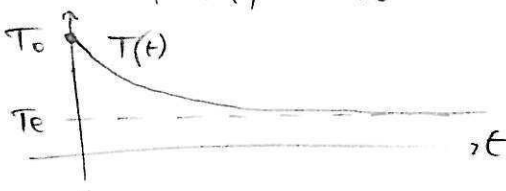


p. 40-44 #5 a)  $\begin{cases} T' = -h(T - T_e) \\ T(0) = T_0 \end{cases} \xrightarrow{\text{standard 1st order lin. form}} T' + hT = hT_e$

so  $e^{ht} T = \int hT_e e^{ht} dt + c$   
so  $T(t) = T_e + (T_0 - T_e)e^{-ht}$



b)  $T' + hT = h\theta(t) \xrightarrow{\text{solve}} T(t) = h e^{-ht} \left[ \int \theta(s) e^{hs} ds + c \right]$

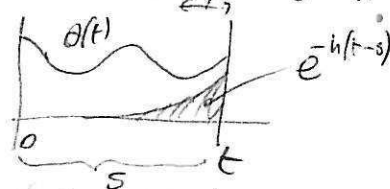
to match IC can write integral starting at  $t=0$

so it contributes nothing at  $t=0$ , so  $ch = T_0$  gives IC.

$$T(t) = h e^{-ht} \int_0^t \theta(s) e^{hs} ds + T_0 e^{-ht}$$

$$= h \int_0^t \theta(s) e^{-h(t-s)} ds + T_0 e^{-ht}$$

time of recent memory  $\sim \frac{1}{h}$

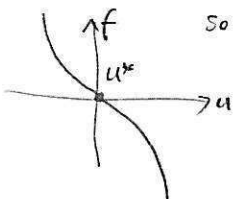


this is Duhamel's Principle:

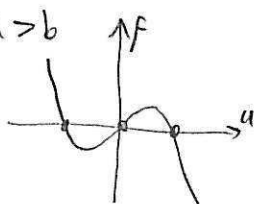
value at  $t$  is a weighted average (convolution) of recent  $\theta(t)$  values.

p. 52-54 #6  $f(u) = (\lambda - b)u - au^3 \longrightarrow f'(u) = \lambda - b - 3au^2$

a)  $\lambda < b$  so  $f'(0) < 0$  equilibrium points given by  $f(u) = 0$ ; note  $u^* = 0$  is always equilibrium.



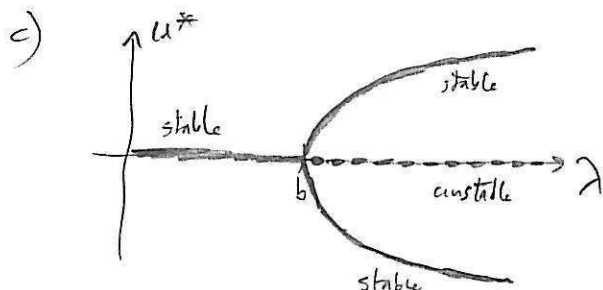
b)  $\lambda > b$  3 equilibrium points:  $u^* = 0$  now has  $f'(0) > 0$  so is unstable.



solve for other  $u^*$  (roots of  $f$ ):

$$\frac{f(u)}{u} = 0 = (\lambda - b) - au^2 \quad \text{so} \quad u^* = \pm \sqrt{\frac{\lambda - b}{a}}$$

They have  $f'(u^*) < 0$  so are stable.

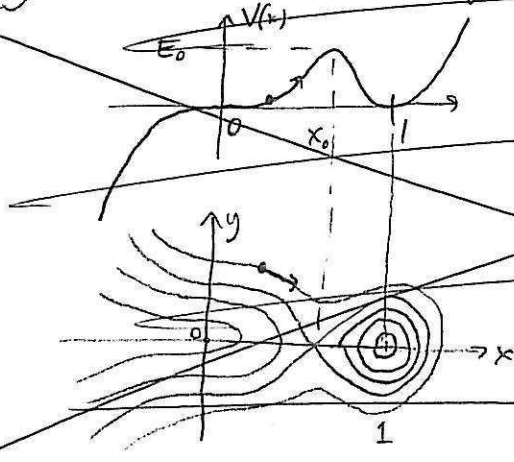


'pitchfork bifurcation'.

p.67-68 #1

Sketch  $V(x)$  then get contours (level curves) of  $E$  from it.

