

Second-half material

- Revisit linear algebra with a deeper view
- More conceptual, more challenging!
- May be necessary to commit more effort on review of lectures & notes

Definition: A vector space is the collection of vectors with the same dimension that follows a set of rules

The vector space of vectors of real numbers is \mathbb{R}^n , with n as the dimension of the vectors

Examples:

• $\underline{u} = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$ is in \mathbb{R}^3 ($\underline{u} \in \mathbb{R}^3$ or \underline{u} is an element of \mathbb{R}^3)

• Real scalars lie in \mathbb{R}^1 (or simply \mathbb{R})

• π is in \mathbb{R}

• Complex vectors live in \mathbb{C}^n

$\underline{u} = \begin{bmatrix} -i \\ 1+i \end{bmatrix}$ is in \mathbb{C}^2 ($\underline{u} \in \mathbb{C}^2$)

- Real matrices of dimension $m \times n$ live in the vector space $\mathbb{R}^{m \times n}$

Typically denoted by M_{mn}

- Real functions live in some space F

Vector spaces are defined by their collection and how operations take place

"Vectors" inside vector space remain inside

Rules of a Vector Space

Let $\underline{x}, \underline{y}, \underline{z}$ be in a particular vector space V with a & b as scalars in \mathbb{R}

All vectors spaces must obey:

① $\underline{x} + \underline{y} = \underline{y} + \underline{x}$ must be in V

② $\underline{x} + (\underline{y} + \underline{z}) = (\underline{x} + \underline{y}) + \underline{z}$ must be in V

③ unique zero vector exists, such that

$$\underline{0} + \underline{x} = \underline{x} + \underline{0} = \underline{x}$$

④ for every \underline{x} , there exists $-\underline{x}$, such that

$$\underline{x} + (-\underline{x}) = (-\underline{x}) + \underline{x} = \underline{0}$$

⑤ $a(\underline{x} + \underline{y}) = a\underline{x} + a\underline{y}$ must be in V

⑥ $(a+b)\underline{x} = a\underline{x} + b\underline{x}$ " "

⑦ $a(b\underline{x}) = b(a\underline{x})$ " "

⑧ $1\underline{x} = \underline{x}$

If all of these rules are followed,
then the vector space is closed

Subspaces

A portion of a vector space is called a subset of that vector space

Denote this subset of a vector space V
as W

If W is closed under addition and
multiplication as defined above then...

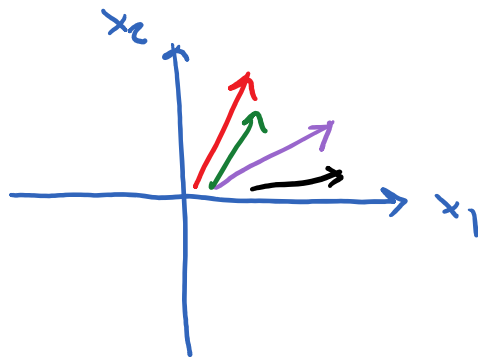
If W is closed under addition and multiplication, as defined above, then W is a subspace of V

Closed means that after addition and multiplication the result is in W

Examples:

1 All vectors in \mathbb{R}^2 , such that

$$\underline{v} = \begin{bmatrix} a \\ b \end{bmatrix} \text{ with } a \geq 0, b \geq 0$$



Is this subset W a vector space?

Check addition:

$$\begin{bmatrix} a \\ b \end{bmatrix} + \begin{bmatrix} c \\ d \end{bmatrix} = \begin{bmatrix} a+c \\ b+d \end{bmatrix} \quad \text{OK, still in } W$$

Check multiplication:

Check multiplication:

$$k \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} ka \\ kb \end{bmatrix} \quad \begin{array}{l} \text{Is } ka \geq 0 \\ \text{Is } kb \geq 0 \end{array}$$

for $k \in \mathbb{R}$ Result not in W for $k < 0$

$\therefore W$ is a subset of U , but not
a subspace

12] Let W be all vectors of the form

$$\left[a, b, \frac{a}{2} - 2b \right] \quad b, a \in \mathbb{R}$$

Is this a subspace of \mathbb{R}^3 ?

