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# Grundlagen CNN

### **Keras Convolution Layer**

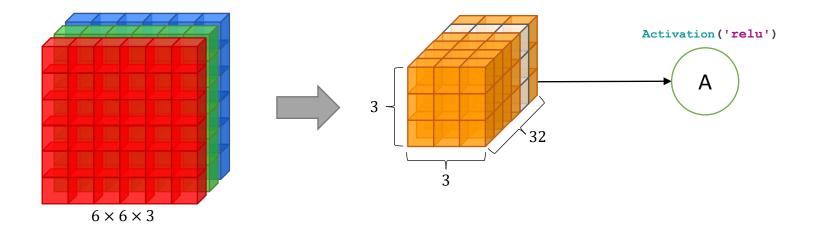
```
Conv2D(...)

- Filters
- kernel_size
- strides=(1, 1)
- padding='valid'
```

```
Conv2D(32, kernel size=2, strides=(2,2))
```

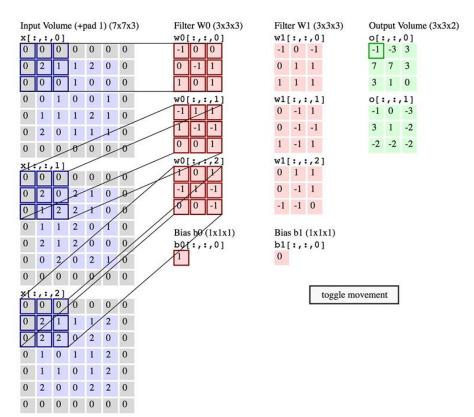
### **Keras Convolution Layer**

Conv2D(32, kernel\_size=(3,3), strides=(2,2))



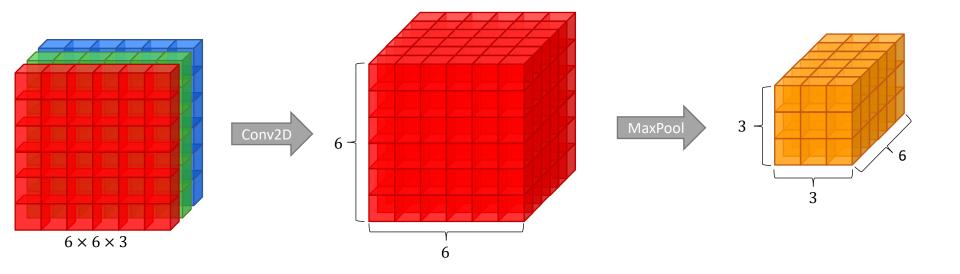
#### **Keras Convolution Layer**

- Two filters (kernel) of size 3x3x3
- Stride of (2,2)
- Filter of 2
- Zero padding

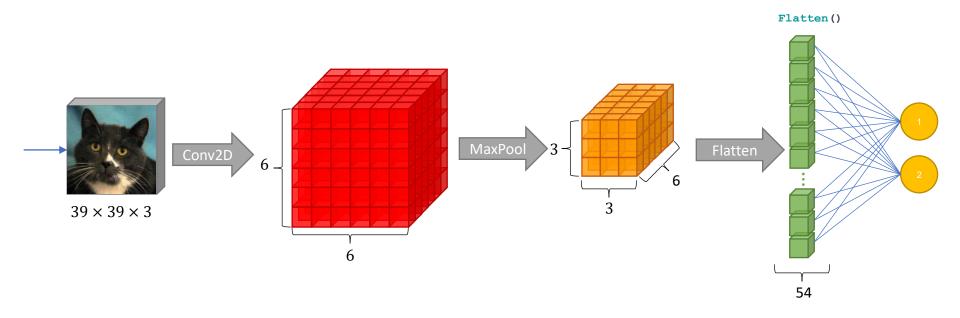


### **Keras MaxPool Layer**

MaxPool(pool\_size=(2,2))



### **Keras Flatten Layer**







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## Danke fürs Zuhören!

Gleich geht es weiter mit dem nächsten Thema.