Surface Crack Detection Using Deep Convolutional Neural Network

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Introduction



Measurement of the extent of cracks on the surface of a material (usually a solid material such as metals, plastics and ceramics).

Fig 1: Surface Crack [1]

Motivation

- 1. Concrete surface cracks are major defect in civil structures
- 2. Detecting Crack of surfaces more accurately
- 3. More accuracy ensures less accident in highway
- 4. Inspecting, finding the cracks and determining the building health

Literature Review

1. Autonomous concrete crack detection using deep fully convolutional neural network [2]

Applied Method - VGG16, Inception V3, ResNet50

Dataset - 40,000

Accuracy - 0.998, 0.997, 0.975

Literature Review

2. Road Crack Detection Using Deep Convolutional Neural

Network [3]

Applied Method - ConvNets

Dataset - 40,000

Accuracy - 0.8965

Dataset



Fig 2: Crack Image [3]



Fig 3: Non Crack Image [3]

- The dataset is created from 458 (4032x3024 pixel) high-resolution images using the method proposed by Zhang et al (2016) [3]
- Consists of 40,000 images of 227 x 227 in RGB
- 20,000 positive images (Crack)
- 20,000 negative images (Non Crack)

Methodology

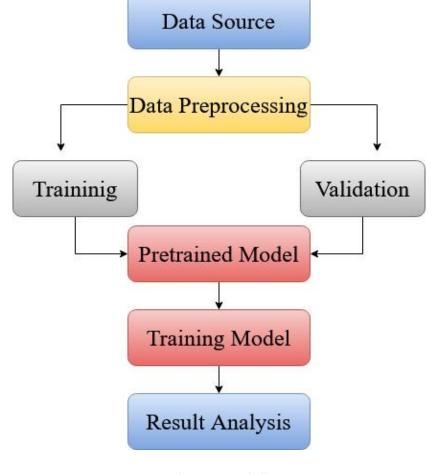


Fig 4: Workflow

Implementation

1. Data Preprocessing:

- (a) Image Resize: Images are resized into 150 x 150 (RGB) to make all image size uniform for VGG16 model [4] (pretrained model)
- (b) Normalization: Images are rescaled between 0 to 1 by dividing each pixel value by 255

2. Data Split:

Datasets are splitted into 'Training' and 'Validation' (30 percent randomly) sets

Implementation

3. Model Architecture:

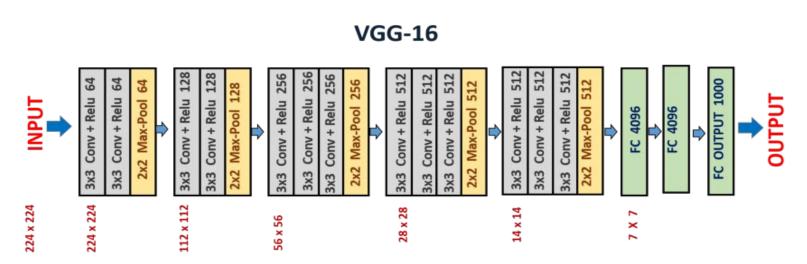


Fig 5: VGG16 Model [4]

Implementation

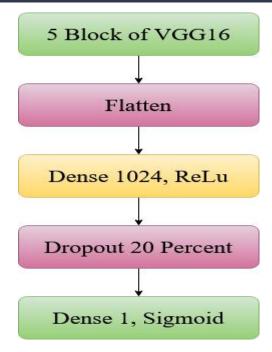


Fig 6: Model Architecture

Parameters:

Epoch: 20

Batch Size: 64

Optimizer: Adam [5]

Loss Function: binary_crossentropy [6]

Dropout: 20 percent

Learning rate: 0.001

```
Epoch 19/20
call_m: 0.9986 - val_loss: 0.0161 - val_accuracy: 0.9973 - val_f1_m: 0.9972 - val_precision_m: 0.9975 - val_recall_m: 0.9971
Epoch 20/20
0.9993
Reached 99.9% accuracy so cancelling training!
call_m: 0.9993 - val_loss: 0.0161 - val_accuracy: 0.9974 - val_f1_m: 0.9974 - val_precision_m: 0.9977 - val_recall_m: 0.9972
```

