

Minimum Spanning Trees: Krushkal's Algorithm and Prim's Algorithm

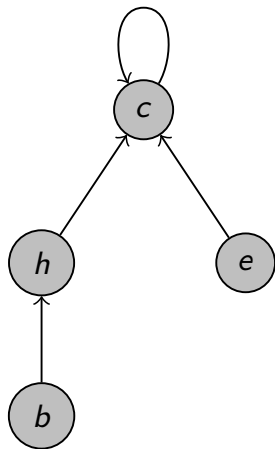
Subhabrata Samajder



IIIT, Delhi
Winter Semester,
31th May, 2023

Disjoint-set Forests (Cont.)

An Example: UNION(e, g) (Recap)

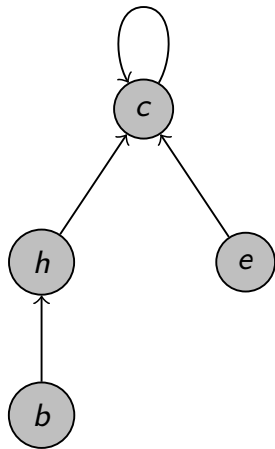


$$S_1 = \{b, c, e, h\}$$



$$S_2 = \{d, f, g\}$$

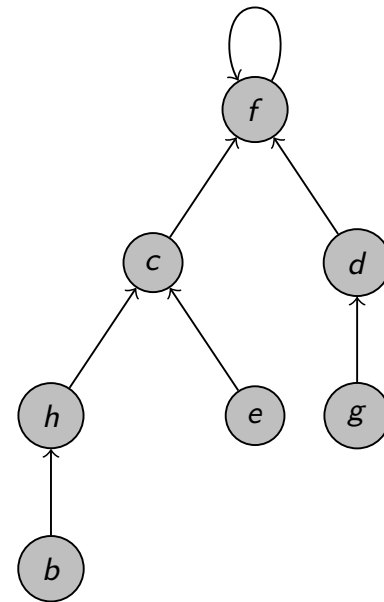
An Example: UNION(e, g) (Recap)



$$S_1 = \{b, c, e, h\}$$



$$S_2 = \{d, f, g\}$$



$$\text{UNION}(e, g) = S_1 \cup S_2$$

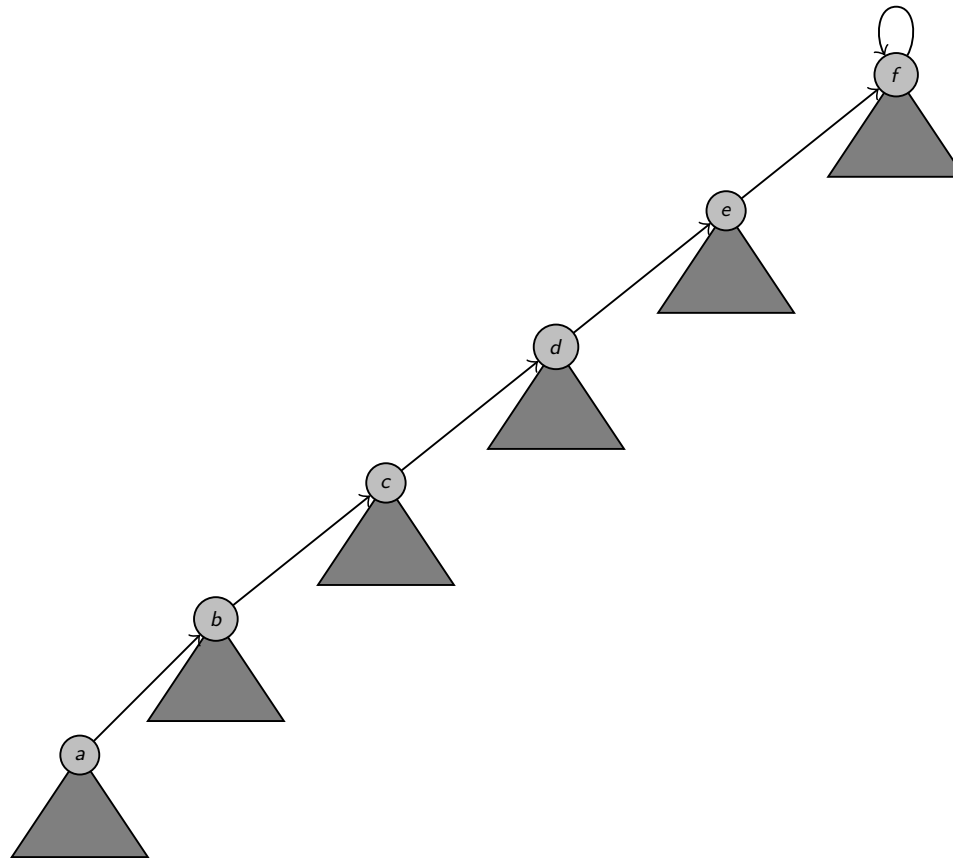
Heuristics 1: Union by Rank (Recap)

- **Idea:** During UNION operation, make the root of the tree with **fewer nodes** point to the root of the tree with more nodes.
- Rather than explicitly keeping track of the size of the subtree rooted at each node, we shall use an approach that **eases the analysis**.
- For each node, we maintain a **rank** that is an **upper bound** on the height of the node.
- **UNION:** Point the root with **smaller rank** to the root with larger rank.

