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Tokamak Magnetic Control Simulation: Applications for JT60-SA and ISTTOK Operation.

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ABSTRACT			
Abstract en ingles			

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RESUMO

Abstract em tuga

Palavras-chave:

SOMMARIO

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LIST OF ABBREVIATIONS

@TODO: Review variable lists as writing the thesis

- AC Alternating Current
- ADC Analog to Digital Converter
- ATCA Advanced Telecommunications Computing Architecture
- CREATE Consorzio di Ricerca per l'Energia, l'Automazione e le Tecnologie dell'Elettromagnetismo
- DAC Digital to Analog Converter
- EO Electronic Offset
- IST Instituto Superior Técnico
- LQR Linear Quadratic Regulator
- MARTe Multi-threaded Application Real-Time executor
- MIMO Multiple-Input Multiple-Output
- PCS Plasma Control System
- PF Poloidal Field
- PID Proportional Integrative Derivative
- XSC eXtreme Shape Controller
- WO Wiring Offset

LIST OF VARIABLES

@TODO: Review variable lists as writing the thesis

VARIABLES:

 \bullet B_p - Poloidal magnetic field

• I_p - Plasma current

• μ_0 - Vacuum permeability

INTRODUCTION

- 1.1 TOKAMAK PLASMA CONTROL
- 1.2 BEHIND THE PLASMA CURRENT
- 1.3 THESIS OUTLINE

PLASMA CONTROL SYSTEMS

2.1 OVERVIEW OF CONTROL SYSTEMS

The control of plasma position, shape and current among other parameters is one of the crucial engineering problems for present and future magnetic confinement devices. The Plasma Control Systems (PCS) lead with the overall control of the fusion devices being responsible also for the plasma configuration and scenarios algorithms [1, Chapter 8]. Currently different PCS's are use in the tokamaks around the world. In this chapter will be approach the "DIII-D-like" PCS and the Multi-threaded Application Real-Time executor (MARTe).

2.1.1 DIII-D Plasma Control System

Early documentation regarding the PCS in DIII-D reefers to digitalization of analog signals transmitted to a high speed processor executing a shape control algorithm [3]

2.2 MARTE FRAMEWORK

MARTe was developed in order to standardize general real-time control systems for the execution of control algorithms. MARTe framework is based on a multiplatform C^{++} library. [2]

PLASMA CONTROL SYSTEMS

- 2.2.1 *MARTe architecture*
- 2.2.2 Hardware containers
- 2.2.3 *MARTe* 2.0
- 2.3 EQUILIBRIUM AND CONTROL ALGORITHMS
- 2.3.1 PID control
- 2.3.2 Multiple-Input Multiple-Output control

JT60-SA CONTROL DESIGN

- 3.1 MACHINE DESCRIPTION
- 3.2 CREATE TOOLS
- 3.3 CONTROLLER DESIGNS
- 3.4 QST TOOLS IMPLEMENTATION
- 3.5 SIMULATION RESULTS

ISTTOK

- 4.1 MACHINE DESCRIPTION
- 4.2 DIAGNOSTICS AND ACTUATORS
- 4.3 ATCA-MIMO-ISOL BOARDS
- 4.3.1 Hardware layout
- 4.3.2 Real-time integration software
- 4.4 RETRIEVING THE CONTRIBUTION OF PLASMA CURRENT

The methods of correction of the magnetic error fields due to inaccuracies of tokamak manufacturing and assembly are considered. The problems of the plasma position and shape reconstruction based on magnetic field measurements are discussed.

4.5 PLASMA CENTROID POSITION DETERMINATION

ISTTOK RESULTS

- 5.1 GENERAL APPLICATION MODULES IMPLEMENTATIONS
- 5.2 PID CONTROL IMPLEMENTATION
- 5.3 MULTIPLE-INPUT MULTIPLE-OUTPUT CONTROL IMPLEMENTATION



CONCLUSIONS

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DEMONSTRATIONS