(2)



oscillates when trapped in potential well around  $x=1$ . (When level curve closes on itself)  
This happens only if  $E < E_0 := \max_{0 < x < 1} V(x)$

$$V'(x) = 3x^2(1-x)^2 - 2x^3(1-x) = 0$$

$$\text{so } 3(1-x) = 2x, \quad x_0 = \frac{3}{5}$$

$$\text{so } E_0 = V(x_0) = \left(\frac{3}{5}\right)^3 \left(\frac{2}{5}\right)^2 = \frac{108}{3125}$$

p.67-68 #2

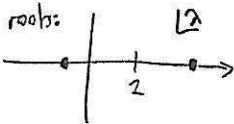
$$A = \begin{pmatrix} 3 & b \\ 1 & 1 \end{pmatrix}$$

eigvals  $\begin{vmatrix} 3-\lambda & b \\ 1 & 1-\lambda \end{vmatrix} = 0$  so  $3-4\lambda+\lambda^2-b=0$

ie  $\lambda^2 - 4\lambda + 3-b = 0$

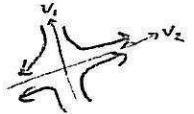
so  $\lambda = 2 \pm \sqrt{4-(3-b)} = 2 \pm \sqrt{1+b}$

$b > 3$

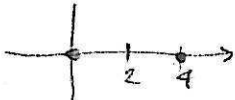


$\lambda_1 < 0 < \lambda_2$

saddle point, (unstable)



$b = 3$

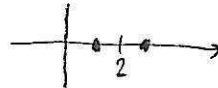


$\lambda_1 = 0 < \lambda_2$

exp. growth in one direction, neutral in other. (unstable)

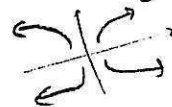


$1 < b < 3$

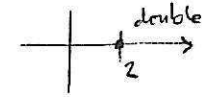


$0 < \lambda_1 < \lambda_2$

unstable node



$b = -1$



$0 < \lambda_1 = \lambda_2$

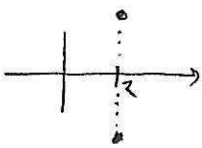
are there 2 L.I. eigenvectors in  $\lambda=2$  eigenspace?

$$A - \lambda I = \begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix}$$

which has  $\dim \text{Nul}(A - \lambda I) = 1$  ie only 1-dim eigenspace.

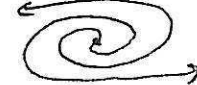
$\Rightarrow te^{\lambda t}$  behaviour, for  $\lambda > 0$ , unstable.

$b < -1$



$\lambda = 2 \pm i\beta$

unstable spiral node



#6

$$\begin{aligned} x' &= y \\ y' &= -\frac{1}{m}(kx + ay) \end{aligned}$$

ie  $\vec{x}' = A\vec{x}$  with

$$A = \begin{pmatrix} 0 & 1 \\ -\frac{k}{m} & -\frac{a}{m} \end{pmatrix}$$

eigvals.

$$-\lambda(-\frac{k}{m} - \lambda) + \frac{k}{m} = 0$$

ie  $m\lambda^2 + a\lambda + k = 0$  (same as char. eqn for 2nd order)

$$\lambda = \frac{-a}{2m} \pm \sqrt{\frac{a^2}{4m^2} - \frac{k}{m}}$$

$k=0$

$\lambda = \pm i\sqrt{\frac{k}{m}}$

center, stable but not loc. asymp. stable. (undamped SHM)

$a^2 - 4mk = 0$

$\lambda = -\frac{a}{2m}$  twice

stable node ( $\alpha e^{\lambda t} + \beta t e^{\lambda t}$  type) (critically damped)

$a^2 - 4mk < 0$

$\lambda = \alpha \pm i\beta$

stable spiral. (damped osc.)

