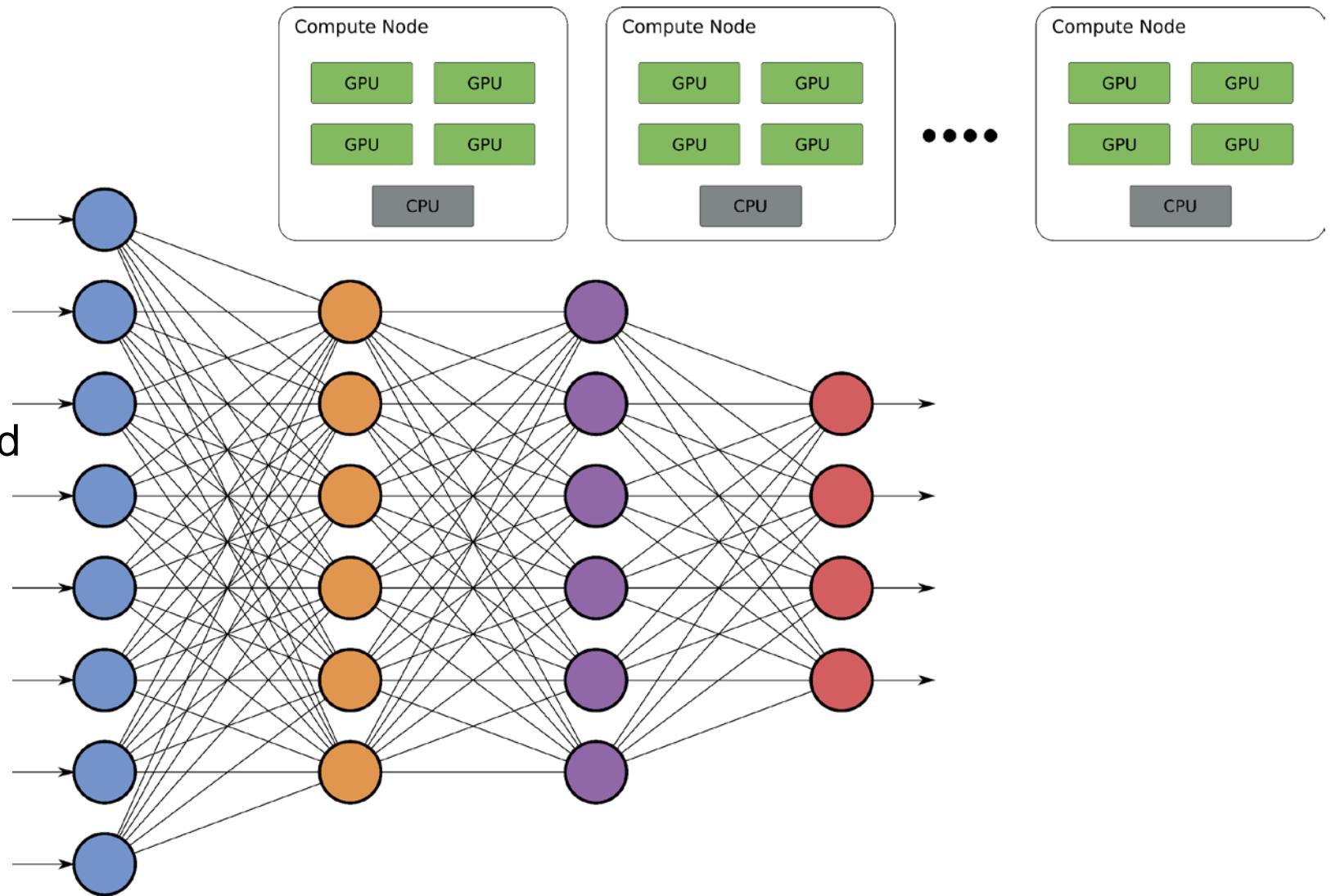


Distributed Deep Learning

Feroz Zahid, Michael
Riegler, and Tor Skeie
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- Full professor, Department of informatics, University of Oslo, Norway
- Adjunct research scientist, Simula Research Laboratory, Norway
- Fabriscale Technologies, CTO and co-founder
- Areas of expertise
 - HPC networking and management/middleware systems
 - Cloud computing and virtualization
 - Industrial Ethernet and wireless networking



[simula . research laboratory]



This presentation will introduce distributed deep learning, walk through prominent techniques, and identify existing challenges and future directions



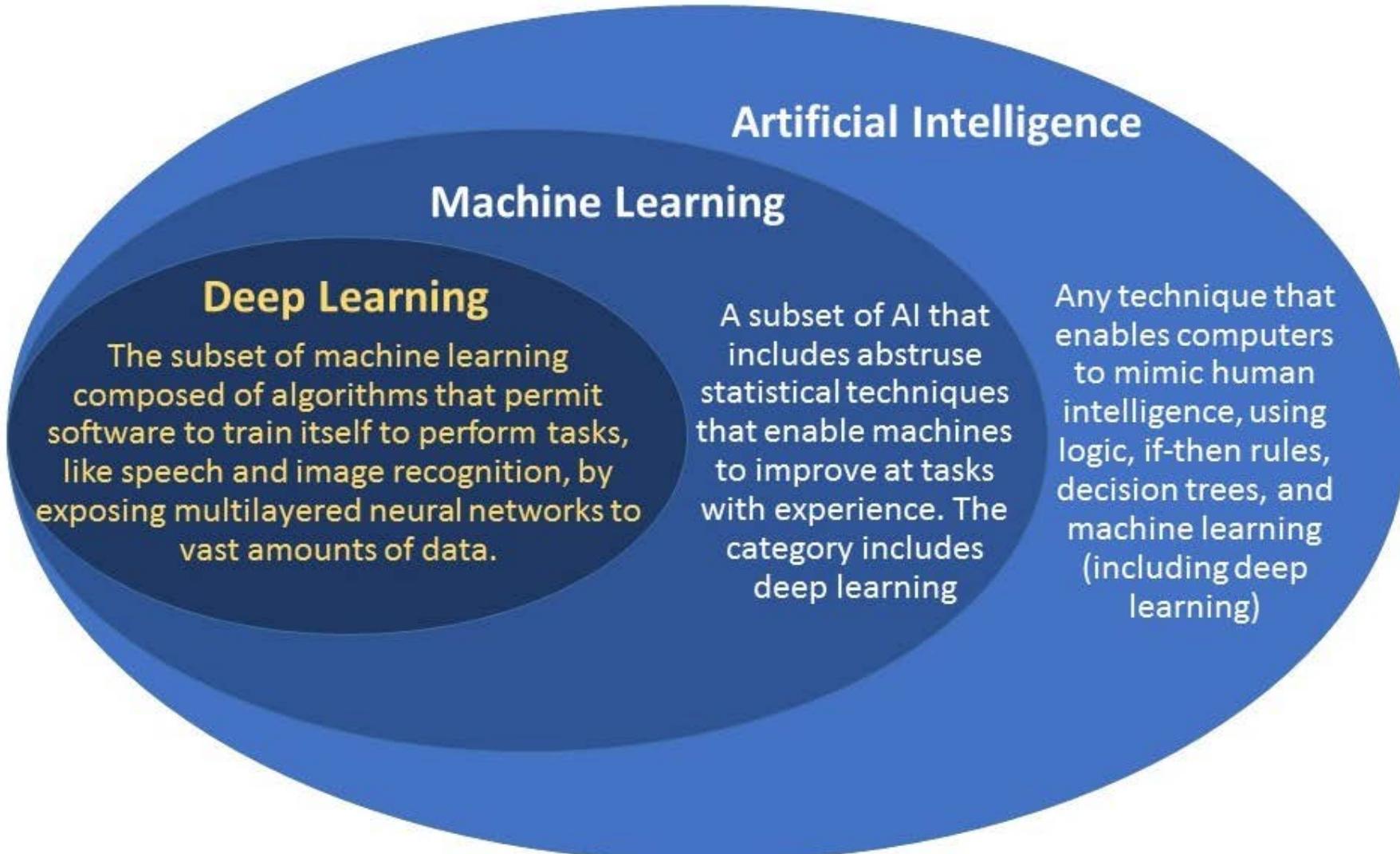
Introduction and Motivation



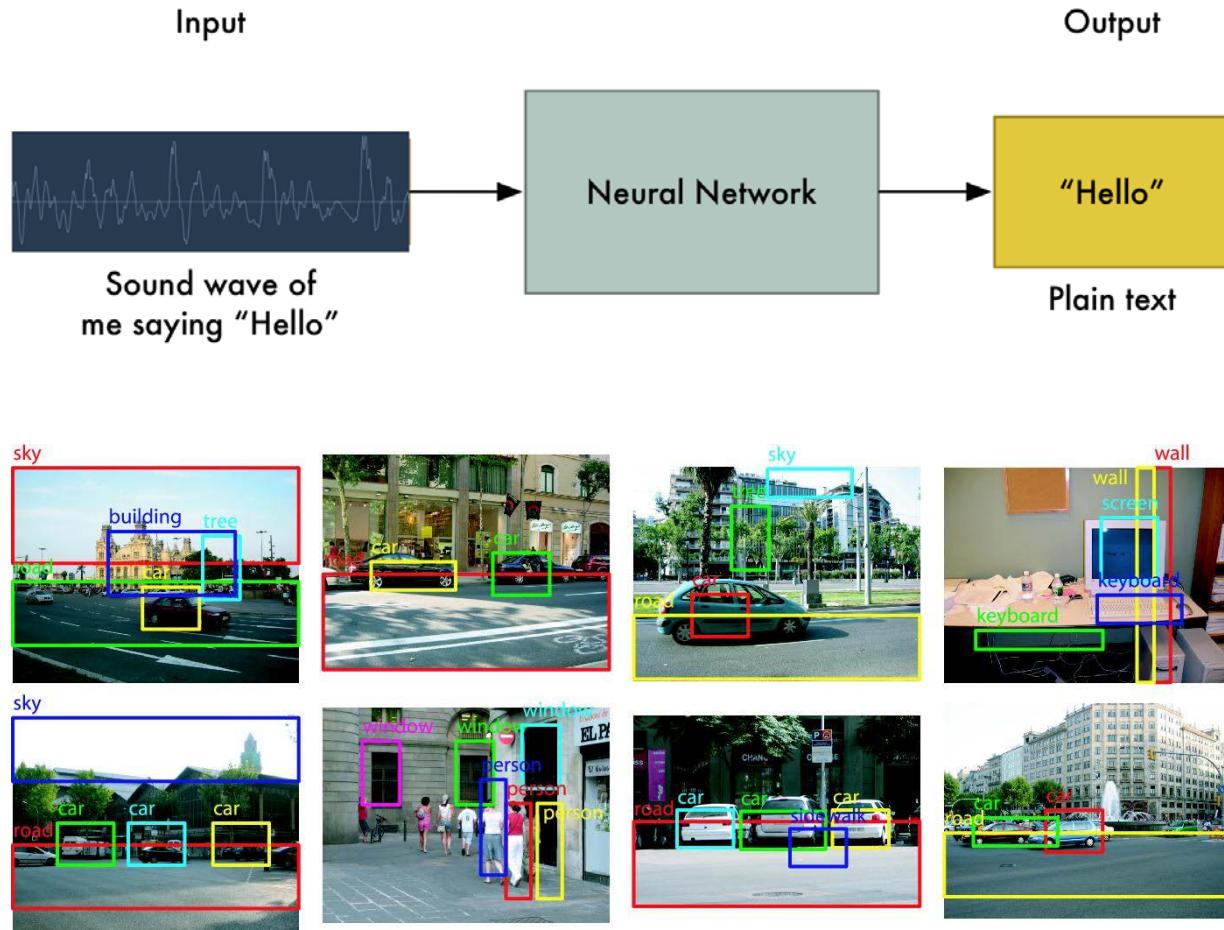
Existing Techniques and Toolsets



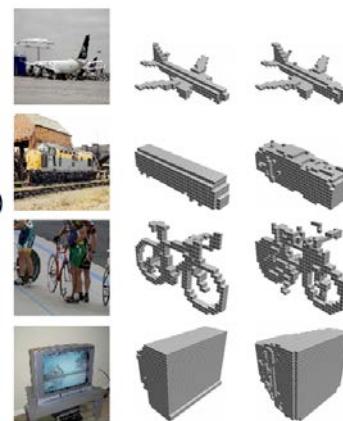
Future Directions



What you can do...



- * Image classification
- * Text processing
- * Traffic classification
- * Predictions of characteristics
- * Climate prediction
- * Health care
- * many more....

