

## Encoders

optical Encoder, digital outputs, 3 channels,  
1000 - 10000 lines per revolution, Line Driver

For combination with  
DC-Micromotors  
Brushless DC-Motors

### Series IER3-10000 L

	IER3	-1000	-2000	-4000	-1024	-2048	-4096	-1700	-3400	-6800	-2500	-5000	-10000	L	
Lines per revolution	<i>N</i>	1000	2000	4000	1024	2048	4096	1700	3400	6800	2500	5000	10000		
Frequency range, up to <sup>1)</sup>	<i>f</i>	250	500	1000	250	500	1000	250	500	1000	250	500	1000	kHz	
Signal output, square wave		2+1 Index and complementary outputs													Channels
Supply voltage	<i>U<sub>DD</sub></i>	4,5 ... 5,5													V
Current consumption <sup>2)</sup>	<i>I<sub>DD</sub></i>	typ. 27, max. 50													mA
Index Pulse width	<i>P<sub>0</sub></i>	90 ± 15													°e
Phase shift, channel A to B	<i>Φ</i>	90 ± 20													°e
Inertia of code disc, typ.	<i>J</i>	0,14													gcm <sup>2</sup>
Operating temperature range <sup>3)</sup>		- 20 ... + 85													°C
Accuracy, typ.		0,3			0,3			0,2			0,1			°m	
Repeatability, typ.		0,05													°m
Hysteresis		< 0,05													°m
Edge spacing, min.		125													ns
Mass, typ.		13,5													g

<sup>1)</sup> Velocity (min<sup>-1</sup>) = *f* (Hz) x 60/*N*

<sup>2)</sup> *U<sub>DD</sub>* = 5V: with unloaded outputs

<sup>3)</sup> Operating temperature range - 40 ... + 85 °C available on request

**Note:** The output signals are TIA-422 compatible. Examples of Line Driver Receivers: ST26C32AB (STM), AM26C32 (TI).

Product combination	IER3	-1000 -2000 -4000	-1024 -2048 -4096	-1700 -3400 -6800	-2500 -5000 -10000	L
Series	Motor, <L1 [mm]	Motor, <L1 [mm]	Motor, <L1 [mm]	Motor, <L1 [mm]	Motor, <L1 [mm]	Drawing
2214 ... BXT H	26,8	26,8	–	–	–	A
3216 ... BXT H	28,7	28,7	–	–	–	A
4221 ... BXT H	34,0	34,0	–	–	–	A
2264 ... BP4	79,1	79,1	–	–	–	B
3274 ... BP4	90,8	90,8	–	–	–	B
2237 ... CXR	52,5	52,5	–	–	–	B
2642 ... CXR	60,5	60,5	–	–	–	C
2657 ... CXR	75,5	75,5	–	–	–	C
2342 ... CR	60,5	60,5	–	–	–	C
2642 ... CR	60,5	60,5	–	–	–	C
2657 ... CR	75,5	75,5	–	–	–	C
2668 ... CR	86,5	86,5	–	–	–	C
3242 ... CR	60,5	60,5	–	–	–	C
3257 ... CR	75,5	75,5	–	–	–	C
3272 ... CR	90,5	90,5	–	–	–	C
3863 ... CR - 2016	82,6	82,6	–	–	–	D
3890 ... CR - 2016	108,6	108,6	–	–	–	D
2232 ... BX4	50,2	50,2	50,2	–	–	E
2250 ... BX4S	68,2	68,2	68,2	–	–	E
2250 ... BX4	68,2	68,2	68,2	–	–	E
3242 ... BX4	60,0	60,0	60,0	60,0	60,0	F
3268 ... BX4	86,0	86,0	86,0	86,0	86,0	F

**Note:** Please note that the available pulse numbers depend on the attachment system and therefore not all motors are available with all pulse numbers. The available pulse numbers for each motor are listed under the Combinatorics section.

#### Characteristics

These incremental encoders with 3 output channels, in combination with the FAULHABER Motors, are used for the indication and control of both shaft velocity and direction of rotation as well as for positioning.

