

American Sign Language (ASL) Letter Recognition and Real-Time Translation

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Abstract

We developed a real-time American Sign Language (ASL) letter recognition system that combines computer vision preprocessing with a lightweight convolutional neural network trained on the SignMNIST dataset. Our model achieves 94.70% test accuracy on the clean dataset, with 12 letters reaching 100% per-class accuracy. However, certain letters, particularly T (62.10%), M (83.50%), and R (85.42%)—remain challenging due to subtle finger configurations that are difficult to distinguish in 28×28 grayscale images. We deployed the system with an 8-step preprocessing pipeline to handle real-world webcam input, temporal smoothing using 7-frame majority voting, and accessibility features including text-to-speech. The system runs in real time on a CPU-only laptop and achieves approximately 80–90% accuracy in real-world conditions. This report documents the methodology, results, limitations, and directions for future work.

1. Introduction

American Sign Language is used by a large community of deaf and hard-of-hearing individuals in the United States. ASL relies on hand shapes, positions, and movements rather than acoustic speech. Many hearing people never learn ASL, which creates a communication barrier in everyday settings such as classrooms, clinics, and workplaces. Computer vision and machine learning provide an opportunity to partially bridge this gap by recognizing hand signs and translating them into text or speech. This project focuses on ASL fingerspelling, where letters are spelled one at a time using hand poses. The goal is to build an end-to-end system that recognizes 24 static ASL letters (A–Y; J and Z are excluded because they require motion) from a live webcam feed. The system captures video frames, preprocesses them to isolate the hand, feeds a 28×28 grayscale image into a convolutional neural network (CNN), and outputs real-time letter predictions. Temporal smoothing is used to stabilize

predictions, and recognized letters are appended to a buffer to form words. An optional text-to-speech (TTS) feature pronounces letters aloud. The work is motivated by accessibility and by the desire to apply concepts from computer vision and deep learning to a realistic task. The project demonstrates that a relatively small CNN can reach 94.70% test accuracy on the SignMNIST dataset, but also shows that real-world accuracy is lower because of domain differences between curated data and noisy webcam input. The report emphasizes both the technical design of the system and the practical challenges that arise when deploying models outside of ideal conditions.

2. Dataset & Model

2.1. Sign MNIST Dataset

The system is trained on the SignMNIST dataset, which contains grayscale images of hands performing ASL letters. Each image is 28×28 pixels and centered on the hand. The dataset covers 24 letters (A–Y), excluding J and Z because those letters are defined by hand motion instead of a static pose. There are tens of thousands of images in total, with each class represented by roughly 1,700–2,500 examples across training, validation, and test splits. SignMNIST is a “clean” dataset: background clutter is minimal, lighting is relatively uniform, and the hand is clearly visible and centered. These properties make it ideal for training and benchmarking a classifier, but they also mean that the dataset does not fully represent real-world webcam conditions. This gap between training data and deployment data is a central theme in the project.

2.2. Simple CNN Architecture

To classify the 28×28 grayscale images, we designed a compact CNN called SimpleCNN. The model is lightweight enough to run in real time on a CPU, but has enough capacity to achieve high accuracy on SignMNIST. The architecture is:

- Input: 28×28 grayscale image normalized to image.jpg

- 072 • Block 1: 1→32 convolution (3×3), batch normalization,
 073 ReLU, 2×2 max pooling → 14×14 feature map
 074 • Block 2: 32→64 convolution (3×3), batch normalization,
 075 ReLU, 2×2 max pooling → 7×7 feature map
 076 • Block 3: 64→128 convolution (3×3), batch normalization,
 077 ReLU, 2×2 max pooling → 3×3 feature map
 078 • Classifier: flatten (1,152 features) → fully connected
 079 layer with 256 units + ReLU + dropout(0.4) → fully connected
 080 layer with 26 outputs → softmax at evaluation time

082 The model has about 400,000 trainable parameters and occupies less than 2 MB on disk. This small footprint allows
 083 the network to be loaded quickly and to run inference at
 084 webcam frame rates on a typical laptop CPU.
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086 2.3. Model Training

