

```
streets_service::streets  
_singleton< streets_configuration >
```



```
graph BT; A[streets_service::streets_configuration] --> B[streets_service::streets_singleton< streets_configuration >];
```

A diagram illustrating a relationship between two C++ classes. At the bottom is a light gray box containing the text 'streets_service::streets_configuration'. A blue arrow points vertically upwards from the top center of this box to the bottom center of a white box above it. The white box contains the text 'streets_service::streets_singleton< streets_configuration >'. This represents that the configuration class is a base class or a template argument for the singleton service class.

```
streets_service::streets  
_configuration
```