Institute of Informatics and Mechatronics

Bachelor's Thesis

in the field of study of Computer Engineering and Mechatronics

Cloud Managed Unmanned Aerial System

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This work is dedicated to my loving and very supportive parents …

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Cloud Managed Unmanned Aerial System

Abstract. Lorem ipsum dolor sit amet, consectetuer adipiscing elit. Ut purus elit, vestibulum ut, placerat ac, adipiscing vitae, felis. Curabitur dictum gravida mauris. Nam arcu libero, nonummy eget, consectetuer id, vulputate a, magna. Donec vehicula augue eu neque. Pellentesque habitant morbi tristique senectus et netus et malesuada fames ac turpis egestas. Mauris ut leo. Cras viverra metus rhoncus sem. Nulla et lectus vestibulum urna fringilla ultrices. Phasellus eu tellus sit amet tortor gravida placerat. Integer sapien est, iaculis in, pretium quis, viverra ac, nunc. Praesent eget sem vel leo ultrices bibendum. Aenean faucibus. Morbi dolor nulla, malesuada eu, pulvinar at, mollis ac, nulla. Curabitur auctor semper nulla. Donec varius orci eget risus. Duis nibh mi, congue eu, accumsan eleifend, sagittis quis, diam. Duis eget orci sit amet orci dignissim rutrum.

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Keywords: AWS, UAV, UAS

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Nomenclature

Acronyms / Abbreviations

AWS	Amazon Web Services
AWS	Amazon Web Services
CDK	Cloud Development Kit
DJI	Da-Jiang Innovations
GCS	Ground Control Station
HHLD	High-High-Level Design
HLD	High-Level Design
IaaS	Infrastructure as a Service
IaC	Infrastructure as Code
LTE	Long Term Evoluton (Telecommunication)
ML	Machine Learning
PaaS	Platform as a Service
test	tdsest
UAS	Unmanned Aerial System
UAV	Unmanned Aerial Vehicle

Chapter 1

Introduction

Unmanned Aerial Vehicles also known as UAVs or Drones, although hardly a new technology, with the first used UAV recorded in history dating back to 1849 [1], have recently gained a lot of attention from various sectors ranging from entertainment to military. This is going to have an impact that cannot be overseen over the coming years as more and more people find uses of UAVs in various applications. UAVs were initially developed to be used for military operations, mainly surveillance, but they were later armed to also enable them to perform long-distance military operations without putting humans at risk. The United States of America has used these types of UAVs mainly in the wars in the Middle East, where UAVs like the General Atomics MQ-9 Reaper also known as Predator B and Northrop Grumman RQ-4 Global Hawk have been widely deployed [2].

Despite their use in the military sector, UAVs have also been employed in other sectors such as commercial and entertainment sectors, where UAVs are being used in things like land geography mapping, industrial surveillance, photography and many more. Companies like SZ DJI Technology Co., Ltd. or Shenzhen DJI Sciences and Technologies Ltd. in full, more popularly known as its trade name DJI have had a lot of success in this area, where as of March 2021 DJI was coveringitself covers (research on the percentage of drones that DJI makes and are on the market). UAVs have also seen great use in the healthcare sector, where companies like Zipline [3] are implementing an end-to-end supply chain system that employs UAVs to supply and deliver medical supplies to hospitals in rural areas in Rwanda that are hard to reach or inefficient to reach by other means of delivery.

Rwanda has also seen great use of UAVs during the COVID-19 pandemic where UAVs were widely used by the Rwanda's Ministry of Health and the Rwanda National Police to spread COVID-19 awareness in Kigali communities [4].

As UAVs gain the market, the need to have robust UAV systems also known as UASs becomes eminent. Therefore, in this thesis, focus was put in designing and building a robust, scalable, highly available cloud deployed Unmanned Aerial System, that can easily be integrated with cloud services like Amazon Web Services also known as AWS to provide a solution where UAV pilots can control UAVs from virtually anywhere in the world. The proposed system comprises of a UAV flying with onboard compute that has an LTE datalink to a ground control system also known as GCS, dashboards and a command-and-control center application running in a highly available and fault tolerant AWS cloud infrastructure. The focus of this thesis is to therefore assess the possibilities of implementing such a solution in an efficient, resilient, reliable, and highly available manner and discuss on the pros and cons of the solution.

The proposed solution, as seen in the high high level design in figure 1.0.1, was developed following the best industry standards in software development and architecture as is going to be described in detail in the next chapters. This thesis is also going to discuss the developments that have already been made in this area as well as areas that need further research and development.