$a^2 - 4mk > 0$

stable node  $0 < \lambda_1 < \lambda_2$  (overdamped)

p. 100-104 #3

$$e^{-t} = o(t^{-2}) \quad \text{as } t \rightarrow \infty$$

(3)

It is proved if  $\lim_{t \rightarrow \infty} \frac{e^{-t}}{t^{-2}}$  exists and is zero, equivalently  $\ln \frac{e^{-t}}{t^{-2}} \rightarrow -\infty$

$$\left[ \begin{array}{l} \ln \frac{e^{-t}}{t^{-2}} = -t + 2 \ln t \quad \text{but } \ln t = o(t) \text{ since } \lim_{t \rightarrow \infty} \frac{\ln t}{t} = \frac{1/t}{1} = \frac{1}{t} \rightarrow 0 \\ \text{so } \lim_{t \rightarrow \infty} \frac{e^{-t}}{t^{-2}} = \lim_{t \rightarrow \infty} (-t + o(t)) = -\infty \quad \text{QED} \end{array} \right.$$

L'Hôpital's rule since both  $\ln t$  and  $t$  diverge

Alternative: (simpler?)  $\lim_{t \rightarrow \infty} \frac{e^{-t}}{t^{-2}} = \lim_{t \rightarrow \infty} \frac{t^2}{e^t} \xrightarrow{\text{L'Hôpital}} \lim_{t \rightarrow \infty} \frac{2t}{e^t} \xrightarrow{\text{L'Hôpital}} \lim_{t \rightarrow \infty} \frac{2}{e^t} = 0.$

#5 d.

$$\begin{aligned} \cos \varepsilon &= 1 - \frac{\varepsilon^2}{2!} + \frac{\varepsilon^4}{4!} - \dots \quad \text{Taylor series,} \\ \text{so } \frac{\varepsilon^{1/2}}{1 - \cos \varepsilon} &= \frac{\varepsilon^{1/2}}{\varepsilon^2/2 + o(\varepsilon^4)} = 2\varepsilon^{-3/2} (1 + o(\varepsilon^2))^{-1} = 2\varepsilon^{-3/2} (1 + o(\varepsilon^2)) \\ &= O(\varepsilon^{-3/2}) \end{aligned}$$

use binomial for small  $\varepsilon^2$ .

g.  $\left| \int_0^\varepsilon e^{-x^2} dx \right| \leq \int_0^\varepsilon |e^{-x^2}| dx \leq \int_0^\varepsilon 1 dx = \varepsilon = O(\varepsilon).$

since  $|e^{-x^2}| \leq 1 \quad \forall x.$

p. 52-54

#10

$$u' = f(u) = u^3 - u + h$$

we seek roots of  $f$ , which we call  $u^*$ , at various fixed  $h$ .

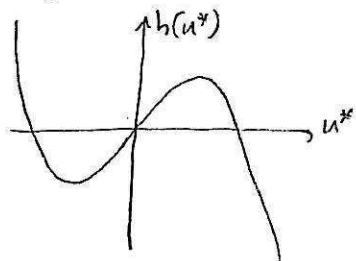
eg.  $h=0$  have  $f(u) = u^3 - u$  so  $u^* = 0, \pm 1$

At other  $h \neq 0$  it would involve solving a cubic to find  $u^*$ .

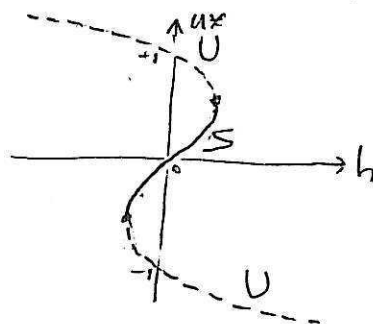
$$\left\{ \begin{array}{l} \text{and } f'(u) = 3u^2 - 1 \\ \text{so } u^* = 0 \text{ has } f'(u^*) < 0 \\ \quad \text{stable,} \\ u^* = \pm 1 \text{ has } f'(u^*) > 0, \\ \quad \text{unstable.} \end{array} \right.$$

However we seek pairs  $(u^*, h)$  in the plane. Since  $f(u)$  contains  $h$  additively this is much easier to do by fixing  $u^*$  and reading off  $h$  explicitly:

$$f(u^*) = 0 \Leftrightarrow u^{*3} - u^* + h = 0 \Leftrightarrow h = -u^{*3} + u^* \quad \text{ie a cubic for } h(u^*)$$



flip to usual axes



as usual, at the transition from  $U$  to  $S$  you get points where it's SS (semistable).

