

Definition of embedded system is ~~basically~~ ~~an electronic~~ ~~and~~ ~~electro~~ ~~Mechanical~~ ~~System~~.

An embedded are electronic and electro-  
Mechanical System.

→ Design to perform a specific function and is  
a combination of both hardware & software  
(HW).

→ EMBEDDED Systems are becoming a inevitable  
part of any project or equipment in all fields  
including household Applications. telecommunicat-  
ion, medical equipment, Industrial control,  
Consumer products, etc.

Difference b/w Embedded system and general  
computing systems.

General computing  
systems

Embedded system

1) A system which is a combination of generic HW and general purpose OS for executing variety of Applications.

1) A system is a combination of special purpose HW and embedded OS for executing a specific set of Applications.

- CHARTERED  
MEMBER IIT KANPUR
- 2) Contains a GP OS
  - 2) May or may not contain an OS for functioning.
  - 3) Applications are ALTERABLE.  
 (i) programmable by the user
- ↳ One without drivers is not good for application.*
- 4) Performance is the key deciding factor in the selection of the system.  
 Always faster is better.
  - 4) Application specific Requirements like performance power requirement memory usage etc. are the key deciding factors.
  - 5) Response requirement does not time critical.
  - 5) for certain category of low level applications like mission critical systems. The response time requirement is highly critical.

History of EMBEDDED systems.

→ ES exists in existence even before the IT evolution and embedded algorithm was developed in low level languages.

→ Advances in semi conductors, nano technologies and IT development give way to the development of miniature ES.

→ The first recognized ES is the Apollo guidance computer (AGC) developed by MIT Instrumentation Laboratory for lunar exploration. Then they did the essential guidance system. The command module and <sup>execution</sup> Lunar module (LEM).

→ CM :- It is design to encircle the Moon.

→ LEM :- It is design to go down to the Moon surface and land there safely.

→ AGC is consist of 18 engines.

→ The LM featured in total 18 engines.

The first NASA produced ES was guidance computer for the Minuteman one missile in 1961.

→ It was Automatic DIT guidance computer built using discrete diodes, logic and a hard disk for a main memory.

→ The first IC and their early usage of ES apart from computers, were used by NASA in 1958.

→ AGC built by the USA Military in the Minuteman missile.  
Now fool proofed (Safety) structures showing  
comes out programmed with some state PGM

### Classification of Embedded system

Classification is based on 4 types

1. Based on generation
2. Based on complexity & performance
3. Based on deterministic behaviours.
4. Based on triggering

#### 1. Classification based on generation:

i) 1G :- The early years where built around 8-bit Microprocessors like 8085 & Z-80 & 16-bit Microcontroller. Simple in H/W circuit with programs be developed in Assembly code.  
Ex:- Digital telephone key pads, step up motor control unit.

ii) 2G :- There are years built around 8-Bit 16-bit Microcontrollers & 16-bit Microprocessor like 8086 following the 1st generation Es.

→ The instructions sets for the 2G processors (or) controllers where much more complex and powerful than the 1G.

Ex:- Data acquisition systems, daq systems.

iii) 3G: - Developers started making use of power 32-bit processors and 16-bit microcontrollers for their design.

→ A new concept of application and domain specific processors (CSP) controllers like digital signal processor (DSP) and Application Specific integrated circuit (ASIC) come into picture.

→ The instruction set of processors became more complex and henceforth the concept of instruction pipelining.

Ex:- Robotics, Media, Industrial processor control, Networking.

iv) 4G :- System on chip (SoC), Reconfigurable processors (FPGA) Multi core processor. Due to being high performance. Miniaturization into embedded device market.

These generations making use of high performance real time embedded OS for their functioning.

Ex:- Smartphone devices, Mobile Internet devices etc.

v) 56:-

2) Classification based on complexity & performance

i) Small scale ES :-

It uses low cost 8-bit microprocessors (or) 16-bit Microcontrollers if may or may not contain OS for functioning.

ii) Medium scale ES :-

ES which are slightly complex in H/w & S/w (F/w) requirements fall under these category. It uses low cost 16-bit microprocessor (or) 32-bit Micro controllers. It contains an OS either general purpose or real-time OS for functioning.

iii) Large scale ES :-

In these ES involve high complex H/w and S/w requirements fall under these category. If uses 32-bit disk processors (or) 64-bit controllers (or) PLD's.

→ Decoding of encoding of medium cryptographic function implementation.

### 3) Classification based on Deterministic Behaviours

- It is Applicable for real time systems
- The Application are task execution behaviours for on ~~yes~~ ES can either Deterministic (D) undeterministic
- Based on execution behaviours real time yes are classified into hard & soft real time.

### 4) Based on Triggering :-

- ES which are reactive in nature.
- ~~Ex: process control systems in industrial~~ control applications can be classified based on triggered.

- It can be either event (D) time triggered

### Major Applications areas of ES

- 1) Consumer electronics: ~~connected comp. devices, cameras, etc.~~
- 2) House hold appliances :- DVD players, TV, washing machine, refrigerator, microwave oven, etc.

3) Home Automation & Security systems :-  
air conditioners, sprinklers, intrud detection alarms,  
CCTV (CAT), cameras, fire alarm etc.

4) Automotive industry :-  
Anti lock breaking system, Engine control cognition  
systems, Automatic navigation systems.

5) Telecom :-  
cellular telephones, Telephone switches,  
Hand set multimedia Applications, etc.

