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MAE 298 Aeroacoustics – Homework #3
Generalized Differentiation and Farassat's Formulation

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Nomenclature

0	Subscript for undisturbed, quiescent parameters
e	Subscript for emission parameters
L	Subscript for loading parameters
t	Time
τ	Retarded time
ret	Evaluated at retarded time
$\hat{n}$	Unit surface normal vector
$\vec{r}$	Radial direction vector
$\hat{r}$	Radial unit vector
r	Magnitude of radial vector $\lvert\vec{r}\rvert$
θ	Angle between $\hat{n}$ and $\hat{r}$
f	Function of surfaces within a fluid space
$\vec{V}$	General velocity vector
V_r	Velocity component in radial direction
V_n	Velocity component in surface normal direction
M	Mach number
c	Speed of Sound
$\overline{\rho}$	Mean density
p	Pressure
$\widetilde{p}$	Pressure (Discontinuous across data surface)
$\overline{p}$	Mean pressure
p'	Perturbation pressure
ΔP	Pressure difference from CFD solution
L	Pressure loading
$\overline{\partial}$	Generalized derivative
δ	Dirac delta function
FW-H	Ffowcs Williams-Hawkings

Overview

In this assignment, we will first derive the wave equation for sound generated by a moving body using generalized differentiation. This process is similar to that used by Ffowcs Williams and Hawkings in the derivation of their equation describing aeroacoustic noise. Equations like these are useful for computing aeroacoustic effects once source terms such as body loading are calculated.

Secondly, we will derive Farassat's Formulation 1A of the Ffowcs Williams-Hawkings (FW-H) equation for pressure due to loading noise beginning with Formulation 1. This result will demonstrate the process for solving the FW-H equation and may be applied to the other terms to obtain Farassat's complete Formulation 1A of the FW-H equation.

I. Problem 1 – Generalized Differentiation of Wave Equation

In this section, we will derive the wave equation for sound generated by a moving body, which is known as the Kirchhoff formula for moving surfaces. The general acoustic wave equation with no source term (homogeneous) is expressed as follows:

$$\boxed{\frac{1}{c^2}\frac{\partial^2 p}{\partial t^2} - \nabla^2 p = 0} \tag{1}$$

We will used generalized differentiation to show that the wave equation whose sound is generated by an arbitrary moving body $f = 0$ can be expressed as follows:

$$\boxed{\frac{1}{c^2}\frac{\bar{\partial}^2 \tilde{p}}{\partial t^2} - \bar{\nabla}^2 \tilde{p} = -\left[\frac{M_n}{c}\frac{\partial p}{\partial t} + p_n\right]\delta(f) - \frac{1}{c}\frac{\partial}{\partial t}\left[M_n p \delta(f)\right] - \nabla \cdot \left[p\hat{n}\delta(f)\right]} \tag{2}$$

where $\hat{n}$ is the unit normal vector on the surface and $p_n = \nabla p \cdot \hat{n}$.

We will use Greens function of the wave equation in the unbounded space to find the unknown function $p(\vec{x}, t)$, which exists everywhere in space. This result is called the Kirchhoff formula for moving surfaces.

I.A. Data Surface Definition

The moving surface generating acoustic effects will be defined as $f(\vec{x}, t) = 0$ and will be referred to as a "data surface". The definition of f allows the fluid to be defined at all points in space, which can be divided into three regions:

Data Surface:	$f = 0$
Exterior Region:	$f > 0$
Interior Region:	$f > 0$

We will also assume that the gradient of f is the surface outward unit normal vector $\hat{n}$:

$$\nabla f = \hat{n} \tag{3}$$

Under this definition of f, the fluid will exist in all regions of unbounded space and thus enable the usage of Green's function to solve for the sound field.

We will solve for the sound field in the surface exterior region, but we will assume that the fluid that extends into the interior region has the same conditions as an undisturbed, quiescent medium. We can define a pressure variable with these properties as $\tilde{p}$ using the embedding technique as follows:

$$\boxed{\tilde{p} = \begin{cases} p, & f > 0 \\ 0, & f < 0 \end{cases}} \tag{4}$$

Thus, pressure will vary outside of the data surface and will be undisturbed inside. Though not continuous, this function of pressure will be defined at all points in an unbounded space and thus applicable to Green's function.