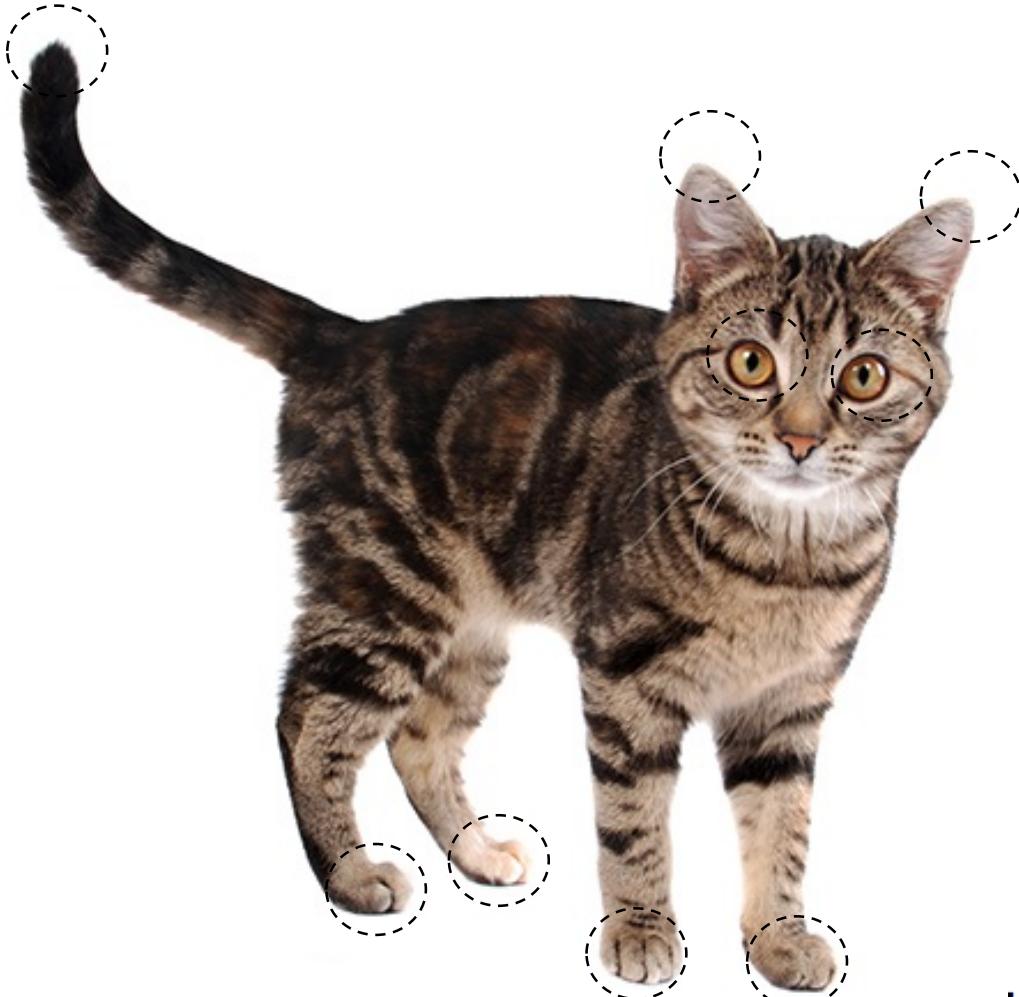


Deep learning in Computer Vision, Fei-Fei Li et al., 2016

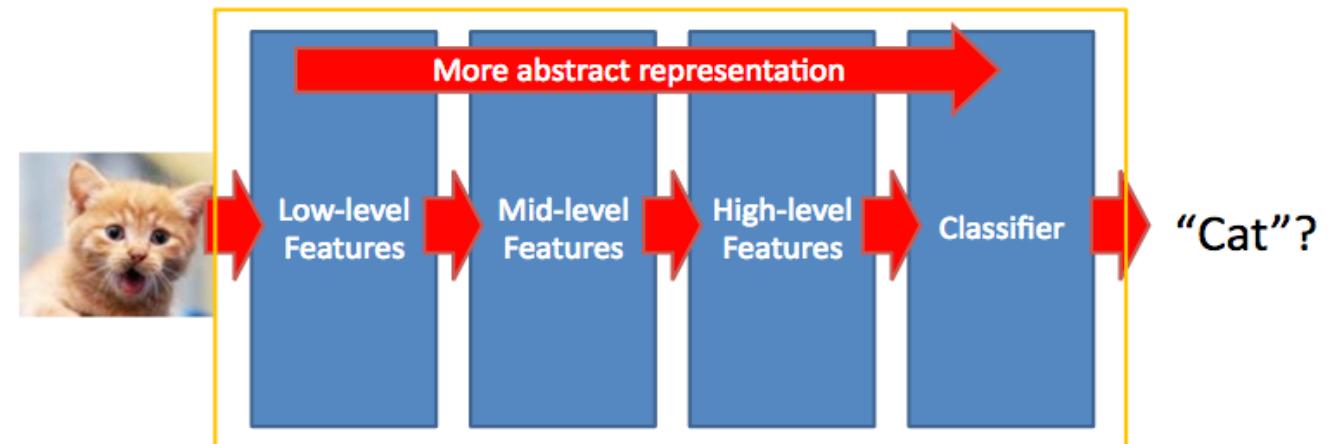
Classification refers to identifying the category to which a new observation belongs based on previous examples



Classification refers to identifying the category to which a new observation belongs based on previous examples

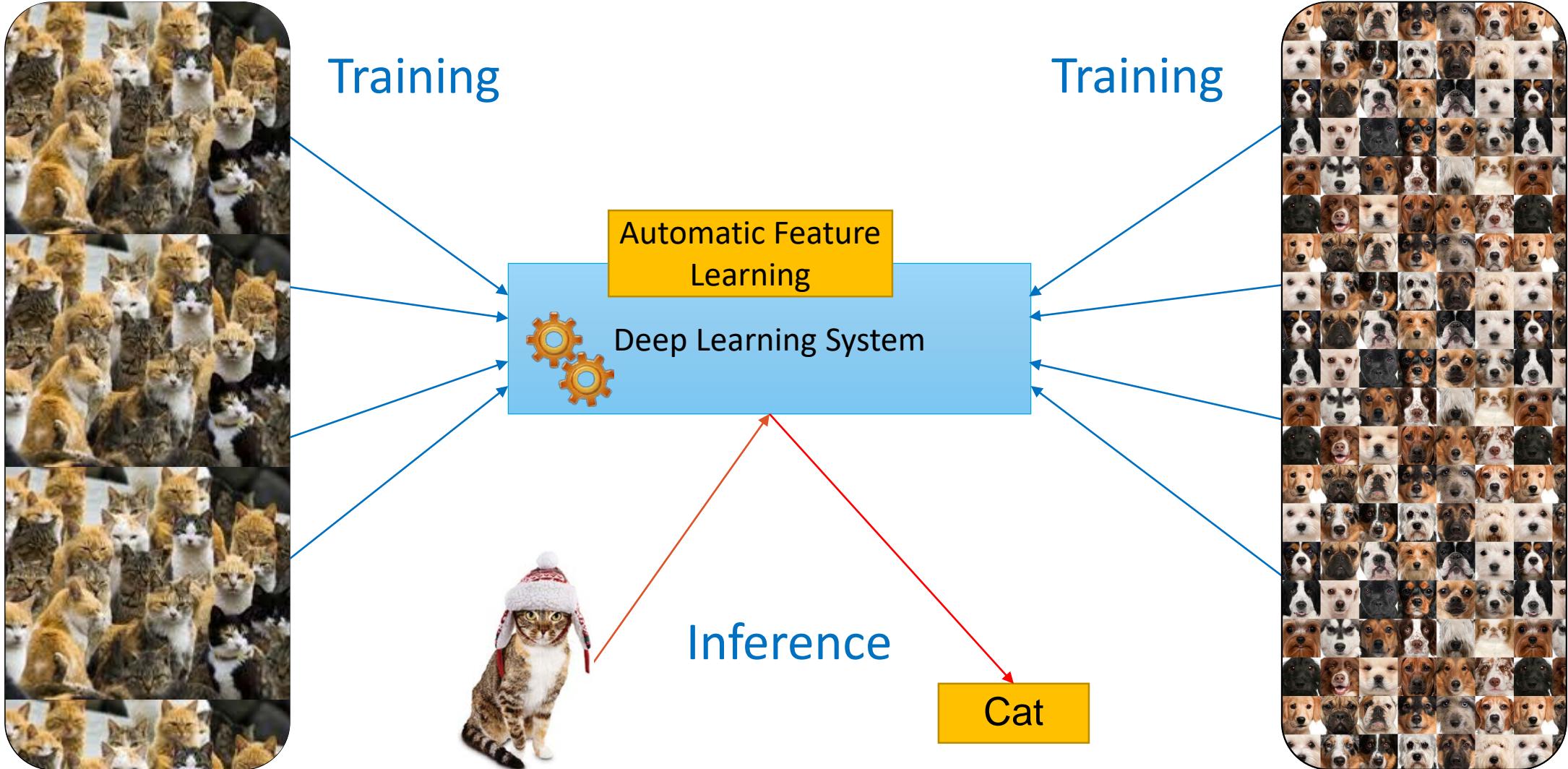


Typical ML Flow

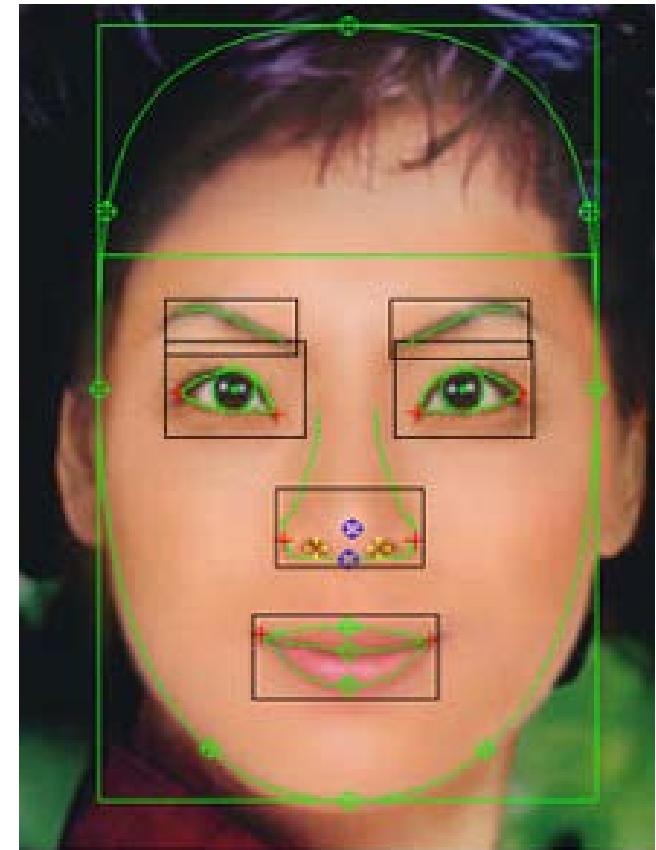


Deep Learning: train layers of features so that classifier works well.

Deep learning is a machine learning technique in which identification and extraction of features is directly done from the dataset



- Deep learning to create automatically features from data
- Features describe the data content in an abstract representation
- For example face features, edges, color distribution, time series, etc.



