

Project progress report: Boosting collaborative filtering with sentiment analysis

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ABSTRACT

Sentiment analysis has been used to do rating prediction and achieved remarkable success. However, it requires user's review as input, which makes it impossible to predict ratings for items that user has never interacted with. Therefore, only using sentiment analysis for recommendation is impractical.

Given the success of sentiment analysis, researchers start to investigate how to integrate sentiment analysis with collaborative filtering. However, previous work ([1], [3]) only focus on how to use the benefits of sentiment analysis to boost collaborative filtering, but ignore the feedback that collaborative filtering can contribute to sentiment analysis. Sentiment analysis can provide continuous approximation of ratings instead the discrete values; while collaborative filtering can provide extra user and item information for sentiment analysis. Therefore, it's important to maximize the mutual interest of sentiment analysis and collaborative filtering.

1 PROBLEM DEFINITION

Input: User-item interaction history with reviews: $\{(u, i, s, r)\}$, where the four entities in one history record are user, item, rating, review, respectively.

Output: Let \mathcal{U} and \mathcal{I} be the collection of users and item, for any user-item pair $(u, i) \in \mathcal{U} \times \mathcal{I}$, output probability of u interact with i in the future p_{ui}

2 PROPOSED FRAMEWORK

Maximizing Mutual Information is a popular technique in recent years that tries to maximize the agreement between two models. Although directly maximizing mutual information is intractable, InfoNCE Loss[4] is often adopted to maximize the lower bound of mutual information. Therefore, we can leverage both benefits of semantic analysis and collaborative filtering by maximizing the mutual information (adding InfoNCE Loss term) between two backbone model: semantic analysis backbone model \mathcal{M}_s that output review embedding $\{e_r\}$; collaborative filtering backbone model \mathcal{M}_c that output user embedding $\{e_u\}$ and item embedding $\{e_i\}$.

Specifically, for a record (u, i, s, r) , we want to extract the user and item information from e_r , i.e., $e_u^r = f_u(e_r)$, $e_i^r = f_i(e_r)$, where f_u, f_i are user feature and item feature extractor that extracts users' and items' information from reviews' features. Then we want to maximize the mutual information between $\{e_u^r\}$, e_u , and mutual information between $\{e_i^r\}$, e_i . Finally, p_{ui} will be predicted by dot product like in most existing works, e.g., LightGCN [2]. The backbone models can be implemented by Transformer [5] and LightGCN [2]. Note that these backbone models are just selected for this project, it can be replaced by any other models that give desired

embeddings. The framework is shown in Figure 1. More details will be introduced in Section 4.

3 DATASET PREPROCESSING

Amazon Digital Music Dataset¹ is used for this project.

During data preprocessing, I only selected those ratings over 3.0 and they are all normalized into $(0, 1]$, i.e, given a rating in range $[3, 5]$, the normalized rating will be

$$\hat{s} = \frac{s - 2}{3} \quad (1)$$

The whole dataset are split into test set and training set with proportion 3:7.

After data preprocessing, the dataset contains 16518 users, 11794n digital musics, 116020 ratings and reviews for training and 49599 ratings and reviews for testing.

4 MODEL IMPLEMENTATION

4.1 LightGCN

LightGCN is a GNN-based method that considers users' and items' embeddings as model parameters. It first construct all user-item historical interactions as a undirected and unweighted bipartite graph. To apply message passing on this graph, LightGCN simply considers aggregation of neighbors' embeddings as the messages.

$$m_{j \rightarrow i}^{(l)} = \frac{1}{\sqrt{|\mathcal{N}(i)| |\mathcal{N}(j)|}} e_j^{(l-1)} \quad (2)$$

where $|\mathcal{N}(i)|$ is the number of neighbors of i . Then layer-wise representation ends up in a simple formula:

$$e_i^{(l)} = \sum_{j \in \mathcal{N}_i} m_{j \rightarrow i}^{(l)} \quad (3)$$

and the final representation aggregate those layer-wise representations

$$e_i = \frac{1}{L+1} \sum_{l=0}^L e_i^{(l)} \quad (4)$$

Note that this is actually different from the original paper because I adapted some improvement from SimGCL [6]. After updating these embeddings by message passing, embeddings are again updated by gradient descent to minimize BPR loss and L2 regularization loss.

$$\mathcal{L} = \mathcal{L}_{BPR} + \mathcal{L}_2 = - \sum_{(u,i,j) \in O} \log \sigma(\hat{p}_{ui} - \hat{p}_{uj}) + \lambda \|\Theta\|_2 \quad (5)$$

where $\Theta = \{E = \{e_i\}\}$ is the collection of model parameters, \hat{p}_{ui} is the predicted probability defined as $\hat{p}_{ui} = e_u \cdot e_i$, $O = \{(u, i, j) | (u, i) \in R^+, (u, j) \in R^-\}$ denotes the pairwise training