I.B. Generalized Differentiation

Due to the discontinuity in $\tilde{p}$ at the data surface $f = 0$, we will not be able to use standard differentiation to solve for the sound field and must instead use a technique called generalized differentiation, which will be denoted with a bar over the differential operator (e.g. $\bar{d}, \bar{\partial}, \bar{\nabla}$, etc).

To illustrate the principles of generalized differentiation, we will use the piecewise-continuous pressure $\tilde{p}$. The following rules will also apply to other piecewise-continuous fluid properties such as density $\tilde{\rho}$. Without a formal proof, we can state the rules of generalized differentiation as:

$$\frac{\bar{d}\tilde{p}}{dx} = \frac{d\tilde{p}}{dx} + \Delta\tilde{p}\delta(x - c) \tag{5}$$

where x is an arbitrary variable of differentiation, δ is the Dirac delta function, $x = c$ is the location of the discontinuity in $\tilde{p}$, and $\Delta\tilde{p} = \tilde{p}(c^+) - \tilde{p}(c^-) = p - p_0$ is the discontinuous difference in $\tilde{p}$ at the location of the discontinuity, or the difference in the parameter between the exterior and interior regions of the defined space.

For the case of the arbitrary moving body $f = 0$, where $x = f$ and $c = 0$, the Dirac delta function $\delta(x - c)$ becomes $\delta(f)$. Applying Eqn 5 to the gradient operator ∇ and using the chain rule, we obtain:

$$
\begin{aligned}
\overline{\nabla}\bar{p} &= \frac{\overline{\partial}\bar{p}}{\partial x_i} = \frac{\overline{\partial}\bar{p}}{\partial f}\frac{\partial f}{\partial x_i} \\
&= \left(\frac{\partial\bar{p}}{\partial f} + \Delta\bar{p}\delta(f)\right)\frac{\partial f}{\partial x_i} \\
&= \frac{\partial\bar{p}}{\partial f}\frac{\partial f}{\partial x_i} + \Delta\bar{p}\frac{\partial f}{\partial x_i}\delta(f) \\
&= \frac{\partial\bar{p}}{\partial x_i} + \frac{\partial f}{\partial x_i}\Delta\bar{p}\delta(f)
\end{aligned}
$$

Substituting the gradient operator $\nabla = \dfrac{\partial}{\partial x_i}$:

$$
\overline{\nabla}\bar{p} = \nabla\bar{p} + \nabla f \Delta\bar{p}\delta(f) \tag{6}
$$

Recall the assumption that gradient of f is the outward normal vector, as summarized in Eqn 3. Additionally, we can apply the definition of $\bar{p}$ to the pressure difference at the discontinuity $\Delta\bar{p} = p - p_0 = p - 0 = p$. Making these substitutions, we can rewrite Eqn 6:

$$
\overline{\nabla}\bar{p} = \nabla\bar{p} + \hat{n}p\delta(f) \tag{7}
$$

I.C. Kirchhoff Formula Derivation

We will now apply the principles of generalized differentiation to Eqn 1 to derive the general equation for the sound field generated by a moving surface. Beginning with the first term on the LHS of Eqn 1, we will first take a single partial derivative WRT time and then perform another derivative on the resulting term:

$$
\begin{aligned}
\frac{1}{c}\frac{\overline{\partial}\bar{p}}{\partial t} &= \frac{1}{c}\frac{\overline{\partial}\bar{p}}{\partial f}\frac{\partial f}{\partial t} \\
&= \frac{1}{c}\left(\frac{\partial\bar{p}}{\partial f} + \Delta\bar{p}\delta(f)\right)\frac{\partial f}{\partial t} \\
&= \frac{1}{c}\frac{\partial\bar{p}}{\partial f}\frac{\partial f}{\partial t} + p\frac{1}{c}\frac{\partial f}{\partial t}\delta(f) \\
&= \frac{1}{c}\frac{\partial\bar{p}}{\partial t} + p\frac{\partial f/\partial t}{c}\delta(f)
\end{aligned}
$$