- Algorithms
- Data
- Computational power

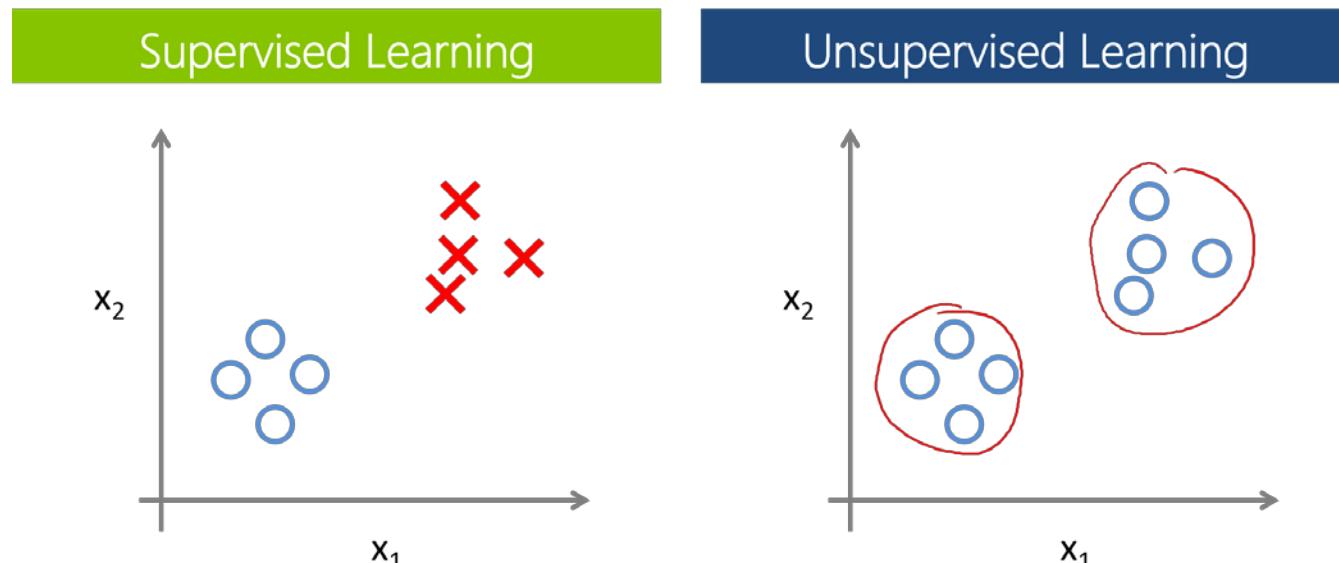


- **Supervised**

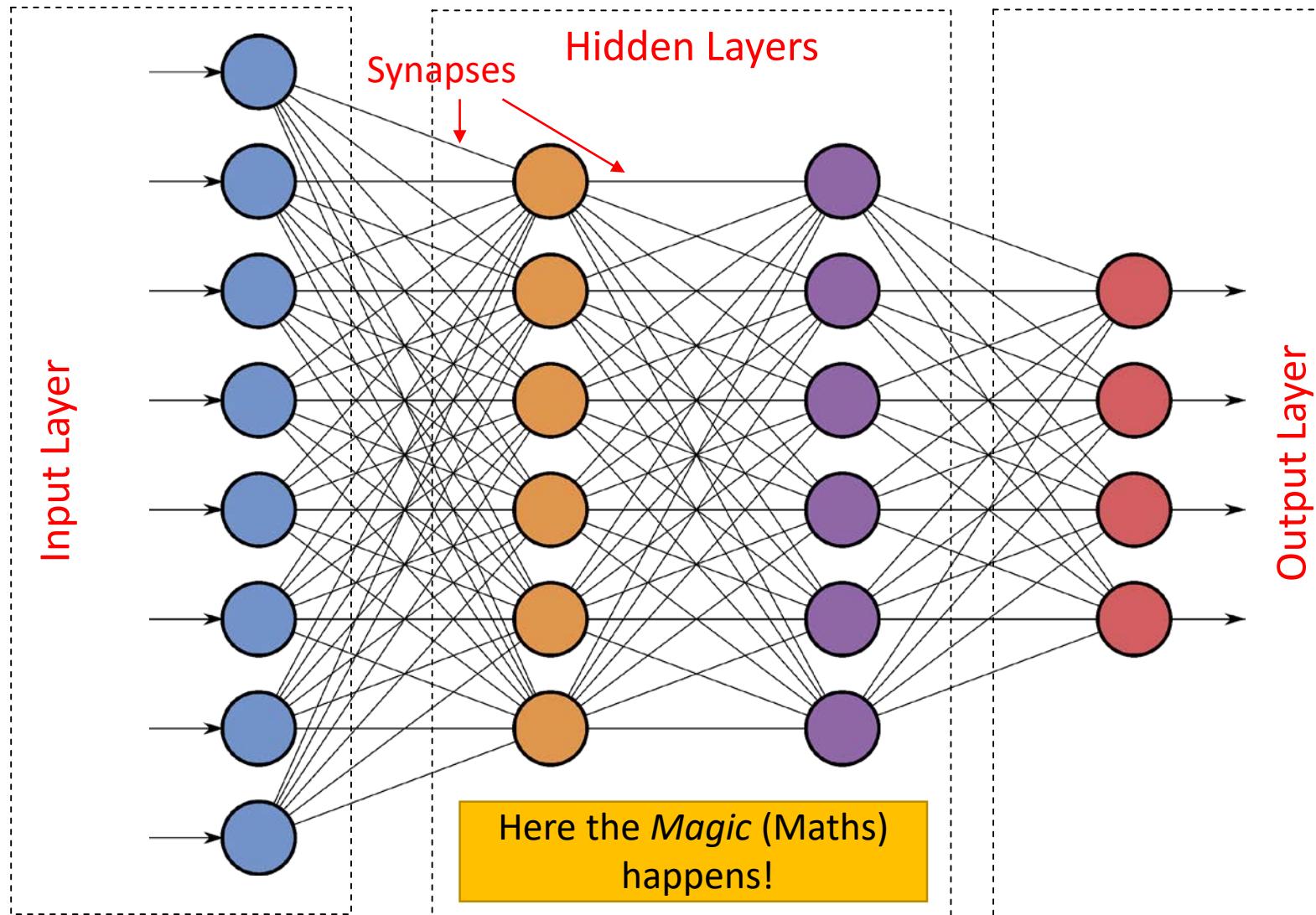
- Labelled training data
- Algorithm learns from data

- **Unsupervised**

- No training data
- Algorithm learns by itself

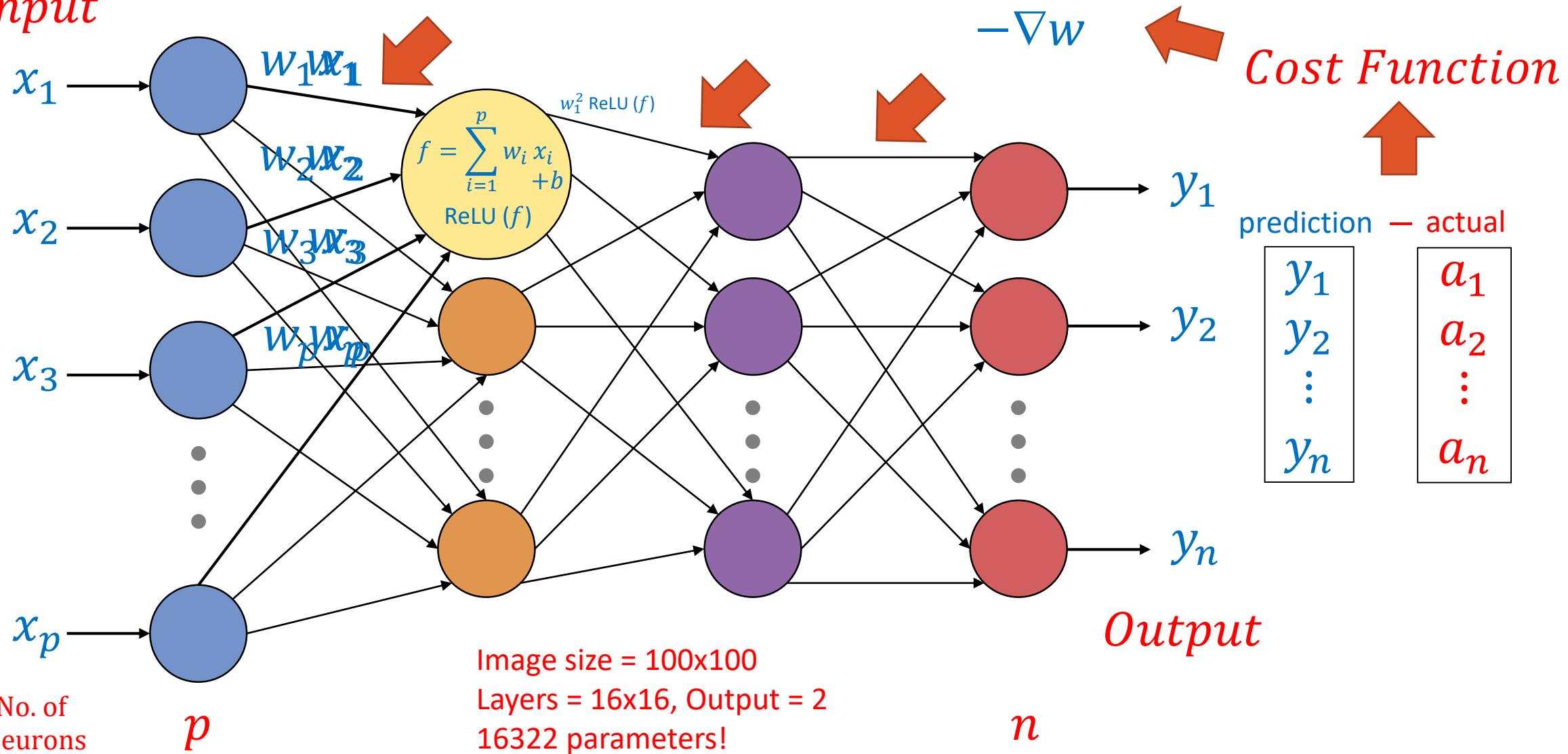


Deep learning is predominately based on artificial neural networks (ANNs).
ANNs progressively *learn* using *neurons* arranged in many layers



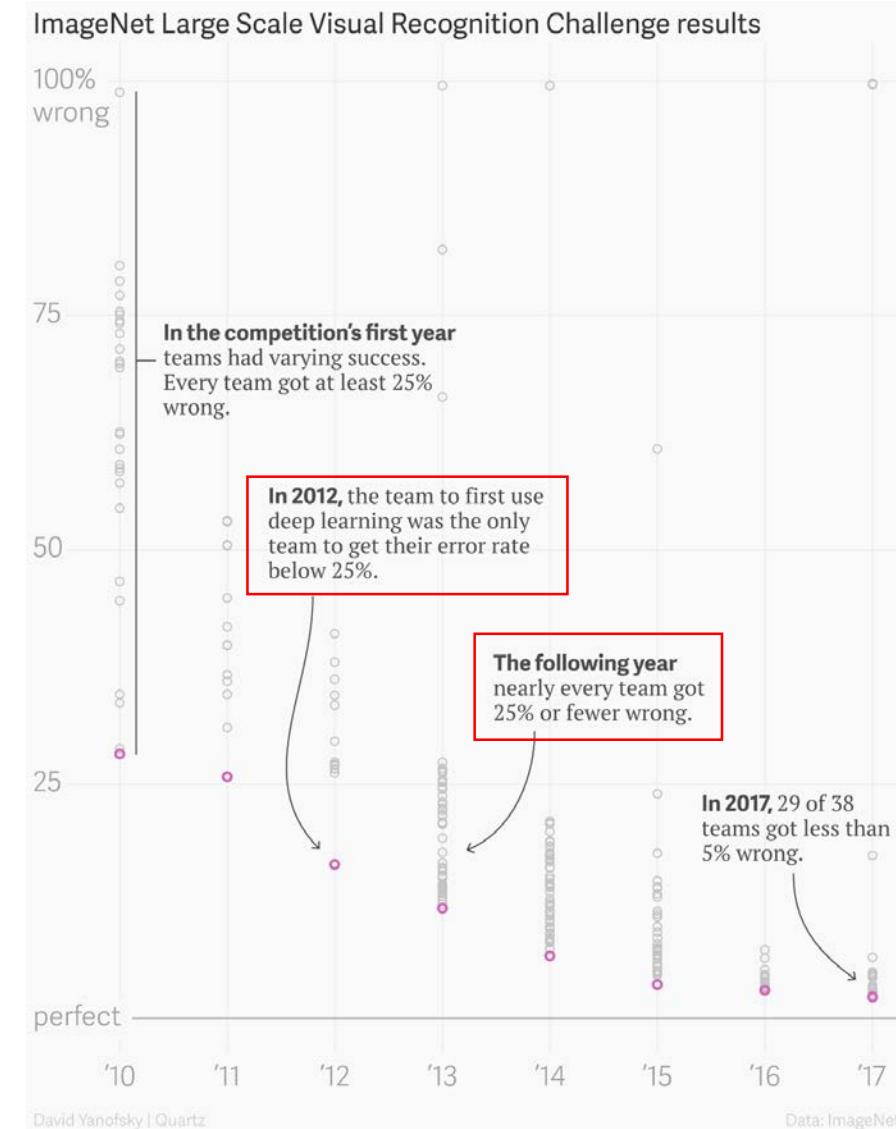
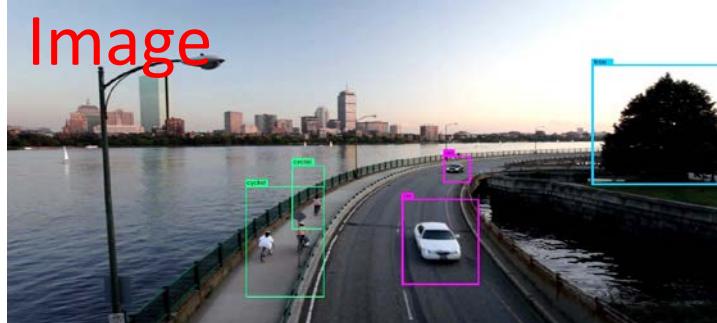
In training neural networks, prediction errors are *backpropagated* for gradually tuning weights and biases to values that predict better