With a reflective code disc two square wave signals with 90° phase shift and one index impulse per motor revolution are generated.

The optical measurement principle allows high accuracy and repeatability for positioning applications. The high resolution encoder provides up to 4096 lines per revolution. In combination with the brushless DC-Servomotors BX4 with diameter 22 mm up to 6800 lines per revolution are available. In combination with the brushless DC-Servomotors BX4 with diameter 32 mm up to 10000 lines per revolution are available.

The Line Driver version has differential signal outputs (TIA-422). Differential signals reduce ambient interference and are suitable for applications with high ambient interference.

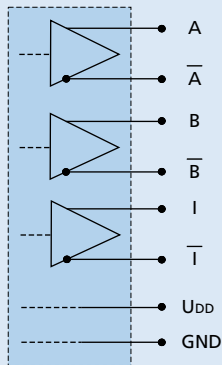
The Line Driver amplifies the encoder signal which means that long cables can be used without signal degradation. Differential signal outputs must be decoded by the appropriate receiver module. In addition, a suitable line termination resistance (100 ohm) is possibly useful.

The encoder is connected via a ribbon cable. The pins are compatible to the FAULHABER Encoder IE3 L.

To view our large range of accessory parts, please refer to the "Accessories" chapter.

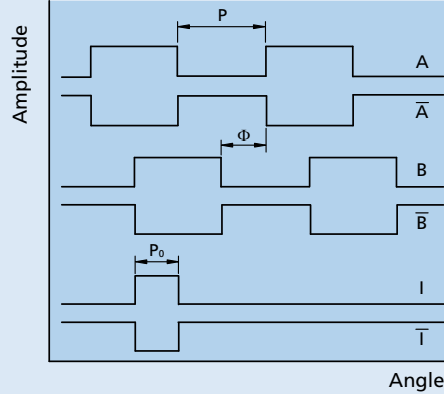
## Circuit diagram / Output signals

### Output circuit



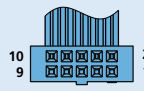
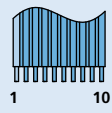


### Output signals

with clockwise rotation as seen from the shaft end



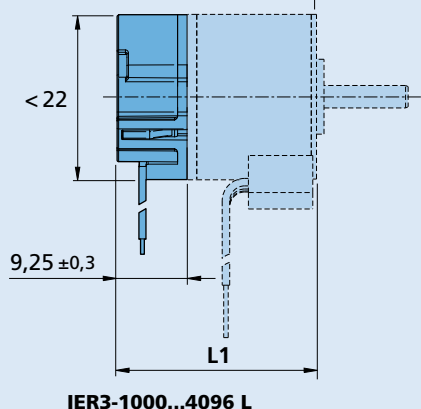
## Connector information / Variants

Example product designation: 2232S024BX4 IER3-6800L 3589

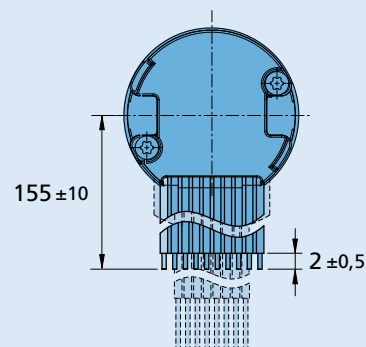
Option	Type	Description	Connection Encoder
3806	Connector 	for combination with DC-Motors series CR, CXR and with Brushless DC-Motor series BP4 and BXT H. Connector variants AWG 28 / PVC ribbon cable with connector EN 60603-13 / DIN-41651.	<b>No. Function</b> 1 N.C. 2 UDD 3 GND 4 N.C. 5 Channel A 6 Channel A 7 Channel B 8 Channel B 9 Channel I 10 Channel I  <b>Standard cable</b> PVC-ribbon cable, 10-AWG 28, 1,27 mm <b>Caution:</b> Incorrect lead connection will damage the motor electronics!
3589	Connector 	for combination with Brushless DC-Motors series BX4. Connector variants AWG 28 / PVC ribbon cable with connector EN 60603-13 / DIN-41651.  Inclusive motor connector 3830	

