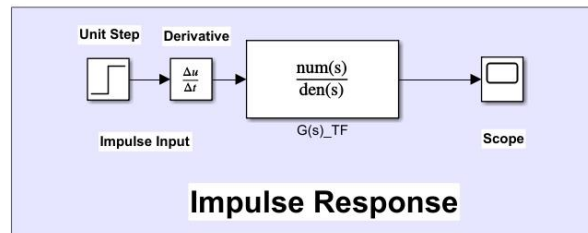
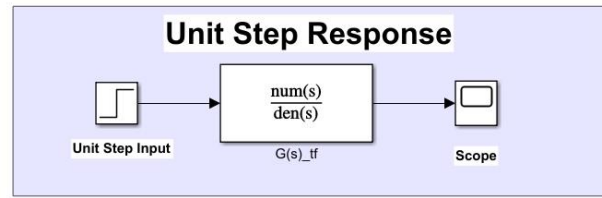
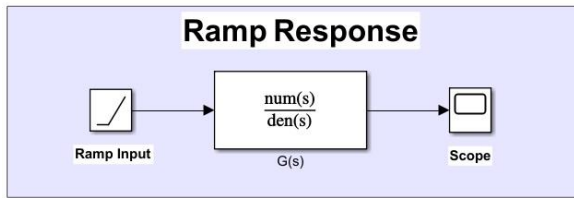


Project Part 2:

Answer (2)



Simulink Model of the Responses

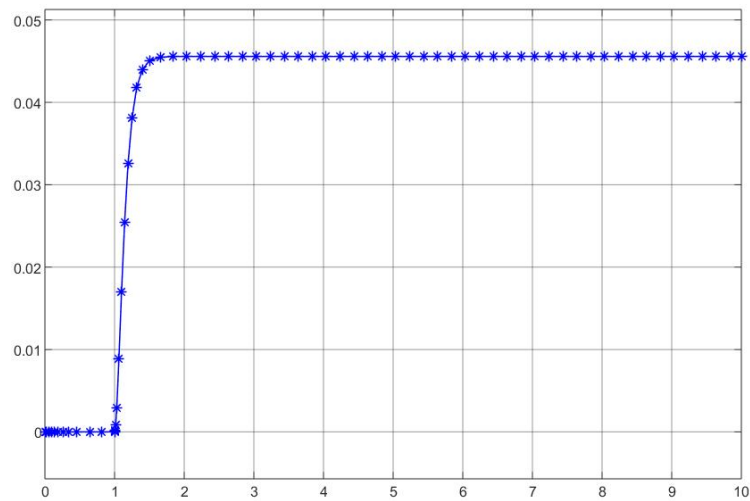


Figure 1: Impuse Response

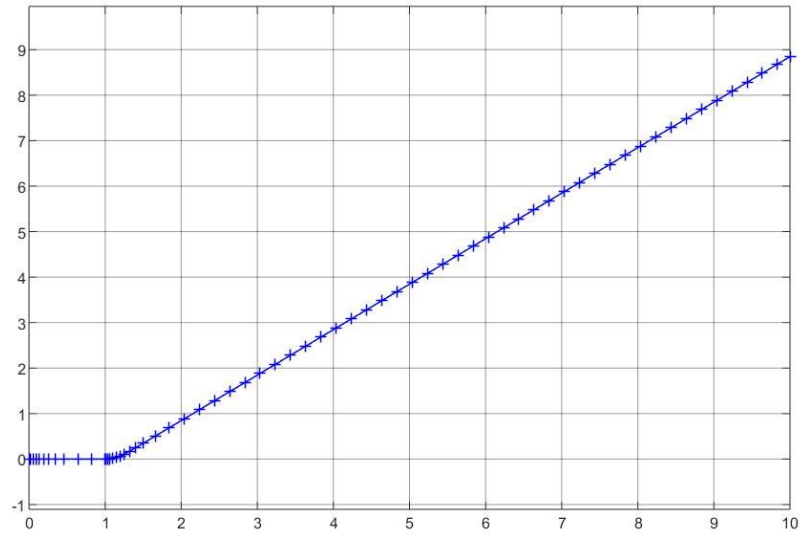


Figure 2: Step Response

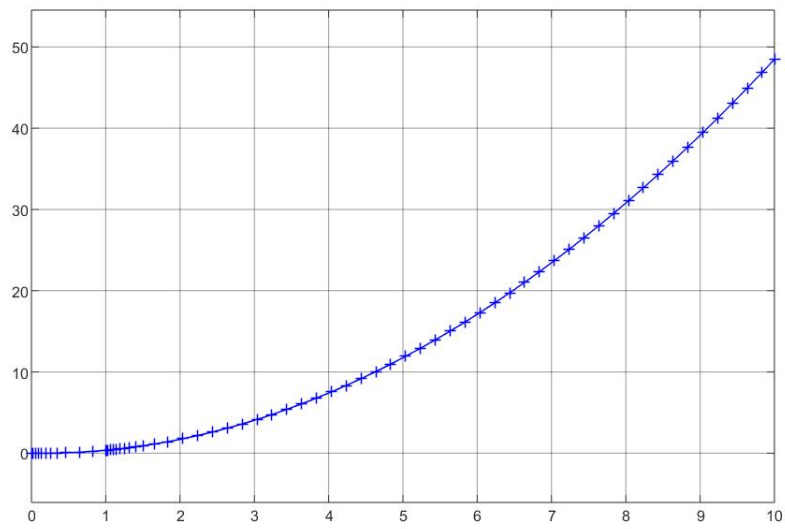


Figure 3: Ramp Response

```
27
28 %4
29 - BIBO_stability = isstable(G)
30
```

Command Window

```
BIBO_stability =  
  
logical
```

Figure 4: BIBO stability

Matlab Code: (Part 2)

```
%Part 2  
clc;  
clear all;  
close all;  
%1  
G = tf([0 0 0 168.0436],[1 25.921 168.0436 0]);  
figure(1)  
pzmap(G, 'r');  
grid on  
%2  
figure(2)  
step(G)  
grid on  
  
figure (3)  
impulse(G)  
grid on  
  
figure(4)  
  
figure(5)  
bode(G)  
grid on  
% 3  
b=[0 0 0 168.0436]; a= [1 25.921 168.0436 0];  
[z,p,k] = tf2zp(b,a)  
  
%4  
BIBO_stability = isstable(G)
```