Input

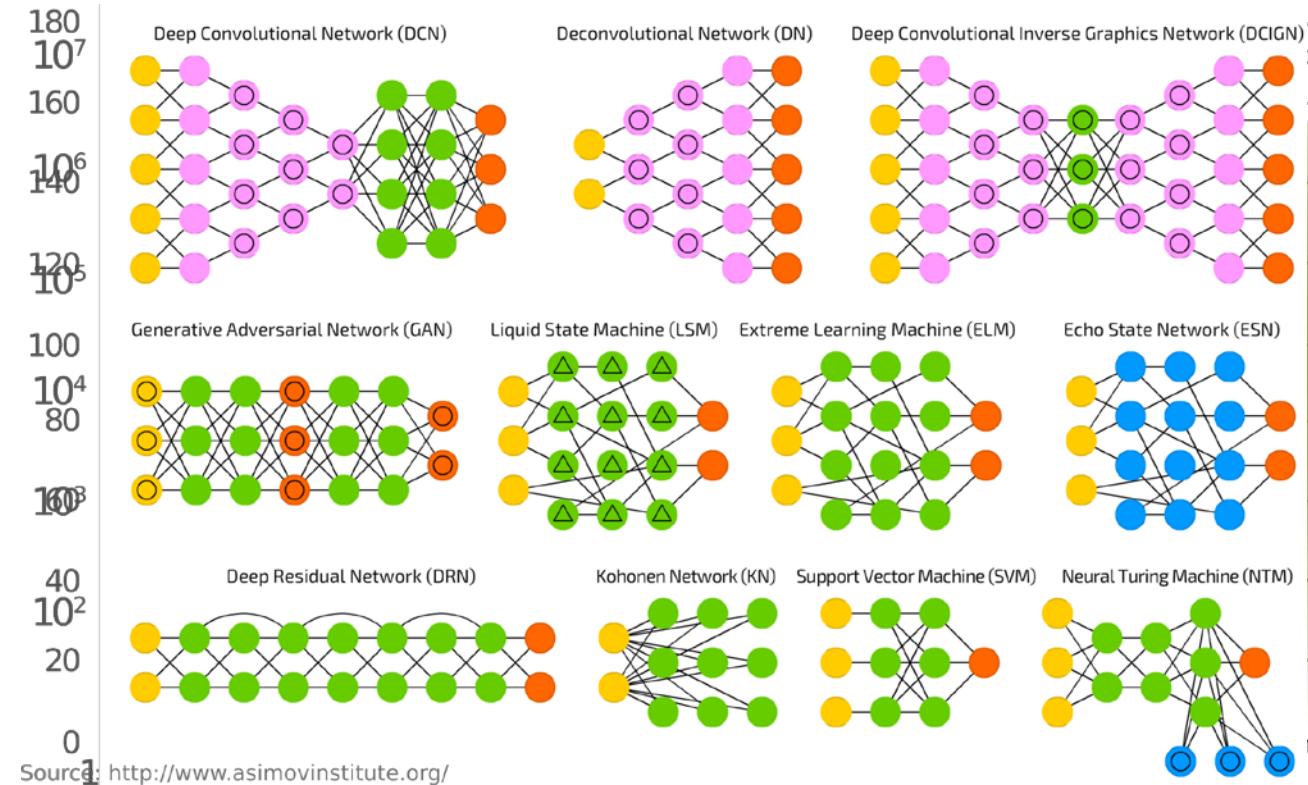


Deep learning has greatly improved prediction accuracies in various fields, and has become a backbone of artificial intelligence

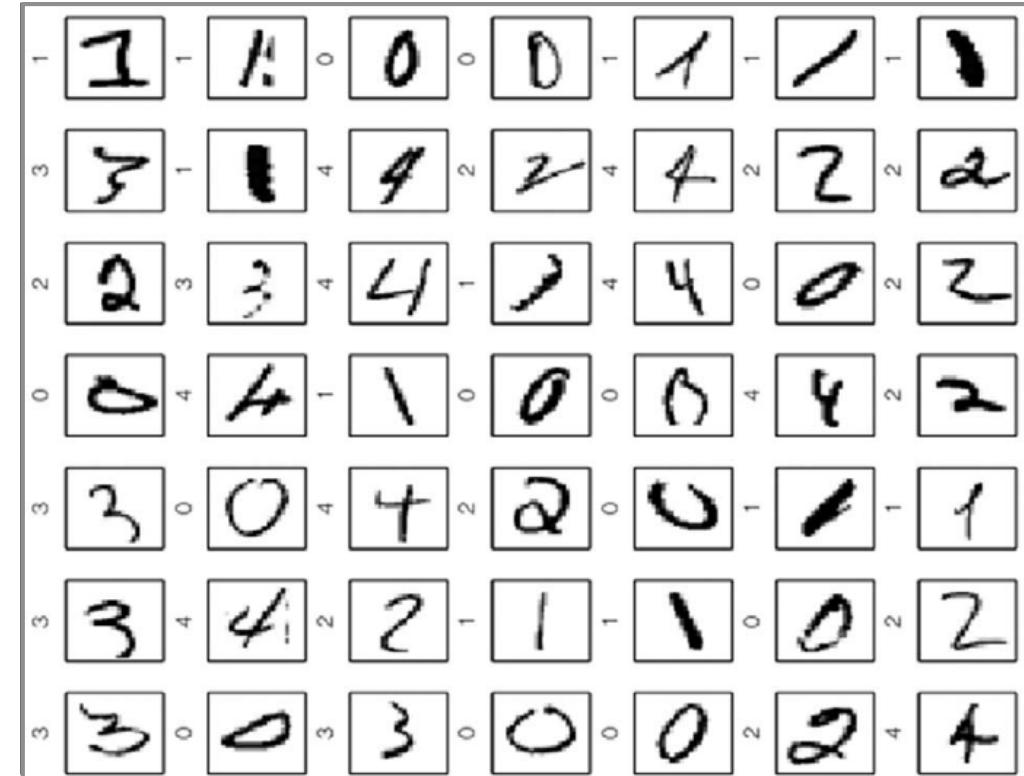
- Improving prediction accuracies
 - Important in real-world applications such as disease identification, self-driving cars
- Fueling new applications
 - Science, Finance, Healthcare, Automotive



Availability of large amount of data, improved processing capabilities, and advances in neural networks contributed to the deep learning success



Source: <http://www.asimovinstitute.org/>



ImageNet is a large database of URLs of about 14 million images containing 600k handwritten digits with labels.

- Availability of large amount of data, improved processing capabilities and advances made it possible to execute previously infeasible computations
 - Digitally inferable networks, Recurrent Neural Networks, LSTM
- Availability of large amounts of data, VGG19, InceptionV3, InceptionResNetV2
 - Trespasser N1000 is capable of 15 TFLOPS of single-precision operations

Large, complex models and training using large datasets improves classification accuracy of deep learning algorithms

- State-of-the-art accuracies are achieved using very large models
 - Millions / Billions of parameters, Large number of layers and depth
 - Neural network of Google Brain¹ has 137 billion parameters!
- Size and depth of the model, Top-1 accuracy, ImageNet dataset²

Model	Top-1 Accuracy %	No. of Parameters	Network Depth
MobileNet	66.5	4,253,964	88
ResNet50	75.9	25,636,712	168
Xception	79.0	22,910,480	126
VGG16	71.5	138,357,544	23
VGG19	72.7	143,667,240	26
InceptionV3	78.8	23,851,784	159
InceptionResNetV2	80.4	55,873,736	572

Note: Recently, Google's NASNet³ reached accuracy of 82.7% with 22.6 Million parameters.

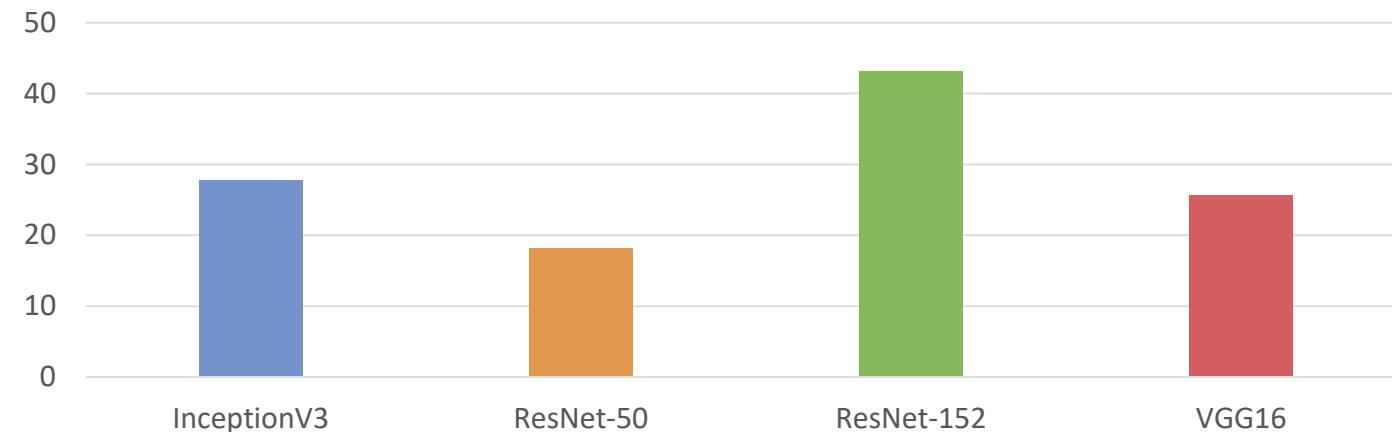
¹Shazeer, Noam, et al. "Outrageously large neural networks: The sparsely-gated mixture-of-experts layer." arXiv preprint arXiv:1701.06538, 2017.

²<https://keras.io/applications/> ³Zoph, Barret, et al. "Learning transferable architectures for scalable image recognition." arXiv preprint arXiv:1707.07012, 2017.

Efficient distributed deep learning across a large number of nodes is critical for modern deep learning applications

- It takes hours, and even days to train today's models on a single node
 - The models will only become more bigger and complex
 - The amount of training data will only increase
 - Increase in GPU processing power cannot cope up
 - Billions of parameters will not fit in GPU memory

Training Time in Hours, NVIDIA DGX-1, 1 GPU, Tesla P100, ImageNet dataset, TensorFlow



Data: <https://www.tensorflow.org/performance/benchmarks>

Distributed deep learning should be scalable, should not affect the accuracy of the classification, and should fully utilize available resources

Benchmarking distributed deep learning systems

- Same hardware, software stack
 - Some frameworks more scalable than others
 - Trained to the same accuracy
 - 0.5% change in accuracy could mean a substantial affect on speed-up!
 - Some models more scalable than others
 - Due to computation / communication ratio

Scaling Efficiency and Communication Overhead

- Ratio affected by the batch size iteration on 1 nodes to total training time when distributed over n nodes
- Number of epochs required for convergence $\propto \frac{1}{n}$ nodes with 8x GPUs
- Learning rate adaptation, trade-off between runtime and accuracy

Goyal, Priya, et al. "Accurate, Large Minibatch SGD: Training ImageNet in 1 Hour." arXiv preprint arXiv:1706.02677, 2017.