Recalling the total time derivative of f, which is equal to zero by definition, we can write the time derivative of f in terms of normal velocity V_n:

$$
\begin{aligned}
\frac{df}{dt} &= \frac{\partial f}{\partial t}\cancelto{1}{\frac{dt}{dt}} + \frac{\partial f}{\partial x_i}\frac{\partial x_i}{\partial t} = 0 \\
&\frac{\partial f}{\partial t} + \hat{n}\cdot\overline{V} = 0 \\
&\boxed{\frac{\partial f}{\partial t} = -V_n} \quad ✓
\end{aligned}
$$

where V_n is the local normal velocity component along the data surface $f = 0$. Now, recalling that Mach number $M = \dfrac{V}{c}$, we can rewrite the previous expression of the first derivative WRT time in terms of Mach number:

$$
\frac{1}{c}\frac{\overline{\partial}\bar{p}}{\partial t} = \frac{1}{c}\frac{\partial\bar{p}}{\partial t} + p\frac{-V_n}{c}\delta(f) \quad ✓
$$

$$\frac{1}{c}\frac{\bar{\partial} \bar{p}}{\partial t} = \frac{1}{c}\frac{\partial \bar{p}}{\partial t} - M_n p\delta(f) \tag{8}$$

Applying the second partial derivative WRT time to Eqn 8, we can derive the first term of Eqn 1:

$$\frac{1}{c^2}\frac{\bar{\partial}^2 \bar{p}}{\partial t^2} = \frac{1}{c}\frac{\bar{\partial}}{\partial t}\left(\frac{1}{c}\frac{\bar{\partial} \bar{p}}{\partial t}\right) = \frac{1}{c}\frac{\bar{\partial}}{\partial t}\left(\frac{1}{c}\frac{\partial \bar{p}}{\partial t} - M_n p\delta(f)\right)$$

Distributing the differential to the first term and applying the same assumptions and substitutions that were used to derive Eqn 7:

$$\begin{aligned}
\frac{1}{c}\frac{\bar{\partial}}{\partial t}\left(\frac{1}{c}\frac{\partial \bar{p}}{\partial t}\right) &= \frac{1}{c}\frac{\bar{\partial}}{\partial f}\left(\frac{1}{c}\frac{\partial \bar{p}}{\partial t}\right)\frac{\partial f}{\partial t} \\
&= \frac{1}{c}\left[\frac{1}{c}\frac{\partial}{\partial f}\left(\frac{\partial \bar{p}}{\partial t}\right) + \frac{1}{c}\frac{\partial \Delta \bar{p}}{\partial t}\delta(f)\right]\frac{\partial f}{\partial t} \\
&= \frac{1}{c^2}\frac{\partial}{\partial t}\left(\frac{\partial \bar{p}}{\partial t}\right) + \frac{\partial p}{\partial t}\frac{1}{c}\frac{-V_n}{c}\delta(f)
\end{aligned}$$

which results in the final expression for the first term of the second general derivative of pressure WRT time:

$$\frac{1}{c}\frac{\bar{\partial}}{\partial t}\left(\frac{1}{c}\frac{\partial \bar{p}}{\partial t}\right) = \frac{1}{c^2}\frac{\partial^2 \bar{p}}{\partial t^2} - \frac{M_n}{c}\frac{\partial p}{\partial t}\delta(f) \tag{9}$$

Now, distributing the differential to the second term, we notice that all three parameters are continuous at the surface $f = 0$, thus making the generalised differentiation identical to standard differentiation $\left(\frac{\bar{\partial}}{\partial t} = \frac{\partial}{\partial t}\right)$

$$\frac{1}{c}\frac{\bar{\partial}}{\partial t}\left[-M_n p\delta(f)\right] = -\frac{1}{c}\frac{\partial}{\partial t}\left[M_n p\delta(f)\right] \tag{10}$$