## Dimensional drawing A

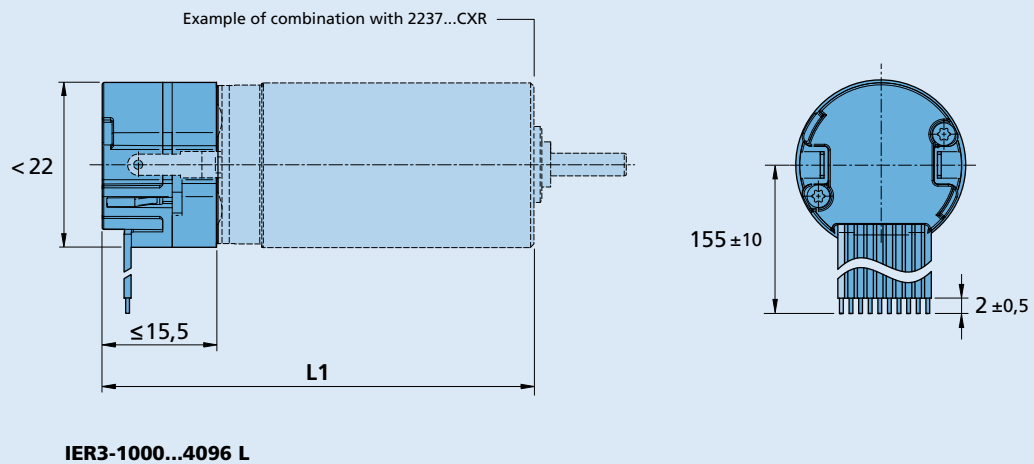
Example of combination with 2214...BXTH



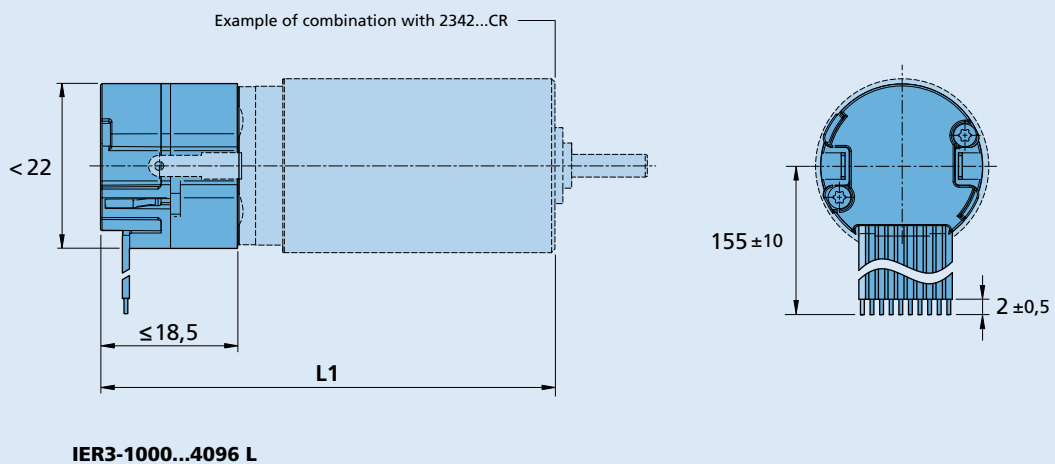
IER3-1000...4096 L



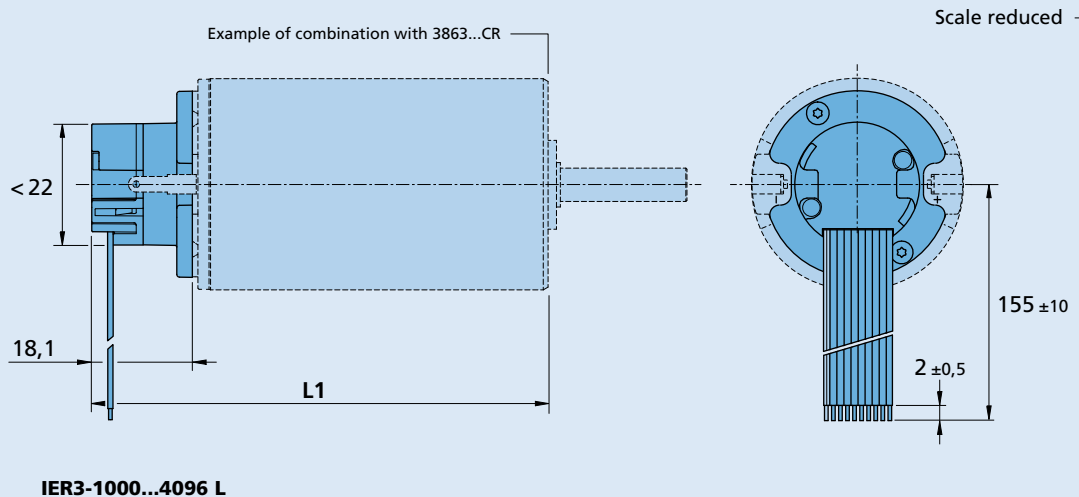
### Dimensional drawing B



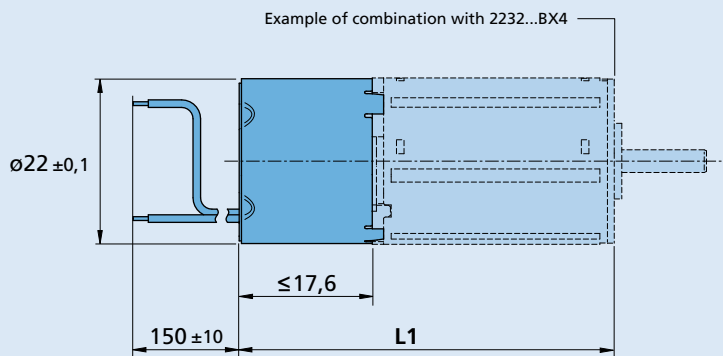
### Dimensional drawing C



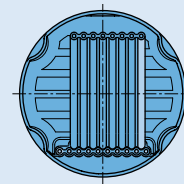
