

Math 11, Fall 2007

Lecture 2

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Outline

- 1 Recap and overview
 - Last class
 - Quick review of reading topics
- 2 Further discussion
 - Examples
 - Group Work
- 3 Summary
- 4 Next class

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Coordinates in three space

- (x, y, z) coordinates to denote points
- Planes: $\alpha x + \beta y + \gamma z + \delta = 0$
- Spheres: $(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = r^2$

Vectors in three space

- Vectors have magnitude and direction
- $\langle x, y, z \rangle$ coordinates to denote vectors
- We intentionally confuse points and vectors
- Vector operations: both numeric and geometric

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Concepts from reading

- Multiplication of vectors, $\vec{u} = \langle a, b, c \rangle$, $\vec{v} = \langle d, e, f \rangle$

- 1 dot product:

$$\vec{u} \cdot \vec{v} = ad + be + cf$$

- 2 cross product:

$$\vec{u} \times \vec{v} = \langle bf - ce, cd - af, ae - bd \rangle$$

- Geometric meaning:

- 1 The dot product measures angles:

$$\vec{u} \cdot \vec{v} = |\vec{u}| |\vec{v}| \cos(\theta)$$

- 2 The cross product measures area: $|\vec{u} \times \vec{v}|$ is the area of the parallelogram determined by \vec{u} and \vec{v} .

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Components and Projections

$$\text{comp}_{\vec{u}} \vec{v} = \frac{\vec{u} \cdot \vec{v}}{|\vec{u}|}$$

$$\text{proj}_{\vec{u}} \vec{v} = (\text{comp}_{\vec{u}} \vec{v}) \frac{\vec{u}}{|\vec{u}|} = \frac{\vec{u} \cdot \vec{v}}{|\vec{u}|^2} \vec{u}$$

Sample problem types

- Find dot products
- Find projections, components
- Find cross products

Properties of the cross product

- $\vec{u} \times \vec{v}$ is perpendicular to both \vec{u} and \vec{v}
- If θ denotes the angle between \vec{u} and \vec{v} then

$$|\vec{u} \times \vec{v}| = |\vec{u}||\vec{v}| \sin(\theta)$$

- Two nonzero vectors are parallel if and only if their cross product is zero.
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Examples: dot product

- 1 Find all vectors that are perpendicular to $\vec{u} = \langle 1, 2 - 2 \rangle$
- 2 If a force, \vec{F} , moves an object from point P to point Q , the work done by this force is $W = \vec{F} \cdot \vec{D}$ where $D = \vec{PQ}$.
Gravity acts on a box positioned at the top of a 45 degree incline. The box moves 3 m down the ramp, how much work is done?

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Examples: cross product

- 1 Torque is defined to be the cross product of the position and force vectors:

$$\vec{\tau} = \vec{r} \times \vec{F}$$

A wrench 30cm long lies along the positive y-axis and grips a bolt at the origin. A force is applied in the direction $\langle 0, 3, -4 \rangle$ at the end of the wrench. Find the magnitude of the force needed to supply 100 J of torque to the bolt.

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Problems to work on

- 1 Let $\vec{v} = 5\vec{j}$ and let \vec{u} be a variable vector in the xy -plane whose tip lies on the circle of radius 3. Find the maximum and minimum values of the length of the vector $\vec{u} \times \vec{v}$. In what direction does $\vec{u} \times \vec{v}$ point?
- 2 Prove that $\vec{u} \times \vec{v}$ is perpendicular to \vec{u} and \vec{v}

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Summary

- dot product: measures angle, projections, components, work
- cross product: measures volume/area, torque, cross product is perpendicular to components

Work for next class

- Reading: 13.5
- f07hw3