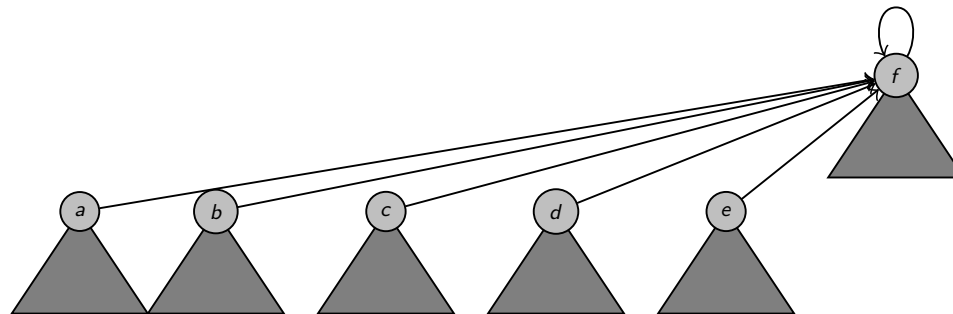
Heuristics 2: Path Compression (Recap)

- **FIND-SET:** Make each node on the **FIND-PATH** to point directly to the root.
- Path compression **does not** change any ranks.

An Example: Before FIND-SET(a) (Recap)



An Example: After FIND-SET(a) (Recap)



Pseudocode for Disjoint-set Forests

- Each node x maintains an integer value $rank[x]$.
- $rank[x]$: Is an upper bound on the height (the number of edges in the longest path between x and a descendant leaf) of x .
- After MAKE-SET the initial rank of the single node in the corresponding tree is 0.
- FIND-SET operation leaves all ranks unchanged.
- When applying Union to two trees, there are two cases, depending on whether the roots have **equal rank**.
 - **Unequal rank**: Make the root of higher rank the parent of the root of lower rank, but the **ranks** themselves remain **unchanged**.
 - **Equal ranks**: Arbitrarily choose one of the roots as the parent and increment its rank by 1.

MAKE-SET, UNION and LINK

MAKE-SET(x)

1. $p[x] \leftarrow x$; // $p[x]$ denotes the parent of x
2. $rank[x] \leftarrow 0$;

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LINK(x, y) // Takes pointers to the roots of x and y as inputs

1. if ($rank[x] > rank[y]$)
2. $p[y] \leftarrow x$;
3. else
4. $p[x] \leftarrow y$;
5. if ($rank[x] = rank[y]$)
6. $rank[y] = rank[y] + 1$;

FIND-SET

FIND-SET(x)

1. if ($x \neq p[x]$)
2. $p[x] \leftarrow \text{FIND-SET}(p[x]);$
3. return $p[x];$

It is a **two-pass method**:

- Takes one pass up the find path to find the root.
- Second pass back down the find path to update each node so that it points directly to the root.
- **Note:** Line 2 updates node x to point directly to the root, and this pointer is returned in line 3.

Effect of the Heuristics on the Running Time

- Separately, either union by rank or path compression improves the running time of the operations on disjoint-set forests.
- The improvement is even greater when the two heuristics are used together.
- Alone, **union by rank** yields a running time of $\mathcal{O}(m \log n)$ and this bound is **tight**.
- If there are n MAKE-SET operations (and hence at most $n - 1$ UNION operations) and f FIND-SET operations, the **path-compression heuristic alone** gives a worst-case running time of $\mathcal{O}(n + f \cdot \log_{2+f/n} n)$.
- **Worst-case Complexity (Together):** $\mathcal{O}(m \cdot \alpha(n))$, where $\alpha(n)$ is a **very slowly growing function**.
- In any conceivable application $\alpha(n) \leq 4$.
- \therefore in most practical situations the running time is **linear** in m .

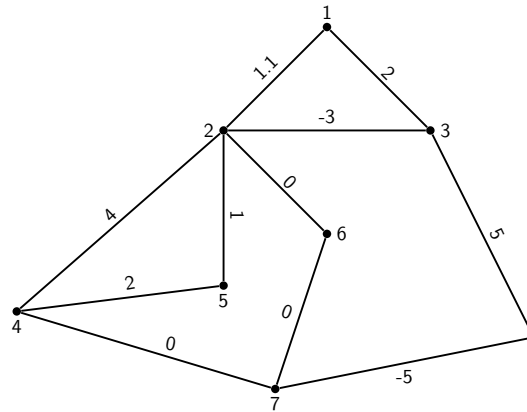
Minimum Spanning Tree (MST)

Some Definitions

Definition (Weighted Graph)

A **weighted graph** $G = (V, E, w)$ is a graph $G = (V, E)$ with an associated function $w : E \rightarrow \mathbb{R}$, called the **weight function**.

Example: Let H be a subgraph of G .



Then w is easily extended to subgraphs in a natural way,

$$w(H) = \sum_{e \in H} w(e).$$

Some Definitions (Cont.)

Definition (Spanning Tree)

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Definition (Minimum Spanning Tree (MST))

A **minimum spanning tree** for a **weighted graph** $G = (V, E)$ is a spanning tree T , such that $w(T)$ is the minimum among the weights of all spanning trees of G .

Note: There may be more than one MST's for G .

Motivation

Problem: Suppose there are n cities in a country. For each pair of cities c_1 and c_2 one can estimate the cost of connecting c_1 and c_2 by a direct highway. What is the **minimum cost** of connecting all the cities?

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Solution: A MST for K_n with a suitable weight function.

