BRIGHTNESS AND VOLUME

CONTROLLER USING HAND GESTURE RECOGNITION

A PROJECT REPORT

Submitted by

N.Suryateja(RA2011003011021)

N.Sainathreddy(RA2011003011026)

K.Abhinav reddy(RA2011003011013)

Under the Guidance of

MR. KAVISANKAR.L

In partial fulfilment for the Course

of

18CSC305J – Artificial Intelligence

in

Computer Science & Engineering



FACULTY OF ENGINEERING AND TECHNOLOGY

SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

Kattankulathur, Chengalpattu District

April 2023

SRM INSTITUTE OF SCIENCE AND TECHNOLOGYKATTANKULATHUR -

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SIGNATURE

MR.KAVISANKAR.L

GUIDE

Assistant Professor

Department of Computing Technologies

SIGNATURE

Dr. M. Pushpalatha

HEAD OF THE DEPARTMENT

Professor & Head

Department of Computing Technologies

SRM Institute of Science and Technology

Own Work Declaration Form

Degree/ Course: B.Tech in Computer Science and Engineering

Student Names : SURYATEJA, SAINATH, ABHINAV

Registration Number: RA2011003011021,RA2011003011026,RA2011003011013

Title of Work : BRIGHTNESS AND VOLUME CONTROLLER USING

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ACKNOWLEDGEMENT

We express our humble gratitude to **Dr. C.Muthamizhchelvan**, Vice-Chancellor, SRM Institute of Science and Technology, for the facilities extended for the project work and his continued support.

We extend our sincere thanks to Dean-CET, SRM Institute of Science and Technology, **DR. T.V.Gopal**, for his invaluable support.

We wish to thank **DR. Revathi Venkataraman**, Professor & Chairperson, School of Computing, SRM Institute of Science and Technology, for her support throughout the project work.

We register our immeasurable thanks to our Faculty Advisor, MR.KAVISANKAR.L Assistant Professor, Department of Computer Science, SRM Institute of Science and Technology, for leading and helping us to complete our course.

Our inexpressible respect and thanks to our guide, MR.KAVISANKAR.L Assistant Professor, Department of Artificial Intelligence, SRM Institute of Science and Technology, for providing us with an opportunity to pursue our project under his mentorship. He provided us with the freedom and support to explore the research topics of our interest. His passion for solving problems and making a difference inthe world has always been inspiring.

We sincerely thank the Artificial Intelligent Department staff and students, SRM Institute of Science and Technology, for their help during our project. Finally, we would like to thank parents, family members, and friends for their unconditional love, constant support, and encouragement.

N.SURYATEJA(RA2011003011021) K.ABHINAVREEDY(RA2011003011013) N.SAINATHREEDY(RA2011003011026)

ABSTRACT

Hand Gesture Detection is receiving a lot of attention these days because it has a lot of applications and the ability to connect with machines efficiently via human interaction. We are attempting to gain knowledge of hand gesture detecting systems in this project. In this project, we're attempting to figure out how image processing works and how we can utilize it to create a hand motion recognition system that allow us to operate the computer without touching it. Many studies have been conducted and are continuously being conducted. Many big companies are currently working on this technology so that they can make their products even more useful that they are now because this technology has very high scope in the upcoming future. The people that are not mentally stable or weak from mind can also benefit by technology and can operate the computer. This technology can be used to make computers even more user-friendly.

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INTRODUCTION

1.1 Introduction

The majority of the time, hands are employed for daily physical activities involving manipulation, although communication is occasionally also done with them. We use hand gestures to help us communicate accurately throughout the day. Hand gestures are essential for sign language communication since mute and deaf persons rely on their hands and gestures to communicate.

In order to communicate with and engage with machines, people most usually use their hands. The two primary input/output devices for computers the mouse and keyboard both need the use of hands to operate. The most crucial and immediate method of communication between a computer and a human is through visual and audible aids, yet this interaction is one-sided.

Gesture recognition helps computers to understand human body language. Instead of using only the simple text user interfaces or graphical user interfaces, this aids in creating a stronger connection between humans and technology (GUIs). In this gesture recognition project, a computer camera interprets the movements of the human body. This information is subsequently used as input by the computer to handle applications.

