3-parallel-reduction-cu

May 8, 2025

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[21]: | !pip install git+https://github.com/afnan47/cuda.git
     Collecting git+https://github.com/afnan47/cuda.git
       Cloning https://github.com/afnan47/cuda.git to /tmp/pip-req-build-j25w8mkj
       Running command git clone --filter=blob:none --quiet
     https://github.com/afnan47/cuda.git /tmp/pip-req-build-j25w8mkj
       Resolved https://github.com/afnan47/cuda.git to commit
     aac710a35f52bb78ab34d2e52517237941399eff
       Preparing metadata (setup.py) ... done
     Building wheels for collected packages: NVCCPlugin
       Building wheel for NVCCPlugin (setup.py) ... done
       Created wheel for NVCCPlugin: filename=NVCCPlugin-0.0.2-py3-none-any.whl
     size=4290
     sha256=c8f6e034779b7f0ee8c1ae200e11bd714d79a77cfdafa9d2d8e593d1a96c8fd3
       Stored in directory: /tmp/pip-ephem-wheel-cache-
     jia_5g_f/wheels/bc/4e/e0/2d86bd15f671dbeb32144013f1159dba09757fde36dc51a963
     Successfully built NVCCPlugin
     Installing collected packages: NVCCPlugin
     Successfully installed NVCCPlugin-0.0.2
[22]: %load_ext nvcc_plugin
     created output directory at /content/src
     Out bin /content/result.out
[26]: %%cu
      // WARNING: DO NOT COPY THIS CODE, INSTEAD DOWNLOAD IT TO AVOID ERRORS.
      #include <stdio.h>
      #define BLOCK_SIZE 256
      // Kernel for parallel reduction using min operation
      __global__ void reduceMin(int* input, int* output, int size) {
          __shared__ int sdata[BLOCK_SIZE];
          unsigned int tid = threadIdx.x;
          unsigned int i = blockIdx.x * blockDim.x + threadIdx.x;
          // Load data into shared memory
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if (i < size) {</pre>
        sdata[tid] = input[i];
    } else {
        sdata[tid] = INT_MAX;
    __syncthreads();
    // Perform reduction within each block
    for (unsigned int stride = blockDim.x / 2; stride > 0; stride >>= 1) {
        if (tid < stride) {</pre>
            sdata[tid] = min(sdata[tid], sdata[tid + stride]);
        }
        __syncthreads();
    }
    // Write the result for this block to global memory
    if (tid == 0) {
        output[blockIdx.x] = sdata[0];
    }
}
// Kernel for parallel reduction using max operation
__global__ void reduceMax(int* input, int* output, int size) {
    __shared__ int sdata[BLOCK_SIZE];
    unsigned int tid = threadIdx.x;
    unsigned int i = blockIdx.x * blockDim.x + threadIdx.x;
    // Load data into shared memory
    if (i < size) {</pre>
        sdata[tid] = input[i];
    } else {
        sdata[tid] = INT_MIN;
    }
    __syncthreads();
    // Perform reduction within each block
    for (unsigned int stride = blockDim.x / 2; stride > 0; stride >>= 1) {
        if (tid < stride) {</pre>
            sdata[tid] = max(sdata[tid], sdata[tid + stride]);
        __syncthreads();
    }
    // Write the result for this block to global memory
    if (tid == 0) {
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output[blockIdx.x] = sdata[0];
   }
}
// Kernel for parallel reduction using sum operation
__global__ void reduceSum(int* input, int* output, int size) {
    __shared__ int sdata[BLOCK_SIZE];
    unsigned int tid = threadIdx.x;
    unsigned int i = blockIdx.x * blockDim.x + threadIdx.x;
    // Load data into shared memory
    if (i < size) {</pre>
        sdata[tid] = input[i];
    } else {
        sdata[tid] = 0;
    }
    __syncthreads();
    // Perform reduction within each block
    for (unsigned int stride = blockDim.x / 2; stride > 0; stride >>= 1) {
        if (tid < stride) {</pre>
            sdata[tid] += sdata[tid + stride];
        }
        __syncthreads();
    }
    // Write the result for this block to global memory
    if (tid == 0) {
        output[blockIdx.x] = sdata[0];
    }
}
// Kernel for parallel reduction using average operation
__global__ void reduceAverage(int* input, float* output, int size) {
    __shared__ float sdata[BLOCK_SIZE];
    unsigned int tid = threadIdx.x;
    unsigned int i = blockIdx.x * blockDim.x + threadIdx.x;
    // Load data into shared memory
    if (i < size) {</pre>
        sdata[tid] = static_cast<float>(input[i]);
    } else {
        sdata[tid] = 0.0f;
    }
    __syncthreads();
```

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// Perform reduction within each block
   for (unsigned int stride = blockDim.x / 2; stride > 0; stride >>= 1) {
        if (tid < stride) {</pre>
            sdata[tid] += sdata[tid + stride];
        __syncthreads();
   }
   // Write the result for this block to global memory
   if (tid == 0) {
        output[blockIdx.x] = sdata[0] / static_cast<float>(size);
   }
}
int main() {
   // Input array
   const int array_size = 256;
   int input[array_size];
   // Initialize input array
   for (int i = 0; i < array_size; ++i) {</pre>
        input[i] = i + 1;
   }
   // Allocate device memory
   int* d_input;
   int* d_output_min;
   int* d_output_max;
   int* d_output_sum;
   float* d_output_avg;
    cudaMalloc((void**)&d_input, sizeof(int) * array_size);
    cudaMalloc((void**)&d_output_min, sizeof(int) * array_size);
    cudaMalloc((void**)&d_output_max, sizeof(int) * array_size);
    cudaMalloc((void**)&d_output_sum, sizeof(int) * array_size);
    cudaMalloc((void**)&d_output_avg, sizeof(float) * array_size);
   // Copy input array to device memory
    cudaMemcpy(d_input, input, sizeof(int) * array_size,_
 // Determine the number of threads and blocks
   int threads_per_block = BLOCK_SIZE;
    int blocks_per_grid = (array_size + threads_per_block - 1) /_
 →threads_per_block;
   // Launch the kernels for parallel reduction
```

```
reduceMin << <blocks_per_grid, threads_per_block>>> (d_input, d_output_min,__
 →array_size);
   reduceMax<<<br/>blocks_per_grid, threads_per_block>>>(d_input, d_output_max,_
 →array size);
   reduceSum<<<br/>blocks_per_grid, threads_per_block>>>(d_input, d_output_sum,_
 →array_size);
   reduceAverage << < blocks per grid, threads per block >>> (d input, _
 →d_output_avg, array_size);
   // Copy the results back to the host
   int min_result, max_result, sum_result;
   float avg_result;
    cudaMemcpy(&min_result, d_output_min, sizeof(int), cudaMemcpyDeviceToHost);
    cudaMemcpy(&max_result, d_output_max, sizeof(int), cudaMemcpyDeviceToHost);
    cudaMemcpy(&sum_result, d_output_sum, sizeof(int), cudaMemcpyDeviceToHost);
    cudaMemcpy(&avg_result, d_output_avg, sizeof(float),__
 // Print the results
   printf("Minimum value: %d\n", min_result);
   printf("Maximum value: %d\n", max_result);
   printf("Sum: %d\n", sum_result);
   printf("Average: %.2f\n", avg_result);
   // Free device memory
    cudaFree(d_input);
    cudaFree(d output min);
    cudaFree(d output max);
    cudaFree(d_output_sum);
   cudaFree(d_output_avg);
   return 0;
}
```

Minimum value: 0 Maximum value: 0

Sum: 0

Average: 0.00