# AHSANIA MISSION UNIVERSITY OF SCIENCE & TECHNOLOGY

# Lab Report-8

**Lab No:** 08

**Course Code:** CSE 2202

**Course Title:** Computer Algorithm Sessional.


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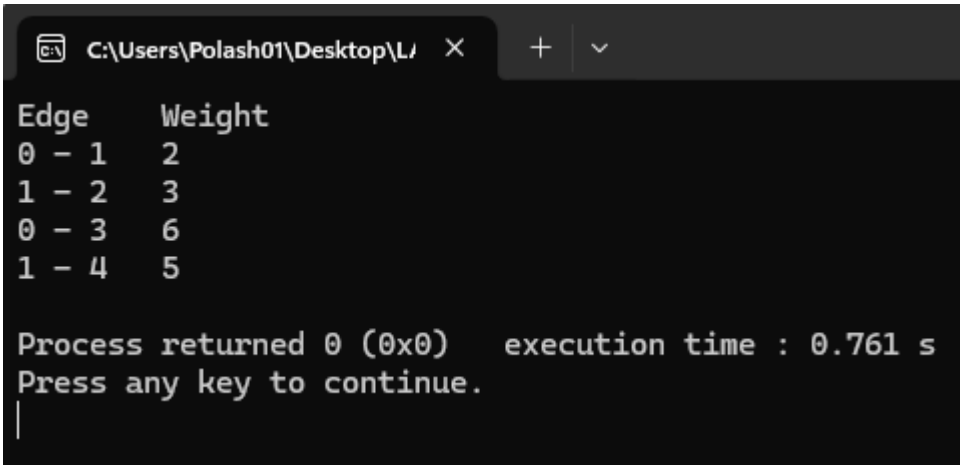
## Task01: Prim's Algorithm

```
#include <iostream>
#include <limits.h>
using namespace std;

#define V 5

// Find the vertex with the smallest key value
int findMinKey(int key[], bool inMST[]) {
   int min = INT_MAX, index;
   for (int i = 0; i < V; i++) {
      if (!inMST[i] && key[i] < min) {
         min = key[i];
         index = i;
      }
   }
   return index;
}

// Print the MST using parent array
void printMST(int parent[], int graph[V][V]) {
   cout << "Edge\tWeight\n";
   for (int i = 1; i < V; i++) {
      cout << parent[i] << " - " << i << "\t" << graph[i][parent[i]] << "\n";
   }
}

// Prim’s algorithm to construct MST
void primMST(int graph[V][V]) {
   int parent[V];     // Store MST structure
   int key[V];       // Store edge weights
   bool inMST[V];     // Track included vertices

   for (int i = 0; i < V; i++) {
      key[i] = INT_MAX;
      inMST[i] = false;
   }

   key[0] = 0;
   parent[0] = -1;

   for (int i = 0; i < V - 1; i++) {
      int u = findMinKey(key, inMST);
```

```
        inMST[u] = true;

        for (int v = 0; v < V; v++) {
            if (graph[u][v] && !inMST[v] && graph[u][v] < key[v]) {
                parent[v] = u;
                key[v] = graph[u][v];
            }
        }
    }

    printMST(parent, graph);
}

int main() {
    int graph[V][V] = {
        {0, 2, 0, 6, 0},
        {2, 0, 3, 8, 5},
        {0, 3, 0, 0, 7},
        {6, 8, 0, 0, 9},
        {0, 5, 7, 9, 0}
    };

    primMST(graph);
    return 0;
}
```

Output:



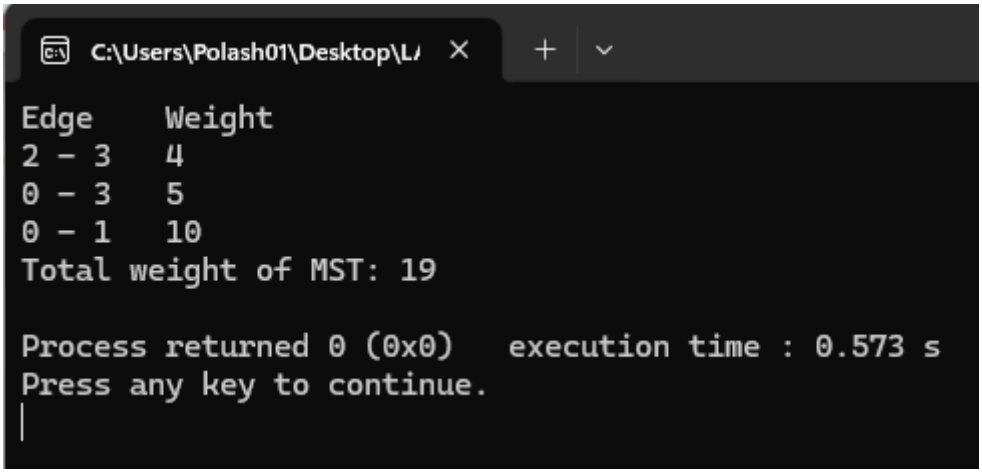
| Test Case | Input Adjacency Matrix | Output MST Edges (Edge : Weight) | Total Cost |
|---|---|---|---|
| **1** | { {0,2,0,6,0}, {2,0,3,8,5}, {0,3,0,0,7}, {6,8,0,0,9}, {0,5,7,9,0} } | 0–1:2, 1–2:3, 0–3:6, 1–4:5 | **16** |
| **2** | { {0,1,2,0}, {1,0,4,6}, {2,4,0,3}, {0,6,3,0} } | 0–1:1, 0–2:2, 2–3:3 | **6** |
| **3** | { {0,10,0,0,5}, {10,0,1,0,2}, {0,1,0,4,0}, {0,0,4,0,3}, {5,2,0,3,0} } | 0–4:5, 4–1:2, 1–2:1, 4–3:3 | **11** |

## Task02: Kruskal's Algorithm

```
#include <iostream>
#include <vector>
#include <algorithm>
using namespace std;

struct Edge {
   int u, v, weight;
   bool operator<(const Edge& other) {
      return weight < other.weight;
   }
};

int findSet(int node, vector<int>& parent) {
   if (parent[node] == node)
      return node;
   return parent[node] = findSet(parent[node], parent);
}

void unionSet(int a, int b, vector<int>& parent, vector<int>& rank) {
   a = findSet(a, parent);
   b = findSet(b, parent);

   if (a != b) {
      if (rank[a] < rank[b])
         swap(a, b);
      parent[b] = a;
      if (rank[a] == rank[b])
         rank[a]++;
   }
}
```

```
int main() {
    int V = 4;
    vector<Edge> edges = {
        {0, 1, 10},
        {0, 2, 6},
        {0, 3, 5},
        {1, 3, 15},
        {2, 3, 4}
    };

    sort(edges.begin(), edges.end());

    vector<int> parent(V), rank(V, 0);
    for (int i = 0; i < V; i++)
        parent[i] = i;

    vector<Edge> mst;

    for (Edge e : edges) {
        if (findSet(e.u, parent) != findSet(e.v, parent)) {
            mst.push_back(e);
            unionSet(e.u, e.v, parent, rank);
        }
    }

    cout << "Edge\tWeight\n";
    int total = 0;
    for (Edge e : mst) {
        cout << e.u << " - " << e.v << "\t" << e.weight << "\n";
        total += e.weight;
    }
    cout << "Total weight of MST: " << total << endl;

    return 0;
}
```

Output:



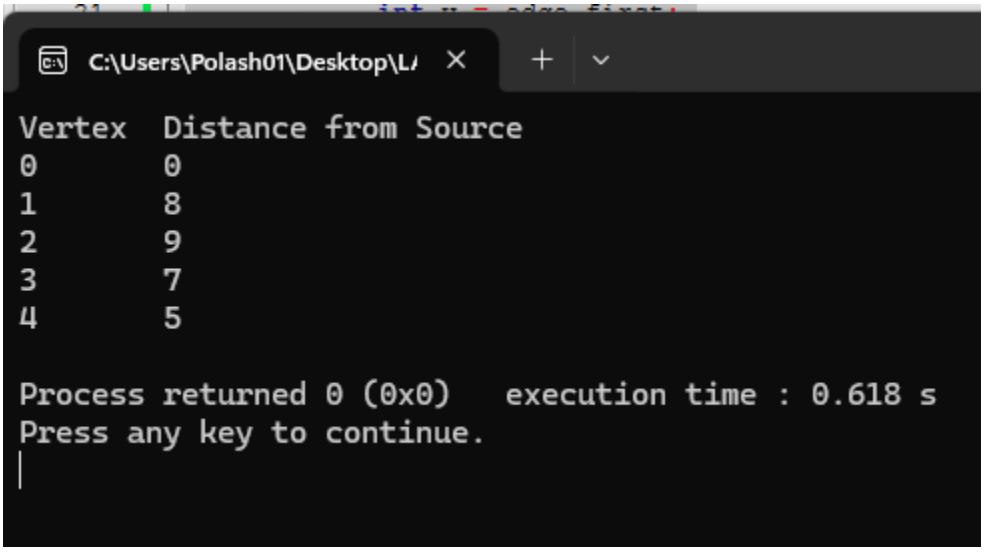
| Test Case | Input Edges (u, v, weight) | Output MST Edges (Edge : Weight) | Total Cost |
|---|---|---|---|
| **1** | (0,1,10), (0,2,6), (0,3,5), (1,3,15), (2,3,4) | 2–3:4, 0–3:5, 0–1:10 | **19** |
| **2** | (0,1,1), (0,2,3), (1,2,2), (1,3,4), (2,3,5) | 0–1:1, 1–2:2, 1–3:4 | **7** |
| **3** | (0,1,2), (0,3,6), (1,2,3), (1,3,8), (2,3,5) | 0–1:2, 1–2:3, 2–3:5 | **10** |

## Task03: Dijkstra's Algorithm

```
#include <iostream>
#include <vector>
#include <queue>
#include <climits>
using namespace std;

typedef pair<int, int> pii;

void dijkstra(int V, vector<pii> adj[], int source) {
   vector<int> dist(V, INT_MAX);
   dist[source] = 0;

   priority_queue<pii, vector<pii>, greater<pii>> pq;
   pq.push({0, source});

   while (!pq.empty()) {
      int u = pq.top().second;
      pq.pop();

      for (auto& edge : adj[u]) {
         int v = edge.first;
         int weight = edge.second;

         if (dist[v] > dist[u] + weight) {
            dist[v] = dist[u] + weight;
            pq.push({dist[v], v});
         }
      }
   }
```

```
    cout << "Vertex\tDistance from Source\n";
    for (int i = 0; i < V; ++i)
        cout << i << "\t" << dist[i] << "\n";
}

int main() {
    int V = 5;
    vector<pii> adj[V];

    adj[0].push_back({1, 10});
    adj[0].push_back({4, 5});
    adj[1].push_back({2, 1});
    adj[1].push_back({4, 2});
    adj[2].push_back({3, 4});
    adj[3].push_back({2, 6});
    adj[3].push_back({0, 7});
    adj[4].push_back({1, 3});
    adj[4].push_back({2, 9});
    adj[4].push_back({3, 2});

    dijkstra(V, adj, 0);
    return 0;
}
```

Output:



| Test Case | Input Edges (Adjacency List) | Source Vertex | Output (Vertex : Distance from Source) |
|---|---|---|---|
| **1** | 0→(1,10),(4,5);<br>1→(2,1),(4,2); 2→(3,4);<br>3→(2,6),(0,7);<br>4→(1,3),(2,9),(3,2) | 0 | 0:0, 1:8, 2:9, 3:7, 4:5 |
| **2** | 0→(1,4),(2,1); 1→(3,1);<br>2→(1,2),(3,5); 3→() | 0 | 0:0, 1:3, 2:1, 3:4 |
| **3** | 0→(1,2),(2,4);<br>1→(2,1),(3,7); 2→(4,3);<br>3→(5,1); 4→(3,2); 5→() | 0 | 0:0, 1:2, 2:3, 3:8, 4:6, 5:9 |