1.2 Objectives

It would be a major advance in the field of human computer interaction if computers could translate and comprehend hand gestures. The problem is that today's photos are information-rich, and in order to complete this work, substantial processing is needed. Each gesture is distinguished from others by a few unique characteristics.

The aim of this work is to create an interface that dynamically captures human hand gestures and controls volume and brightness level.

Basic Principle

This project makes advantage of our device's camera. It recognizes our hand as having points on it so that it can measure the space between the tips of our thumb and index fingers. The volume of the gadget is exactly proportional to the distance between points 4 (thumb tip) and 8 (index finger tip).

1.3 Literature Survey

Reference	Methodology	Outcome/Results	Remarks
Author name	Algorithms/concepts		
	used		
Devendra	Here the concept of	Hand gestures	1. Can't be used for
Kumar	hand gesture	detection system is	long distance
Sharma;	detection using the	being used for different	2. Sometimes not
Mala	methods for	applications in different	accurate
Saraswat	extracting data and	fields. Some hand	3. Requires a decent
	extraction of	gesture detection	camera
	characteristics. The	application fields are	4. May be confused by
	system is classified	mentioned below.	two palms
	in three steps	1.Recognition of Sign	
	Extraction Method,	Language	
	features extraction	2. Controlling Features	
	and classification.	of computer	
		3.Virtual	
		Environments	
Munir Oudah	Here the Algorithm	The outcome is to	The main remark will
Ali Al-Naji	depends on	recognition and is to	be if any person of
and Javaan	extracting the image	introduce a system that	physically
Chahl	features in order to	can detect specific	handicapped hand who
	model visual	human gestures and use	don't have proper no
	appearance such as	them to convey	

	hand and comparing	information or for	of fingers, then it will
	these parameters	command-and-control	be difficult to detect.
	with feature	purposes. Therefore, it	be difficult to detect.
	extracted from the	includes tracking of	
		human movement and	
	input image frames.		
	Where the features	also the interpretation	
	are directly	of that	
	calculated by the	movement as	
	pixel intensities	significant commands	
	without a previous		
	segmentation		
	process.		
	In this they	So, it can identify the	Hand Gesture
Viraj Shinde;	mentioned about	hand and we can	Recognition Using
Tushar	mediapipe library to	control the volume and	Camera is based on
Bacchav;	detect hand	brightness with	concept of Image
Jitendra	landmark positions	different hands at a	processing. In recent
Pawar;	and handedness. If	time, like left hand to	year there is lot of
Mangesh	the frame detects	control brightness and	research on gesture
Sanap	one hand, it finds	right hand to control	recognition using
	out if it's a left hand	volume. It detects hand	sensor on using HD
	or right hand and	and control respective	camera but camera and
	triggers the	feature it is assigned to	sensors are more
	brightness control	it.	costly.
	and volume control		
	function		
	respectively.		

Salman	This article shows	The outputs are:	The biggest remark of
Shaikh,	how gesture	1: Image preprocessing	the system is the
Raghav	recognition is pre-	2: Tracking of fingers	background should be
Gupta,	processed. Color	3.Recognisation of	white if there is any
Imran Shaikh	space detection,	gestures	other background than
, Jay Borade	colour space		white the system will
	conversion [RGB]		fails to recognize the
	& differentiation,		Hand.
	Skin colour		
	detection using open		
	cv, and lastly line		
	segment detection		
	for finger detection		
	are used to pre-		
	process the acquired		
	picture.		
Soeb	In this paper, we	This technique	It can identify only a
Hussain;	propose a technique	identifies the hand	few gestures and
Rupal	which commands	gesture and converts	commands.
Saxena; Xie	computer using six	data into required	
Han; Jameel	static and eight	command.	
Ahmed	dynamic hand		
Khan;	gestures. The three		
	main steps are: hand		
	shape recognition,		
	tracing of detected		
	hand (if dynamic),		
	and converting the		
	data into the		
	required command.		