Check addition:

$$\left[a, b, \frac{a}{2} - 2b \right] + \left[c, d, \frac{c}{2} - 2d \right]$$

$$= \left[a+c, b+d, \frac{a}{2} - 2b + \frac{c}{2} - 2d \right]$$

$$= \left[a+c, b+d, \frac{(a+c)}{2} - 2(b+d) \right] \quad \checkmark \text{ ok}$$

Check multiplication:

$$k \left[a, b, \frac{a}{2} - 2b \right]$$

$$= \left[ka, kb, \frac{ka}{2} - 2kb \right] \quad \text{for } k \in \mathbb{R}$$

✓ ok

$\therefore W$ is a subspace of \mathbb{R}^3

Span

Let S be a non-empty subset of vectors in vector space V . Then,

$$S \subseteq V$$

(is contained in)

All finite linear combinations of the vectors in S form the span of S , written $\text{span}(S)$

Examples:

$$\boxed{1} \quad \text{Let } S = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

Then, $\text{span}(S)$ is all of \mathbb{R}^2

Any vector in \mathbb{R}^2 can be written as

$$a \begin{bmatrix} 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} a \\ b \end{bmatrix}$$

12 Let $S = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

Then, $\text{span}(S)$ is all vectors in \mathbb{R}^4 of the form $\begin{bmatrix} a \\ 0 \\ 0 \\ b \end{bmatrix}$

Is this a subspace?

All vectors in this subset are

$$a \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} + b \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

Check addition:

$$\text{span}(S) =$$

$$a \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} + c \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} a \\ 0 \\ 0 \\ a+c \end{bmatrix}$$

\downarrow
 b

$$\left(a \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} + b \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right) + \left(c \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} + d \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right)$$

$$= (a+c) \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} + (b+d) \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \quad \text{Yes, in } \text{span}(S)$$

Check multiplication:

$$k \left(a \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} + b \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right) = ka \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} + kb \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \quad \text{Yes!}$$

$\therefore \text{span}(S)$ is a subspace of \mathbb{R}^4

Ideas of subspace and span also applies to matrix and function spaces

Examples:

[1] Let U_2 be set the of 2×2 upper triangular

matrices and L_2 be the set of 2×2 lower triangular matrices, such that

$$U_2 = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right\}$$

$$L_2 = \left\{ \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

$$\text{Let } S = U_2 \cup L_2$$

↳ union

Then, $\text{span}(S)$ contains all 2×2 matrices, called M_{22}

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Theorem

Let S be a non-empty subset of vector space V . Then,

① $S \subseteq \text{span}(S)$
(S is contained in)

② $\text{span}(S)$ is a subspace of V

③ If W is a subspace of V with $S \subseteq W$, then $\text{span}(S) \subseteq W$

④ $\text{span}(S)$ is the smallest subspace of V containing S

① Any vector in $S: \{v_1, v_2, \dots, v_n\}$ can be written as a linear combination of the subset S

$$v_1 = 1v_1 + 0v_2 + \dots + 0v_n$$

② $\text{span}(S)$ is a subspace of V

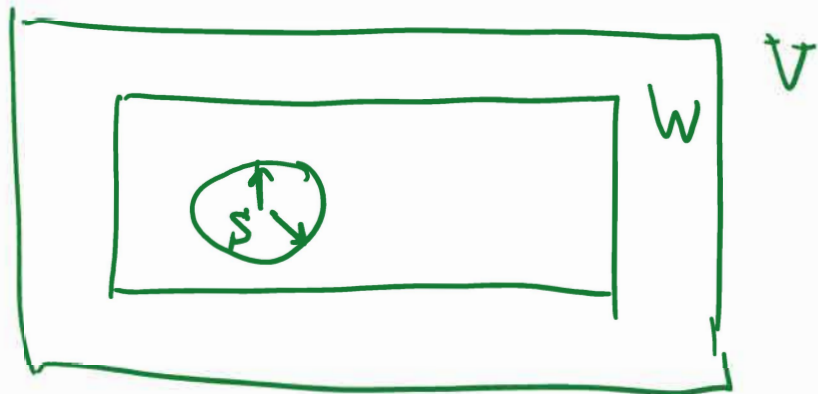
$$\text{span}(S): a_1v_1 + a_2v_2 + \dots + a_nv_n$$

$$(a_1v_1 + a_2v_2 + \dots + a_nv_n) + (b_1v_1 + b_2v_2 + \dots + b_nv_n)$$

$$(a_1 \underline{v}_1 + a_2 \underline{v}_2 + \dots + a_n \underline{v}_n) + (b_1 \underline{v}_1 + b_2 \underline{v}_2 + \dots + b_n \underline{v}_n) \\ = (a_1 + b_1) \underline{v}_1 + (a_2 + b_2) \underline{v}_2 + \dots + (a_n + b_n) \underline{v}_n$$

$$k(a_1 \underline{v}_1 + a_2 \underline{v}_2 + \dots + a_n \underline{v}_n) \\ = k a_1 \underline{v}_1 + k a_2 \underline{v}_2 + \dots + k a_n \underline{v}_n \\ \rightarrow \text{span}(\underline{S}) \text{ is a subspace}$$