This presentation will introduce distributed deep learning, walk through prominent techniques, and identify existing challenges and future directions



Introduction and Motivation

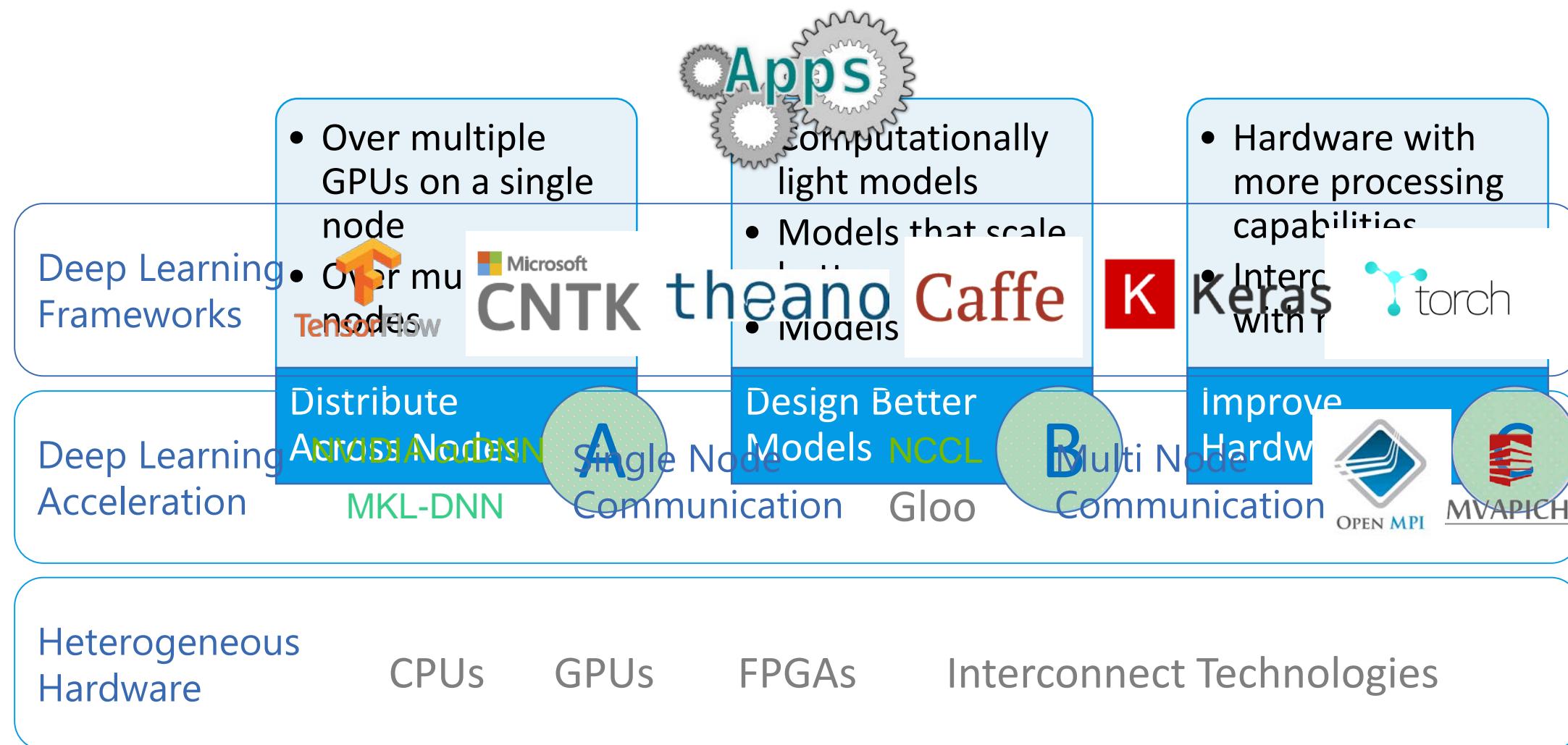


Existing Techniques and Toolsets



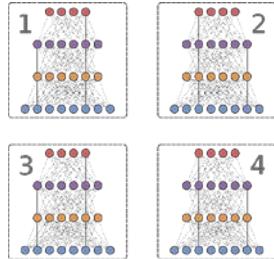
Future Directions

Scaling efficiency of distributed deep learning can be improved at different levels, and a co-design approach is needed



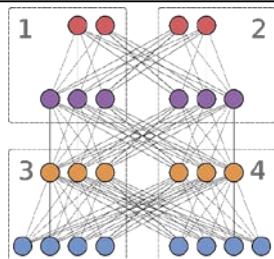
Distribute Across Nodes

There are three parallelization methods employed in distributed implementation of deep learning applications



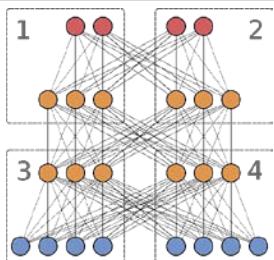
Data Parallelism

- Data partitioned across machines, each machine holds local copy of the model, synchronization required



Model Parallelism

- Neural network partitioned across machines, Parallelizing mathematical operations across machines



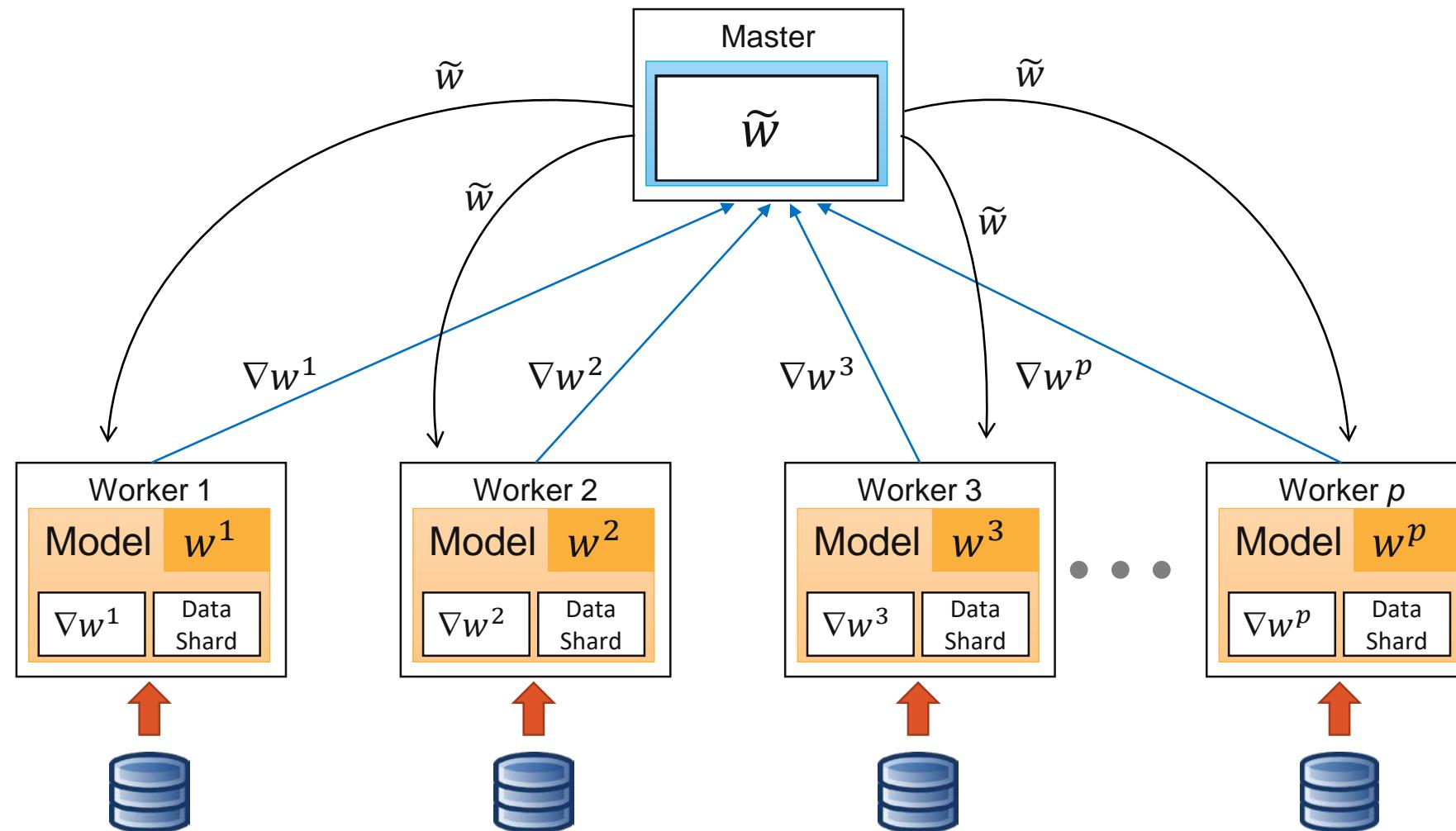
Hybrid Approaches

- Data partitioning for some parts of neural network, model partitioning for correctness on some parts, Automatic selection

Distribute
Across Nodes

A

Data Parallelism: In Synchronized data parallelism, the algorithm includes two parts: sum of local gradients and broadcast of global weight to workers



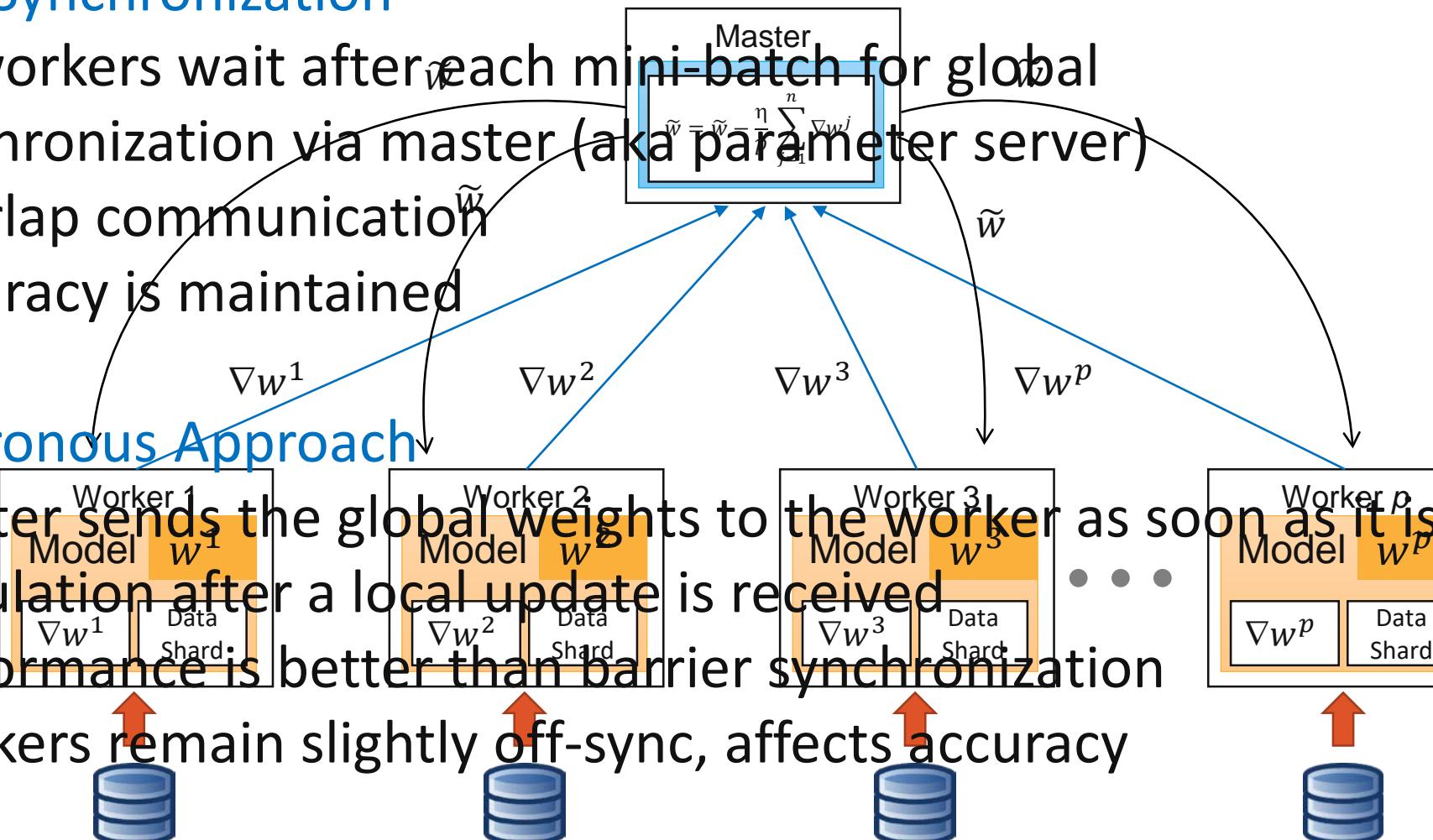
Data Parallelism: Barrier before each update, overlapping communication and computation, or asynchronous approaches are generally employed

- **Barrier Synchronization**

- All workers wait after each mini-batch for global synchronization via master (aka parameter server)
- Overlap communication
- Accuracy is maintained