1.4 Existing system

The interaction between social life and information technology has grown increasingly intimate in recent years as a result of advancements in computer hardware and software technologies. Future consumer electronics devices' interfaces, particularly those for smart phones, video games, and infotainment systems, will have an increasing number of features and be more complicated. It has become crucial to figure out how to create an easy-to-use human-machine interface (HMI) for every consumer electronics product. The most popular form of interaction is still via a mouse, keyboard, or joystick, which are all classic examples of electronic input devices. It does not imply, however, that these gadgets are the most practical and natural input methods for the majority of users.

Gestures have been an important form of human contact and communication since ancient times. Before the development of language, people could simply convey their ideas through gestures. Many individuals still use gestures in everyday life, and deaf people in particular find gestures to be the most natural and important form of communication. Many human-based electronics items, including computers, TVs, and games, have adopted the gesture control technology in recent years. With the aid of the current system, this method enables users to operate the items in a more natural and intuitive manner.

1.5 Proposed system

The majority of gesture recognition systems include three primary steps. The detection of objects is the initial stage. This stage's goal is to identify hand items in digital images or videos. At this step, several environment and picturechallenges must be resolved in order to ensure that hand contours or areas can be extracted correctly in order to improve recognition accuracy. Unstable brightness, noise, low resolution, and contrast are all common picture issues. These issues can be successfully improved by a better atmosphere and camera technologies. However, it is hard to control when the gesture recognition system is working in the real environment or is become a product. Object recognition is the second stage. To identify the movements, the detected hand objects are identified. Differentiated characteristics and successful classifier selection are important issues in most studies at this point. The third stage is analyzing successive motions in order to determine what users are instructing or doing.

SYSTEM REQUIREMENTS

2.1 Hardware requirements

- ➤ Hard Disk minimum of 40 GB.
- > RAM minimum of 2 GB.
- > Dual Core and up ,15" Monitor.
- ➤ Integrated webcam or external webcam (15 -20 fps).

2.2 Software requirements

- ➤ Operating system- Microsoft Windows 7 or above
- > Pycharm or Microsoft Visual Studio 2010
- Supporting Webcam Drivers
- Packages: OpenCV, Numpy, comtyes, pycaw, screen-brightness-control, mediapipe.
- ➤ **Python:** Python is a general-purpose, interpreted programming language. published for the first time in 1991 and created by Guido van Rossum. It supports a variety of programming paradigms, including procedural, object-oriented, and functional programming as well as structured programming (especially).
- ➤ **Numpy:** A general-purpose array processing software is called Numpy. It offers a multidimensional array object with outstanding speed as well as capabilities for interacting with these arrays.

Mediapipe: MediaPipe is a module for processing video, audio and several types of related data across platform like Android, iOS, web, edge device and several pplied ML pipeline. Several types of functions are performed with the help of this module, we have used this module in our project to recognize the hand gesture and detect the input from it.

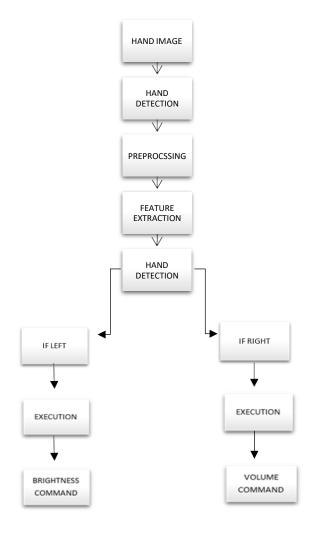
- 1. Face Detection
- 2. Multi-hand Tracking
- 3. Object Detection and Tracking

