

Scheduling Pipelined Circuits

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Abstract—This seminar work is about scheduling pipelined circuits where a circuit is allowed to perform multiple tasks at the same time with maximum overall timing proficiency. In this paper, it is explained what a pipelined circuit is, ways to schedule it, why to use it, the mathematical proof of its efficiency, examples with mathematical computations, area of uses, etc. Different scheduling techniques and comparisons will help us to use the maximum efficiency of hardware components.

I. INTRODUCTION

With the development of science and technology, more and more complicated tasks are easily handled using modern methods and techniques. Hardware components are costly and not easy to build. So, it is always better to make the maximum use of a hardware component. Circuits are the main building blocks of hardware components regarding the functionalities. Pipelining circuit has added a milestone on getting maximum output from a circuit with the fastest time. The main idea behind pipelining is dividing an operation in many stages so that a design can accept new operation even if the previous operation has not been finished completely yet. Pipelining is not using a circuit concurrently, but, it uses the part of a circuit which is unused for another process without interrupting the ongoing execution. Sharing resources like this way has boosted the efficiency of a circuit (e.g. CPU) like an unimaginable way. There are different types of pipelined circuits like asynchronous, synchronous which is discussed on this paper with proper explanation and examples. What is pipelining and how it works are also been elaborated. Processes in a pipelined circuit can be scheduled in many ways. This is also discussed on this paper.

II. PIPELINING

To get the better understanding of Pipelining, Let's go through an well known example before we move to pipelined circuits.

While washing clothes in a washing machine in a dormitory or anywhere else, there is a washing machine as well as a dryer. Let's consider Figure 1, a washing machine takes 90 min. for a wash, and a dryer takes 90 min. for a drying.

Suppose, there is 10 cloth load, So, If someone wants to wash and dry these all, by normal calculation, the amount of time necessary =

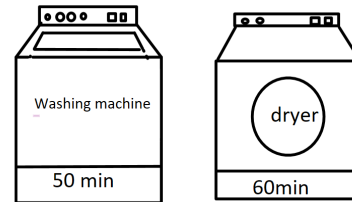


Figure 1. washing machine and dryer

$$N * (\text{washing time} + \text{drying time}) = N * (50 + 60) = N * 110$$

And this is without pipelining.

But this is not the smartest way. One can easily put 2nd bundle of cloths to washing machine after the first wash while 1st load is drying. Figure 2 explains it very well where this task is done step by step with a pipelined technique:

So, the amount of time necessary in this case would be $= N * 60$ minutes.

It is more like to be $(N * 60 + 50)$.

But we have considered mostly the steady state situation which is our interest in pipelining.

The technique described here is nothing but Pipelining !!

A. Some Definition

Latency: The delay between the establishment of an input until the output associated with this input is valid.

for the above mentioned example, for 11 hours (660 minutes), if there is no pipelining,

total load that is finished washing and drying = $660 / 110 = 6$ load

while with pipelining, that is = $660 / 60 = 11$ load. It is easily noticeable that with pipelining, with the same time, 11 load of cloths are washed and dried!!

Throughput:

throughput is the rate of which input and output are processed. For this scenario, without pipelining = $1 / 110 = 0.009$ min/sec with pipelining = $1 / 60 = 0.016$ min/sec

B. pipelined circuits

Let's consider combinational circuit shown in Figure 3. there are several block A, B, C and D, the input of the circuit

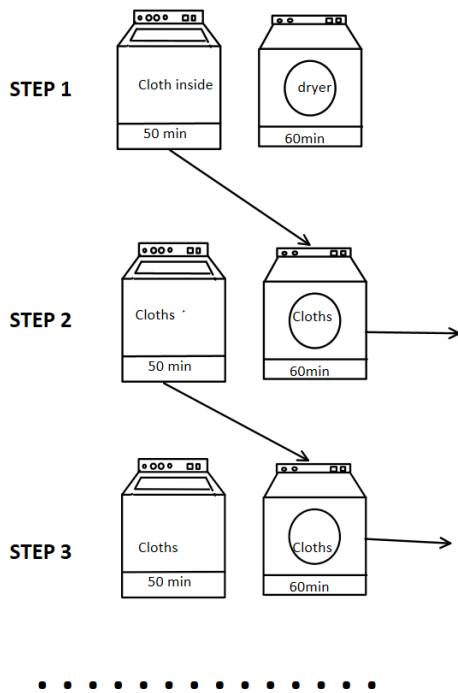


Figure 2. pipelining for using washing machine and dryer multiple time

is X and the output of the circuit is O .

