First assignment - Solution

Problem setting

Observations

Let

$$\mathbf{x} = [x_1, \dots, x_N] \tag{1}$$

be a row vector of features and let

$$\mathbf{t} = [t_1, \dots, t_C] \tag{2}$$

be a one-hot encoded row vector corresponding to the class of \mathbf{x} , i.e.

$$t_k \in \{0, 1\} \quad \forall k \tag{3}$$

and

$$\sum_{k=1}^{C} t_k = 1 \tag{4}$$

such that $t_k = 1$ if and only if **x** belongs to class k.

Model

Let **W** be a $N \times H$ matrix, **V** be a $H \times C$ matrix, **b** be a H-dimensional row vector and **d** be a C-dimensional row vector.

We define a one-hidden-layer MLP classifier as follows: let

$$\mathbf{h} = \sigma(\mathbf{x}\mathbf{W} + \mathbf{b}) \tag{5}$$

where

$$\sigma(z) = \frac{1}{1 + e^{-z}} \tag{6}$$

is the sigmoid elementwise nonlinearity, and let

$$\mathbf{y} = \operatorname{softmax}(\mathbf{h}\mathbf{V} + \mathbf{d}) \tag{7}$$

where

$$softmax(\mathbf{z}) = \frac{e^{\mathbf{z}}}{e^{\mathbf{z}} \cdot \mathbf{1}} = \frac{e^{\mathbf{z}}}{\sum_{i} e^{z_{i}}}$$
(8)

is a normalized version of the exponential elementwise nonlinearity. Finally, let

$$\mathcal{L} = -\mathbf{t} \cdot \log \mathbf{y} = -\sum_{k=1}^{C} t_k \log y_k \tag{9}$$

be the loss function of the MLP classifier.

Solution

Function derivatives

Sigmoid

$$\frac{d}{dz}\sigma(z) = \frac{d}{dz}(1+e^{-z})^{-1}$$

$$= -(1+e^{-z})^{-2} \cdot -e^{-z}$$

$$= \frac{1}{1+e^{-z}} \frac{e^{-z}+1-1}{1+e^{-z}}$$

$$= \frac{1}{1+e^{-z}} \left(1 - \frac{1}{1+e^{-z}}\right)$$

$$= \sigma(z)(1-\sigma(z))$$
(10)

Softmax

Let $\mathbf{s} = \operatorname{softmax}(\mathbf{z})$ be the softmax function. Then

$$\frac{\partial s_k}{\partial z_l} = \frac{\partial}{\partial z_l} \frac{e^{z_k}}{\sum_r e^{z_r}}$$

$$= \frac{\delta_{k,l} e^{z_k} - e^{z_k} e^{z_l}}{\left(\sum_r e^{z_r}\right)^2}$$

$$= s_k (\delta_{k,l} - s_l)$$
(11)

Scalar derivatives

Derivatives with respect to y

$$\frac{\partial \mathcal{L}}{\partial y_k} = \frac{\partial}{\partial y_k} \sum_{r=1}^{C} -t_r \log y_r = -\frac{t_k}{y_k}$$
(12)

Derivatives with respect to h

$$\frac{\partial y_k}{\partial h_j} = \sum_{r=1}^C \frac{\partial y_k}{\partial (\sum_{s=1}^H h_s V_{s,r} + d_r)} \frac{\partial (\sum_{s=1}^H h_s V_{s,r} + d_r)}{\partial h_j}$$

$$= \sum_{r=1}^C y_k (\delta_{k,r} - y_r) V_{j,r}$$

$$= y_k V_{j,k} - y_k \sum_{r=1}^C y_r V_{j,r}$$
(13)

This means

$$\frac{\partial \mathcal{L}}{\partial h_{j}} = \sum_{k=1}^{C} \frac{\partial \mathcal{L}}{\partial y_{k}} \frac{\partial y_{k}}{\partial h_{j}}$$

$$= \sum_{k=1}^{C} -t_{k} \left(V_{j,k} - \sum_{r=1}^{C} y_{r} V_{j,r} \right)$$

$$= \sum_{k=1}^{C} -t_{k} V_{j,k} + \left[\sum_{k=1}^{C} t_{k} \right] \left[\sum_{r=1}^{C} y_{r} V_{j,r} \right]$$

$$= \sum_{k=1}^{C} -t_{k} V_{j,k} + \sum_{r=1}^{C} y_{r} V_{j,r} \quad \text{(because } \sum_{k} t_{k} = 1 \text{ by definition)}$$

$$= \sum_{k=1}^{C} V_{j,k} (y_{k} - t_{k})$$
(14)