SYSTEM DESIGN

3.1 System architecture

CAPTURE	OBJECT	HAND	FEATURE	GESTURE
	DETECTION	DETECTION	EXTRACTION	CONTROL

3.2 Algorithms/ Flow charts



IMPLEMENTATION

4.1 Pseudocode

To Detect the hand:

```
class handDetector:
  def init (self, mode=False, maxHands=2, detectionCon=0.7, trackCon=0.5):
    self.results = None
    self.mode = mode
    self.maxHands = maxHands
    self.detectionCon = detectionCon
    self.trackCon = trackCon
    self.mpHands = mp.solutions.hands
    self.hands = self.mpHands.Hands(self.mode, self.maxHands,
                       self.detectionCon, self.trackCon)
    self.mpDraw = mp.solutions.drawing_utils
  def findHands(self, img, draw=True):
    imgRGB = cv.cvtColor(img, cv.COLOR_BGR2RGB)
    self.results = self.hands.process(imgRGB)
    if self.results.multi_hand_landmarks:
       for handLms in self.results.multi_hand_landmarks:
         if draw:
           self.mpDraw.draw_landmarks(img, handLms,
                           self.mpHands.HAND_CONNECTIONS)
    return img
To Detect the hand positions:
  def findPosition(self, img, draw=True):
    rlmlist = []
    if self.results.multi_hand_landmarks:
       if len(self.results.multi_hand_landmarks) == 2:
```

```
rlmlist.append('both')
elif len(self.results.multi_hand_landmarks) == 1:
    rlmlist.append(self.results.multi_handedness[0].classification[0].label)
for n in self.results.multi_hand_landmarks:
    lmList = []
    myHand = n
    for id1, lm in enumerate(myHand.landmark):
        h, w, c = img.shape
        cx, cy = int(lm.x * w), int(lm.y * h)
        lmList.append([id1, cx, cy])
        if draw:
            cv.circle(img, (cx, cy), 15, (255, 0, 255), cv.FILLED)
        rlmlist.append(lmList)
return rlmlist
```

To control the volume and brightness using hand gesture

- > Right hand- Volume
- > Left hand- Brightness

```
0.WRIST
                        11. MIDDLE FINGER_DIP
1. THUMB_CMC
                        12. MIDDLE FINGER_TIP
2. THUMB_MCP
3. THUMB_IP
                        13. RING FINGER_MCP
4. THUMB_TIP
                        14. RING FINGER_PIP
                        15. RING FINGER DIP
5. INDEX FINGER_MCP
                        16. RING FINGER_TIP
6. INDEX FINGER_PIP
7. INDEX FINGER DIP
                        17. PINKY MCP
                        18. PINKY PIP
8. INDEX FINGER_TIP
                        19. PINKY_DIP
9. MIDDLE FINGER MCP
10. MIDDLE FINGER PIP
                        20. PINKY TIP
```

Figure 4.1.0 Hand Landmarks

The figure 4.1.0 displays the MediaPipe point numbers, which are used to identify various hand points. After detecting the palm over the whole picture, our subsequent hand landmark model uses regression, or direct coordinate prediction, to accomplish exact key point localization of 21 (figure 4.1.0) 3D hand-knuckle coordinates inside the identified hand areas.

So, we are using the 4-thumb tip and 8-index finger tip to increase and decrease the volume and brightness.

Function for volume control:

```
def setVolume(dist,frame):
    cv.circle(frame,(xr1,yr1),15,(255,0,255),cv.FILLED)
    cv.circle(frame, (xr2, yr2), 15, (255, 0, 255), cv.FILLED)
    cv.line(frame,(xr1,yr1),(xr2,yr2),(255,0,255),3)
    vol = np.interp(int(dist), [35, 215], [minVolume, maxVolume])
    volbar=np.interp(dist,[50,250],[400,150])
    volper=np.interp(dist,[50,250],[0,100])
    cv.rectangle(frame, (50, 150), (85, 400), (0, 255, 0), 3)
    cv.rectangle(frame, (50, int(volbar)), (85, 400), (0, 255, 0), cv.FILLED)
cv.putText(frame,f'{int(volper)}%',(40,450),cv.FONT_HERSHEY_COMPLEX,1,(0,250, 0),3)
    cv.putText(frame, f'RIGHT-VOLUME', (40, 50), cv.FONT_HERSHEY_COMPLEX, 1, (255, 0, 0), 3)
    volume.SetMasterVolumeLevel(vol, None)
```

