD and Adam

Create graphs to compare training loss and validation accuracy between SGD and Adam. The code is similar to the above code, but instead of comparing train and validation, we are comparing SGD and Adam.

```
In [26]: input_size = 32 * 32 * 3
    num_layers = 2
    hidden_size = 110
    hidden_sizes = [hidden_size] * (num_layers - 1)
    num_classes = 10
    epochs = 5000
    batch_size = 200
    learning_rate = 1e-3
    learning_rate_decay = 1
    regularization = 1e-2
```

```
In [27]: # Plot the loss function and train / validation accuracies
         plt.subplot(2, 1, 1)
         plt.plot(sqd loss, label='sgd_loss')
         plt.plot(adam loss, label='adam loss')
         plt.title('Loss history')
         plt.xlabel('Epoch')
         plt.ylabel('Loss')
         plt.legend()
         plt.subplot(2, 1, 2)
         plt.plot(sqd accuracy, label='sqd acc')
         plt.plot(adam accuracy, label='adam acc')
         plt.title('Classification accuracy history')
         plt.xlabel('Epoch')
         plt.ylabel('Classification accuracy')
         plt.legend()
         plt.show()
```