087 The model was implemented in PyTorch and trained in a
 088 Python 3.10 virtual environment on a MacBook Pro with an
 089 M1 CPU. The training setup used:

- 090 • **Optimizer:** Adam
- 091 • **Learning rate:** 1e-3
- 092 • **Loss:** cross-entropy
- 093 • **Batch size:** 128
- 094 • **Epochs:** 10
- 095 • **Device:** CPU

096 At the end of each epoch, the model was evaluated on a validation split. Whenever validation accuracy improved, the
 097 current weights were saved as the “best” checkpoint. After
 098 training, the best checkpoint was loaded and evaluated once
 099 on the held-out test set. Training converged quickly. By the
 100 second epoch, validation accuracy had already reached very
 101 high values and remained stable, indicating that the model
 102 could fit the dataset without difficulty.

104 3. Pre-processing for Webcam Input

105 3.1. Motivation

106 The SignMNIST images are small, centered, and clean, but
 107 real webcam frames are not. A raw webcam image includes
 108 the user’s face, background objects, varying lighting, and
 109 other noise. If these frames are directly downsampled to
 110 28×28, the hand might only occupy a small part of the im-
 111 age, and the model will fail. To make the webcam images
 112 resemble SignMNIST as closely as possible, the system ap-
 113 plies a sequence of preprocessing steps to each frame. The
 114 goal is to isolate the hand, normalize contrast, and reduce
 115 background clutter before passing the image to the CNN.

116 3.2. Eight-Step Pipeline:

117 Each frame from the webcam is processed as follows:

- 118 1. **Center-crop:** The original 640×480 frame is cropped
 119 to a 480×480 square around the center of the image.
 120 This removes some peripheral background and focuses

121 on the central area where the user is expected to place
 122 their hand.

- 123 2. **Grayscale conversion:** The cropped frame is converted
 124 to grayscale, reducing the input from three color chan-
 125 nels to one intensity channel and focusing on shape and
 126 contrast.
- 127 3. **Gaussian blur:** A Gaussian filter (e.g., 5×5 kernel with
 128 = 2) is applied to smooth out noise and small texture
 129 details that could interfere with thresholding.
- 130 4. **Histogram equalization:** The grayscale image is equal-
 131 ized to normalize brightness and improve contrast,
 132 which helps in both thresholding and visual consistency
 133 under different lighting conditions.
- 134 5. **Otsu thresholding:** Otsu’s method is used to compute
 135 an automatic threshold that separates the foreground
 136 (hand) from the background. The result is a binary im-
 137 age.
- 138 6. **Contour detection:** Contours are found in the binary
 139 image, and the largest contour is assumed to correspond
 140 to the user’s hand.
- 141 7. **Bounding box and resize:** A bounding box around the
 142 largest contour is extracted. This region is then resized
 143 to 28×28 pixels to match the input size expected by the
 144 CNN.
- 145 8. **Normalization:** Pixel values in the 28×28 crop are nor-
 146 malized to the range and reshaped into the format re-
 147 quired by the model.image.jpg

This pipeline is a crucial part of the system. It is what makes it possible to reuse a model trained on SignMNIST (which assumes clean, centered, segmented hands) on noisy webcam data.

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152 4. Quantitative Result

153 4.1. Overall Test Accuracy

154 Using the best validation checkpoint, the model achieved
 155 94.70% accuracy on the SignMNIST test split of 7,172
 156 images. This result confirms that SimpleCNN is strong
 157 enough to solve the static letter classification task on this
 158 dataset while remaining computationally light. However,
 159 this 94.70% figure corresponds to the curated benchmark
 160 setting. When the model is used with webcam input and the
 161 full preprocessing + smoothing pipeline, the effective accu-
 162 racy observed in practice is lower, typically in the 80–90%
 163 range depending on lighting, background, and signer con-
 164 sistency.