Function for brightness control:

```
def setBrightness(dist,frame):
    cv.circle(frame, (xr1, yr1), 15, (255, 0, 255), cv.FILLED)
    cv.circle(frame, (xr2, yr2), 15, (255, 0, 255), cv.FILLED)
    cv.line(frame, (xr1, yr1), (xr2, yr2), (255, 0, 255), 3)
    brightness = np.interp(int(dist), [35, 230], [minBrightness, maxBrightness])
    volbar = np.interp(dist, [50, 250], [400, 150])
    briper = np.interp(dist, [50, 250], [0, 100])
```

```
cv.rectangle(frame, (50, 150), (85, 400), (0, 255, 0), 3)
  cv.rectangle(frame, (50, int(volbar)), (85, 400), (0, 255, 0), cv.FILLED)
  cv.putText(frame, f'{int(briper)}%', (40, 450), cv.FONT_HERSHEY_COMPLEX, 1,
  (0, 250, 0), 3)
  cv.putText(frame, f'LEFT-BRIGHTNESS', (40, 50),
  cv.FONT_HERSHEY_COMPLEX, 1, (255, 0, 0), 3)
  sbc.set_brightness(int(brightness))

To capture the video:
  while True:
  success,frame = cap.read()
  frame = cv.flip(frame, 1)
  frame = handlmsObj.findHands(frame,draw=True)
```

To get the landmarks of the Thumb tip and Index finger tip:

```
if lndmrks:
```

```
# print(lndmrks[4],lndmrks[8])
xr1, yr1 = lndmrks[1][4][1], lndmrks[1][4][2]
xr2, yr2 = lndmrks[1][8][1], lndmrks[1][8][2]
```

lndmrks = handlmsObj.findPosition(frame, draw=False)

To calculate the distance between Thumb tip and Index finger tip:

```
dist = math.hypot(xr2 - xr1, yr2 - yr1)
```

If the hand is left then brightness function will be called or If the hand is right hand then the volume function will be called:

```
if Indmrks[0] == 'Left':
    setBrightness(dist,frame)
elif Indmrks[0] == 'Right':
    setVolume(dist,frame)
    cv.imshow("stream", frame)
if cv.waitKey(1) & 0xFF ==
    ord('q'):break
    cv.destroyAllWindows()
```

4.2 Results

The distance between Right hand thumb tip and index finger tip is at maximum

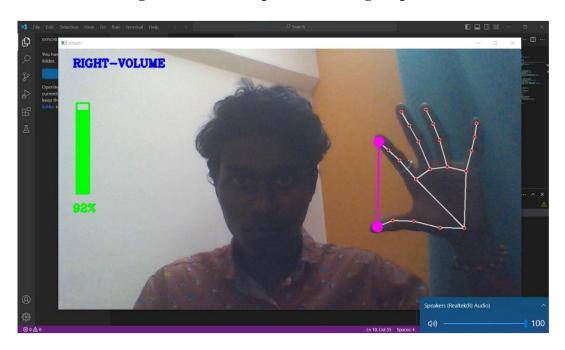


Figure 4.2.0 - Right hand - Volume is at maximum (100%)

The distance between Right hand thumb tip and index finger tip is at minimum

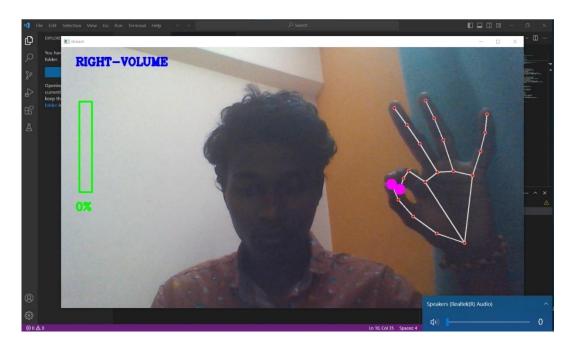


Figure 4.2.1 – Right hand - Volume at minimum (0%)