Kruskal's Algorithm

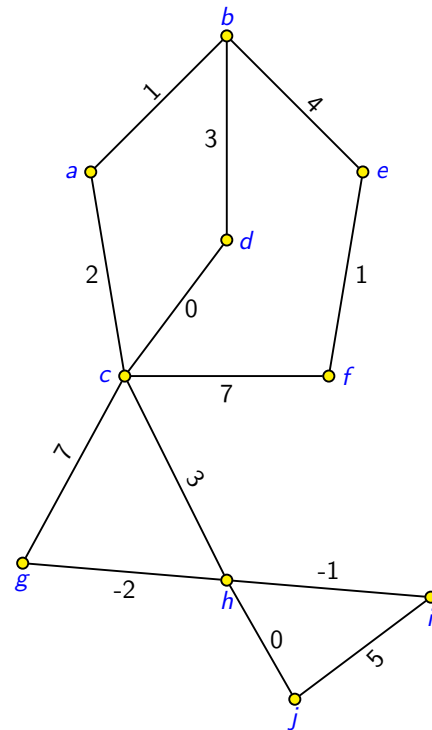
Introduction

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- Uses a [Greedy strategy](#).
- **Idea:** Finds an edge of the least possible weight connecting any two trees in the forest.
- [Connected graphs](#): It finds a subset of the edges that forms a tree that includes every vertex, such that the total weight of all the edges in the tree is minimized.
- [Disconnected graphs](#): It finds a [minimum spanning forest](#).
- **Other MST Algorithms:** Prim’s algorithm, Reverse-delete algorithm, and Borůvka’s algorithm.

