

Chapter 6.1: Direct Methods For Solving Linear Systems



Operations

$$E_1 : a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1,$$

$$E_2 : a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2,$$

$$\vdots$$

$$E_n : a_{n1}x_1 + a_{n2}x_2 + \cdots + a_{nn}x_n = b_n.$$

is a linear system with given constants a_{ij} , for each $i, j = 1, 2, \dots, n$, and b_i , for each $i = 1, 2, \dots, n$, and we need to determine the unknowns x_1, \dots, x_n .

1. Equation E_i can be multiplied by any nonzero constant λ with the resulting equation used in place of E_i . This operation is denoted $(\lambda E_i) \rightarrow (E_i)$.
2. Equation E_j can be multiplied by any constant λ and added to equation E_i with the resulting equation used in place of E_i . This operation is denoted $(E_i + \lambda E_j) \rightarrow (E_i)$.
3. Equations E_i and E_j can be transposed in order. This operation is denoted $(E_i) \leftrightarrow (E_j)$.

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Definition (6.1)

An $n \times m$ (n by m) **matrix** is a rectangular array of elements with n rows and m columns in which not only is the value of an element important, but also its position in the array.

The notation for an $n \times m$ matrix will be a capital letter such as A for the matrix and lowercase letters with double subscripts, such as a_{ij} , to refer to the entry at the intersection of the i th row and j th column; that is,

$$A = [a_{ij}] = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1m} \\ a_{21} & a_{22} & \cdots & a_{2m} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nm} \end{bmatrix}.$$

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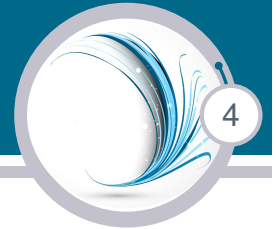
An $n \times (n + 1)$ matrix can be used to represent the linear system

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n &= b_1, \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n &= b_2, \\ &\vdots \\ a_{n1}x_1 + a_{n2}x_2 + \cdots + a_{nn}x_n &= b_n, \end{aligned}$$

by constructing the **augmented matrix**

$$[A, \mathbf{b}] = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & b_1 \\ a_{21} & a_{22} & \cdots & a_{2n} & b_2 \\ \vdots & \vdots & & \vdots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} & b_n \end{bmatrix}.$$

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Gaussian elimination with backward substitution

Through a sequential procedure for $i = 2, 3, \dots, n - 1$ we perform the operation

$$(E_j - (a_{ji}/a_{ii})E_i) \rightarrow (E_j) \quad \text{for each } j = i + 1, i + 2, \dots, n,$$

provided $a_{ii} \neq 0$. This eliminates (changes the coefficient to zero) x_i in each row below the i th for all values of $i = 1, 2, \dots, n - 1$. The resulting matrix has the form:

$$\tilde{\tilde{A}} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & a_{1,n+1} \\ 0 & a_{22} & \cdots & a_{2n} & a_{2,n+1} \\ \vdots & & & \vdots & \vdots \\ 0 & \cdots & 0 & a_{nn} & a_{n,n+1} \end{bmatrix},$$

where, except in the first row, the values of a_{ij} are not expected to agree with those in the original matrix $\tilde{A} = [A, b]$. The matrix $\tilde{\tilde{A}}$ represents a linear system with the same solution set as the original system .

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Algorithm 6.1: GAUSSIAN ELIMINATION WITH BACKSUB

To solve the $n \times n$ linear system

$$\begin{array}{rccccccccc} E_1 : & a_{11}x_1 & + & a_{12}x_2 & + & \cdots & + & a_{1n}x_n & = & a_{1,n+1} \\ E_2 : & a_{21}x_1 & + & a_{22}x_2 & + & \cdots & + & a_{2n}x_n & = & a_{2,n+1} \\ \vdots & \vdots & & \vdots & & & & \vdots & & \vdots \\ E_n : & a_{n1}x_1 & + & a_{n2}x_2 & + & \cdots & + & a_{nn}x_n & = & a_{n,n+1} \end{array}$$

INPUT number of unknowns and equations n ; augmented matrix $A = [a_{ij}]$, where $1 \leq i \leq n$ and $1 \leq j \leq n + 1$.

OUTPUT solution x_1, x_2, \dots, x_n or message that the linear system has no unique solution.

$$x_i = \frac{a_{i,n+1} - \sum_{j=i+1}^n a_{ij} x_j}{a_{ii}} ; \quad i = n-1, n-2, \dots, 2, 1$$

6 (a)

$$E_1 \quad x_2 - 2x_3 = 4$$

$$E_2 \quad x_1 - x_2 + x_3 = 6$$

$$E_3 \quad x_1 - x_3 = 2$$

$$\tilde{A} = \left[\begin{array}{ccc|c} 0 & 1 & -2 & 4 \\ 1 & -1 & 1 & 6 \\ 1 & 0 & -1 & 2 \end{array} \right] \xrightarrow{(E_2) \leftrightarrow (E_1)} \left[\begin{array}{ccc|c} 1 & -1 & 1 & 6 \\ 0 & 1 & -2 & 4 \\ 1 & 0 & -1 & 2 \end{array} \right] \xrightarrow{(-E_1 + E_3) \rightarrow (E_3)}$$

$$\left[\begin{array}{ccc|c} 1 & -1 & 1 & 6 \\ 0 & 1 & -2 & 4 \\ 0 & 1 & -2 & -4 \end{array} \right]$$

no solutions.