p. 102-104 (#1)

Newton's 2nd Law: net force equals mass times acceleration:

$$m\ddot{y} = -a|\dot{y}| - k y$$

magnitude  $\dot{y}^2$  but with sign of  $\dot{y}$

dimensions

$$\frac{M}{L} \begin{bmatrix} 1 & a & k & A \\ & -1 & 1 & 1 \\ & & -2 & 1 \end{bmatrix}$$

4 params.

if damping small want to choose length & time scales not involving  $a$ , which is possible since crossing out this column leaves a  $3 \times 3$  full rank matrix.

so  $\begin{cases} y_c = A \\ t_c = \sqrt{\frac{m}{k}} \end{cases}$

IC release distance.

osc. period (undamped).

rescale:

$$m \frac{y_c}{t_c^2} \bar{y}'' = -a \frac{y_c^2}{t_c^2} \bar{y}' |\bar{y}'| - k y_c \bar{y}$$

substitute & simplify ---

(use eg  $\frac{t_c^2 k}{m} = 1$ )

get.  $\begin{cases} \bar{y}'' + \frac{Aa}{m} \bar{y}' |\bar{y}'| + \bar{y} = 0 \\ \text{with } \bar{y}(0) = 1, \bar{y}'(0) = 0 \end{cases}$

so  $\epsilon = \frac{Aa}{m} \ll 1$

notice the book gives  $(\bar{y}')^2$  instead of  $\bar{y}' |\bar{y}'|$  which will not always give resistive force opposed to velocity, as it should! since damping small

#2

Unperturbed is  $u'' - u_0 = 0$  which has gen. soln.  $c_1 e^t + c_2 e^{-t}$

It is not oscillatory!

The zeroth-order always inherits original ICs, vzs.  $\begin{cases} u_0(0) = 1 \\ u_0'(0) = -1 \end{cases} \begin{cases} \text{solve for } c_1, c_2 \\ \text{get } c_1 = 0, c_2 = 1. \end{cases}$

Thus  $u_0(t)$  is special in that it couples only into the decaying solution ~ this is unusual since generic case is to have  $c_1 \neq 0$  where the growing dominates as  $t \rightarrow \infty$  (expect perturbation to cause this too!)

Subst.  $u = u_0 + \epsilon u_1, \dots$  into ODE:

$$u_0'' + \epsilon u_1'' + \dots - u_0 - \epsilon u_1 - \dots = \epsilon t u_0 + \epsilon^2 t u_1 + \dots$$

$O(\epsilon^2): u_1'' - u_1 = t u_0 = t e^{-t}$

Guess  $A t^2 e^{-t} + B t e^{-t}$

$(d/dt) \hookrightarrow 2A t e^{-t} - A t^2 e^{-t} + B e^{-t} - B t e^{-t}$

$(d/dt) \hookrightarrow -2A t e^{-t} + A t^2 e^{-t} + (2A - B) e^{-t} + (2A - B) t e^{-t} - B e^{-t}$

So ODE for  $u_1$  becomes  $\cancel{A t^2 e^{-t}} + (-4A + B) t e^{-t} + (2A - 2B) e^{-t} - \cancel{A t^2 e^{-t}} - \cancel{B t e^{-t}} = t e^{-t}$

so  $B = +A$  and  $A = -\frac{1}{4}$

Gen. soln. for  $u_1$  is  $u_1(t) = -\frac{1}{4}(t e^{-t} + t^2 e^{-t}) + c_1 e^{-t} + c_2 e^{-t}$

ICs for  $u_1$  are (see worksheet) both zero  $u_1(0) = 0, u_1'(0) = 0$  gives  $c_1 = -1/8, c_2 = 1/8$

[p, 100-104 #2 cont.]

