

Möbius Strip Modeling – Write-Up

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◆ How I Structured the Code:

The Python script is structured around an **object-oriented approach** for modularity and clarity:

1. **MobiusStrip class** encapsulates all logic:
 - Accepts radius, width, and resolution as parameters.
 - Initializes a mesh grid using `numpy.meshgrid`.
 - Computes 3D points (x, y, z) using the standard Möbius strip parametric equations.
 - Methods include:
 - `plot()` – for 3D surface visualization using matplotlib with color mapping.
 - `compute_surface_area()` – estimates surface area numerically.
 - `compute_edge_length()` – computes total edge length along the boundary.
 2. **Main block (if `__name__ == "__main__"`):**
 - Uses default (static) parameters for polished output.
 - Includes optional input (commented) to show generalization capabilities.
 - Displays key outputs and renders a 3D visualization.
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◆ How I Approximated Surface Area:

The surface area is numerically approximated using the **magnitude of the cross product** of the partial derivatives of the parametric surface:

- For a parametric surface $r(u,v)$, the area is:
$$A = \iint |(\partial r / \partial u) \times (\partial r / \partial v)| \, du \, dv$$
- I computed these partial derivatives symbolically in NumPy for:
 - $\partial r / \partial u$ and $\partial r / \partial v$
- Then, using vector cross product and norm, I integrated the resulting values using `numpy.trapz`.

This gives a **high-resolution numerical approximation** of the surface area.

◆ How I Approximated Edge Length:

The edge is defined where $v = \pm w/2$

I used:

- A fine sampling of the edge path by sweeping u from 00 to $4\pi\backslash\pi$
- Computed (x, y, z) positions along this path
- Used `np.diff()` to compute segment vectors and `np.linalg.norm()` to sum Euclidean distances between them.

This gives the **total edge length** of the Möbius strip.

◆ Challenges Faced:

- Ensuring the **visual accuracy** of the Möbius strip with the right combination of width and resolution was tricky. A higher resolution ($n = 500$) and small width ($w = 0.05$) helped maintain the expected thin and smooth appearance.
 - Handling the surface area calculation required careful use of **partial derivatives** and correct application of **numerical integration** techniques.
 - Visualizing color gradients across the 3D surface in a visually appealing way was addressed using matplotlib's colormap normalization.
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Final Thoughts:

This project was a great exercise in combining **3D parametric modeling**, **numerical integration**, and **visualization**. The code is modular, human-readable, and allows both static and dynamic usage, making it ready for further extensions (e.g., animation, interactivity).