- **Asynchronous Approach**

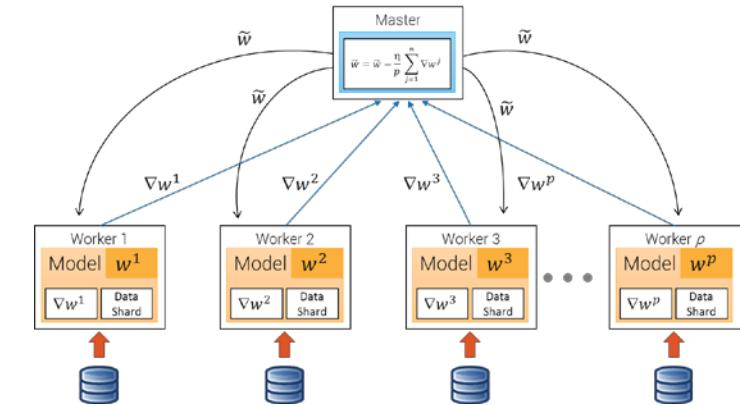
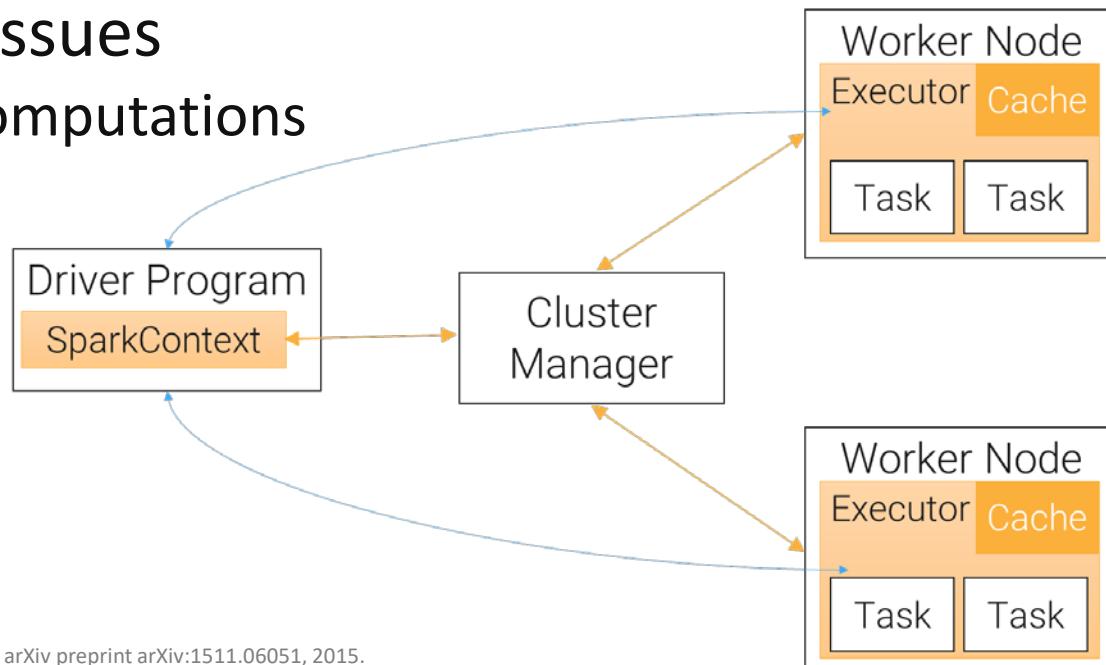
- Master sends the global weights to the worker as soon as it is done calculation after a local update is received
- Performance is better than barrier synchronization
- Workers remain slightly off-sync, affects accuracy



Dean, Jeffrey, et al. "Large scale distributed deep networks." Advances in neural information processing systems. 2012.

Data Parallelism: Big data processing frameworks and resource management systems also make good candidates for distributed deep learning

- Spark-based Solutions
 - Integration of deep learning frameworks, e.g. TensorFlow with Spark
 - ClusterManager takes role of parameter server
 - Mesos used as resource manager
 - Performance issues
 - Iterative computations

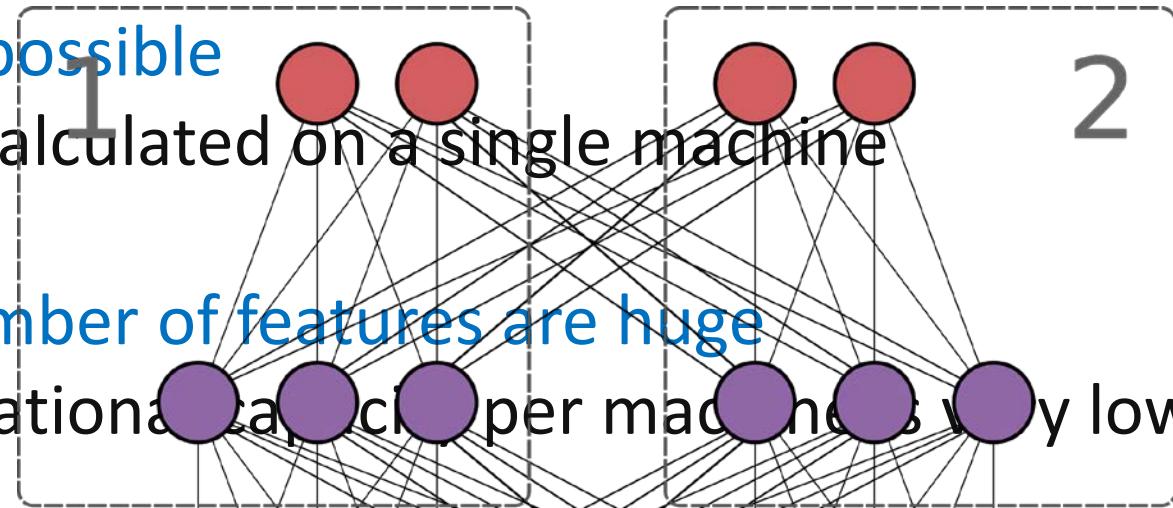


Moritz, Philipp, et al. "Sparknet: Training deep networks in spark." arXiv preprint arXiv:1511.06051, 2015.

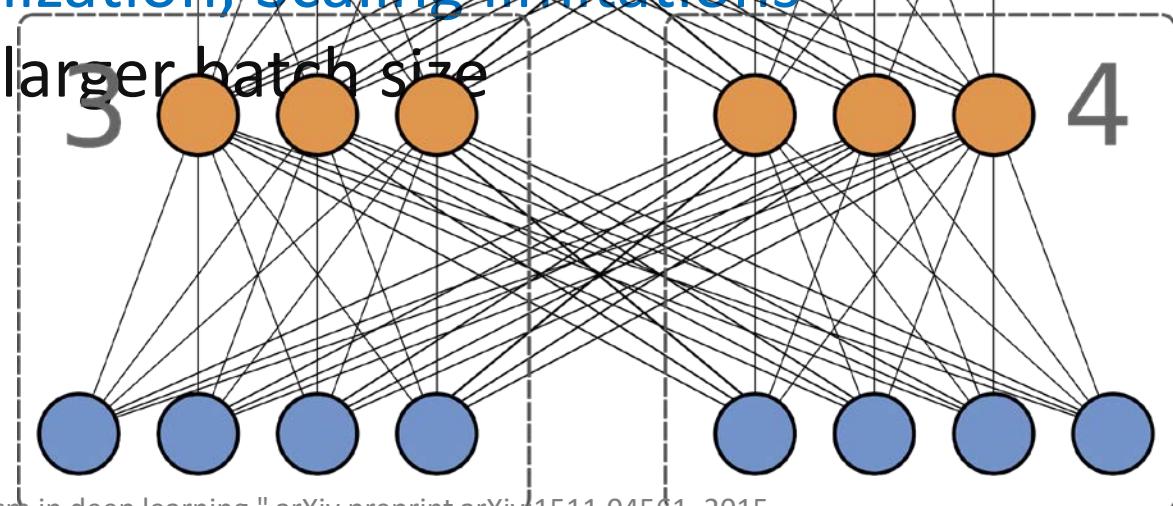
Kim, Hanjoo, et al. "Deepsparck: Spark-based deep learning supporting asynchronous updates and caffe compatibility." CoRR, vol. abs/1602.08191, 2016.

Model Parallelism: Neural network is divided into several mini-models and distributed across multiple nodes

- Highest accuracy possible
 - As if model is calculated on a single machine
- Feasible when number of features are huge
 - Or the computational capacity per machine is very low



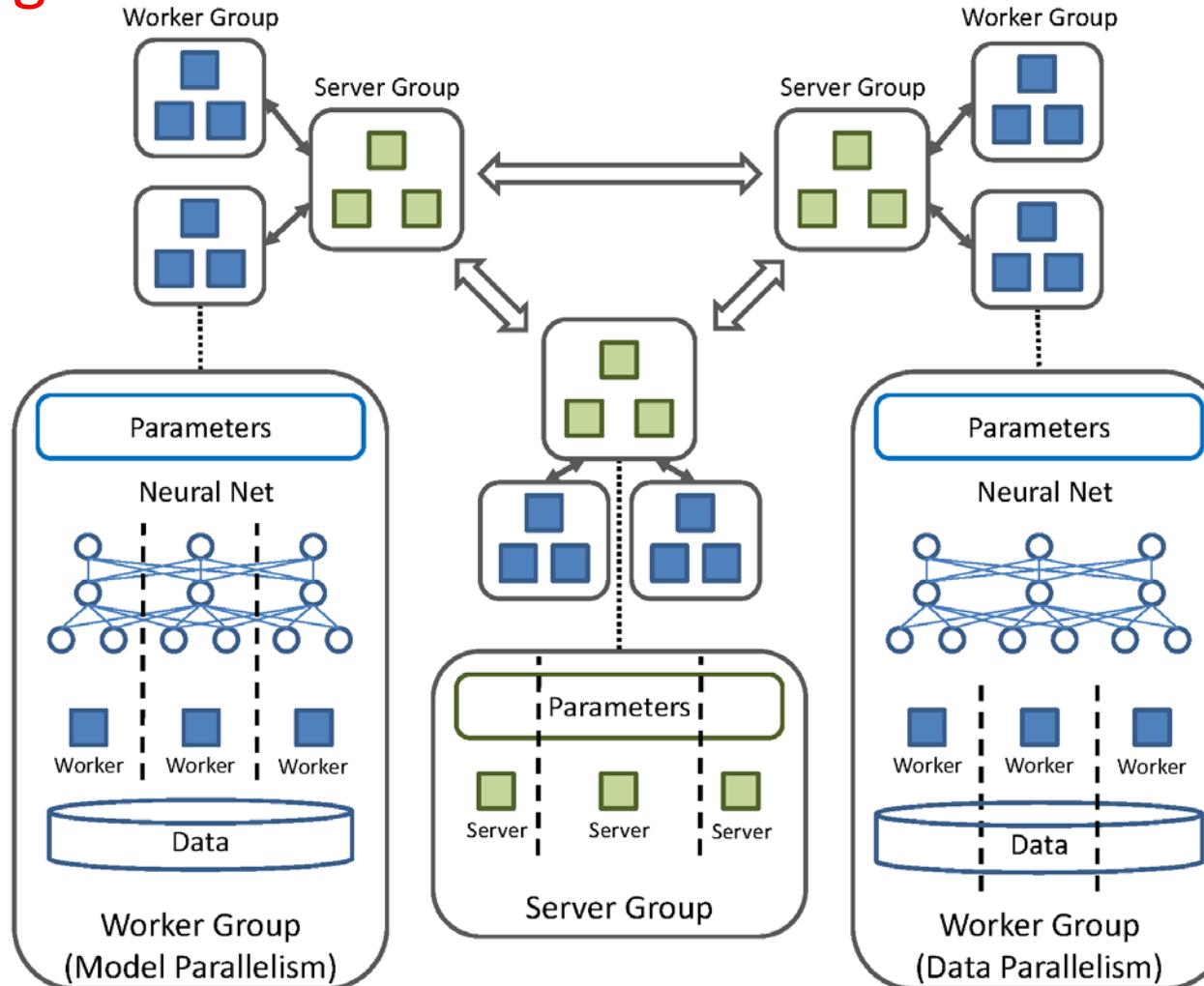
- Frequent synchronization, Scaling limitations
 - Problems with larger batch size



Dettmers, Tim. "8-bit approximations for parallelism in deep learning." arXiv preprint arXiv:1511.04561, 2015.