Here's code to plot

%  $y'' + y = \epsilon \sin t$  ..... convert to 1st-order system  $y_1' = y_2$ ,  $y_2' = y_1(1 + \epsilon \sin t)$

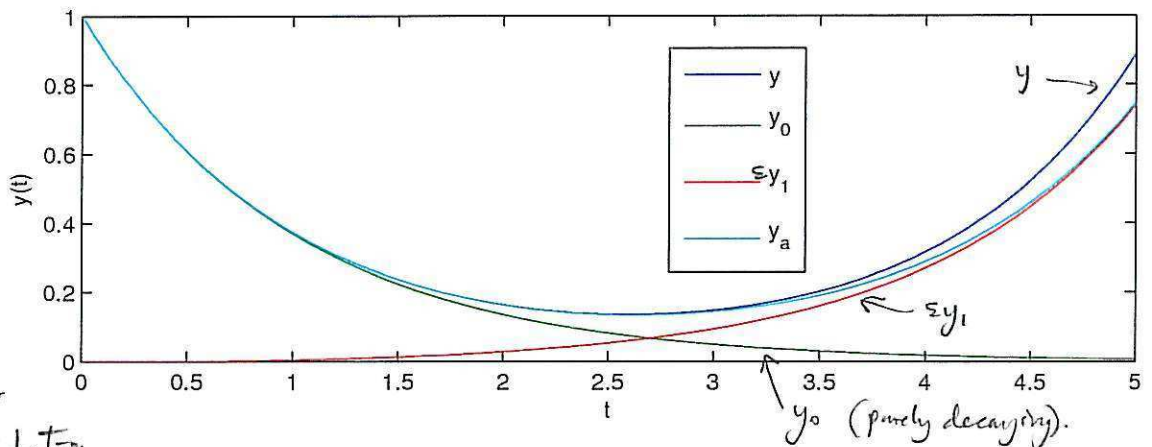
```
eps = 0.04;
f = @(t,y) [y(2); y(1).*(1+eps*t)]; % construct a vector func to rep ODE
y0 = [1; -1];
tmax = 5;
[t,y] = ode45(f, [0, tmax], y0);
figure; plot(t, y(:,1), 'k-'); xlabel t; ylabel y(t); % check your solution
```

```
y0 = exp(-t); % zeroth-order
y1 = -(1+t).*t.*exp(-t) / 4 + (exp(t)-exp(-t))/8; % first-order
ya = y0 + eps*y1; % 2-term approximation
E = ya - y(:,1); % error vs time
```

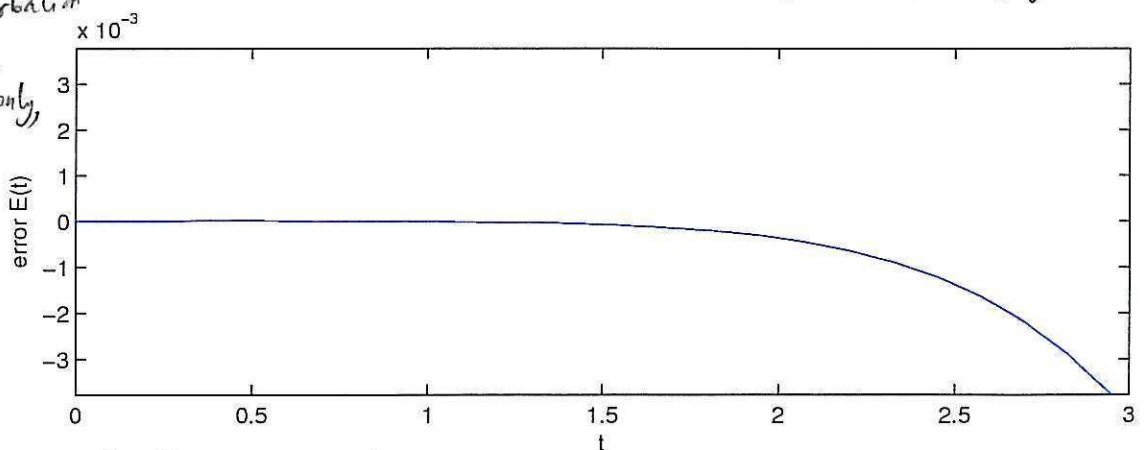
```
figure; subplot(2,1,1); % allows you to put multiple plots on one figure
plot(t, [y(:,1) y0 eps*y1 ya], '-'); % plot the 4 curves asked for
xlabel t; ylabel y(t); legend('y', 'y_0', 'y_1', 'y_a');
subplot(2,1,2); plot(t, E, '-'); xlabel t; ylabel('error E(t)');
T=3; v = max(abs(E(find(t<T)))); axis([0 T -v v]); % trick: zoom in correctly
print -depsc2 p100_ex2.eps % make a printable file
```

this analytic formula  
is what the  
Method of  
Und. Coeffs  
gave us.