The distance between Right hand thumb tip and index finger tip is at 75%

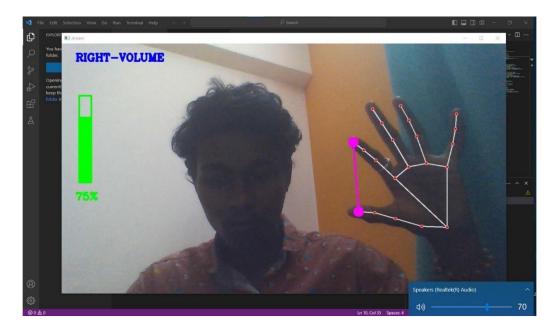


Figure 4.2.2 – Right hand -Volume at 75%

The distance between Left hand thumb tip and index finger tip is at maximum

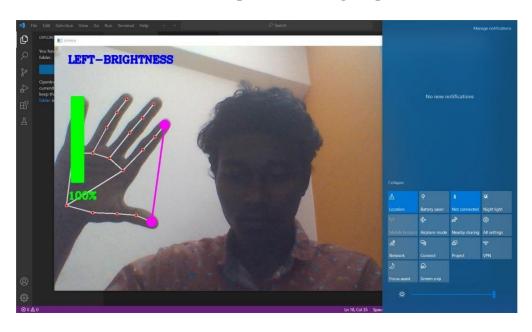


Figure 4.2.3 – Left hand – Brightness at maximum (100%)

The distance between Left hand thumb tip and index finger tip is at minimum

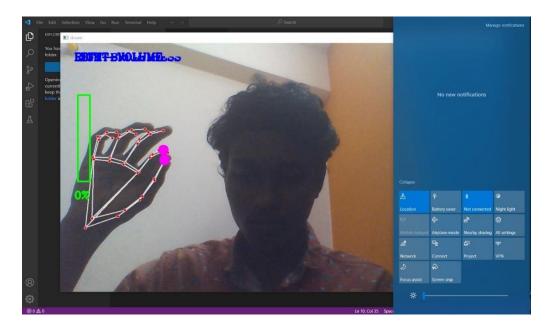


Figure 4.2.4 – Left hand - Brightness at minimum (0%)

The distance between Left hand thumb tip and index finger tip is at 37%.

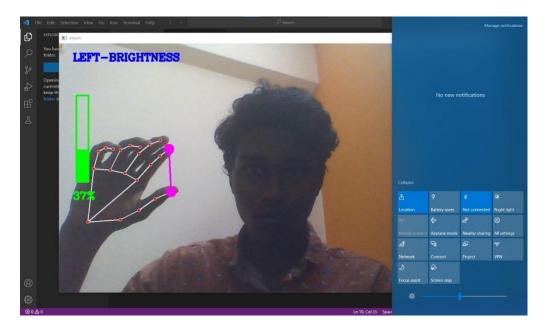


Figure 4.2.5 – Left hand - Brightness at 37%

CONCLUSION AND FUTURE ENHANCEMENT

5.1 Conclusion

In this project we have planned, designed and implemented the system for Hand gesture recognition system for controlling Volume and brightness using OpenCV and Mediapipe. we coded the program for recognizing the hand gestures and accordingly mapping the identified gestures to specific system operations.

This project showcases a program that enables hand gestures as a practical and simple method of software control. A gesture-based volume and Brightness controller doesn't need any special markers, and it can be used in real life on basic PCs with inexpensive cameras because it doesn't need particularly high-definition cameras to recognize or record the hand movements. The method keeps track of the locations of each hand's index finger and counter tips. This kind of system's primary goal is to essentially automate system components so that they are easy to control. Therefore, using this technique, we have made the concept realistic.

5.2 Future Enhancement

This technique for recognizing hand gestures effectively solves the issue of processing and extracting video frames.

Different hand gestures can be identified and used as computer input in the future. The hand movements used to represent numbers can also be translated in to orders that will carry out relevant action immediately.

Future research can focus on improving the ability to recognize different lighting circumstances and recognize both hands also recognize improper hands for handicap which is a encountered in this project.

In future we would like to improve the accuracy further and add more gestures to implement more functions.

The hand gesture recognition system can be used further to control the operation of other system applications like Explorer, Media Player etc.

To create a website which operates using hand gestures. JavaScript can be dynamically combined with the gesture recognition logic for the same.

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