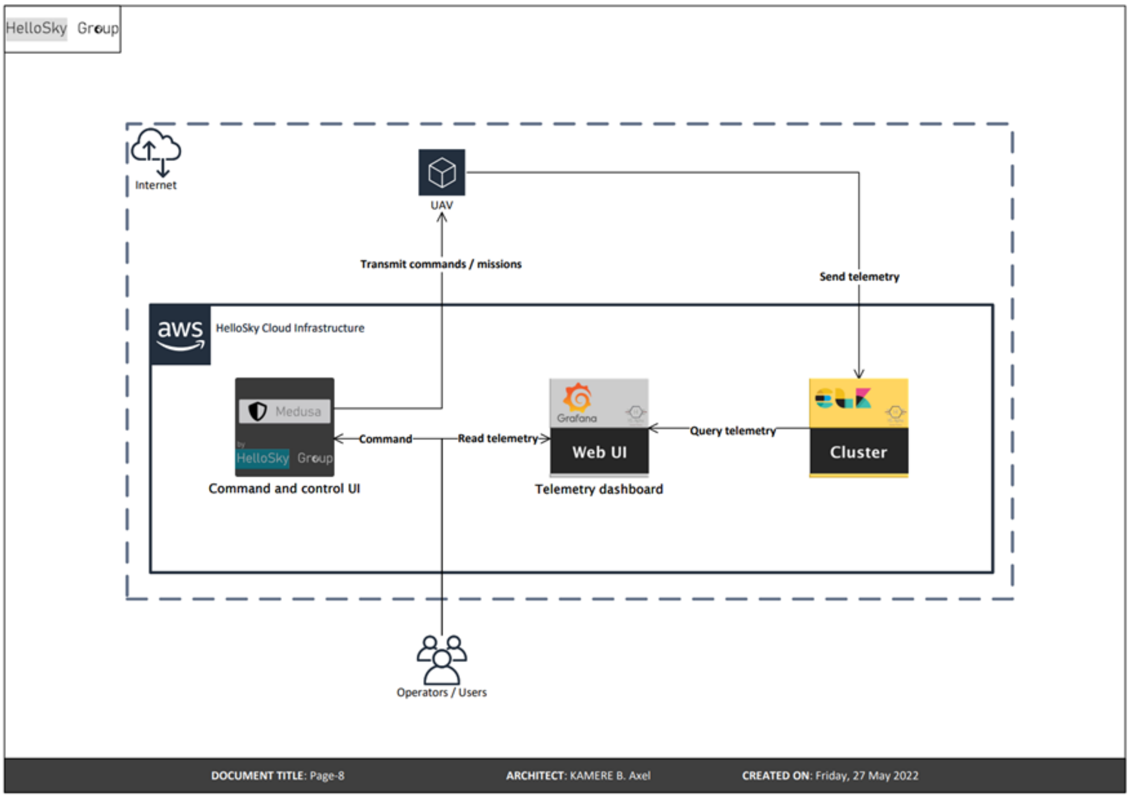

Figure 1.0.1. Proposed system high-high-level design.

Source: Own creation. Designed with Microsoft Visio. Refer to 2.4.6.

1.1 Related work

UAVs and UASs in general is a field that has undergone substantial development through various researches done by scientists, engineers and academicians.

One of the challenges still faced by UAVs, especially in the capability of being able to deploy them in urban areas, is the safety of their operations. Being able to build a

UAV with highly effective collision avoidance algorithms is a still a field under active research. And this is one of the main challenges that need to be solved for the world to see robust autonomous UAVs employed widely in communities for various use cases. Pedro et. al have studied on how UAVs can be made more resiliant and safe with the help of artificial intelligence, machine learning and the likes. In their article "Framework for fully autonomous UAVs" [5], they reviewed the current collision avoidance algorithms for both static and dynamic objects and proposed a conceptual framework to improve more the safety and realiability of UAVs.

<ADD ONE MORE USECASE??>

1.2 Use case

As UAVs emerge, there will be a need to be able to centrally manage a fleet of UAVs. Depending on the UAV use case, operators might need to also control them at a long distance beyond eyesight. A UAV operates as part of a system comprised of multiple other components that support the operation of a UAV. The main components are a Ground Control System, (Research on the main components of a UAV). UAVs can either be fully autonomous, fully manual, or semi-autonomous. UAVs can also be employed in various use cases, below are various scenarios in which UAVs can be used (CITE SOURCES OF THE BELOW USE CASES)

- Agricuture.
- Facility inspection.
- Terrain mapping.
- Shipping and delivery.
- Search and rescue.
- Law enforcement.
- Military reconnaissance / Surveillance.