you can replace  
this line with  
the simpler  
 $\text{axis}([0 \ 3 \ -4e-3 \ 4e-3]);$   
if you want.



Note that the perturbation  
has broken the special  
condition of decaying only,  
so there's some growing  
 $e^t$ , which of course  
rapidly dominates!



Notice how small the error is! We've done a great job even with  
going to only 1st-order in  $\epsilon$ .

#8) a.

$$y'' + y = \varepsilon y y'^2$$

$$\text{ICs: } y(0) = 1, y'(0) = 0$$

$$\varepsilon = 0 \text{ zeroth order } y'' + y = 0$$

$$\text{has } y_0(t) = A \cos t + B \sin t$$

$$\xrightarrow{\text{match ICs}} A=1, B=0$$

$$\text{so } y_0 = \cos t$$

$$\tau = \omega t \quad \text{with } \omega = 1 + \varepsilon \omega_1 + \dots$$

$$\text{sub. in ODE: } \omega^2 y'' + y = \varepsilon y (\omega y')^2 \quad \text{where now prime means } \frac{d}{d\tau}$$

$$\Rightarrow (1 + \varepsilon \omega_1 + \dots)^2 (y_0'' + \varepsilon y_1'' + \dots) + y_0 + \varepsilon y_1 + \dots = \varepsilon (y_0 + \varepsilon y_1 + \dots) (1 + \varepsilon \omega_1 + \dots)^2 (y_0' + \varepsilon y_1' + \dots)^2$$

We've already done  $O(\varepsilon^0)$  which gave  $y_0(\tau) = \cos \tau$

$$O(\varepsilon^1): 2\omega_1 y_0'' + y_1'' + y_1 = y_0 y_0'^2$$

sub  $y_0$ :

$$y_1'' + y_1 = \underbrace{\cos \tau \sin^2 \tau}_{\text{want to extract Fourier components to try to cancel secular term (on-resonance driving eg. } \sin \tau \text{ or } \cos \tau)} - 2\omega_1 (-\cos \tau)$$

Same differential operator (LHS) as for  $y_0$ , so homogeneous solns. are  $\sin \tau, \cos \tau$ .

$$\begin{aligned} \cos \tau \sin^2 \tau &= \frac{1}{2} \left( \frac{1}{2i} (e^{i\tau} + e^{-i\tau}) \right) (e^{i\tau} - e^{-i\tau})^2 \\ &= \frac{-1}{8} [e^{3i\tau} + (1-2)e^{i\tau} + (-2+1)e^{-i\tau} + e^{-3i\tau}] \\ &= -\frac{1}{4} \cos 3\tau + \frac{1}{4} \cos \tau \end{aligned}$$

so choose  $\omega_1 = -\frac{1}{8}$  to cancel secular  $\cos \tau$  term in the driving.

Then use Meth. Und. Coeffs:

$$y_1'' + y_1 = -\frac{1}{4} \cos 3\tau$$

$$\left. \begin{aligned} y_1(\tau) &= A \cos 3\tau \\ y_1'' &= -9A \cos 3\tau \end{aligned} \right\} \text{ so } -9A + A = -\frac{1}{4} \quad \text{so } A = \frac{1}{32}$$

Don't forget to match  $y_1$  to its ICs ( $y_1(0) = y_1'(0) = 0$ ):  $y_1(\tau) = \frac{1}{32} \cos 3\tau + c_1 \cos \tau + c_2 \sin \tau$

$$y_1(\tau) = \frac{1}{32} (\cos 3\tau - \cos \tau) \quad \text{so } c_1 = -\frac{1}{32}, c_2 = 0$$