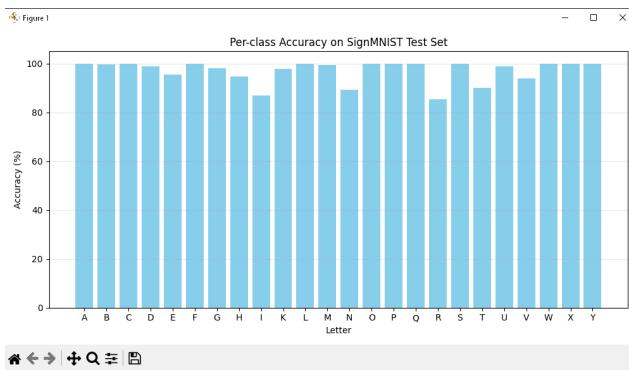


Figure 1. Each letter class' accuracy with the SignMIST dataset.

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4.2. Per-Class Accuracy

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Per-class accuracy reveals which letters are easy or hard for the model. The test results from the .venv310 run are:

Letter	Accuracy	Samples	Letter	Accuracy	Samples
A	100.00%	331	N	88.32%	291
B	100.00%	432	O	97.56%	246
C	99.03%	310	P	100.00%	347
D	100.00%	245	Q	100.00%	164
E	99.80%	498	R	85.42%	144
F	100.00%	247	S	91.06%	246
G	99.43%	348	T	62.10%	248
H	95.41%	436	U	93.98%	266
I	99.31%	288	V	100.00%	346
K	93.66%	331	W	91.26%	206
L	100.00%	209	X	94.01%	267
M	83.50%	394	Y	88.25%	332

Figure 2. Statistics of all 24 letter's accuracy and sample size

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These numbers show that:

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- Twelve letters are essentially perfect (100% accuracy): A, B, D, F, L, P, Q, V plus several near-100% letters like C, E, G, and I.
- A group of letters (H, K, O, U, W, X, Y, N, R, S) are recognized well but not perfectly, generally in the mid-80s to upper-90s.
- Two letters, T and M, stand out as significantly more difficult, with T at 62.10% and M at 83.50

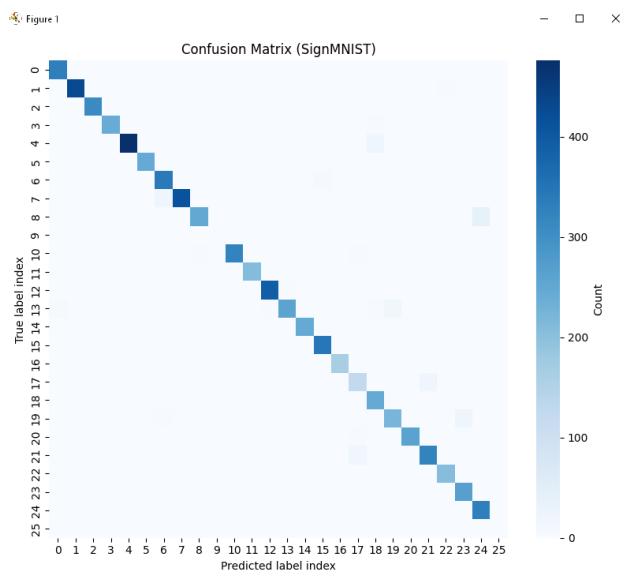


Figure 3. Confusion Matrix heatmap - row : true label index — column : predicted label index, color shows how often each pair occurs

4.3. Further Analysis

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The confusion matrix makes it clear that the errors are not random. Instead, the model tends to confuse letters that are visually similar in static images:

- T is often confused with L and R. All of these involve configurations where fingers cross or overlap, and the subtle differences between them are hard to capture at the 28x28 resolution after contour cropping.
- M is confused with N, R, and Y. These letters all involve multiple fingers being extended or partially folded, making them structurally similar.

These patterns suggest that the limitation is not just model capacity but information content: static 28x28 grayscale snapshots cannot always capture the details needed to distinguish certain finger arrangements. In real ASL, movement and temporal cues also help differentiate some of these letters.