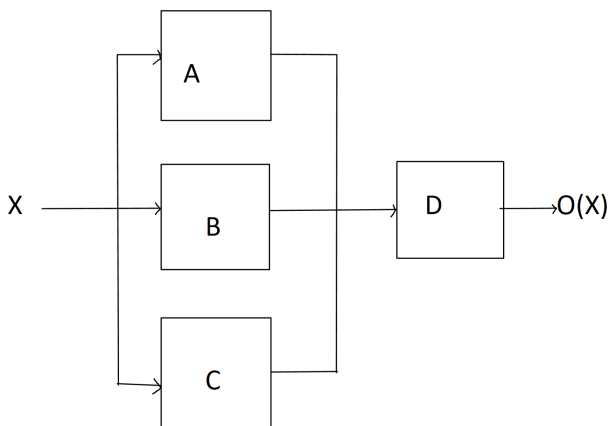


Figure 3. A combinational circuit

Suppose, Latency = L
 so throughput = $1/L$.
 assume that , the processing time of A , B and C is not equal.
 Now how this circuit performs a execution ?
 in Figure 4, The executional behaviour with time is given. It

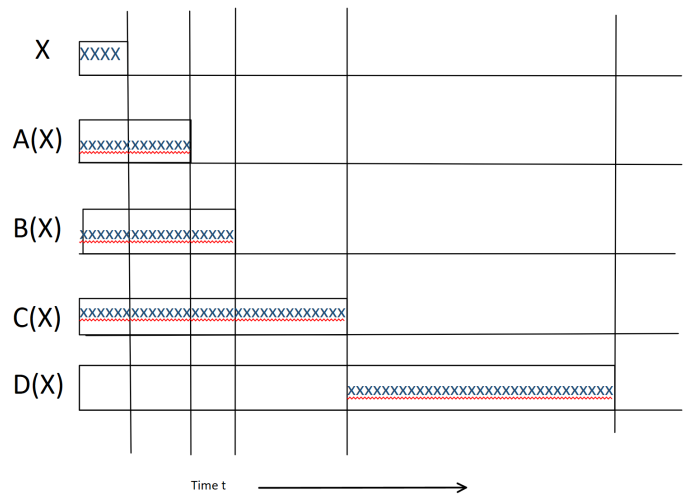


Figure 4. execution of a process in a the combinationa circuit shown in Figure 3

is clearly noticed that, while D performs its execution, A,B and C are idle just keeping the output stable.

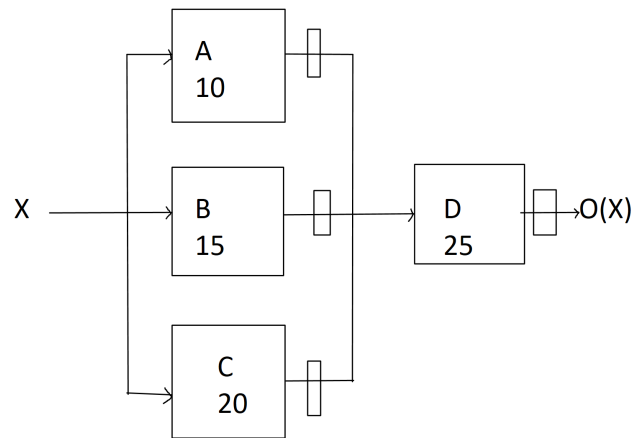


Figure 5. Pipelined circuit

Let's use registers to hold the input values for D stable.
 and we put some execution time for each elements. Consider
 Figure 5 where a register is used after each of the blocks
 shown in Figure 3.

Now, we can consider this combinational circuit as 2 stage
 pipeline.

A, B and C are working on input

$$X_{i+1}$$

A valid input X during clock cycle j,
O(X) is valid till j+2.

Now, Suppose,
Propagation delays of A, B ,C and D in Figure 5 is 10,15,20
and 25 ns.

As we used ideal zero delay registers.