Hybrid Approach: Some parts of the neural network are divided using model parallelism while other parts employ data parallelism

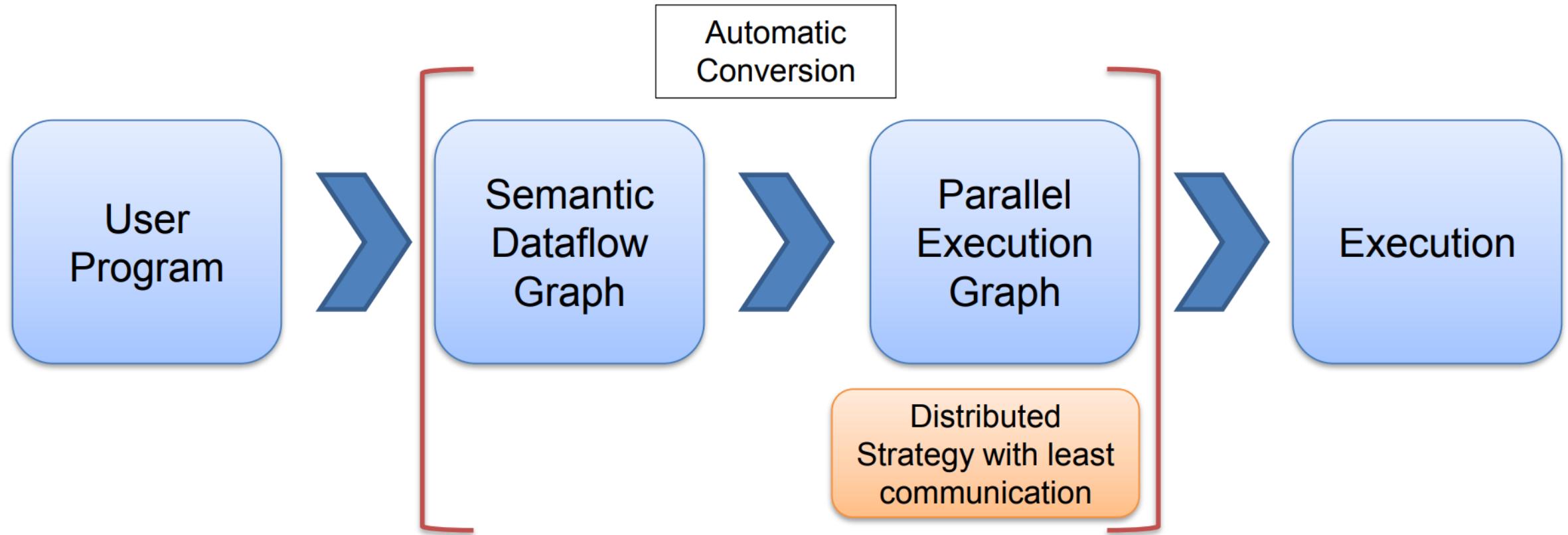
Example: Apache Singa



Source: <http://singa.incubator.apache.org/>

Hybrid Approach: Automatic selection of the best possible parallelism model has also been proposed in literature

Example: Tofu



Automatic generation of Neural networks using evolutionary algorithm, ORNL.

Source: Tofu – Parallelizing Deep Learning Systems with Automatic Tiling, Minjie Wang, 2017

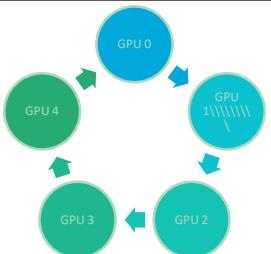
Communication efficiency plays an important role in the scalability of the distributed deep learning algorithms

Communication overhead is the difference between runtime of one iteration when distributed over n processing units and runtime of one iteration on a single unit



Interconnect Bandwidth and Latency

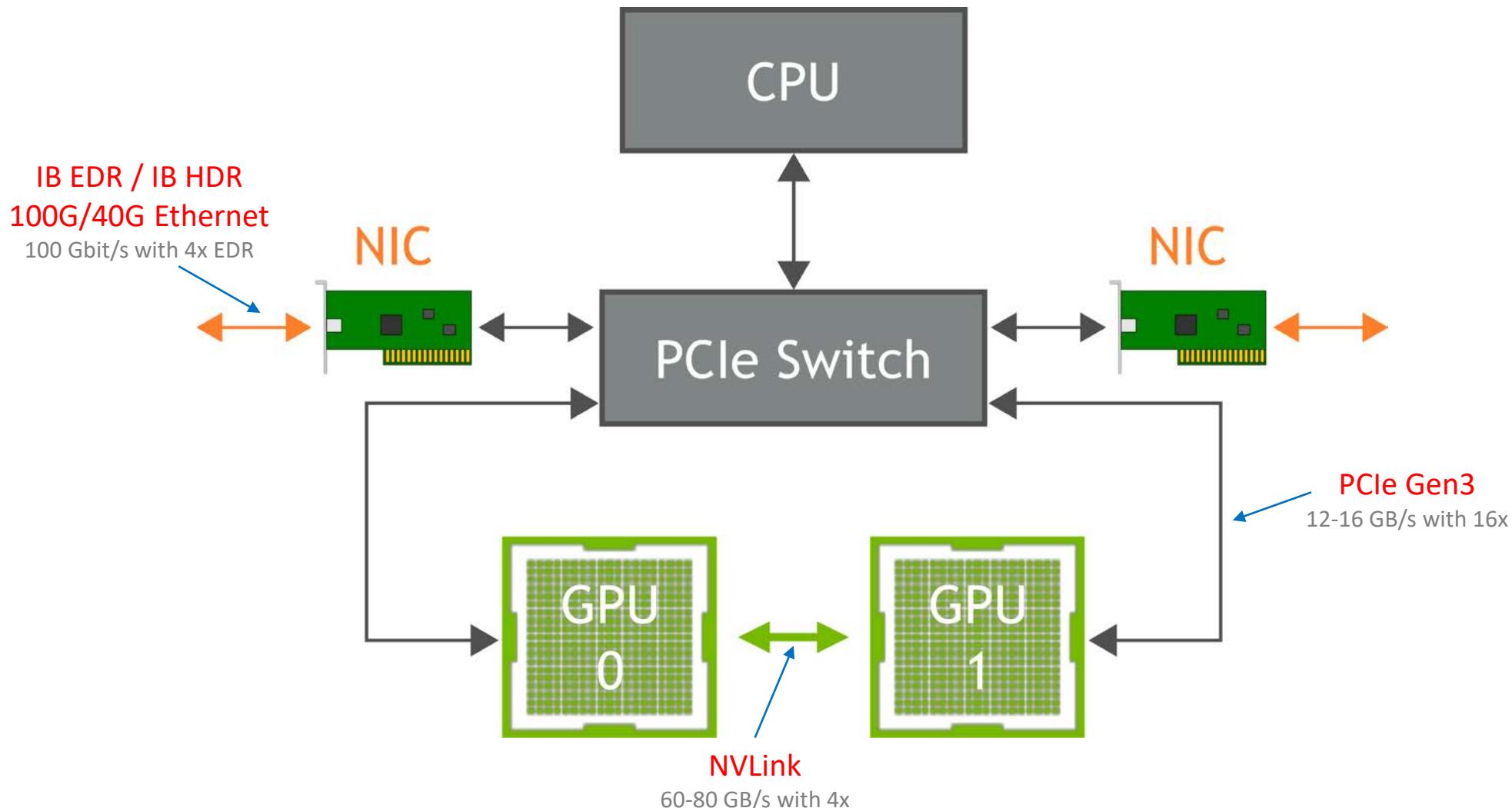
- Inter-node communication, Intra-node communication



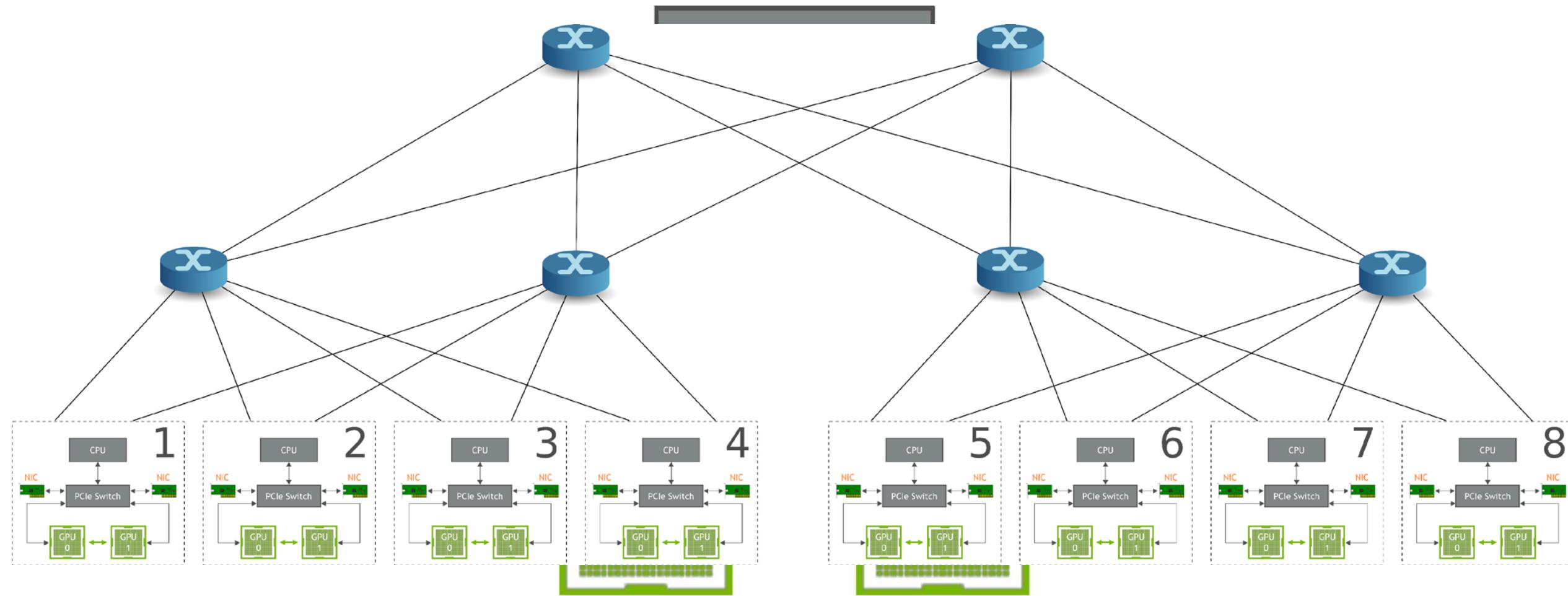
Communication Algorithm and Libraries

- Topology-aware, Adaptive to the configuration

In large-scale systems, a hierarchy of interconnect technologies are used giving different bandwidths, latencies, and connectivity



In large-scale systems, a hierarchy of interconnect technologies are used yielding different bandwidths, latencies, and connectivity



- In such distributed scenarios, topology and routing also plays an important role
 - Communication algorithm must adapt

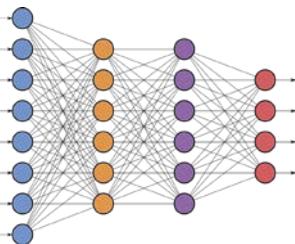
60-80 GB/s with 4x

Communication algorithm can optimize utilization of the available link capacity by avoiding contention in data transfers

- Collective operations
 - All-Reduce operations in synchronous data parallelism
 - All-Gather and broadcast in asynchronous data parallelism / model parallelism
- Communication Libraries
 - MPI is very mature, standardized, and provide excellent scale-out performance
 - Scale-Up?
 - NICCL
 - Scale Up, Across multiple nodes is an issue even though supported now

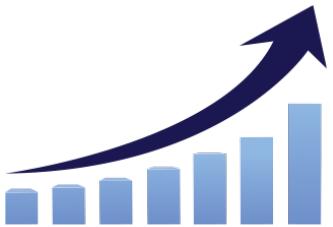
Design Scalable Models

Distributed deep learning can be accelerated through the use of computationally lighter & scalable models and define-by-run methodologies



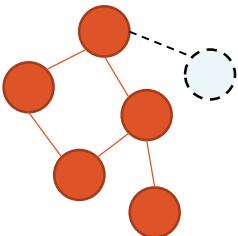
Computationally Lighter Models

- Some models are inherently more computationally expensive than others, VGG vs Inception