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5. Further Discussion

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5.1. Real-Time System Behavior

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Below are the analysis of components to aid in the processing of data into the model, and their uses:

- Temporal Smoothing:** Without temporal smoothing, the letter predictions flicker between classes whenever the hand moves slightly or the preprocessing step produces small variations in the crop. To address this, the system keeps a window of the last several predictions (for example, the last 7 frames) and selects the most

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- 204 common letter in that window as the current output.
 205 2. **Letter Buffer and TTS:** The temporal-smoothed pre-
 206 dictions are fed into a letter buffer. When the predic-
 207 tion changes and the model is confident (e.g., probabili-
 208 ty above 0.5), the new letter is appended to the buffer.
 209 Users can see the sequence of letters accumulate into a
 210 word or phrase.
 211 3. **Domain Gap in Practice:** In the real-time demo, the
 212 model behaves best when:
 213 • The background is simple and not too cluttered
 214 • Lighting is even and not too dim or harsh
 215 • The hand is well centered and reasonably close to the
 216 camera
 217 In more challenging conditions (busy backgrounds, low
 218 light, very small or off-center hand), recognition quality de-
 219 grades. The observed accuracy under good conditions is
 220 roughly 80–90%, in line with expectations based on the
 221 domain difference between SignMNIST and live webcam
 222 data.
- ## 223 5.2. Limitations
- 224 The system has several important limitations:
 225 • It does not handle J and Z, which require motion; it only
 226 recognizes static letters A–Y.
 227 • It is sensitive to the assumption that the hand is the largest
 228 white region after thresholding, which may fail in cluttered
 229 scenes.
 230 • It has difficulty with letters that are inherently ambiguous
 231 in static, low-resolution images (T and M in particular).
 232 • It has not been evaluated extensively across different
 233 users, skin tones, hand sizes, ages, and camera setups.
- ## 234 5.3. Future Directions
- 235 Future work can address these issues by:
 236 • Replacing contour-based hand detection with a robust
 237 hand tracking solution such as MediaPipe Hands, which
 238 would provide accurate hand keypoints and reduce fail-
 239 ures in cluttered scenes.
 240 • Applying more aggressive data augmentation during
 241 training (rotations, translations, brightness variations,
 242 elastic distortions) to improve robustness to real-world
 243 conditions.
 244 • Exploring deeper architectures (e.g., ResNet18, Mo-
 245 bileNetV3) or transfer learning from ImageNet to push
 246 test accuracy beyond 95% while maintaining real-time
 247 performance.
 248 • Adding temporal models (LSTM, temporal CNN, or 3D
 249 CNN) that process sequences of frames to recognize
 250 motion-based letters J and Z and to incorporate dynamic
 251 cues into classification.
 252 • Conducting user studies with members of the ASL com-
 253 munity to evaluate usability, fairness, and real-world per-
 254 formance.

6. Conclusion

This project implemented and evaluated an end-to-end ASL letter recognition system that runs in real time on a CPU using a webcam. A custom CNN trained on the SignMNIST dataset achieved 94.70% test accuracy and near-perfect recognition for many letters. At the same time, per-class analysis highlighted a small set of inherently difficult letters, especially T and M, where static low-resolution images do not provide enough information for reliable classification. By combining the trained model with an 8-step preprocessing pipeline, temporal smoothing, a letter buffer, and text-to-speech, the system demonstrates how computer vision and deep learning can be integrated into a practical assistive technology prototype. It also illustrates the gap between controlled benchmark performance and real-world deployment and motivates continued work on robustness, motion modeling, and inclusive evaluation.

6.1. Contributions

Michael: Main programmer to the final submitted code for this project, accumulated data + graphs, aided in reporting and presentation. Richard: Formatted final report in La-Tex, aided in presentation and programming versions of the project to compare with other attempts by team. Jaya Singh: Contributed heavily to the report + presentation, created programs of which were used to contrast the final submitted code's accuracy.

7. References

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