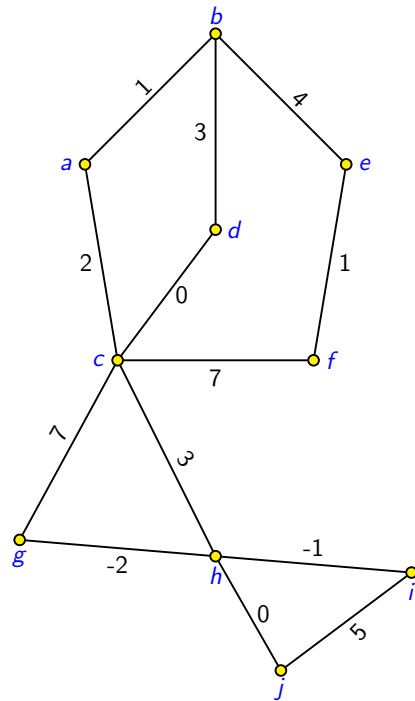
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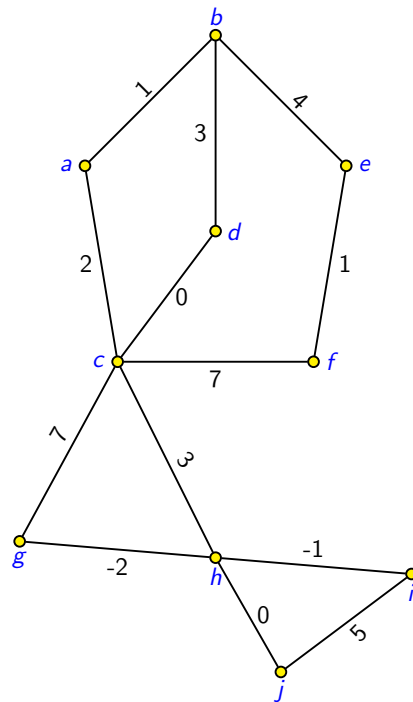
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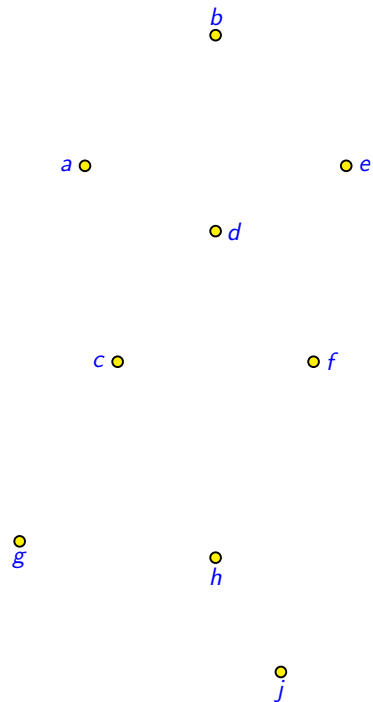
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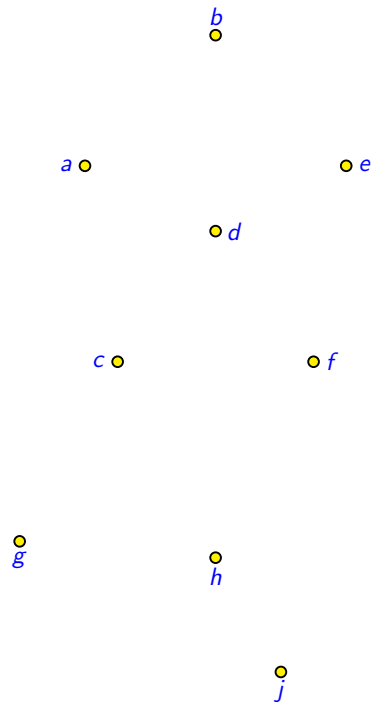
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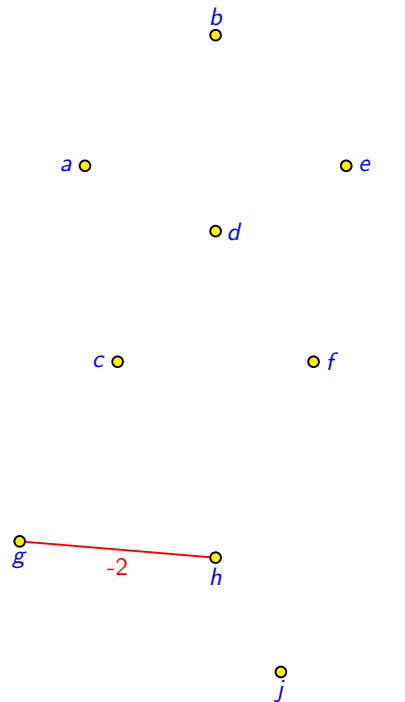
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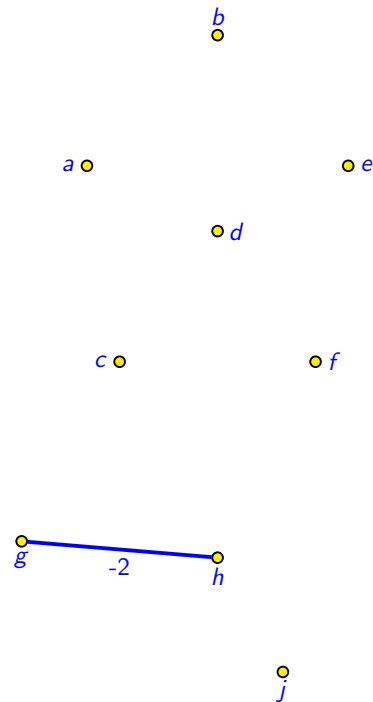
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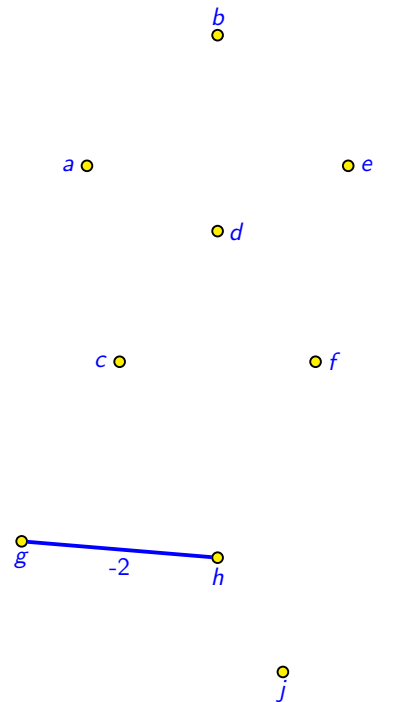
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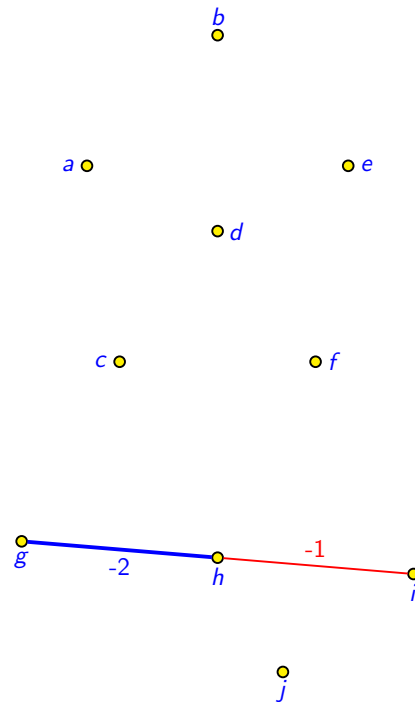
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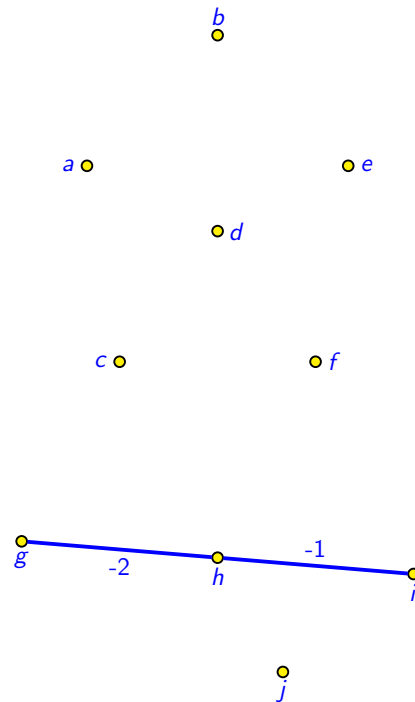
