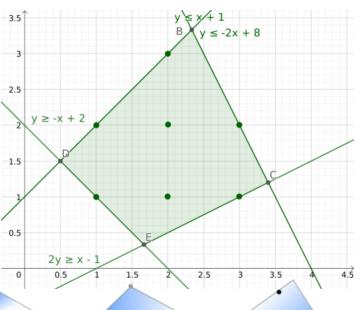
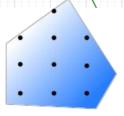
Mixed-Integer Programming 4 COMP4691/8691

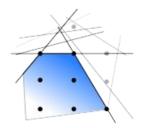


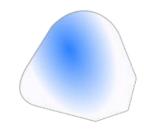






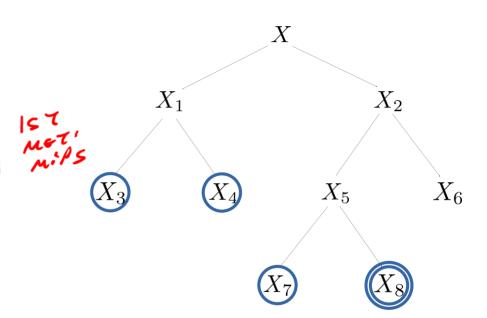






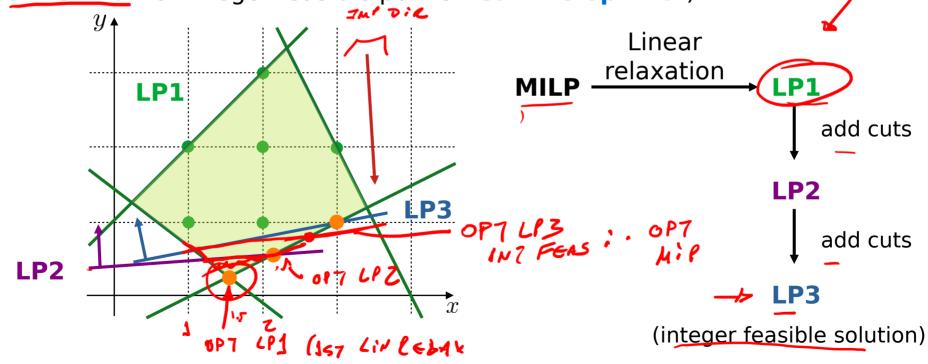
MILP Topic Outline

- Linear relaxation -
- Modelling and solving
- Branch and bound
- Cutting plane methods
 - Gomory cuts
- Duality for ILPs →



Cutting Plane Methods

Iteratively add cuts (<u>linear inequalities</u>) to the problem until the solution to the linear relaxation becomes integer feasible (have captured the **convex hull** of integer feasible points **near the optimal**).



Cutting Plane Methods

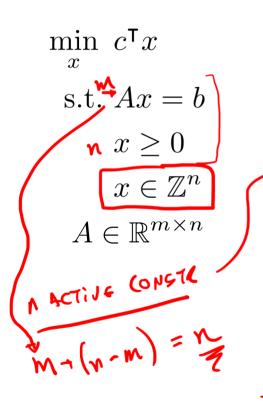
to the linear relaxation becomes integer feasible (have captured the convex hull of integer feasible points near the optimal).

Can solve ILPs on their own, or the techniques can be used in conjunction with branch and bound to improve relaxations.

Different types of cuts with varying complexity can be added.

We will focus on the **Gomory cutting plane algorithm**, developed by Ralph Gomory in the 1950s (served in the US Navy), which makes use of **Gomory cuts**.

Recap: Revised Simplex



We work with variables instead of constraints.

Basic feasible solution (BFS): just another way of saying a vertex of the feasible polyhedron.

BFS.
$$B_k \longrightarrow$$
 Pick entering \longrightarrow Pick leaving \longrightarrow BFS: B_{k+1} variable variable

basis

Variables can be basic or non-basic

- Basic variables: $x_j \ge 0$ $\forall j \in B_k$ (n
- Non-basic variables: $x_j = 0 \quad \forall j \notin B_k$ (n-m

Gomory Cuts

 $\min c^{\mathsf{T}} x$

s.t.
$$Ax = b$$

$$x \ge 0$$

$$x \in \mathbb{Z}^n$$

$$A \in \mathbb{R}^{m \times n}$$

Let x^* be an optimal BFS of the linear relaxation with basis B. and **non-basic parts**:

$$A \in \mathbb{R}^{m \times m} \qquad A \in \mathbb{R}^{m \times (n)}$$

$$\bar{x} \in \mathbb{R}^m \qquad \tilde{x} \in \mathbb{R}^{n-m}$$

$$\tilde{A} \in \mathbb{R}^{m \times m}$$
 $\tilde{A} \in \mathbb{R}^{m \times (n-m)}$

$$\tilde{x} \in \mathbb{R}^{n-n}$$

For the linear relaxation optimal solution:

$$\rightarrow \bar{A}\bar{x}^* = b$$

$$\tilde{x} = 0$$

Rewrite constraint:

$$Ax = \bar{A}\bar{x} + \tilde{A}\tilde{x} = b$$

 $\bar{A}\bar{x}=b$ has a solution so we can invert:

$$\bar{x} + \bar{A}^{-1}\tilde{A}\tilde{x} = \bar{A}^{-1}b$$

$$\bar{x} + \hat{A}\tilde{x} = \hat{b}$$



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Gomory Cuts *

PLEN
$$\bar{x} + \hat{A}\tilde{x} = \hat{b}$$

Element-wise floor operator

Haven't done anything significant yet, as it still holds for all feasible solutions to linear relaxation

te
$$x \ge 0$$
: $\bar{x} + \lfloor \hat{A} \rfloor \tilde{x} \le \bar{x} + \hat{A} \tilde{x} = \hat{b}$

For our original problem all x should be integer, and the coefficients on the LHS are now integer \Rightarrow we can tighten the inequality without losing any integer feasible solutions:

$$ightharpoonup \bar{x} + |\hat{A}|\tilde{x} \leq |\hat{b}|$$
 & Gomery Cuts

$$x_i + \sum_{j \notin B} \lfloor \hat{A}_{i,j} \rfloor x_j \leq \lfloor \hat{b}_i \rfloor \quad \forall i \in B$$

These are **Gomory cuts**.

Gomory cuts can also be derived for the mixed-integer case.

Gomory Cuts

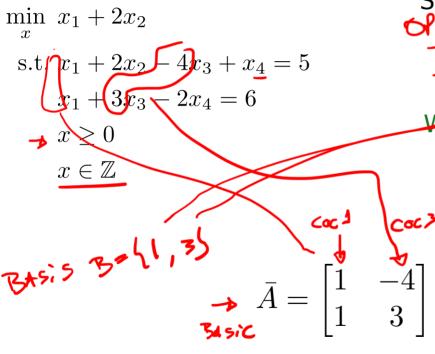
$$x_{i} + \sum_{j \notin B} \lfloor \hat{A}_{i,j} \rfloor x_{j} \leq \lfloor \hat{b}_{i} \rfloor \quad \forall i \in B \quad 4$$

If all basic variables are integral, we have an optimal solution to original problem, otherwise if one (x_i^*) is fractional:

Noting:
$$\hat{x}_i$$
 \hat{x}_i \hat{x}_i \hat{x}_i \hat{x}_i \hat{x}_i \hat{x}_i \hat{x}_i Noting: $\hat{x}_i^* = \hat{A}^{-1}b = \hat{b}$ Now Basic walk \hat{x}_i $\hat{x}_i^* = 0$ Now Basic walk \hat{x}_i \hat{x}_i \hat{x}_i \hat{x}_i

If added to the problem, the cut will ensure that the optimal for the LP relaxation is no longer feasible.





Solve linear relaxation:

Objective =
$$39/7$$
 $\Rightarrow x' = (39/7, 0, 1/7, 0)$

Which variables are basic?

 x_1 and x_3 are basic.

$$ilde{A} = egin{bmatrix} 2 & 1 \\ 0 & -2 \end{bmatrix}$$

$$\hat{A} = \bar{A}^{-1}\tilde{A} = \begin{bmatrix} \frac{6}{7} & -\frac{5}{7} \\ -\frac{2}{7} & -\frac{3}{7} \end{bmatrix} \quad \hat{b} = \bar{A}^{-1}b = \bar{x}^* = \begin{bmatrix} \frac{39}{7} \\ \frac{1}{7} \end{bmatrix} \quad \text{Objective} = 39/7$$

$$\hat{x} = (39/7, 0, 1/7, 0)$$
Small abuse of notation for \hat{A} :

$$x_i + \sum_{j \notin B} \lfloor \hat{A}_{i,j} \rfloor x_j \leq \lfloor \hat{b}_i \rfloor \quad \forall i \in B$$
 Small abuse of notation for $\hat{A}_{\underline{i},\underline{j}}$ i is the index associated with x_i not the i-th row • same for columns and non-basic vars

$$i = 1: \quad x_1 + \left\lfloor \frac{6}{7} \right\rfloor \underline{x_2} + \left\lfloor -\frac{5}{7} \right\rfloor \underline{x_4} \le \left\lfloor \frac{39}{7} \right\rfloor^{\text{Fol}} x_{1} - x_{4} \le 5 \Rightarrow x_{1} - x_{4} \le 5 = 5$$

Small abuse of notation for
$$A_{\underline{i},\underline{j}}$$
 i is the index associated with $\mathbf{x_i}$ not the i-th row

$$x_1 - x_4 \le 5 \Rightarrow x_1 - x_4 + 5_1 = 5$$

Verify LP BFS no longer valid

$$i = 3: \quad x_3 + \left[-\frac{2}{7} \right] x_2 + \left[-\frac{3}{7} \right] x_4 \le \left[\frac{1}{7} \right]$$

$$x_3 - x_2 - x_4 \le 0$$

$$x_7 - x_7 - x_4 \le 0$$

 $\min_{x} c^{\mathsf{T}} x$

Previous LP relaxation optimal:

Objective =
$$39/7 = 5.571428$$

x = $(39/7, 0, 1/7, 0) = (5.571428, 0, 0.142857, 0)$

s.t. Ax = b $x \ge 0$ $x \in \mathbb{Z}^{n-1}$

M=Z

New LP relaxation optimal after adding both Gomory cuts:

More basic variables than before?