¹https://cseweb.ucsd.edu/~jmcauley/datasets/amazon_v2/

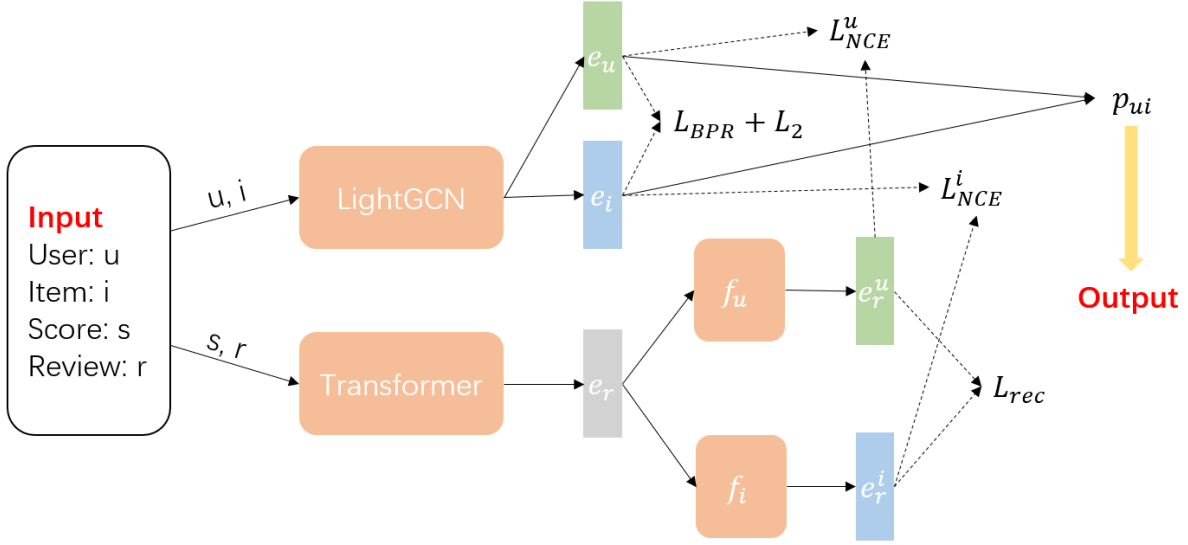


Figure 1: Proposed framework

data, R^+ indicates the observed interactions (positive samples), and R_- is the unobserved interactions (negative samples). In our case, items in negative samples are randomly sampled from item set.

4.2 Transformer

I leverage `nn.TransformerEncoderLayer` and `nn.TransformerEncoder` in pytorch to implement transformer. Before feeding our data into the interface of pytorch, I first use tools in `torchtext` to parse the words in reviews into tokens and build the vocabulary. Then, I also added positional encoding in the tokens, which align with the implementation of original paper [5]. The d-dimensional output embedding of Transformer will be further fed into f_u and f_i (which are implemented as two fully connected layers) to extract e_r^u , e_r^i . Finally, transformer will use a MAE (mean absolute error) loss with L_2 regularization to update.

$$\mathcal{L} = \mathcal{L}_1 + \mathcal{L}_2^r = \sum_{(u,i,s)} |\hat{p}_{ui}^r - \hat{s}_{ui}| + \lambda(\|e_u^r\|_2 + \|e_i^r\|_2) \quad (6)$$

where \hat{s}_{ui} is the ground truth normalized rating, \hat{p}_{ui}^r is the predicted rating defined as $\hat{p}_{ui}^r = e_u^r \cdot e_i^r$.

4.3 Mutual Information Maximization

To align the two views of embeddings learnt from text data and historical interaction matrix, we use InfoNCE Loss to maximize the mutual information between two views. For a training batch $\{(u, i, s, r)\}$, we denote the series of users as \mathcal{U} , and the series of items as \mathcal{I} , then the loss is defined as

$$\mathcal{L}_{CL} = \mathcal{L}_u + \mathcal{L}_i = - \sum_{(u,i,s,r)} \log \frac{\exp(\cos(e_u, e_u^r)/\tau)}{\sum_{v \in \mathcal{U}} \exp(\cos(e_u, e_v^r)/\tau)} \quad (7)$$

$$- \sum_{(u,i,s,r)} \log \frac{\exp(\cos(e_i, e_i^r)/\tau)}{\sum_{v \in \mathcal{I}} \exp(\cos(e_i, e_v^r)/\tau)} \quad (8)$$

where τ is a hyperparameter known as temperature in softmax, e_u and e_i are embeddings learnt from LightGCN, e_u^r and e_i^r are embeddings obtained from Transformer. The overall objective function will be

$$\mathcal{L} = \mathcal{L}_{BPR} + \mathcal{L}_1 + \lambda(\mathcal{L}_2 + \mathcal{L}_2^r) + \beta \mathcal{L}_{CL} \quad (9)$$

where λ, β are two hyperparameters.

