

BFS 2

```
import collections
```

```
# Function to perform Breadth First Search
```

```
def bfs(graph, start, goal):
```

```
    visited = set() # Set to keep track of visited vertices
```

```
    queue = collections.deque([start]) # Queue for BFS traversal
```

```
    visited.add(start) # Mark the start vertex as visited
```

```
    while queue:
```

```
        vertex = queue.popleft()
```

```
        print(vertex)
```

```
        # Check if the current vertex is the goal
```

```
        if vertex == goal:
```

```
            print("GOAL FOUND")
```

```
            return
```

```
        # Visit all the adjacent vertices of the current vertex
```

```
        for neighbor in graph[vertex]:
```

```
            if neighbor not in visited:
```

```
                queue.append(neighbor)
```

```
                visited.add(neighbor)
```

```
# Main program
```

```
if __name__ == "__main__":
```

```
    graph = collections.defaultdict(list)
```

```
    # Get the number of nodes from the user
```

```
    num_nodes = int(input("Enter the number of nodes: "))
```

```
# Construct the graph
for i in range(1, num_nodes + 1):
    node = input("Enter node {}: ".format(i))
    adj_nodes = int(input("Enter the number of adjacent nodes: "))
    for j in range(adj_nodes):
        adj_node = input("Enter adjacent node: ")
        graph[node].append(adj_node)

start_node = input("Enter the starting node: ")
goal_node = input("Enter the goal node: ")

# Perform BFS
print("BFS traversal:")
bfs(graph, start_node, goal_node)
```