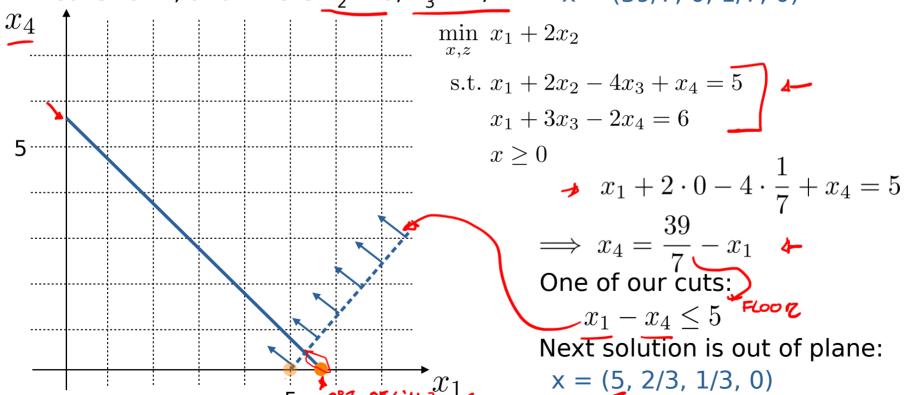
The final optimal solution to the ILP:

In equality form we have 2 more constraints and 2 more slack variables (implicit here)

Objective
$$\neq 1$$
 $\vec{x} = (7, 0, 1, 2)$

Objective $\neq 1$
 $\vec{x} = (7, 0, 1, 2)$

Let's try to visualise this by plotting the feasible region of just the first constraint, and where $x_2 = 0$, $x_3 = 1/7$. x = (39/7, 0, 1/7, 0)



Gomory Cutting Plane Method

Iteratively solve linear relaxation, adding one or more Gomory cuts each time for any fractional basic variables.

Once an integer solution is obtained for the linear relaxation, return optimal for original problem.

The number of constraints increases over time, and in equality form, the number of slack variables.

This terminates in a finite number of iterations.

Cuts gradually improve over time until they become **facet-defining** for the convex hull.

Branch and Cut

Which will FOR ALITTICE Which will ger feasible where

Combine branch and bound with cut generation at nodes, which will improve lower bounds and improve the ability to find integer feasible solutions.

Gomory cuts are one option, but there are multitude of different types of cuts that can work well in particular settings. Let's take a look at the output of CBC on one of our problems...

https://github.com/coin-or/Cbc https://github.com/coin-or/Cgl (cut generation library)

These cuts are also known as **valid inequalities**: they are valid for all ILP feasible point (i.e. don't remove any ILP feasible points, but hopefully tighten up the linear relaxation)

Understanding CBC Messages

The code to the left of the printed output are defined in CbcMessage.cpp of the CBC source. Some of the common ones CbcXXXXI:

0010 Overall status update0012 Summary of after finding integer feasible solution

0013 Cuts improved root node**0014** Cut generation output

0031 Status on cuts**0032** Status on branching

0035 Branching depth

0038 Feasibility pump output

CBC vs ... scip i.i. survers: http://plato.asu.edu/ftp/milp.html socvets coup of Mip Socvets rea. Cicause yor in comp the ps://www.minizine.com scip coup of Mip socvets rea. Cicause ps://www.minizine.com i.i.

CP solvers (e.g., Geocode/Chuffed):

Other MILP solvers:

Note that the problems and timescales in this challenge are really geared towards comparing the strengths of CP solvers: very hard feasibility problems with a focus on getting a solution quickly. No mixed (integer and continuous) problems either.

Duality for ILPs

There are a number of different duality theories for ILPs.

Some of them (e.g., Superadditive Duality) lead to **strong duality**, like for LPs, but result in problems that have exponential-sized formulations.

The duality theory we have explored for LPs is Lagrangian Duality, which can be applied to ILPs also. However, while weak duality holds, strong duality doesn't for the Lagrangian dual of an ILP.

CONVEX

A key result is that the **Lagrangian dual** provides a lower bound that is at least as strong as the linear relaxation, and can often be stronger.

This process is called **Lagrangian Relaxation**. We can solve for a feasible point of the dual, it doesn't need to be optimal (weaker relaxation).