$$\#5(a) \quad x_1 - x_2 + 3x_3 = 2$$

$$3x_1 - 3x_2 + x_3 = -1$$

$$x_1 + x_2 = 3$$

$$\tilde{A} = \left[\begin{array}{ccc|c} 1 & -1 & 3 & 2 \\ 3 & -3 & 1 & -1 \\ 1 & 1 & 0 & 3 \end{array} \right] \xrightarrow{(-3E_1 + E_2) \rightarrow (E_2)} \left[\begin{array}{ccc|c} 1 & -1 & 3 & 2 \\ 0 & 0 & -8 & -7 \\ 1 & 1 & 0 & 3 \end{array} \right] \xrightarrow{(-E_1 + E_3) \rightarrow (E_3)}$$

$$\left[\begin{array}{ccc|c} 1 & -1 & 3 & 2 \\ 0 & 0 & -8 & -7 \\ 0 & 2 & -3 & 1 \end{array} \right] \xrightarrow{(E_2) \leftrightarrow (E_3)} \left[\begin{array}{ccc|c} 1 & 1 & 3 & 2 \\ 0 & 2 & -3 & 1 \\ 0 & 0 & -8 & -7 \end{array} \right]$$

$$x_3 = \frac{7}{8}$$

$$2x_2 - 3x_3 = 1$$

$$2x_2 = 1 + \frac{21}{8} = \frac{29}{8}$$

$$x_2 = \frac{29}{16}$$

$$x_1 + x_2 = 3$$

$$x_1 = 3 - \frac{29}{16} = \frac{48-29}{16} = \frac{19}{16}$$

#10. $x_1 - x_2 + \alpha x_3 = -2$

$$-x_1 + 2x_2 - \alpha x_3 = 3$$

$$\alpha x_1 + x_2 + x_3 = 2$$

$$\tilde{A} = \left[\begin{array}{ccc|c} 1 & -1 & \alpha & -2 \\ -1 & 2 & -\alpha & 3 \\ \alpha & 1 & 1 & 2 \end{array} \right] \xrightarrow{(+E_1 + E_2) \rightarrow (E_2)} \left[\begin{array}{ccc|c} 1 & -1 & \alpha & -2 \\ 0 & 1 & 0 & 1 \\ \alpha & 1 & 1 & 2 \end{array} \right] \xrightarrow{(\alpha E_1 + E_3) \rightarrow (E_3)}$$

$$\left[\begin{array}{ccc|c} 1 & -1 & \alpha & -2 \\ 0 & 1 & 0 & 1 \\ 0 & +\alpha+1 & -\alpha+1 & 2\alpha+2 \end{array} \right]$$

$$\underbrace{(-(d+1)E_2 + E_3)} \rightarrow (E_3) \quad \left[\begin{array}{ccc|c} 1 & -1 & d & -2 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & -d^2+1 & d+1 \end{array} \right]$$

$$(1-d^2)x_3 = d+1$$

$$(1-d)(1+d)x_3 = d+1$$

(a) $\boxed{d \neq -1}$ x_3 - any real number

(b) \nearrow $x_2 = 1$

$x_1 - x_2 + d = -2 \Rightarrow x_1 - 1 - 1 = -2 \Rightarrow x_1 = 0$
 infinite number of solutions $\begin{pmatrix} 0 \\ 1 \\ x_3 \end{pmatrix}$

(b) $d = 1$

(a)

$0 \cdot x_3 = 2 \Rightarrow$ no solutions

(c) $d \neq -1, 1$

$(1-d)x_3 = 1$

$x_3 = \frac{1}{1-d}$

$x_2 = 1$

$x_1 - 1 + \frac{d}{1-d} = -2$

$x_1 = -1 - \frac{d}{1-d} = \frac{-1+d-d}{1-d} = -\frac{1}{1-d}$

Unique solution $\begin{pmatrix} \frac{1}{d-1} \\ 1 \\ \frac{1}{1-d} \end{pmatrix}$

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Algorithm 6.1: GAUSSIAN ELIMINATION WITH BACKSUB

Step 1 For $i = 1, \dots, n - 1$ do Steps 2–4. (*Elimination process.*)
Step 2 Let p be the smallest integer with $i \leq p \leq n$ and $a_{pi} \neq 0$.
If no integer p can be found
then OUTPUT ('no unique solution exists'); STOP.
Step 3 If $p \neq i$ then perform $(E_p) \leftrightarrow (E_i)$.
Step 4 For $j = i + 1, \dots, n$ do Steps 5 and 6.
Step 5 Set $m_{ji} = a_{ji} / a_{ii}$.
Step 6 Perform $(E_j - m_{ji}E_i) \rightarrow (E_j)$;
Step 7 If $a_{nn} = 0$ then OUTPUT ('no unique solution exists'); STOP.
Step 8 Set $x_n = a_{n,n+1} / a_{nn}$. (*Start backward substitution.*)
Step 9 For $i = n - 1, \dots, 1$ set $x_i = \left[a_{i,n+1} - \sum_{j=i+1}^n a_{ij}x_j \right] / a_{ii}$.
Step 10 OUTPUT (x_1, \dots, x_n) ; (*Procedure completed successfully.*)
STOP.

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Operation Counts

Both the amount of time required to complete calculations and the subsequent round-off error depend on the number of floating-point arithmetic operations needed to solve a routine problem.

Multiplications/divisions

The total number of multiplications and divisions in Algorithm 6.1

$$\frac{2n^3 + 3n^2 - 5n}{6} + \frac{n^2 + n}{2} = \frac{n^3}{3} + n^2 - \frac{n}{3}.$$

Additions/subtractions

The total number of additions and subtractions in Algorithm 6.1

$$\frac{n^3 - n}{3} + \frac{n^2 - n}{2} = \frac{n^3}{3} + \frac{n^2}{2} - \frac{5n}{6}.$$