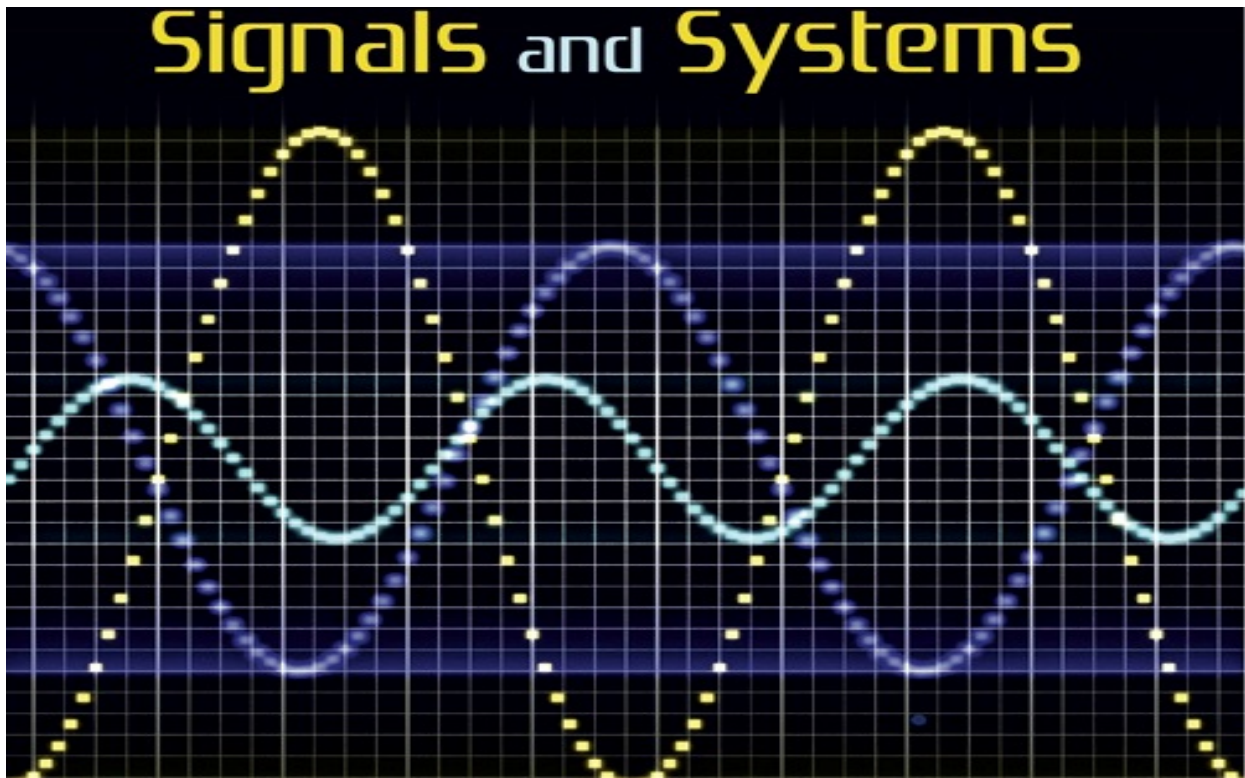


Project Report
For
PROGRAMMING ASSIGNMENT
Signals and Systems
(EEL2010)
IIT JODHPUR