Finally, applying the results for the first (Eqn 9) and second (Eqn 10) terms of the second derivative, we derive the final expression:

$$\frac{1}{c^2}\frac{\bar{\partial}^2 \bar{p}}{\partial t^2} = \frac{1}{c^2}\frac{\partial^2 \bar{p}}{\partial t^2} - \frac{M_n}{c}\frac{\partial p}{\partial t}\delta(f) - \frac{1}{c}\frac{\partial}{\partial t}\left[M_n p\delta(f)\right] \tag{11}$$

Next, we will solve for the second term on the LHS of Eqn 1; the generalized Laplacian of $\bar{p}$. Beginning with the results for a single gradient (Eqn 7) and applying the same assumptions and substitutions as used in that derivation:

$$\begin{aligned}
\bar{\nabla}^2 \bar{p} = \bar{\nabla}\bar{p}\left(\bar{\nabla}\bar{p}\right) &= \bar{\nabla}\left(\nabla \bar{p} + \hat{n}p\delta(f)\right) \\
&= \nabla^2 \bar{p} + \hat{n}\cdot\nabla p\delta(f) + \nabla\cdot\left[\hat{n}p\delta(f)\right]
\end{aligned}$$

Letting $p_n = \hat{n}\cdot\nabla p$ be the spatial partial derivative of surface pressure in the outward normal direction of $f = 0$, we can write the final form of the generalised Laplacian of pressure:

$$\bar{\nabla}^2 \bar{p} = \nabla^2 \bar{p} + p_n\delta(f) + \nabla\cdot\left[p\hat{n}\delta(f)\right] \tag{12}$$

Finally, we will apply generalized differentiation to Eqn 1, the homogeneous acoustic wave equation, and then substitute the results for Eqns 11 and 12 to derive the final form of Eqn 2:

$$\begin{aligned}
\frac{1}{c^2}\frac{\bar{\partial}^2 \bar{p}}{\partial t^2} - \bar{\nabla}^2 \bar{p} &= \frac{1}{c^2}\frac{\partial^2 \bar{p}}{\partial t^2} - \frac{M_n}{c}\frac{\partial p}{\partial t}\delta(f) - \frac{1}{c}\frac{\partial}{\partial t}\left[M_n p\delta(f)\right] - \nabla^2 \bar{p} - p_n\delta(f) - \nabla\cdot\left[p\hat{n}\delta(f)\right] \\
&= \underbrace{\frac{1}{c^2}\frac{\partial^2 \bar{p}}{\partial t^2} - \nabla^2 \bar{p}}_{=0} - \frac{M_n}{c}\frac{\partial p}{\partial t}\delta(f) - p_n\delta(f) - \frac{1}{c}\frac{\partial}{\partial t}\left[M_n p\delta(f)\right] - \nabla\cdot\left[p\hat{n}\delta(f)\right]
\end{aligned}$$

The terms grouped in the bracket are exactly equal to the Right Hand Side (RHS) of Eqn 1 and are thus exactly equal to zero since this equation is homogeneous. Grouping like terms in the resulting equation, we derive the final expression for the sound field generated by a moving surface $f = 0$, which is equivalent to Kirchoff's formula for moving surfaces:

$$\boxed{\frac{1}{c^2}\frac{\bar{\partial}^2 p}{\partial t^2} - \bar{\nabla}^2 p = -\left[\frac{M_n}{c}\frac{\partial p}{\partial t} + p_n\right]\delta(f) - \frac{1}{c}\frac{\partial}{\partial t}\left[M_n p \delta(f)\right] - \nabla \cdot \left[p \hat{n} \delta(f)\right]} \tag{13}$$

II. Problem 2 – Farassat Formulation 1A for Loading Noise

In Section I, we derived Eqn 2 for the sound field produced by an arbitrary moving body. To solve equations of this form, we must apply Green's function. This was achieved for the FW-H equation by Farassat, first in his "Formulation 1", which transformed the spatial derivatives into terms of observer time t and then into "Formulation 1A", which further transformed t into terms of retarded time τ.