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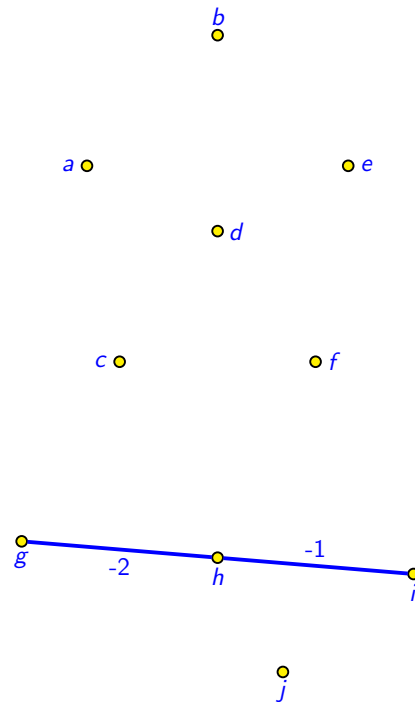
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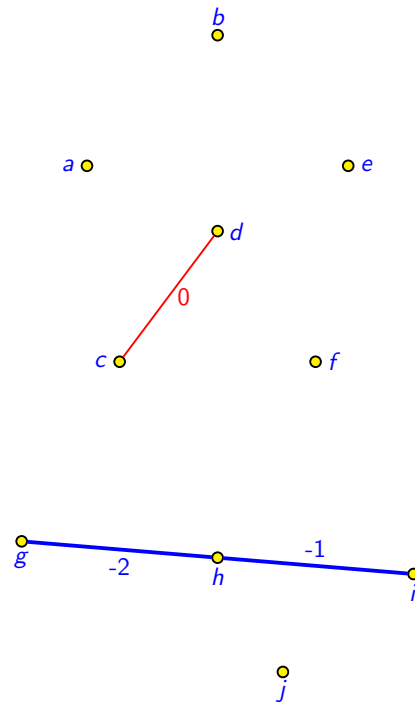
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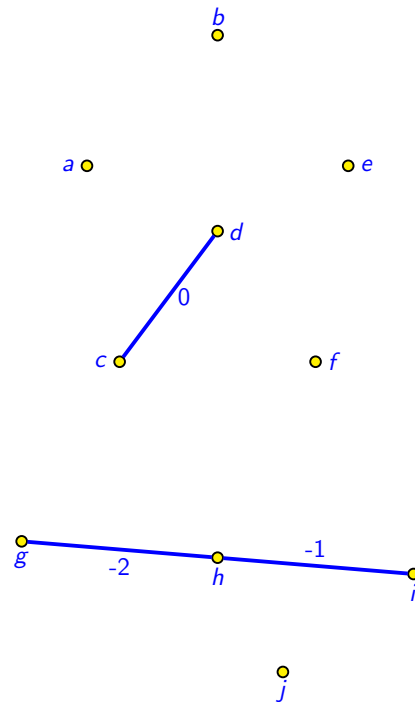
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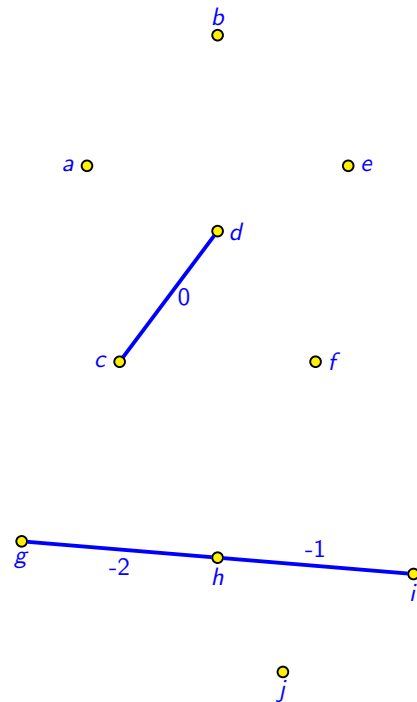
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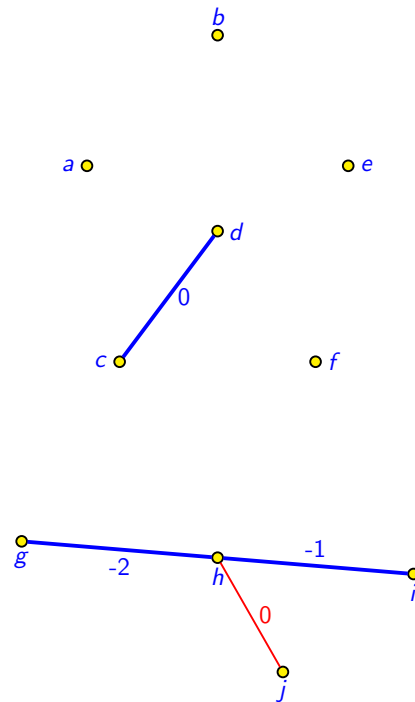
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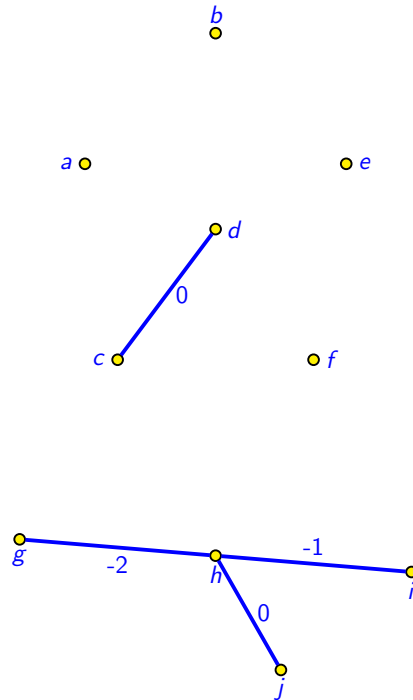
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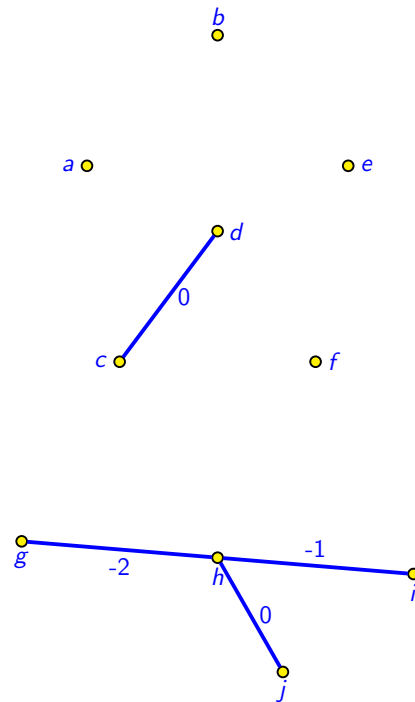
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KRUSKAL ALGORITHM(G)