For a UAV to perform any of the above, it needs to meet certain criteria, a UAV should:

- Have onboard computer to process mission commands on the fly.
- Have onboard key components like,
  - Sensors, depending on the mission.
  - Cameras.
  - Battery.
  - LTE modules or Satnav modules to allow communication with ground control.

- Have LTE or Satellite communication to enable the UAV to set up a datalink with the ground control. The UAV would have to send data such as
  - Ground speed.
  - Altitude.
  - Battery levels.
  - Yaw.
  - Location.
  - Direction.
  - Sensor data.
  - Send the data frequently for real-time or near real-time communication.
  - Be able to react and if necessary, take evasive maneuvers when:
    * On collision course.
    * The batteries are low on power.
    * Out of connectivity range.

1.3 Problem definition

1.4 About HelloSky group

Across this thesis, there will be mentions of the name "HelloSky group". Several designs built for the project as well as source codes all have mentions of HelloSky group or hsg in abbreviations.

HelloSky group is a company name that I came up with to brand my work done and future developments that will be made on this project and many other related projects that will be built in the future. HelloSky group in itself was though as a group company that will have multiple child companies, and in the scope of this project, it will be used to represent the part of the company that is envisioned to deal with aerial monility, hence being the scope of the thesis. Figure 1.4.1 shows the HelloSky group logos used throughout the thesis project.

(a) Colored 500 x 200.

(b) Black and white 500 x 200.

Figure 1.4.1. HelloSky group logos.

Source: Own creation. Designed with Affinity Designer. Refer to 2.4.4.

Chapter 2

Theory

In this chapter, key background concepts and methodologies used in the thesis are going to be discussed. The chapter is going to discuss explain what is meant by unmanned aerial system and its components.

The chapter is also going to discuss on the cloud provider, Amazon Web Services (AWS), used to host various components of developed system, simulation and software development tools used, as well as laws and regulations around unmanned aerial systems.

2.1 Unmanned Aerial System

bla bla

2.1.1 Unmanned Aerial Vehicle

bla bla

Classification of Unmanned Aerial Vehicles

bla bla

2.2 Amazon Web Services

Amazon Web Services, commonly known as AWS, is a cloud platform provided by Amazon that provides various service offerings such as platform as a service, PaaS, and infrastructure as a service, IaaS[6]. AWS makes it easy for developers, engineers and businesses to deploy scalable, resilient, agile and highly available infrastructures for databases, servers, applications, storage, analytics, *et cetera*. AWS offers attractive and cost saving payment strategies of which there are pay-as-you-go, save when you commit, and pay less by using more[7].

Cloud computing is an emerging technology that has revolutionized how businesses go online. Cloud computing has been and still is of great use in various industries, including the aerospace and energy industries. Burak et al developed a cloud and edge solution running on AWS that aimed at increasing turbine maintanance inspections' efficiency through automation and a serverless AWS architecture while reducing operations cost[8]. A serverless architecture is a type of architecture where servers' configuration and patching is taken care by the provider, thus allowing developers and engineers to focus on the actual resources, applications, databases *et cetera*, to be deployed. The solution proposed by Burak et al was comprised of drones, machine learning and Internet of Things running on cloud and edge.

The proposed solution in this thesis also takes advantage of what AWS and clound computing offers. Several components, like the ground control system, of the proposed solution are running on AWS. See the high-high-level design in figure 1.0.1.

2.2.1 Infrastructure as code

Infrastructure as Code also known as IaC, a technique very often used in the DevOps and automation community, is an infrastructure that is provisioned through code and scripts written in familiar programming languages like Python, PHP, Node.JS, C# *et cetera*. The infrastructure deployed through code can be servers, databases, firewalls, data centers *et cetera*. The main advantages of defining an infrastructure as code are:

- Improved efficiency and consistency.
- Reduced human error.
- Infrastructure agility. An infrastructure defined as code can be deployed as many times as needed, which reduces the effort invested by developers in case a replica of an environment is needed elsewhere.
- It allows developers to take advantage of programming languages features like loops, variables *et cetera* to build more agile infrastructures.
- The infrastructure can be versioned and tightly controlled. Since the infrastructure is basically standard code, it can be versioned with various versioning tools like Git or Subversion. This facilitates maintanance and makes the infrastructure easy to be rolled back, in case of issues.
- It helps with cost savings. Since the whole infrastructure is basically deployed automatically through code, engineers can then shift their focus to work on other important tasks.