So, for unpipelined:

$$\text{Latency} = 20 + 25 = 45$$

$$\text{Throughput} = 1/45$$

For two stage pipeline:

$$\text{Latency} = 50$$

$$\text{Throughput} = 1/25$$

we see that, though latency is worse in pipelined circuits
than the unpipelined circuit, the processing rate which is called
throughput is better in pipelined version.

in Figure 6, overall timing behaviour of the circuit shown in

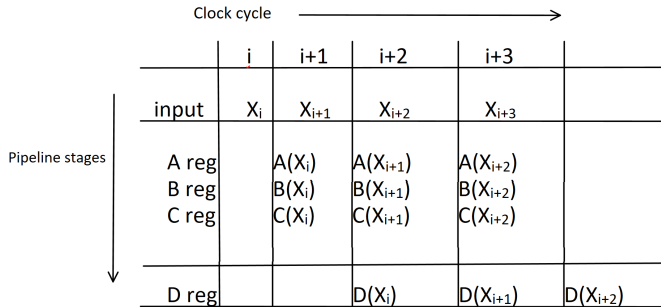


Figure 6. Pipeline diagram of the circuit shown in Figure 5

Figure 5 is explained .

for a particular set of inputs data, the result move diagonally
through the diagram progressing one pipeline stage for each
clock cycle.

C. K-stage pipeline

A K-stage pipeline is an acyclic circuit having exactly K
number of register through the path from input to output.
for every pipeline stages, there is an register on it's output.

Latency = K times the period of the clock common to
all registers

Throughput = the frequency of the clock

III. SYNCHRONOUS PIPELINING

In a synchronous pipelined circuit, all the pipelining stages
are controlled by the same clock signal, a global clock.
consider Figure 7, Where pipelining is controlled by global
clock, for each stage, input data is processed by combinational
logic and output is latched to the input of another stage. The
clock duration is large enough which result in filtering hazards
or glitch.

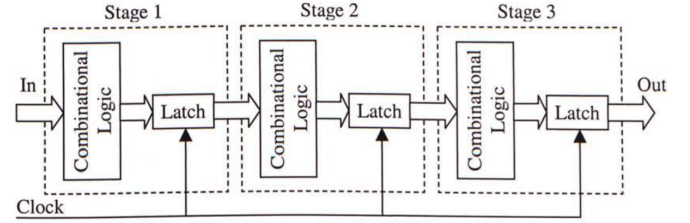


Figure 7. architecture of a pipelined synchronous circuit (from reference [5])

Asynchronous pipelining

In a asynchronous pipelined circuit, all the pipelining stages
are controlled by localizes signal instead of global clock signal
in synchronous pipelining. Figure 8 shows a classical asyn-
chronous pipelined architecture that makes use of Differential
Cascode Voltage-Switch-Logic (DCVSL) as logic cell. here,
handshake control signal is used instead of global clock to

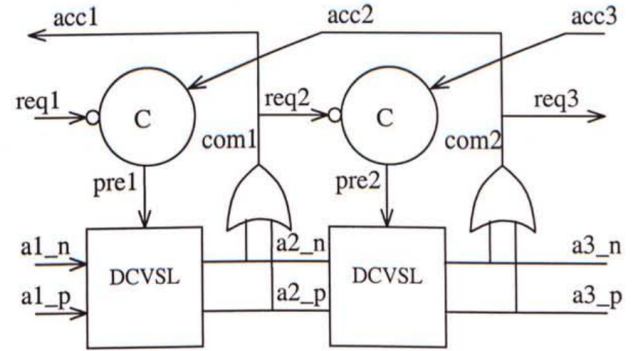


Figure 8. architecture of a pipelined asynchronous circuit (from reference [5])

manage the data flow as well as operation between two
pipelined stages. completion of each stages is determined by
the data output.

IV. SCHEDULING PIPELINE CIRCUITS

generally, a pipelined circuits consists of a sequential graph
model and corresponding data rate.

we consider nonpipelined sequencing graphs whose operations
can be bound to pipelined resources. (i.e., pipelined submod-
els).

In Figure 9, a scheduling example of pipelined circuit or
resources is shown.