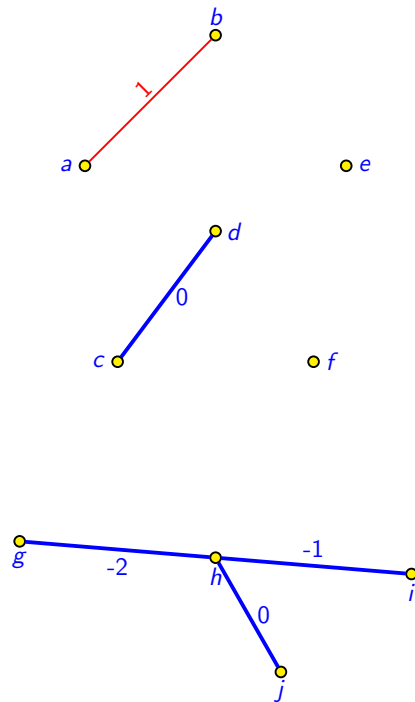
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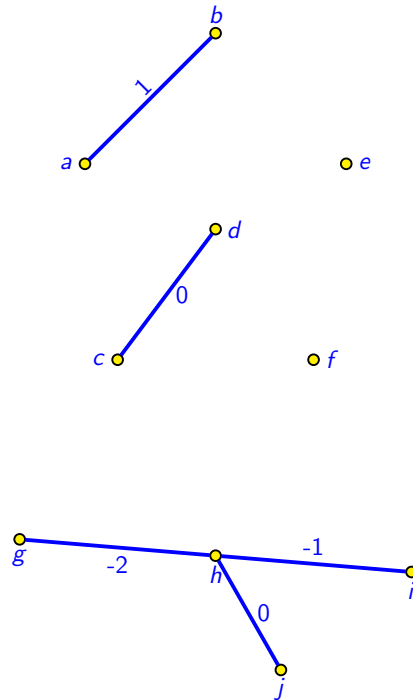
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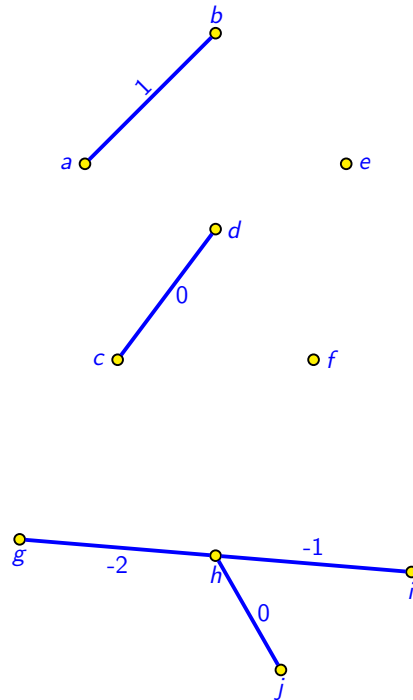
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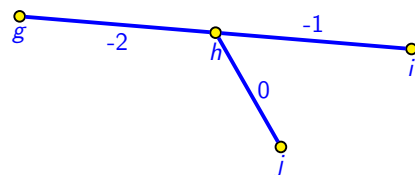
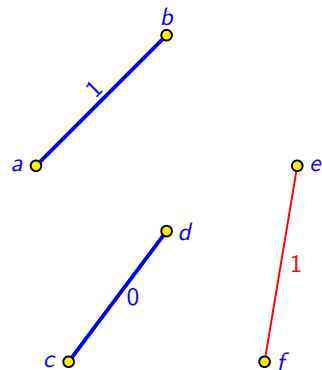
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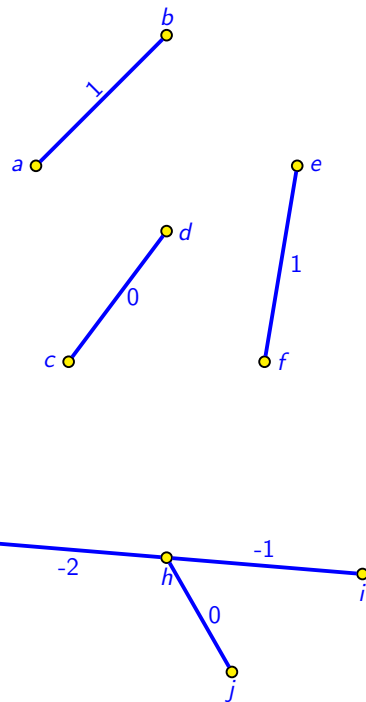
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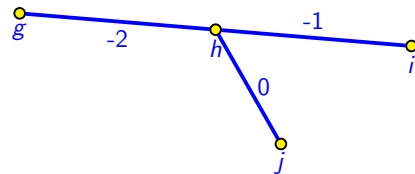
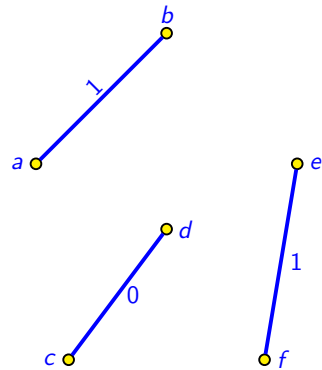
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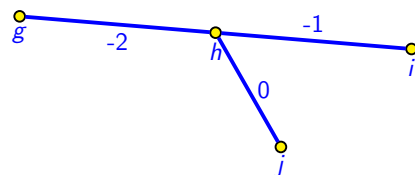
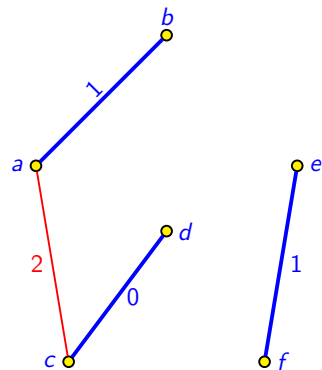
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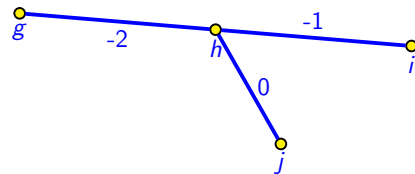
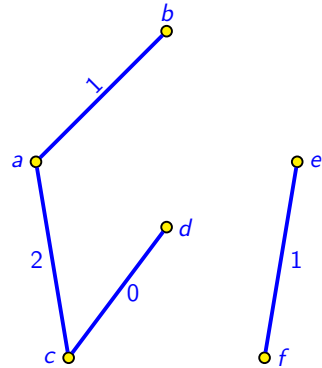
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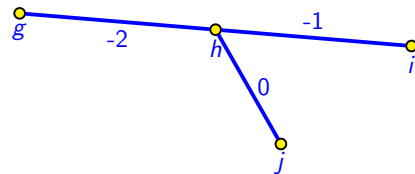
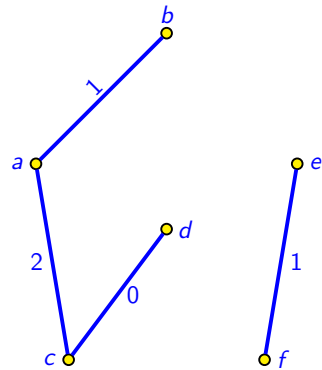
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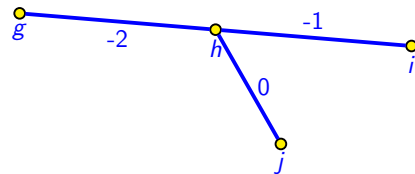