Scalable Models

- Models that are more scalable, tolerant to delayed parameter updates



Define-by-Run Paradigm

- Dynamic graph updates, Potential for adaptation to the changing data

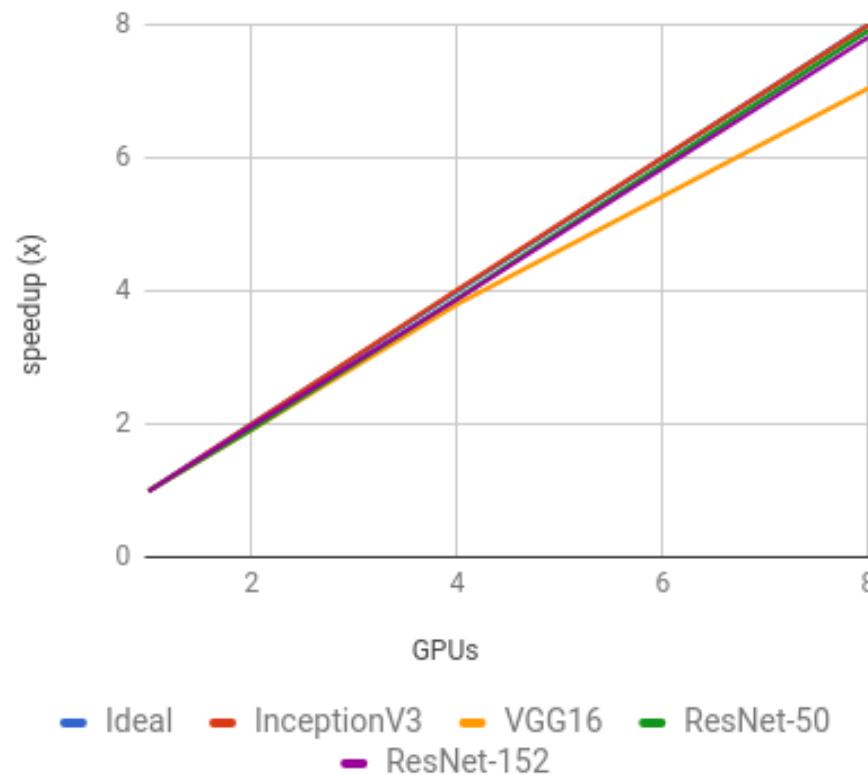
Design Better
Models

B

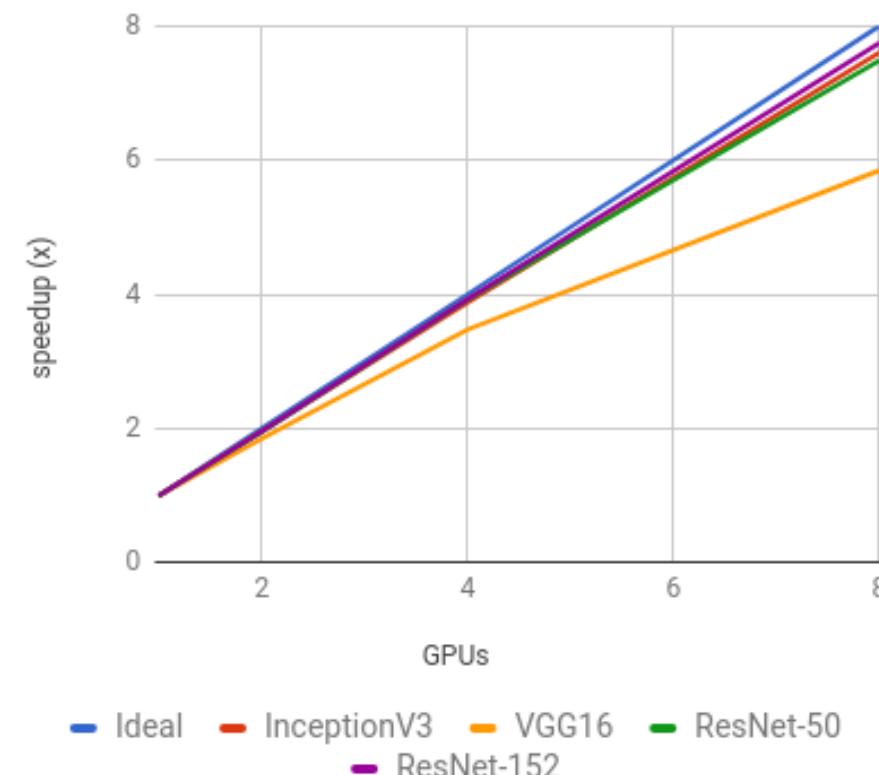
Models can also be designed in a way that they are more scalable and suited for the distributed deep learning

Example: VGG16 vs ResNet-152 – Single node, ImageNet, TensorFlow

Tesla® P100 speedup (synthetic data)



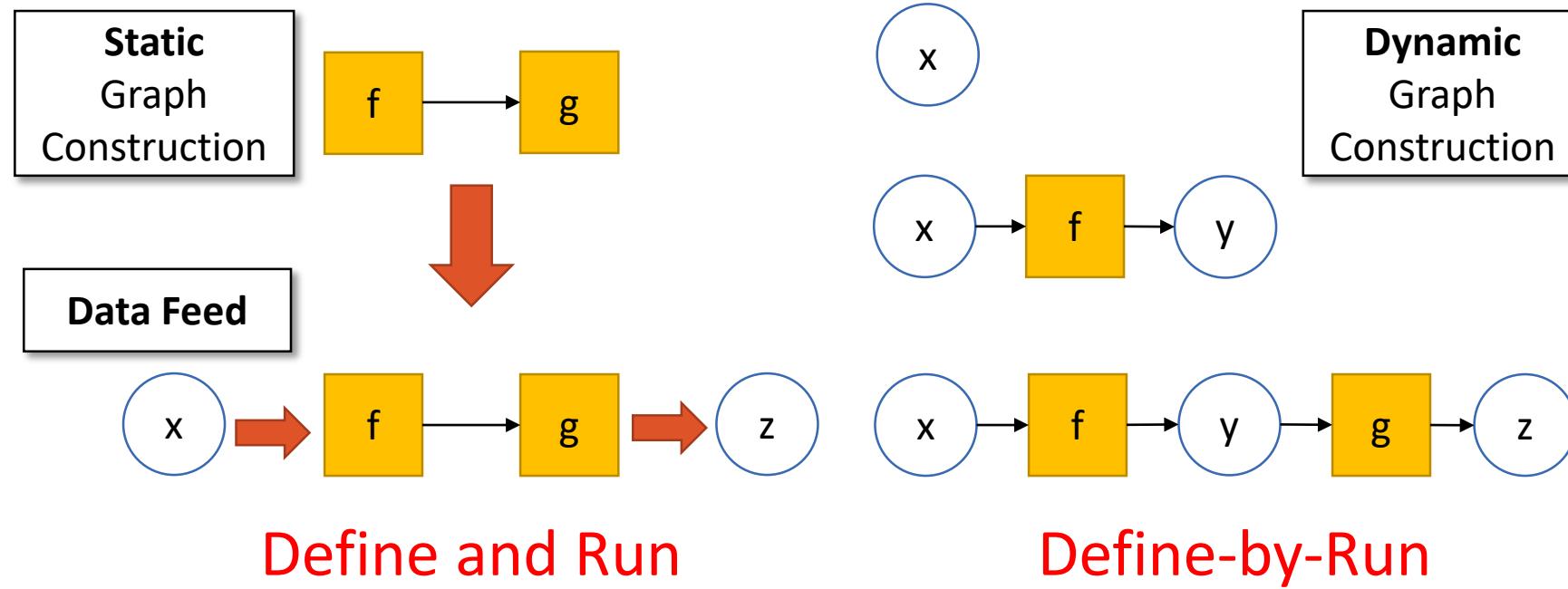
Tesla® P100 speedup (real data)



Source: <https://www.tensorflow.org/performance/benchmarks>

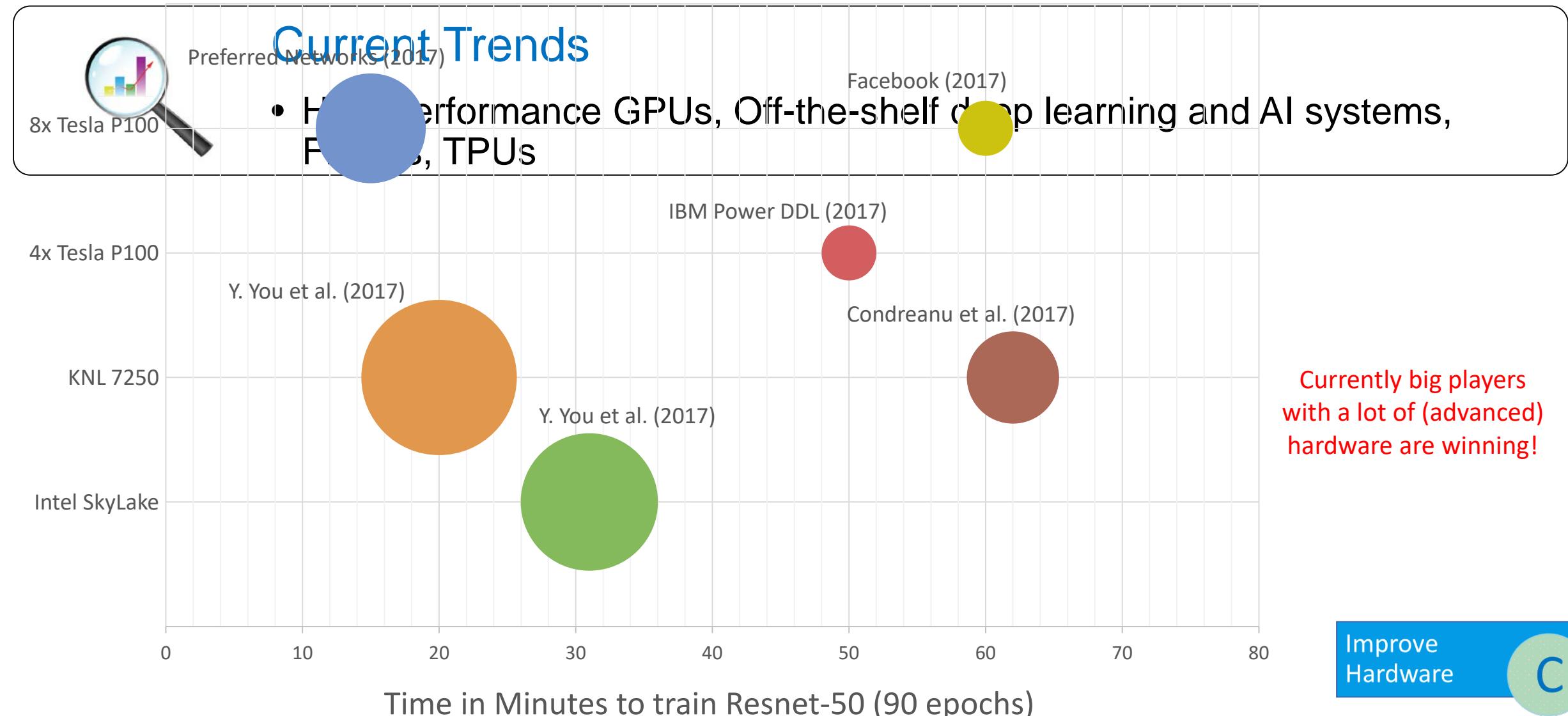
In Define-by-Run frameworks, graphs constructions *on the fly* giving more flexibility and potential performance improvements

- Chainer
 - The first define-by-run deep learning framework
- TensorFlow
 - Eager execution



Improve Hardware

Hardware advances will still play an integral role in improving efficiency of deep learning algorithms



This presentation will introduce distributed deep learning, walk through prominent techniques, and identify existing challenges and future directions



Introduction and Motivation



Existing Techniques and Toolsets



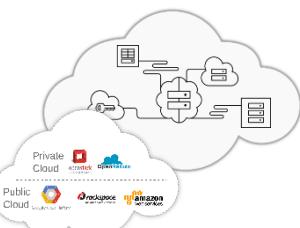
Future Directions

Future research directions include a holistic approach for variety of workloads & heterogeneous environments, and NN-aware communication



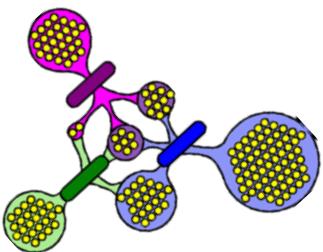
Holistic Approach

- New workloads are emerging, different toolsets, in modern apps workload of different types will co-exist



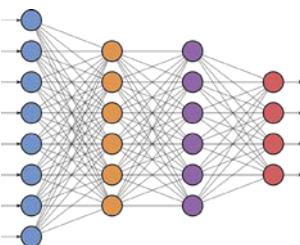
Heterogeneous Environments

- Accelerators, Adaptive to the configuration, Dynamic resource allocations, Clouds (challenges related to multi-tenancy)



Neural Network Aware Communication

- Pipelining communication with computation, Topology-aware, Offloading



Improved Algorithms and Models

- Less communication requirements, Good accuracy with large batch sizes, adaptive learning rates, Automatic neural network

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