

Introduction :

Background :

Figure : Bot in a mango field.

Significance and scope :

Figure : Similar bot ~~as~~ made by others  
(2 figures needed)

Literature review :

Agricultural Robots :

Papers (cite number)	Objective & Application	Findings	Structure
			(Picture)
		(At least 4 robots)	

Human-Robot Interaction (HRI) in Agricultural Bots :

→ New section add ~~as per~~

→ Enhancing Efficiency ~~and occur in Autonomous robotic system:~~

{ Add a similar table like Table(1) }

{ Accuracy vs Epochs graph with other mentioned model }

→ Cost-Effective Innovation with Enhanced Mobility :

{ 2nd part of Table ~~as per~~ ~~as per~~ Just ~~as per~~ ~~as per~~ }

→ AI Implementation :

{ Add a similar table like Table(1) }

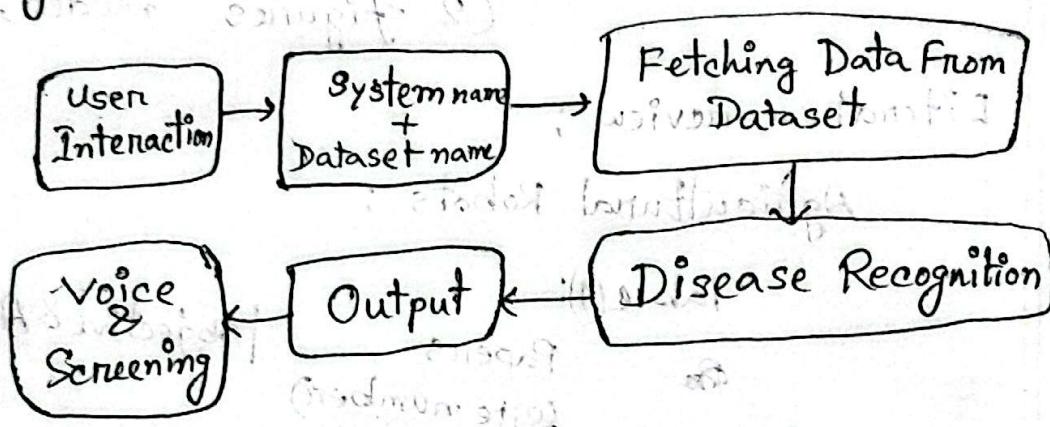
→ User interaction & Evaluation :

System design :

Figure : Agribot 3D Design  
(Labeled!)

Comprehensive functionality :

Figure :



(Block Diagram of Agribot)

Robot Hardware :

Figure : (Image/Picture3.png)

Component Diagram

Interaction Design : (Image/Picture1A)

Figure : (Image/Picture4.png)

Interaction Design diagram

Voice Interaction Design

Figure : (System reply screenshot)

Question & Response Interface

Requirement Gathering and System Specification;  
Figure ; Survey Results .

Prototype Development & Iteration ;

Figure 1 (Image/ Picture 12. png)

(Survey based on 39 randomly Trial & Evaluation based Building Process)

Software Development :

Figure : (Bot  $\Rightarrow$  Screen  $\Rightarrow$  pic)

Interface of the Robot .

Environment Design :

Figure : (Cylinder  $\Rightarrow$  pic)

Mango field environment view

Architecture of Agriobot ;

Design Overview ;

Figure : 3d [full] body [Not Labeled]

Disease Detection Module :

Figure : (Image / Picture 14. png)

Navigation module :

Figure : (Robot  $\Rightarrow$  Base  $\Rightarrow$  3D view)

Framework of hardware:

Functional Description :

Figure : (Raspberry Pi go Labeled view)

(Image / Picture 17.png)

Figure : (Image / Picture 18.png)

Arduino go pic.

(Basically saying Hardware & component go Labeled picture)

Comprehensive system Integration :

Table (2) :

components	Specifications	Price (\$)	Price (Bdt)
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Main Interface :

Figure : (Software Interface go pic)

Dataset :

New  
Add  
যোগ

Preference for a Agricultural Robot's appearance and characteristics :

(New subsection adds a lot with questions for participants like "What should the robot look like?" etc.) with pie charts of answers.