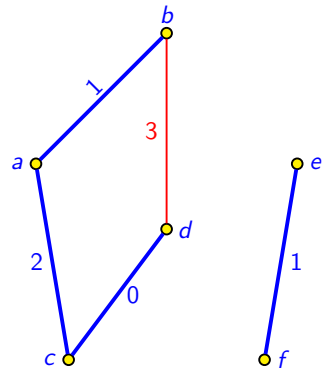
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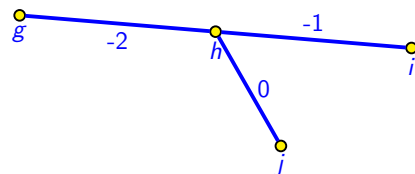
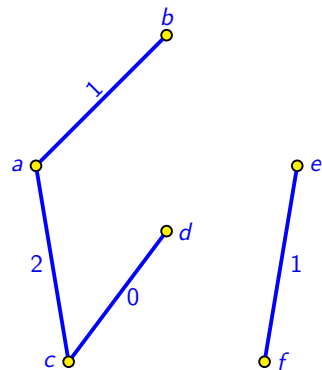
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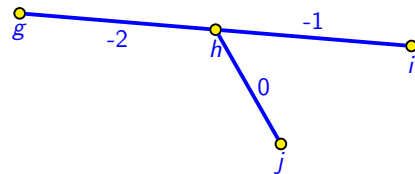
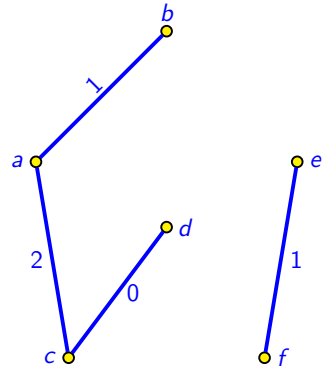
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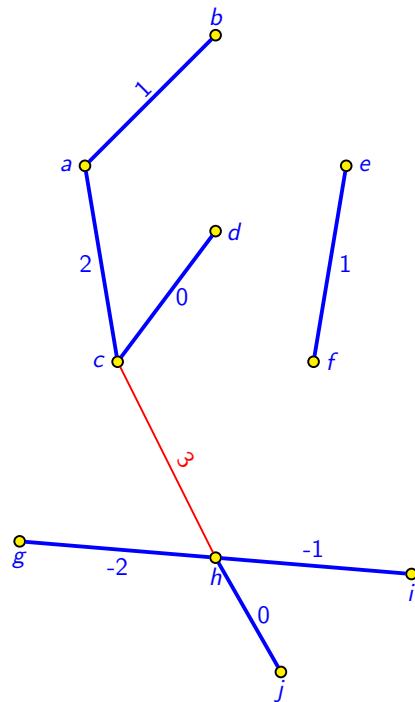
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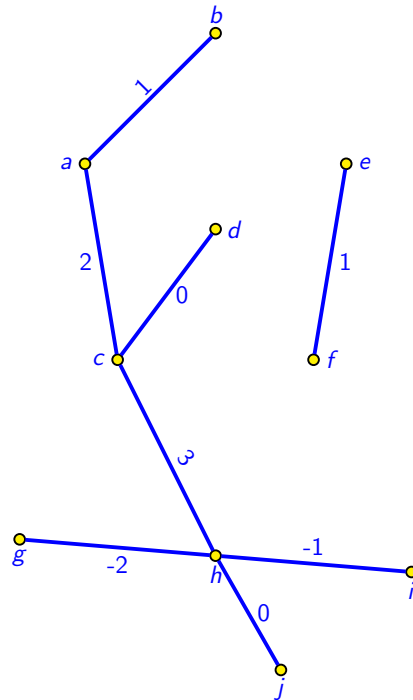
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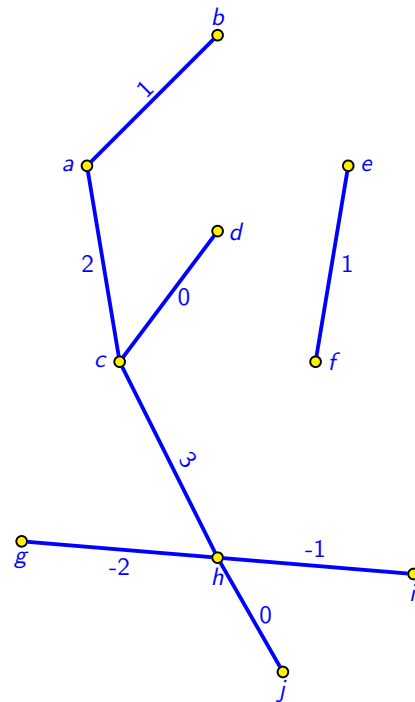
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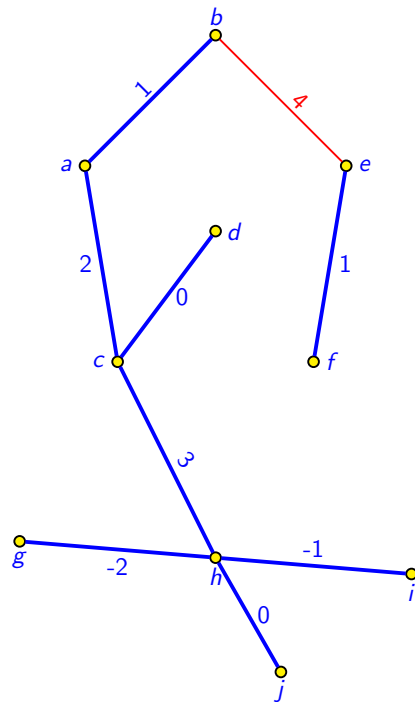
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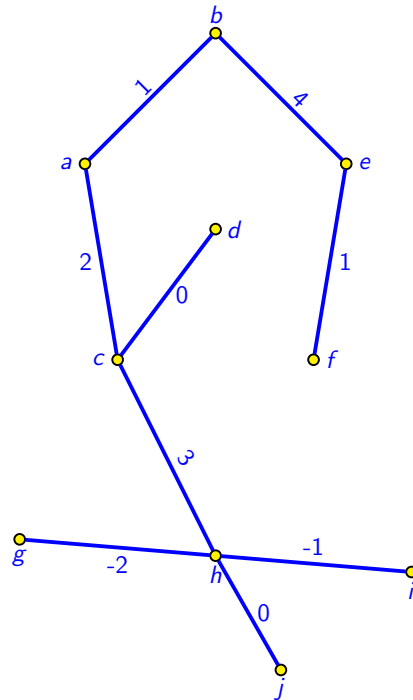
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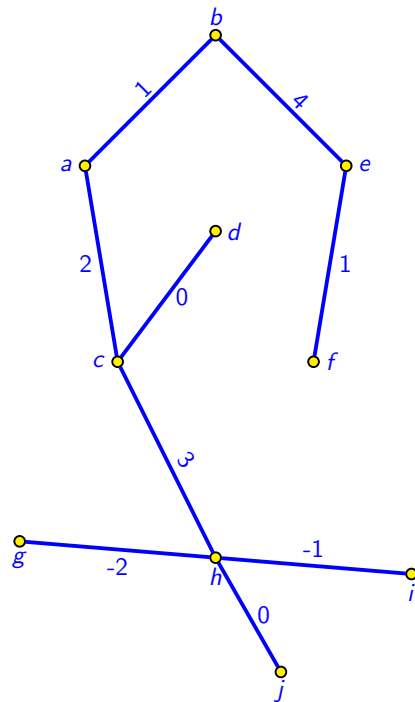
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(g, h)	-2	(a, b)	1	(c, h)	3	(c, g)	7
(h, i)	-1	(e, f)	1	(b, e)	4		
(c, d)	0	(a, c)	2	(j, i)	5		
(h, j)	0	(b, d)	3	(c, f)	6		