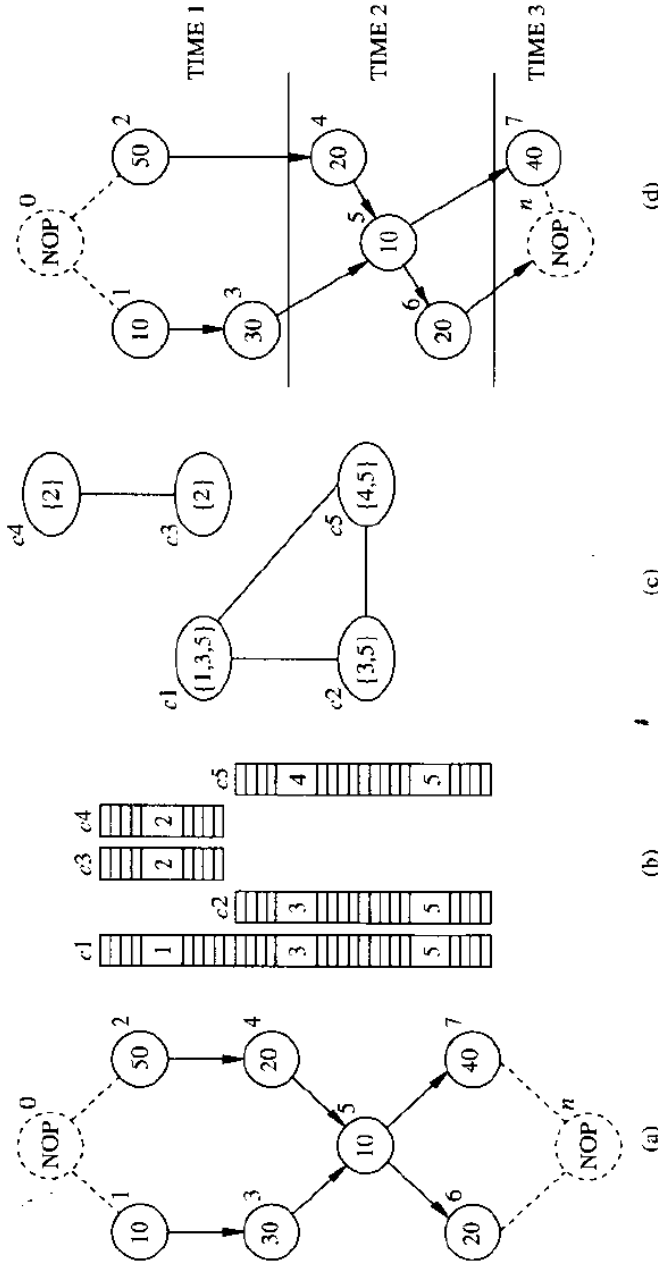


Figure 9. (a) sequential graphs (b) cuts (c) cut intersection graph (d) scheduled sequencing graph (from reference [3])

A. Scheduling with pipelined resources

pipelined resources or hardware components or pipelined circuits consume and produces data at time interval less than the execution delay. the time interval which is called data introduction interval are assumed to be constant.

It is possible for pipelined resources to be shared even operations overlap. The fact is, there should be no data dependency, and the operations do not begin at the same time step .

In this case, The list scheduling algorithm can be used to

schedule this operation with different time steps and with no data dependency. considering the time introduction interval is 1, the list scheduling algorithm for constraint resources is usable.

Interested reader can find details of List scheduling on page 207 to 210 of the book on reference [3]. In Figure 10, a sched-