Separating the FW-H equation into separate source terms of thickness, loading, and quadrupole volume, we can look specifically at Farassats Formulation 1 for the loading noise, which is given as:

$$\boxed{4\pi p_L' = \frac{1}{c}\frac{\partial}{\partial t}\int_{f=0}\left[\frac{L_r}{r(1-M_r)}\right]_{ret} ds + \int_{f=0}\left[\frac{L_r}{r^2(1-M_r)}\right]_{ret} ds} \tag{14}$$

where $L_r = \Delta P \hat{n} \cdot \hat{r} = \Delta P \cos\theta$ is the loading in the radial direction and ret denotes that the expression is evaluated at the retarded time $\tau = \tau_e$.

In practice, Formulation 1 is difficult to compute since the observer time differentiation is outside the integrals. Farassat's Formulation 1A presents a much more efficient and practical approach, which can be derived by carrying the observer time derivate inside the integrals. In the following section, we will show that Formulation 1A for the loading noise becomes:

$$\begin{aligned} 4\pi p_L' = \frac{1}{c}\int_{f=0}\left[\frac{\dot{L}_r}{r(1-M_r)^2}\right]_{ret} ds + \int_{f=0}\left[\frac{L_r - L_M}{r^2(1-M_r)}\right]_{ret} ds \\ + \frac{1}{c}\int_{f=0}\left[\frac{L_r[r\dot{M}_r + c(M_r - M^2)]}{r^2(1-M_r)^3}\right]_{ret} ds \end{aligned} \tag{15}$$

where $L_M = \vec{L} \cdot \vec{M}$.

II.A. Formulation 1A Transformation

To obtain Farassat's formulations, it is required to transform the time derivative into a derivative WRT to τ. This transformation will be performed using Eqn 16 below:

$$\left.\frac{\partial}{\partial t}\right|_x = \left[\frac{1}{1-M_r}\frac{\partial}{\partial \tau}\right]_{ret} \tag{16}$$

where $\frac{\partial}{\partial t}$ is evaluated along some surface x.

II.B. Loading Noise Formulation 1A

Now that we have defined the transformation between Formulation 1 and Formulation 1A, we can apply Eqn 16 to Eqn 14 to derive Formulation 1A of the loading noise. Specifically, we will perform the transformation on the first term of the RHS of Eqn 14, which contains a time derivative:

$$\frac{\partial}{\partial t}\int_{f=0}\left[\frac{L_r}{r(1-M_r)}\right]_{ret} ds = \int_{f=0}\left[\frac{1}{1-M_r}\frac{\partial}{\partial \tau}\left(\frac{L_r}{r(1-M_r)}\right)\right]_{ret} ds \tag{17}$$

Focusing on the term contained in the τ differential, we see that both the numerator and denominator contain functions of τ, so the product rule of differentiation will be required to complete this derivation. Before that, however, let us compute the derivatives of the individual components to simplify the final derivation.

The time derivative of the numerator is straightforward, as shown below:

$$\frac{\partial}{\partial\tau}(L_r) = \frac{\partial L_r}{\partial\tau} = \dot{L}_r \qquad \frac{\partial}{\partial\tau}(L_r) = \frac{\partial L}{\partial\tau}\hat{r} + L\frac{\partial\hat{r}}{\partial\tau} = \dot{L}_r + L\frac{\partial\hat{r}}{\partial\tau} \tag{18}$$

where the dot over L_r denotes the time derivative, or the rate of change of the pressure loading with respect time time. missing

Next, we compute the time derivative of $\frac{1}{r}$ using the chain rule:

$$\frac{\partial}{\partial\tau}\left(\frac{1}{r}\right) = \frac{\partial}{\partial r}\left(\frac{1}{r}\right)\frac{\partial r}{\partial\tau} = -\frac{1}{r^2}(-V_r) = \frac{V_r}{r^2} \tag{19}$$

where $\frac{\partial r}{\partial\tau}$ is:

$$\frac{\partial r}{\partial\tau} = \frac{\partial r}{\partial y_i}\frac{\partial y_i}{\partial\tau} = (-\hat{r})(\vec{V}) = -V_r \tag{20}$$

where V_r is the velocity component in the radial direction.