5 EXPERIMENT

5.1 Experimental setting

Metrics used for evaluation include : NDCG@10, Prec@10 (precision), Recall@10, '@10' denotes that I only keep the top-10 items with highest probability as prediction results.

Baseline I compared my proposed framework with vanilla LightGCN (which is the same as setting $\beta = 0$).

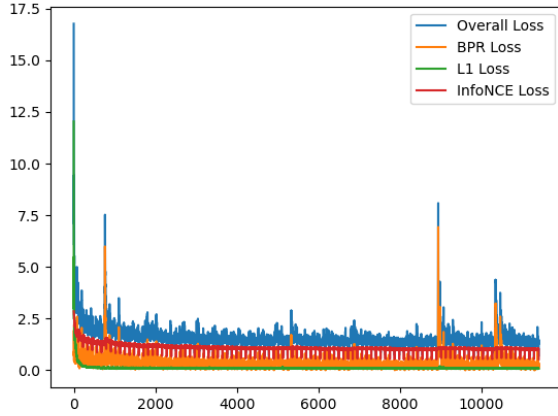
5.2 Experimental Results

The results on test set are shown as below.

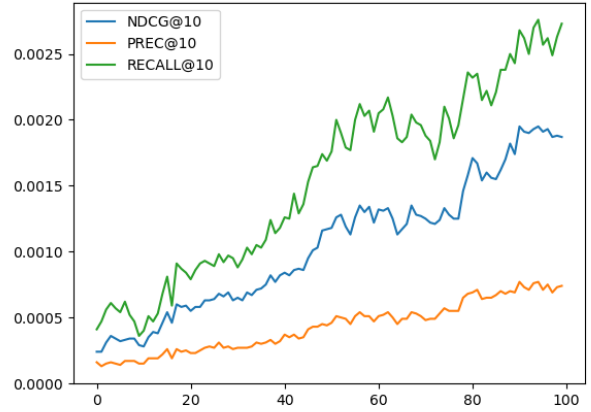
Table 1: Results (higher is better)

Method	NDCG	Prec	Recall
Ours	0.00195	0.00077	0.00268
LightGCN	0.0035	0.00124	0.00462

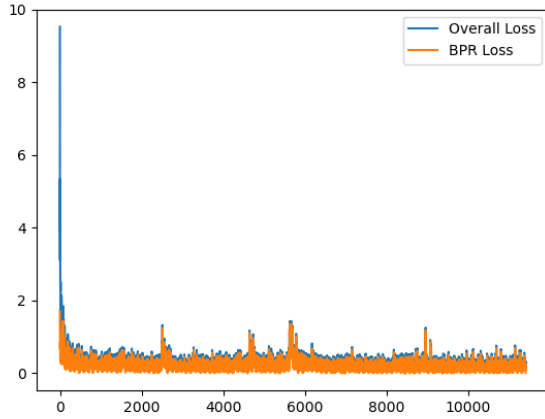
Unfortunately, our model is outperformed by LightGCN in all three metrics. To find the reason behind this, we further analyze the change of losses and performance with respect to epochs in Figure 2. We can see that the metric curves are quite similar; however, for the loss curves, our loss curve is more unstable compared with LightGCN: BPR loss in LightGCN falls into $[0, 2]$ after a few epochs, but in our model, the BPR loss can suddenly change to larger than 5. This could be caused by two reasons:



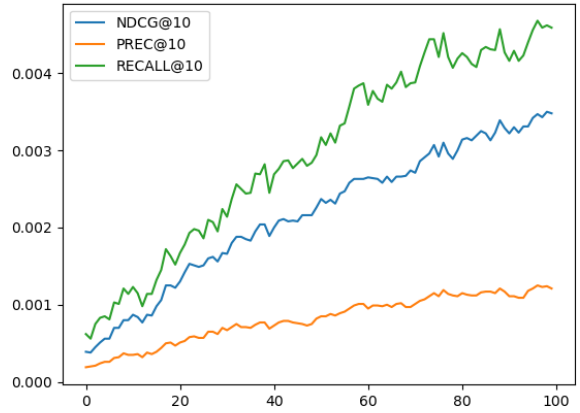
(a) Loss Curve: Ours



(b) Metric Curve: Ours



(c) Loss Curve: LightGCN



(d) Metric Curve: LightGCN

Figure 2: Loss curves and metric curves.

- The involvement of InfoNCE loss has made the parameter space more complex, that it could easily fall into multiple local maximums and is harder to train.
- The design of f_u and f_i are insufficient for mapping text embeddings into users' and items' embedding space, that we might need to change the structure of f_u and f_i or find another way to align the two embedding space.

6 CONCLUSION

I have completed the project as planned, but the experimental results are unsatisfactory and require further research. Self-evaluation is further conducted by analyzing loss curves and metric curves.

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