SAIRAJ RAJENDRA LOKE

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EDUCATION

Degree/Certificate	Institute/Board	CGPA/Percentage	Year
B.Tech.	Indian Institute of Technology Indore	8.47 (Current)	2021-2025
Senior Secondary	HSC (grade 12)	94.67%	2021
Secondary	SSC (grade 10)	95.00%	2019

EXPERIENCE

• Environmental Robotics Lab(ERL) - ETH Zurich | Computer Vision & Robotics Intern

Aug.24 - Present

- Designing and implementing an Optical/Scene Flow-based algorithm to estimate the rigidity of tree branches, utilizing data from a downward-facing camera mounted on a hovering drone to be used for sensor deployment.
- Autonomous Robots Lab(ARL) NTNU | Robotics Research Intern

Oct.23 - Jul.24

- Developed a custom ROS wrapper for the HoloOcean simulator. This is being used for generating datasets in rosbag format and integrating the vehicle control with existing ROS packages.
- Worked on encoding depth information using beta-VAEs to be used for downstream underwater navigation tasks.
- Achieved 500x compression ratio in depth representation with VAE's inference time of less than 1.6 milliseconds.

• Big Data Lab - IIT Indore | Data Augmentation Intern

Jul.23 - Sept.23

- Implemented traditional image augmentation techniques: rotations, blurring of different kinds, shadow, flares, and lot more, for 6 diseases + 1 healthy leaf class on existing 770 images to generate x9 times images to be used further.
- Reviewed and used GANs for data augmentaion, custom as well as models like CycleGAN.
- Quality of generated images were qualitatively evaluated using perceptual studies.

PROJECTS

• IITIHub- Institute App

Jan. 23 - Apr. 23

Software Course Project, under Prof. Puneet Gupta, CSE, IIT Indore

Github

- Applied principles of incremental software development process, to design and build flutter and firebase-based mobile application from scratch targetted for IIT Indore community.
- Features: student-professor project collaboration platform, automatic email categorization, campus news & map.

• Python API for Controlling Drona Aviation's Pluto Drone (Bronze Medal)

Dec. 22 - Feb. 23

Inter IIT TechMeet 11.0, IIT Kanpur

Presentation - Certificate - Github

- Developed a comprehensive Python API based on multithreading and multiprocessing to achieve real-time performance for simultaneous vision and control processes. Established socket communication between the client computer and drone. Implemented waypoint navigation algorithm with visual feedback using ArUco markers.
- Demonstrated hovering, waypoint navigation, localization, and drone swarm control utilizing the developed API.

• Lidar Based Obstacle Avoiding Robot

Jul. 22 - Aug. 22

Team Lead, IIT Indore Summer of Code

Github

- Led a team of four undergraduates to develop a static and dynamic obstacle-avoiding robot simulation in Gazebo,
 utilizing ROS as the middleware with a Jackal robot and Velodyne Lidar.
- Used Time Elastic Band (TEB) local planner, after comparison with Dynamic Window Approach and ElasticBand.

TECHNICAL SKILLS

- Programming Languages: C++, Python, Bash, Dart*, SQL*
- OS & Platforms/Embedded devices: Linux, RaspberryPi, Arduino
- Tools/Frameworks/Libraries: Git, Github, PyTorch, OpenCV, ROS/ROS2, Singularity(HPC Containerization), Sockets, Flutter, Docker*, OpenMP*, Wireshark*, BOUML*, Gazebo(Classic + Ignition)*, HoloOcean

KEY COURSES TAKEN

* Elementary proficiency

- Mathematics: Linear Algebra, Optimization, Numerical Approximations, Differential Equations, Basic Calculus
- Computer Science and Engineering: Computational Intelligence, Computer Networks, Operating Systems, Data Structures and Algorithms, Software Engineering, Parallel Computing, Database and Information System, Automata Theory & Logic, Computer Graphics, Compiler Techniques
- Online Courses: Fundamentals of Reinforcement Learning, Neural Networks and Deep Learning, Hyperparameter Tuning, Regularization and Optimization, other Course Certifications.

Positions of Responsibility

- Chair IEEE- RAS, Student Branch Chapter , IIT Indore- Prof. Trapti Jain (Advisor) Nov. 22 Present Discussions with industry professional on latest robotics developments, ROS workshops. link
- Member, SIRC, International Relations Team (Students' International Relations Cell)

 Dec. 22 Present
- Head- Autonomy Division, IVDC Club, IIT Indore, IGVC team Autonomy lead. Apr. 23 Apr. 24

ACHIEVEMENTS

• ThinkSwiss Scholar 2024, Scholarship for Fall 2024 internship at ETH Zurich	2024
• Bronze Medal, Inter IIT Tech Meet 11.0, IIT Kanpur	
• Ranked 12th Internationally, <u>Team NotABot</u> - <u>CoderOne</u>	
• Gold Medal, IIT Indore Summer of Code-Lidar Based Obstacle Avoiding Robot	
• All India Rank 1219, out of 151,000 Students, Ranked in Top 0.81 % Students, JEE Advanced	
• KVPY Fellow All India Rank (AIR) 165,SX stream (12th Grade)	

• NTS Scholar–NCERT, (National Council of Education Research & Training)

2019