Put together: 
$$y_n = \cos \tau + \frac{\varepsilon}{32} (\cos 3\tau - \cos \tau) \dots \quad \text{where } \tau = \left(1 - \frac{\varepsilon}{8} + \dots\right) t$$

binomial expansion

Recall  $(1+x)^n = 1 + nx + \frac{n(n-1)}{2!}x^2 + \frac{n(n-1)(n-2)}{3!}x^3 + \dots$

holds for any real  $n$ , and any  $x$ . (although series won't converge if  $|x| > 1$  and  $n \neq 0, 1, 2, 3, \dots$ )

Use  $\begin{cases} x = \varepsilon y \\ n = -\frac{1}{2} \end{cases} = \varepsilon y_0 + \varepsilon^2 y_1 + \dots$

So  $f(y, \varepsilon) = 1 - \frac{3}{2}(\varepsilon y_0 + \varepsilon^2 y_1 + \dots) + \frac{(-\frac{1}{2})(-\frac{1}{2})}{2!}(\varepsilon y_0 + \dots)^2 + \dots$

$= 1 - \frac{3}{2}\varepsilon y_0 + \left(-\frac{1}{2}y_1 + \frac{15}{8}y_0^2\right)\varepsilon^2 + O(\varepsilon^3)$



$$= -1 + 2\varepsilon h - 3\varepsilon^2 h^2 + O(\varepsilon^3)$$

use binomial as above (now you see why we did it!)

Sub.  $h = h_0 + \varepsilon h_1 + \varepsilon^2 h_2 + \dots$ :

$$h_0'' + \varepsilon h_1'' + \varepsilon^2 h_2'' + \dots = -1 + 2\varepsilon(h_0 + \varepsilon h_1 + \dots) - 3\varepsilon^2(h_0 + \dots)^2 + \dots$$

Compare powers of  $\varepsilon$ :

$O(\varepsilon^0)$ :  $h_0'' = -1$  integrate twice ie  $h_0(t) = -\frac{t^2}{2} + at + b$  ICs give  $a=1, b=0$   
so  $h_0(t) = t - \frac{t^2}{2}$

$O(\varepsilon^1)$ :  $h_1'' = 2h_0 = 2t - t^2$

integrate once so  $h_1'(t) = t^2 - \frac{t^3}{3} + \dots$  zero by IC  $h_1'(0) = 0$

integrate  $\hookrightarrow h_1(t) = \frac{t^3}{3} - \frac{t^4}{12} + \dots$  zero since  $h_1(0) = 0$

$O(\varepsilon^2)$ :  $h_2'' = 2h_1 - 3h_0^2 = \frac{2}{3}t^3 - \frac{1}{6}t^4 - 3(t - \frac{t^2}{2})^2$

$$= -3t^2 + \frac{11}{3}t^3 - \frac{1}{12}t^4$$

again integrate twice w/ both ICs zero so  $h_2(t) = -\frac{1}{4}t^4 + \frac{11}{60}t^5 - \frac{11}{360}t^6$

Answer:  $h(t) = t - \frac{t^2}{2} + \varepsilon\left(\frac{t^3}{3} - \frac{t^4}{12}\right) + \varepsilon^2\left(-\frac{t^4}{4} + \frac{11}{60}t^5 - \frac{11}{360}t^6\right) + \dots$  only use 2-term for max height.

its derivative vanishes at  $t = t_m$ , ie  $1 - t + \varepsilon(t^2 - \frac{t^3}{3}) = 0$  Subst.  $t = 1 + \varepsilon\alpha + \dots$

So  $1 - 1 - \varepsilon\alpha + \varepsilon(1 + 2\varepsilon\alpha + \dots - \frac{1}{3} - \varepsilon\alpha + \dots) = 0 \Rightarrow \alpha = \frac{2}{3}$ ,  $t_m = 1 + \frac{2}{3}\varepsilon + \dots$

Subst.  $t_m$  into  $h(t)$  to get  $h_{\max} = h(1 + \frac{2}{3}\varepsilon + \dots) = 1 + \frac{2}{3}\varepsilon - \frac{1}{2} - \frac{2}{3}\varepsilon + \dots = \frac{1}{2} + O(\varepsilon^2) \dots$