③



④ Summary of ① \rightarrow ③

Vector Independence

Let $\underline{v}_1, \underline{v}_2$ and \underline{v}_3 be vectors of same dimension

If the only ^{linear} combination of $\underline{v}_1, \underline{v}_2$ and \underline{v}_3 that results in the zero vector is

$$0\underline{v}_1 + 0\underline{v}_2 + 0\underline{v}_3 = \underline{0}$$

then \underline{v}_1 , \underline{v}_2 and \underline{v}_3 are independent

On the other hand, if some non-trivial combination exists, then \underline{v}_1 , \underline{v}_2 + \underline{v}_3 are dependent

Example: Is $\underline{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$, $\underline{v}_2 = \begin{bmatrix} -1 \\ -4 \\ -5 \end{bmatrix}$, $\underline{v}_3 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$

independent?

$$2 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + 1 \begin{bmatrix} -1 \\ -4 \\ -5 \end{bmatrix} + (-1) \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad \text{No!}$$

$$\underline{v}_3 = 2\underline{v}_1 + \underline{v}_2$$

The vectors are not linearly independent

Linear Independence + Dependence

Let S be a subset of vector space V

S is linearly dependent, if some non-zero linear combination of S results in the zero vector

$$S = \{ \underline{v}_1, \underline{v}_2, \dots, \underline{v}_n \}$$

$$\text{Some } a_1 \underline{v}_1 + a_2 \underline{v}_2 + \dots + a_n \underline{v}_n = \underline{0}$$

for some $a_1 \neq 0, a_2 \neq 0, \dots$ or $a_n \neq 0$

and the $\text{span}(S)$ contains linearly dependent vectors.

Example:

$$S \in \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \end{bmatrix} \right\}$$

However,

$$\overset{a_1}{(1)} \underbrace{\begin{bmatrix} 1 \\ 1 \end{bmatrix}}_{\underline{v}_1} + \overset{a_2}{(1)} \underbrace{\begin{bmatrix} -1 \\ -1 \end{bmatrix}}_{\underline{v}_2} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

\therefore Linearly dependent

If not linearly dependent, then

linearly independent

Basis

B is a basis for vector space V iff

- ① B spans all of V
- ② B is linearly independent

Example:

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\} \text{ is a basis for } \mathbb{R}^3$$

Example:

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ -3 \end{bmatrix} \right\} \text{ also form a basis for } \mathbb{R}^3$$

Basis is not unique!

Example:

$$\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

is a basis for M_{22}

Example:

$$S = \left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} \right\} = B$$

$\text{span}(S)$ is a subspace of \mathbb{R}^4 and S is ~~not~~ a basis for that subspace

Dimension

The dimension of a vector space V is the minimum number of vectors needed in a basis B of V

If the number of vectors in B is finite, then $\dim(V) \rightarrow$ dimension of V , is finite
otherwise V has infinite dimension

Example:

$$B = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\} \text{ is a basis}$$

for \mathbb{R}^3 , number of elements in the set $\Rightarrow \dim(\mathbb{R}^3) = |B| = 3$

Example:

$$\dim(\mathbb{R}^n) = n$$

Example:

$$B = \left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} \right\}$$

$$V = \text{span}(B) \Rightarrow \dim(V) = 3$$

Example:

Vector space P_3 : All polynomials of order 3 & below

$$P_3: \{1, x, x^2, x^3\} \quad \checkmark \text{ basis for } P_3$$

$$\Rightarrow a(1) + b(x) + c(x^2) + d(x^3)$$

$$\dim(P_3) = 4$$

More generally

$$\dim(P_n) = n+1$$

Example:

$$\dim(M_{22}) = 4$$

$$\dim(M_{mn}) = mn$$

Basis

$$B = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

Example: Infinite Dimensional Space

Taylor Series

$$B = \left\{ (x-a)^0, (x-a)^1, (x-a)^2, \dots, (x-a)^n, \dots \right\}$$

$$F = \alpha (x-a)^0 + \beta (x-a)^1 + \gamma (x-a)^2 + \dots$$

$$\dim(\text{Taylor Series}) = \infty$$

Summary of Concepts

- Vector space
- Subspace
- Span
- Vector independence
- Basis
- Dimension