Fig 7: Model Accuracy

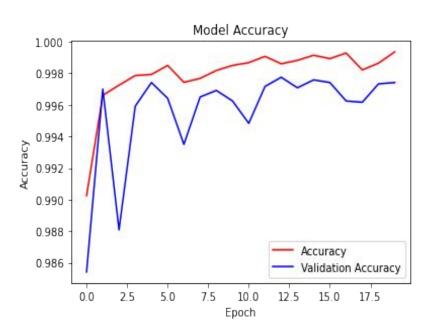


Fig 7: Accuracy vs Epoch Curve (lr=0.001)

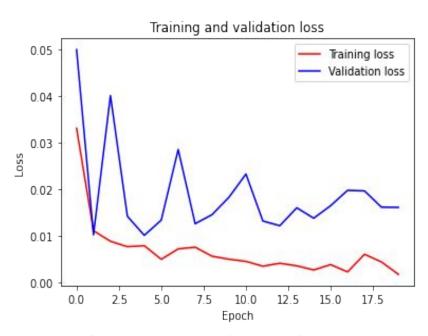


Fig 8: Loss vs Epoch Curve (lr=0.001)

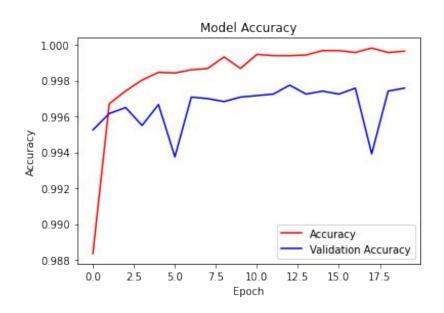


Fig 7: Accuracy vs Epoch Curve (lr=0.0001)

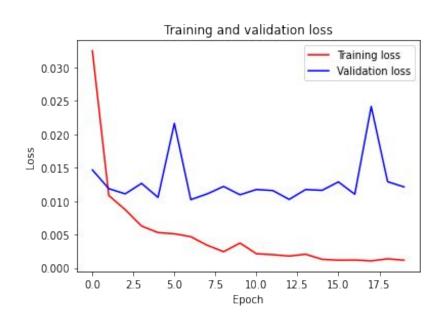


Fig 8: Loss vs Epoch Curve (lr=0.0001)

Performance of Different Methods:

Method	Accuracy	Recall	Precision	F1 Score
VGG16 [2]	0.998	0.999	0.998	0.998
Inception V3 [2]	0.997	0.997	0.998	0.997
ResNet [2]	0.975	0.945	0.994	0.968
Proposed VGG16	0.999	0.9993	0.999	0.999

Table 1: Performance of Different Methods

Conclusion

- 1. The dataset was preprocessed before feeding the network
- 2. VGG16 was successfully implemented and validated
- 3. Performance analysis was done

Future Works:

- 1. Extend the dataset using augmentation
- 2. Performance comparison of different neural network models

References

- [1] https://deeplearninganalytics.org/detection-of-surface-cracks-in-concrete-structures-using-deep-learning.
- [2] Dung, C.V., 2019. Autonomous concrete crack detection using deep fully convolutional neural network. *Automation in Construction*, 99, pp.52-58.
- [3] Zhang, L., Yang, F., Zhang, Y.D. and Zhu, Y.J., 2016, September. Road crack detection using deep convolutional neural network. In 2016 IEEE international conference on image processing (ICIP) (pp. 3708-3712). IEEE.
- [4] https://medium.com/towards-artificial-intelligence/the-architecture-and-implementation-of-vgg-16-b050e5a5920b
- [5] https://towardsdatascience.com/adam-latest-trends-in-deep-learning-optimization-6be9a291375c
- [6] https://keras.io/api/preprocessing/image/

THANK YOU