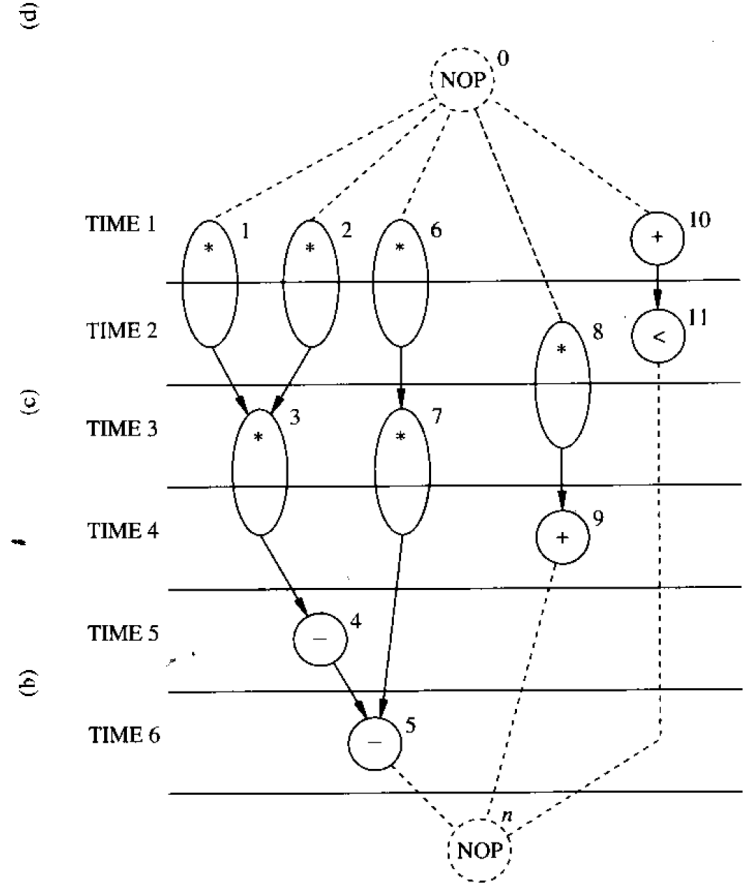


Figure 10. scheduled sequential graphs with pipeline resources(image taken from reference [3])

uled sequential graph with pipeline resources is shown. One can find that , it is divided into time slices which is called data introduction interval.

B. Loop folding

Loop folding is a technique which can reduce the execution delay of a loop. we consider the use of pipelining to speed up the execution of loops. This technique is called loop winding and loop folding.

Let's consider a loop,

number of loop iteration = n_l

So, the execution delay of the loop = $n_l \cdot \lambda_l$

where, Latency of the loop = λ_l

pipelining the loop body with local data introduction interval $\delta_l < \lambda_l$, results in:

overall loop execution delay =

$$[n_l + \lambda_l / \delta_l - 1] * \delta_l$$

So, Loop folding reduces execution delay of a scheduled sequency graph that has loop, possibly nested loop. loop folding can be viewed as pipelining the graph entity of the loop body with the goal of reducing the execution delay.

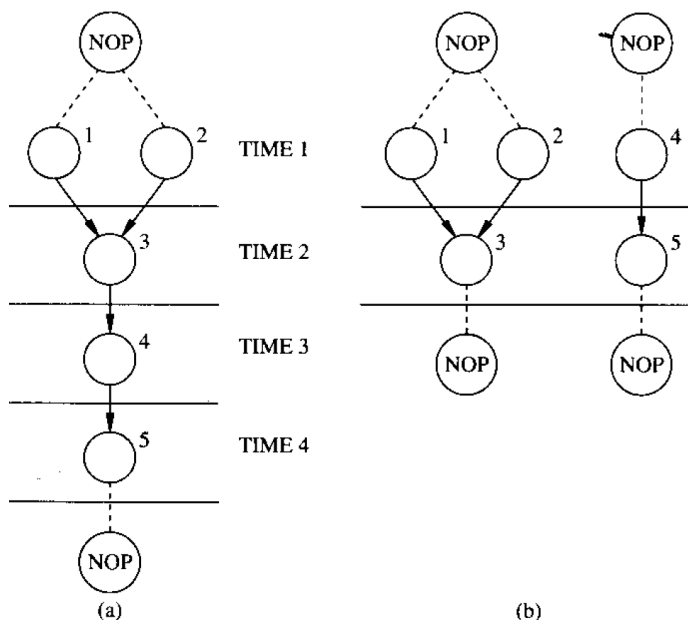


Figure 11. (a) sequential graph of a loop body (b)sequential graph after loop folding (image from reference [3])

V. SUMMERY

Increase in the pipeline stages increases the number of execution executed simultaneously. Faster processing unit can be designed using pipeline techniques. By pipelining, electric circuits increases the processing rate of the desired purposed processes. Pipelined CPU works at higher frequency rate . Pipelining increases the overall circuit proficiency.it makes a greater utilization of logic/circuit resources. it is quite exhaustive the act of a pipeline design . it is necessary to divide overall circuits/system into individual stages at an average instances to make sure optimal performance. However, the hard work results in a awesome advantages during the execution.

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