We will next compute the time derivative of $\frac{1}{1-M_r}$, but will first calculate two derivatives on which it depends. First, we calculate the derivative of the radial unit vector $\hat{r}$, substituting the results and assumptions of Eqn 19:

$$\begin{aligned}
\frac{\partial}{\partial\tau}(\hat{r}) &= \frac{\partial}{\partial\tau}\left(\frac{\vec{r}}{r}\right) = \frac{1}{r}\frac{\partial\vec{r}}{\partial\tau} + \vec{r}\frac{\partial\vec{r}}{\partial\tau}\left(\frac{1}{r}\right) \\
&= \frac{-\vec{V}}{r} + \vec{r}\cdot\frac{V_r}{r^2} = \frac{-\vec{V}}{r} + \frac{1}{r}\frac{\vec{r}}{r}\cdot V_r \\
&= -\frac{\vec{V}}{r} + \frac{1}{r}\hat{r}\cdot V_r
\end{aligned}$$

where $r = |\vec{r}|$ is the magnitude of the radial vector. Finally, multiplying the equation by c/c allows expression in terms of Mach number:

$$\frac{\partial}{\partial\tau}(\hat{r}) = -\frac{c}{r}\left(\vec{M} - \vec{r}\cdot M_r\right) \tag{21}$$

Secondly, the derivative of Mach number in the radial direction can be expressed as:

$$\begin{aligned}
\frac{\partial}{\partial\tau}(M_r) &= \frac{\partial}{\partial\tau}\left(\vec{M}\cdot\hat{r}\right) = \frac{\partial\vec{M}}{\partial\tau}\cdot\hat{r} + \vec{M}\frac{\partial\hat{r}}{\partial\tau} \\
&= \dot{\vec{M}}\cdot\hat{r} + \vec{M}\frac{c}{r}\left(-\vec{M} + \vec{r}\cdot M_r\right) \\
&= \dot{\vec{M}}\cdot\hat{r} + \frac{c}{r}\left(-\vec{M}\cdot\vec{M} + \vec{r}\cdot\vec{M}\cdot M_r\right)
\end{aligned}$$

where Eqn 21 was substituted in for the time derivative of $\hat{r}$. Letting $\dot{\vec{M}} = \frac{\partial\vec{M}}{\partial\tau}$ denote the time derivative of Mach number or the acceleration in terms of Mach, we obtain the final expression for the derivative of radial Mach number:

$$\frac{\partial}{\partial\tau}(M_r) = \dot{M}_r + \frac{c}{r}\left(-|\vec{M}|^2 + M_r^2\right) \tag{22}$$

Now, we now have all of the derivative components required to calculate the time derivative of $\frac{1}{1-M_r}$:

$$
\begin{aligned}
\frac{\partial}{\partial\tau}\left(\frac{1}{1-M_r}\right) &= -\frac{1}{(1-M_r)^2}\frac{\partial}{\partial\tau}(-M_r)\\
&= -\frac{1}{(1-M_r)^2}(-1)\left[\dot{\vec{M}}_r + \frac{c}{r}\left(-|\vec{M}|^2 + M_r^2\right)\right]\\
&= \frac{\dot{\vec{M}}_r + \frac{c}{r}\left(-|\vec{M}|^2 + M_r^2\right)}{(1-M_r)^2}
\end{aligned}
$$

Multiplying by r/r:

$$
\frac{\partial}{\partial\tau}\left(\frac{1}{1-M_r}\right) = \frac{r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)}{r(1-M_r)^2} \tag{23}
$$

