LAB-4

<u>Aim:</u> Program to implement the concept of hill climbing.

Algorithm:

Evaluate the initial state.

Loop until a solution is found or there are no new operators left to be applied:

- Select and apply a new operator
- Evaluate the new state:

```
goal \rightarrow quit
```

better than current state --- new current state

Source Code:

```
import random
# Distance matrix representing distances between cities
# Replace this with the actual distance matrix for your problem
distance_matrix = [
  [0, 10, 15, 20],
  [10, 0, 35, 25],
  [15, 35, 0, 30],
  [20, 25, 30, 0]
]
def total_distance(path):
  # Calculate the total distance traveled in the given path
  total = 0
  for i in range(len(path) - 1):
     total += distance_matrix[path[i]][path[i+1]]
  total += distance_matrix[path[-1]][path[0]] # Return to starting city
  return total
```

```
def hill_climbing_tsp(num_cities, max_iterations=10000):
  current_path = list(range(num_cities)) # Initial solution, visiting cities in order
  current_distance = total_distance(current_path)
  for _ in range(max_iterations):
    # Generate a neighboring solution by swapping two random cities
    neighbor_path = current_path.copy()
    i, j = random.sample(range(num_cities), 2)
     neighbor_path[i], neighbor_path[i] = neighbor_path[i], neighbor_path[i]
     neighbor_distance = total_distance(neighbor_path)
    # If the neighbor solution is better, move to it
    if neighbor_distance < current_distance:
       current_path = neighbor_path
       current distance = neighbor distance
  return current_path
def main():
  num_cities = 4 # Number of cities in the TSP
  solution = hill_climbing_tsp(num_cities)
  print("Optimal path:", solution)
  print("Total distance:", total_distance(solution))
if __name__ == "__main__":
  main()
```

OUTPUT:

Optimal path: [1, 0, 2, 3]

Total distance: 80