In this thesis, Infrastructure as Code is used to its outmost potential. The AWS infrastructure is deployed as code using the AWS proprietary software development framework called AWS Cloud Development Kit or AWS CDK. AWS CDK is an open source kit provided by AWS that allows engineers to define IT infrastructures on AWS using familiar programming languages.

```
#!/usr/bin/env


# Import needed libraries
import aws_cdk as cdk
from aws_cdk import (
    aws_route53 as route53,
    aws_certificatemanager as certificate_manager,
    aws_route53_targets as targets,
    Stack
)
from constructs import Construct


class Route53RecordsStack(Stack):
    def __init__(self, scope: Construct, construct_id: str, props: dict, internet_facing_alb, hosted_zone,
                 **kwargs) -> None:
        super().__init__(scope, construct_id, **kwargs)

        # TODO: #61 Apply removal policy of the hosted zone.

        # Create A record 'helloskygroup.com' pointing to the internet facing ALB alias.
        route53.ARecord(self,
                        f"{props['company_abbreviation']}-medusa-{props['environment']}-alias-a-record",
                        target=route53.RecordTarget(
                            alias_target=targets.LoadBalancerTarget(internet_facing_alb)),
                        zone=hosted_zone,
                        comment="A record for root helloskygroup.com pointing to the internet facing ALB",
                        ttl=cdk.Duration.hours(2)
                        )

        # Create A record 'www.helloskygroup.com' pointing to the internet facing ALB alias.
        route53.ARecord(self,
                        f"{props['company_abbreviation']}-medusa-www-{props['environment']}-alias-a-record",
                        target=route53.RecordTarget(
                            alias_target=targets.LoadBalancerTarget(internet_facing_alb)),
```

```
                        zone=hosted_zone,
                        record_name="www",
                        comment="A record for www pointing to the internet facing ALB",
                        ttl=cdk.Duration.hours(2)
                        )

        # Create A record 'dashboard.helloskygroup.com' pointing to the internet facing ALB alias.
        route53.ARecord(self,
                        f"{props['company_abbreviation']}-grafana-{props['environment']}-alias-a-record",
                        target=route53.RecordTarget(
                            alias_target=targets.LoadBalancerTarget(internet_facing_alb)),
                        zone=hosted_zone,
                        record_name="dashboard",
                        comment="A record for Grafana (dashboard.helloskygroup.com) pointing to the internet "
                                "facing ALB",
                        ttl=cdk.Duration.hours(2)
                        )

        # Create A record 'logs.helloskygroup.com' pointing to the internet facing ALB alias.
        route53.ARecord(self,
                        f"{props['company_abbreviation']}-kibana-{props['environment']}-alias-a-record",
                        target=route53.RecordTarget(
                            alias_target=targets.LoadBalancerTarget(internet_facing_alb)),
                        zone=hosted_zone,
                        record_name="logs",
                        comment="A record for Kibana (logs.helloskygroup.com) pointing to the internet facing ALB",
                        ttl=cdk.Duration.hours(2)
                        )

        # Create A record 'api.helloskygroup.com' pointing to the internet facing ALB alias.
        route53.ARecord(self,
                        f"{props['company_abbreviation']}-node-red-{props['environment']}-alias-a-record",
                        target=route53.RecordTarget(
                            alias_target=targets.LoadBalancerTarget(internet_facing_alb)),
```

```
                            zone=hosted_zone,
                            record_name="api",
                            comment="A record for Node-Red (api.helloskygroup.com)
                            ↪ pointing to the internet facing ALB",
                            ttl=cdk.Duration.hours(2)
                            )
```

Listing 1. helloskygroup.com AWS CDK Python Route 53 snippet.

2.3 Simulation

bla bla

2.3.1 Webots or Ardupilot?

bla bla

2.4 Graphics and software development

bla bla

2.4.1 Microsoft Visual studio code

bla bla

2.4.2 PyCharm by JetBrains

bla bla

2.4.3 PhpStorm by JetBrains

bla bla

2.4.4 Affinity Designer

bla bla

2.4.5 GitHub

bla bla

2.4.6 Microsoft Visio

bla bla

2.5 Law and regulation

bla bla

Chapter 3

Methodology

3.1 Approach

3.2 Solution description

Describe the solution on a higher level. Discuss HLDs.

Chapter 4

Setup

4.1 Software

4.1.1 Command and Control Center

4.1.2 Telemetry dashboard

4.2 Hardware

Chapter 5

Discussion

Chapter 6

Conclusion

6.1 Future Work

6.1.1 Low latency communication

6.1.2 Collision avoidance navigation

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