Sakshi Srivastava USN: 18M18 CSOAD Batch - B3 13th Nov, 2020. Lakser function:dej astar (ssc, larget): Stalas = [Sti] visited - states = set() while len (statu): punt (f"Level: {g}") moves =[] for state in states: visited-states.add (tuple (state)) punt - guid ( wate) y ( state == tayet : print ( " Succes") mars += [more for more ni possible moves (stategrisited-states) ig more not in moves ] costs = Eg + h (move, target) for mon in moves] stales = [moves[i] fo isi range (len moves)) ig costs [i]== mini(costi)]

```
9+=1
 Punt ( "No solution )
 def possible-mover (state, visited-et ater).
   b = state. midex (-1)
  d=[7
 Y € 9) 6-3 >= 0:
   d+= 'u'
 y 9 > 5 + 3 > = 0:
    d + = 1 a^{\prime}
if I not in [2,5,8]:
   d+= 'x'
y 5 not m [0,3,6]:
  d+= 11'
 pos_mores = ()
   for move nod:
     pres - moves, append (gen (state, move, b))
  betunt more por more ni per-mores il tigla
     (move) not in visited - state ]
 def gen (state, direction, b);
   lump = state. copy () o
                      (2)
```

```
if ( direction = = 'U):
       lemp [6-3], temp [6] = temp [6], temp [6-3]
in (duictur = = 1 a):
  lamp[b+3], temp[b] = temp[b], temp[b+3]
y driedio == 'N'
    temp [ 6 + 1 ], lamp [ 6] = temp [ 6], tup [ 6 + 1]
ely direction == 'l':
 long [ 5-1], leap [ 6]- lamp [ 6], long [ 6-1]
 selver temp.
# Manhatlan distance.
     dy h (state, target):
     dist = 0
    for i in state
        d1, d2= slate. videx(i), tayet. Index()
       n1, y1= at 1. 3, a1 //3
       22, y2= d2%, 3, a2/13.
       dust += abs (711- n2 + ab (y1-y2)
   return dist.
```