### Dimensional drawing D



## Dimensional drawing E



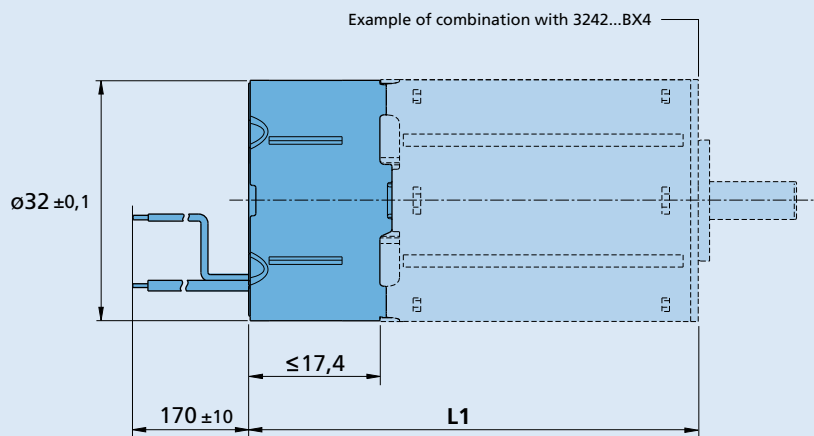
Connection Motor



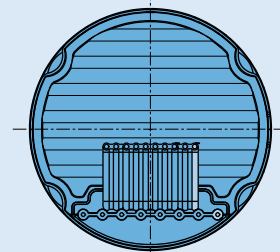
Connection Encoder

IER3-1000...6800 L

## Dimensional drawing F



Connection Encoder



Connection Motor

IER3-1000...10000 L