At long last, we have finally computed all of the necessary terms to complete the transformation of the first term in Eqn 14. The time derivative must be performed using the product rule, as follows:

$$
\begin{aligned}
\frac{\partial}{\partial\tau}\left(\frac{L_r}{r(1-M_r)}\right) &= \frac{\partial}{\partial\tau}\left\{L_r\frac{1}{r(1-M_r)}\right\}\\
&= \frac{\partial L_r}{\partial\tau}\frac{1}{r(1-M_r)} + L_r\boxed{\frac{\partial}{\partial\tau}\left[\frac{1}{r(1-M_r)}\right]} \rightarrow \frac{r\dot{M}_r + c(M_r - M^2)}{r^2(1-M_r)^2}\\
&= \frac{\dot{L}_r}{r(1-M_r)} + L_r\left[\frac{\partial}{\partial\tau}\left(\frac{1}{r}\right)\frac{1}{1-M_r} + \frac{1}{r}\frac{\partial}{\partial\tau}\left(\frac{1}{1-M_r}\right)\right]\\
&= \frac{\dot{L}_r}{r(1-M_r)} + L_r\left[\frac{1}{1-M_r}\frac{-V_r}{r^2} + \frac{1}{r}\frac{r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)}{r(1-M_r)^2}\right]\\
&= \frac{\dot{L}_r}{r(1-M_r)} + L_r\left[\frac{-V_r}{r^2(1-M_r)} + \frac{r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)}{r^2(1-M_r)^2}\right]\\
&= \frac{\dot{L}_r}{r(1-M_r)} + \frac{-L_rV_r}{r^2(1-M_r)} + \frac{L_r\left[r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)\right]}{r^2(1-M_r)^2}\\
&= \frac{\dot{L}_r}{r(1-M_r)} + \frac{-(\vec{L}\cdot\hat{r})(\vec{V}\cdot\hat{r})}{r^2(1-M_r)} + \frac{L_r\left[r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)\right]}{r^2(1-M_r)^2}\\
&= \frac{\dot{L}_r}{r(1-M_r)} + \frac{-(\vec{L}\cdot\vec{V})(\hat{r}\cdot\hat{r})}{r^2(1-M_r)} + \frac{L_r\left[r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)\right]}{r^2(1-M_r)^2}
\end{aligned}
$$

Recalling that any unit vector $\hat{r}$ that is multiplied by itself must equal unity due to the property:

$$
\hat{r}\cdot\hat{r} = \frac{\vec{r}}{|\vec{r}|}\cdot\frac{\vec{r}}{|\vec{r}|} = \frac{\vec{r}\cdot\vec{r}}{|\vec{r}|\cdot|\vec{r}|} = \frac{|\vec{r}|^2}{|\vec{r}|^2} = 1 \tag{24}
$$

we can write our derivative term as such:

$$
\frac{\partial}{\partial\tau}\left(\frac{L_r}{r(1-M_r)}\right) = \frac{\dot{L}_r}{r(1-M_r)} + \frac{-\vec{L}\cdot\vec{V}}{r^2(1-M_r)} + \frac{L_r\left[r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)\right]}{r^2(1-M_r)^2} \tag{25}
$$

Now that we have computed the derivative WRT τ, we can substitute Eqn 25 into Eqn 17:

$$\frac{\partial}{\partial t}\int_{f=0}\left[\frac{L_r}{r(1-M_r)}\right]_{ret}ds = \int_{f=0}\left\{\frac{1}{1-M_r}\left[\frac{\dot{L}_r}{r(1-M_r)} + \frac{-\vec{L}\cdot\vec{V}}{r^2(1-M_r)} + \frac{L_r\left[r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)\right]}{r^2(1-M_r)^2}\right]\right\}_{ret} ds$$
$$= \int_{f=0}\left[\frac{\dot{L}_r}{r(1-M_r)^2} + \frac{-\vec{L}\cdot\vec{V}}{r^2(1-M_r)^2} + \frac{L_r\left[r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)\right]}{r^2(1-M_r)^3}\right]_{ret} ds$$

resulting in the Formulation 1A version of the derivative integral term:

$$\frac{\partial}{\partial t}\int_{f=0}\left[\frac{L_r}{r(1-M_r)}\right]_{ret}ds = \int_{f=0}\left[\frac{\dot{L}_r}{r(1-M_r)^2} + \frac{-\vec{L}\cdot\vec{V}}{r^2(1-M_r)^2} + \frac{L_r\left[r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)\right]}{r^2(1-M_r)^3}\right]_{ret} ds \quad (26)$$