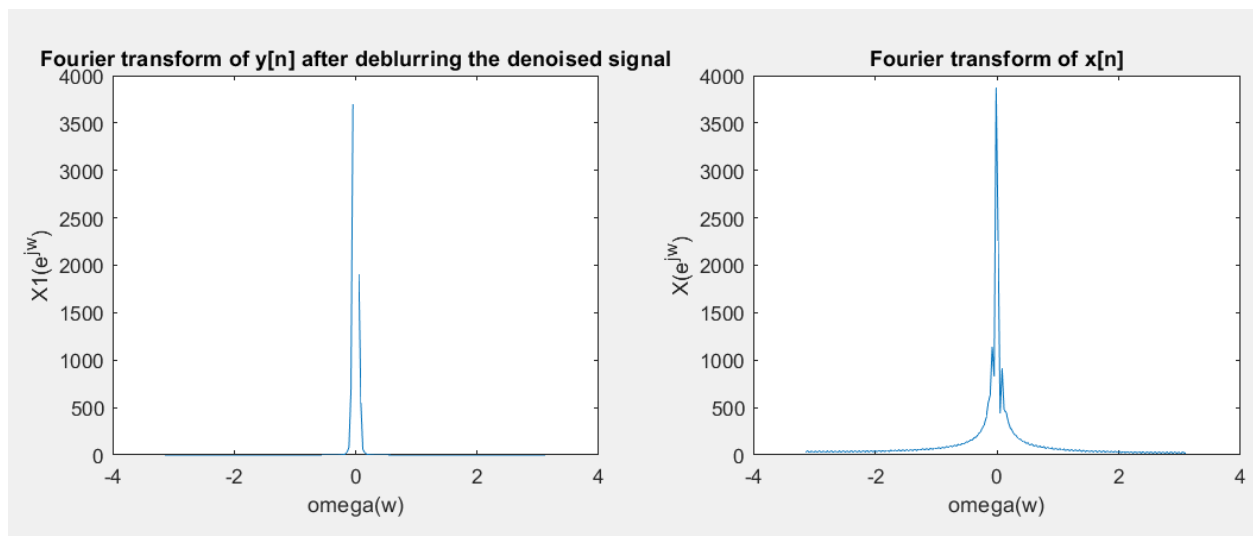


By:-

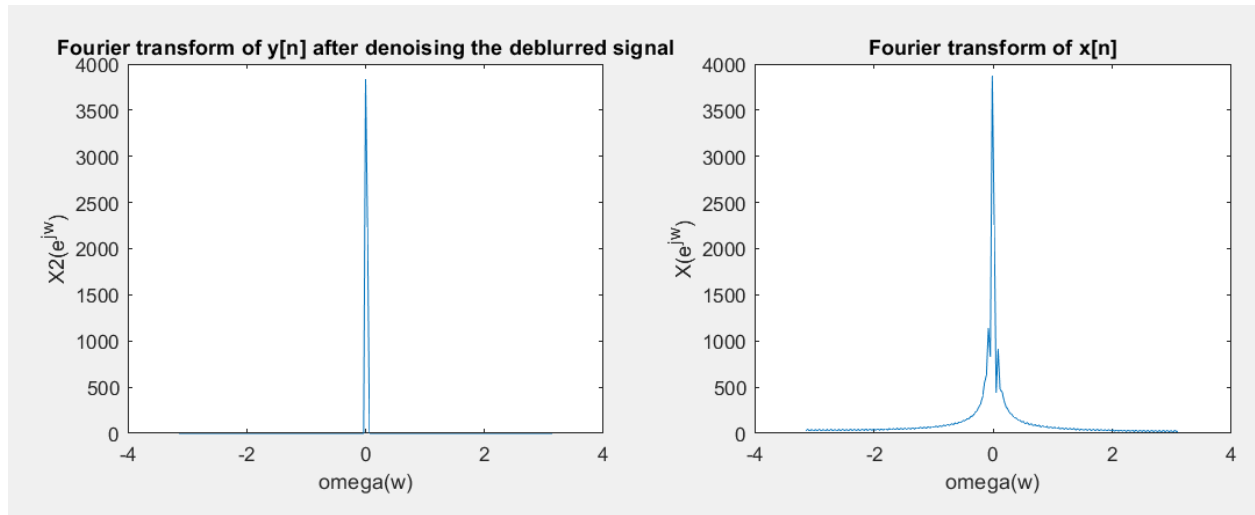
Sakshi Jain (B20ME065)

RESULT:

- First approach: That is, first denoising and then deblurring the signal .In the result, we have shown the two figures showing the fourier transform of $x_1[n]$ and fourier transform of $x[n]$



- Second approach: That is first sharpen(deblur) and then denoise the signal. As a result we get $x_2[n]$. Below given are the two figures showing the fourier transform of $x_2[n]$ and fourier transform of $x[n]$.



OBSERVATIONS AND CONCLUSION:

- While denoising, we noticed that neighboring terms generally have the same values by using low pass filter.
- So, Fourier transform and Inverse Fourier transform can be used to denoise and deblur a signal to enhance its quality.
- After comparing the output of both approaches with the original pure signal, we came to the conclusion that both methods give almost the same output and both are appropriate ways.

THEORETICAL EXPLANATIONS:

We have been given $x[n]$ (true temperatures) .then some noise and blur distortions have been added to the signal and we get an impure signal $y[n]$.So, the signal $y[n]$ needs to be processed so that we can recover $x[n]$ from it.

- For the first way of approach, let's say first denoising will have $h_1[n]$ as impulse response and deblurring has $h_2[n]$ as impulse response.
- Then after denoising the input($y[n]$) the output (let's say $v[n]$) is the convolution sum of $y[n]$ and $h_1[n]$.
- And after deblurring the denoised signal, the output will be the convolution sum of $v[n]$ and $h_2[n]$.
- Final output ($x_1[n]$) will be the convolution of $h_2[n]$ with the convolution of $h_1[n]$ and $y[n]$.
- For the second way of approach, let's say first deblurring will have $h_1[n]$ as impulse response and denoising has $h_2[n]$ as impulse response.
- Then after deblurring the input($y[n]$) the output (let's say $u[n]$) is the convolution sum of $y[n]$ and $h_1[n]$.And after denoising the deblurred signal, the output will be the convolution sum of $u[n]$ and $h_2[n]$.

- Final output ($x_2[n]$) will be the convolution of $h_2[n]$ with the convolution of $h_1[n]$ and $y[n]$.

- From both ways, we get the same output.
- Thus both approaches are appropriate.