Derivatives with respect to V

$$\frac{\partial y_r}{\partial V_{j,k}} = \frac{\partial y_r}{\partial (\sum_{s=1}^H h_s V_{s,k} + d_k)} \frac{\partial (\sum_{s=1}^H h_s V_{s,k} + d_k)}{\partial V_{j,k}}
= y_r (\delta_{k,r} - y_k) h_j$$
(15)

This means

$$\frac{\partial \mathcal{L}}{\partial V_{j,k}} = \sum_{r=1}^{C} \frac{\partial \mathcal{L}}{\partial y_r} \frac{\partial y_r}{\partial V_{j,k}}$$

$$= \sum_{r=1}^{C} -t_r (\delta_{k,r} - y_k) h_j$$

$$= \left[\sum_{r=1}^{C} t_r \right] y_k h_j - t_k h_j$$

$$= (y_k - t_k) h_j \quad \text{(because } \sum_r t_r = 1 \text{ by definition)}$$
(16)

Derivatives with respect to d

$$\frac{\partial y_r}{\partial d_k} = \frac{\partial y_r}{\partial (\sum_{s=1}^H h_s V_{s,k} + d_k)} \frac{\partial (\sum_{s=1}^H h_s V_{s,k} + d_k)}{\partial d_k}
= y_r (\delta_{k,r} - y_k)$$
(17)

This means

$$\frac{\partial \mathcal{L}}{\partial d_k} = \sum_{r=1}^C \frac{\partial \mathcal{L}}{\partial y_r} \frac{\partial y_r}{\partial d_k}$$

$$= \sum_{r=1}^C -t_r (\delta_{k,r} - y_k)$$

$$= \left[\sum_{r=1}^C t_r\right] y_k - t_k$$

$$= y_k - t_k \quad \text{(because } \sum_r t_r = 1 \text{ by definition)}$$
(18)

Derivatives with respect to W

$$\frac{\partial h_j}{\partial W_{i,j}} = \frac{\partial h_j}{\partial (\sum_{s=1}^A x_s W_{s,j} + b_j)} \frac{\partial (\sum_{s=1}^A x_s W_{s,j} + b_j)}{\partial W_{i,j}}$$

$$= h_j (1 - h_j) x_i \tag{19}$$

This means

$$\frac{\partial \mathcal{L}}{\partial W_{i,j}} = \frac{\partial \mathcal{L}}{\partial h_j} \frac{\partial h_j}{\partial W_{i,j}}$$

$$= \sum_{k=1}^{C} V_{j,k} (y_k - t_k) h_j (1 - h_j) x_i$$
(20)

Derivatives with respect to b

$$\frac{\partial h_j}{\partial b_j} = \frac{\partial h_j}{\partial (\sum_{s=1}^A x_s W_{s,j} + b_j)} \frac{\partial (\sum_{s=1}^A x_s W_{s,j} + b_j)}{\partial b_j}
= h_j (1 - h_j)$$
(21)

This means

$$\frac{\partial \mathcal{L}}{\partial b_j} = \frac{\partial \mathcal{L}}{\partial h_j} \frac{\partial h_j}{\partial b_j}
= \sum_{k=1}^{C} V_{j,k} (y_k - t_k) h_j (1 - h_j)$$
(22)

Matrix and vector derivatives

From previous results, it is straightforward to verify that

$$\frac{\partial \mathcal{L}}{\partial \mathbf{V}} = \mathbf{h}^{T}(\mathbf{y} - \mathbf{t}),$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{d}} = \mathbf{y} - \mathbf{t},$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{W}} = \mathbf{x}^{T} \left[(\mathbf{y} - \mathbf{t}) \mathbf{V}^{T} \odot \mathbf{h} \odot (\mathbf{1} - \mathbf{h}) \right],$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{b}} = (\mathbf{y} - \mathbf{t}) \mathbf{V}^{T} \odot \mathbf{h} \odot (\mathbf{1} - \mathbf{h})$$
(23)