The final step in deriving Formulation 1A is to substitute Eqn 26 into Eqn 14 (Loading Noise Formulation 1):

$$4\pi p'_L = \frac{1}{c}\frac{\partial}{\partial t}\int_{f=0}\left[\frac{L_r}{r(1-M_r)}\right]_{ret}ds + \int_{f=0}\left[\frac{L_r}{r^2(1-M_r)}\right]_{ret}ds$$
$$= \frac{1}{c}\int_{f=0}\left[\frac{\dot{L}_r}{r(1-M_r)^2} + \frac{-\vec{L}\cdot\vec{V}}{r^2(1-M_r)^2} + \frac{L_r\left[r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)\right]}{r^2(1-M_r)^3}\right]_{ret} ds + \int_{f=0}\left[\frac{L_r}{r^2(1-M_r)}\right]_{ret}ds$$

Distributing the integral across summed terms:

$$= \frac{1}{c}\int_{f=0}\left[\frac{\dot{L}_r}{r(1-M_r)^2}\right]_{ret}ds + \int_{f=0}\left[\frac{L_r}{r^2(1-M_r)}\right]_{ret}ds + \frac{1}{c}\int_{f=0}\left[\frac{-\vec{L}\cdot\vec{V}}{r^2(1-M_r)^2}\right]_{ret}ds$$
$$+ \frac{1}{c}\int_{f=0}\left[\frac{L_r\left[r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)\right]}{r^2(1-M_r)^3}\right]_{ret}ds$$

Distributing the speed of sound term and combining like integrals:

$$= \frac{1}{c}\int_{f=0}\left[\frac{\dot{L}_r}{r(1-M_r)^2}\right]_{ret}ds + \int_{f=0}\left[\frac{L_r}{r^2(1-M_r)} - \frac{\frac{1}{c}(\vec{L}\cdot\vec{V})}{r^2(1-M_r)^2}\right]_{ret}ds + \frac{1}{c}\int_{f=0}\left[\frac{L_r\left[r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)\right]}{r^2(1-M_r)^3}\right]_{ret}ds$$
$$= \frac{1}{c}\int_{f=0}\left[\frac{\dot{L}_r}{r(1-M_r)^2}\right]_{ret}ds + \int_{f=0}\left[+\frac{L_r - \vec{L}\cdot\vec{M}}{r^2(1-M_r)^2}\right]_{ret}ds + \frac{1}{c}\int_{f=0}\left[\frac{L_r\left[r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)\right]}{r^2(1-M_r)^3}\right]_{ret}ds$$

Substituting the definition $L_M = \vec{L}\cdot\vec{M}$, we derive the final expression for Formulation 1A of Loading Noise:

$$4\pi p'_L = \frac{1}{c}\int_{f=0}\left[\frac{\dot{L}_r}{r(1-M_r)^2}\right]_{ret}ds + \int_{f=0}\left[\frac{L_r - L_M}{r^2(1-M_r)^2}\right]_{ret}ds$$
$$+ \frac{1}{c}\int_{f=0}\left[\frac{L_r\left[r\dot{\vec{M}}_r + c\left(M_r^2 - |\vec{M}|^2\right)\right]}{r^2(1-M_r)^3}\right]_{ret}ds \quad (27)$$

Conclusion

We have now completed the derivation of an aeroacoustic equation describing the pressure fluctuations around a moving body and then demonstrated a method of solving equations such as these. In a real life application, the equation being solved would be more complicated and include more source terms, like the complete FW-H equation does. This equation can be solved by applying Farassat's Formulation 1A and implementing the solution numerically. Source inputs for loading noise (ΔP) would be obtained from an unsteady CFD simulation and used to inform the aeroacoustic solution.