6) Computer peripherals :-  
printers, scanner, Fax machine etc.

7) Computer N/w Systems :-  
N/w routers, switches, firewalls etc.

8) Health care :-  
Different kinds of scanners, electrocardio-  
gram machines, Double egg machines etc.

9) Measurement & instrumentation :-  
Digital Multimeters, digital ERO's,  
Logic Analyzers, PLC systems etc.

10) Banking & Retail :-

Automatic Teller Machine (ATM), currency counters, point of sale Machine.

11) Cash Readers :-

Barcode, smart card readers, House hold devices etc.

Purpose of ES

→ ES are used in various domains and design

to serve the purpose of any one or a combination of following task.

1. Data collection (or) storage (or) representation
2. Data communication
3. Data processing
4. Monitoring
5. Control
6. Application specific user interface.

## 1) Data collection are storage (or) Representation

- It is usual done for storage analysis and manipulation & transmission.
- The term data refers all kinds of information like text, voice message, video, image, electrical signals, and any other measurable quantities

→

## 2) Data communication :-

Embedded data communication systems are deployed in applications ranging from complex satellite communication system to simple home N/W systems. The transmission is achieved either by wire line medium (or) wireless medium

## 3) Data processing :-

- The data collected by Es may be used for various kind of data processing.
- Es with signal processing like speech coding, synthesis, Audio, Video coded. (modem), transmission Applications etc.
- Digital ~~theory~~<sup>Engineering</sup> is a typical example of Data processing.

## 4) Monitoring:-

These are specific design for monitoring purpose  
example ECR.

Examples of ES with monitoring functions are,  
digital CRO's, digital multimeters, logic analyzers,  
status of some variable like current, voltage etc.

## 5) Control:-

It control over some variables according  
to the changing input variables. It contains  
both sensors and actuators. Sensors are connected  
in the i/p ports where as actuators are  
connected to the o/p port.

## 6) Application specific user interface:

→ These are like buttons, switches, keypads, belts,  
lights, display units etc. mobile phone is a  
best example of these.

## characteristics of ES

These characteristics are unique for each ES  
some of them are.

1. Application are domain specific
2. Real time and reactive.

3. operates in harsh environment
4. distributed
5. small size & weight
6. passes commands.

## 1. Application area domain specific :-

- Each ES is having certain functions to perform and they are developed such a manner to do intended functions only. They cannot be used for any other purpose.

e.g. - The cannot replace the embedded control unit of Microwave oven with Air conditioners.

## 2. Reactive and Real time :-

- ES are inconsistent interaction with the real world through sensors and user define i/p devices which are connected to the i/p ports of the system.

- Any changes happening in the real-world are capture by the sensors are i/p devices

e.g. - flight control systems, Anti lock break systems.

### 3. Operates in harsh environment:-

- It is not necessary that all ES should be deployed in control environments. It may be a dust one, a high temperature zone, an area subjected to vibrations & shock. Systems placed in such areas should be capable of performing all operating conditions.

### 4. Distributed :-

- ES may be a part of large systems. Many numbers of such distributed ES from a single large embedded control unit.

Ex:- Automatic welding, automatic teller machine. Which contains control decoder, embedded unit.

Which is used to perform welding functions and transaction to achieve goal.

5. Small size & weight :- ~~and fast speed of~~  
Product as it is important factor  
choosing a product.

Ex:- When you plan buy new hand mobile  
phone.

as it is! - size, space, width, / weight.

6. Power consumption :-

Power management is another important  
factors. That needs to concern to designing  
To minimize heat dissipate by the  
system. The more power consumption the  
less is the battery life.

Quality Attributes of ES :-  
Quality attributes are divide into two operational  
& nonoperational.

Operational :-

- It depends on the quality attributes defined  
to ES. When resides in the operational  
mode (or) online mode.

- The important QA are typically 6 sigma quality system to follow.
  - 1. Response
  - 2. Throughput
  - 3. Reliability
  - 4. Maintainability
  - 5. Security
  - 6. Safety.

1) Response:- It is the measure of thickness of a system it gives the idea about how fast your system is tracking the changes in input variables.

Ex:- Flight Control Application.

2. Throughput :- It deals with the efficiency of the system in general it can be define as the rate of production over a period of time. It is measured in terms of benchmark.

Ex:- Card decorated

3) Reliability: It is a measure of how much percentage it is a measure of how much percentage how can delay upon proper functions of the system (so) what is the percentage sustainability of a system to failures. Mean time between failures. MTB, Mean time to repair. MTR, are the terms used to define system reliability.

#### 4. Maintainability:

It deals with deposit and maintenance to the end user or client in case of technical issue and product failures. are on the bases of definite system check up. → Reliability and maintainability are two complementary discipline as reliability increases. The need for maintainability of the system is reduce.

$$\rightarrow \text{Availability} = \frac{\text{MTF}}{\text{MTF} + \text{MTR}}$$

5. Security :- confidentiality, integrity & availability  
Confidentiality, integrity & availability are the three major measures of information security. Confidentiality deals with protection of data and application from unauthorized disclosures.

Integrity - unauthorized modification.

Availability - unauthorized users.

Ex:- personal digital Assistant.

6. Safety :- safety & security are two confusion terms sometimes you may feel both are same but the dependent has unique aspects in Q.A. Safety deals with possible damages that can happen to the operators. It occurs due to the emission of radio active or hazardous materials from the embedded products.

$$TPI = \text{Hazardous} - RIM + TPI$$