

Demo

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0.1 Demo and Test

In this part, we test the Convex Hull 2D for some cases

```
In [1]: from ConvexHull import ConvexHull2D
import numpy as np
model = ConvexHull2D()
```

0.1.1 Test One: Invalid. input

```
In [2]: points = None
model(points)
```

No valid convex hull is found! Please provide more than 3 unique points

0.1.2 Test Two: Invalid. input

```
In [3]: points = np.array([])
model(points)
```

No valid convex hull is found! Please provide more than 3 unique points

0.1.3 Test Three: Invalid. input (insufficient amount of points)

```
In [12]: points = np.array([[1,2], [-4.9, 0.73]])
model(points)
```

No valid convex hull is found! Please provide more than 3 unique points

0.1.4 Test Four: Invalid. input (points are actually on the same line)

```
In [13]: points = np.array([[1,2], [1, 3], [1,4]])
convex_hull = model(points)
print ("\nThe vertices of convex hull are\n")
print (convex_hull)
```

```

<class 'Exception'>
('The input points are located on the same line. No convex hull is found!')
<class 'Exception'>
('Not enough points are found for convex hull. Please check your input and other information',)

```

The vertices of convex hull are

None

0.1.5 Test Five: Simple case

```

In [5]: points = np.array([[0,0], [1,2], [-4.9, 0.73]])
        model(points)

```

```

Out[5]: array([[ -4.9 ,  0.73],
               [  0.  ,  0.  ],
               [  1.  ,  2.  ]])

```

0.1.6 Test Six: General case

```

In [10]: import matplotlib.pyplot as plt

        points = np.random.random((100,2)) * 100 #draw from normal distribution and scale it
        points -= np.random.random() * 100 # test points with positive and negative coordinates
        plt.plot(points[:,0], points[:,1], 'o')

        convex_hull = model(points)
        print ("The vertices of convex hull are")
        print (convex_hull)

        #Close the hull during plot by making the head and tail as the same point
        convex_hull = np.vstack([convex_hull, convex_hull[0]])
        plt.plot(convex_hull[:,0], convex_hull[:,1])
        plt.show()

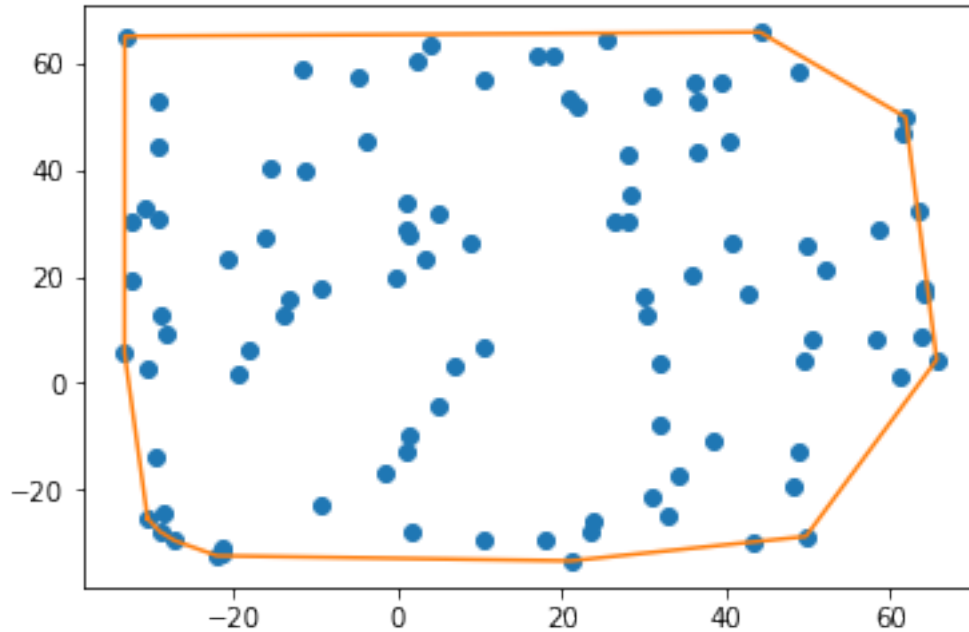
```

The vertices of convex hull are

```

[[-30.34478464 -25.49434852]
 [-28.80982052 -27.97168969]
 [-27.03556445 -29.62912708]
 [-21.92438044 -32.46525418]
 [ 21.12174928 -33.42353813]
 [ 49.75244411 -28.84468783]
 [ 65.68061666  4.33814033]
 [ 61.89855911 49.91768006]
 [ 44.16177304 65.88208679]
 [-33.12044019 65.10176138]
 [-33.15281795  5.67249395]]

```



0.1.7 Test Seven: Given a test set of points, check if they are inside the convex hull

In [7]: `import matplotlib.pyplot as plt`

```

points = np.random.random((100,2)) * 100 #draw from normal distribution and scale it
points -= np.random.random() * 100 # test points with positive and negative coordinates
test_points = np.random.random((10,2)) * 100

plt.plot(points[:,0], points[:,1], 'o')
plt.plot(test_points[:,0], test_points[:,1], 'ro')
convex_hull = model(points)
print ("The vertices of convex hull are\n")
print (convex_hull)

#Close the hull during plot by making the head and tail as the same point
convex_hull = np.vstack([convex_hull, convex_hull[0]])
plt.plot(convex_hull[:,0], convex_hull[:,1])

isInside = model.isInside(test_points)
print ("\n")
print ("Testing the model with random test set")
for point, status in zip(test_points, isInside):
    print("point: ", point, " status: ", status )

plt.show()

```

The vertices of convex hull are

```
[[-24.43333595 -10.16025703]
 [-18.28298976 -18.63656776]
 [-14.7729698  -21.6422585 ]
 [ 1.32096596 -23.79991096]
 [ 56.0300138  -23.88969908]
 [ 70.7858042  -20.71260849]
 [ 74.88493107  39.03853099]
 [ 70.62610472  73.48114179]
 [ 4.64657323  74.66695145]
 [-23.28574506  68.39594002]
 [-24.08897784  57.55102279]]
```

Testing the model with random test set

```
point: [71.93988592 55.35013509] status: True
point: [ 6.29908119 26.5605536 ] status: True
point: [66.47244996 61.7487539 ] status: True
point: [ 5.38516047 18.65902789] status: True
point: [15.64034429  6.01978347] status: True
point: [58.91889175 13.6917658 ] status: True
point: [16.38792149 64.03859936] status: True
point: [20.88248563 41.23138062] status: True
point: [34.69632593 71.56028955] status: True
point: [ 6.76041777 87.9044422 ] status: False
```