KRUSKAL ALGORITHM(G)



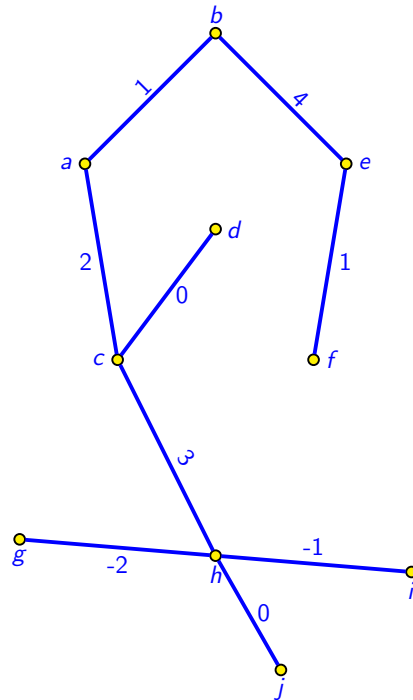
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1. $\mathcal{L} \leftarrow E$
Sort \mathcal{L} in ascending order.
2. (Grow a subgraph $T = (V, E')$ into a tree)
Initially $E' = \emptyset$
3. **while** ($|E'| < n - 1$)
4. **Pick the next edge in \mathcal{L} .**
5. **if** $T \cup \{e\}$ creates a cycle
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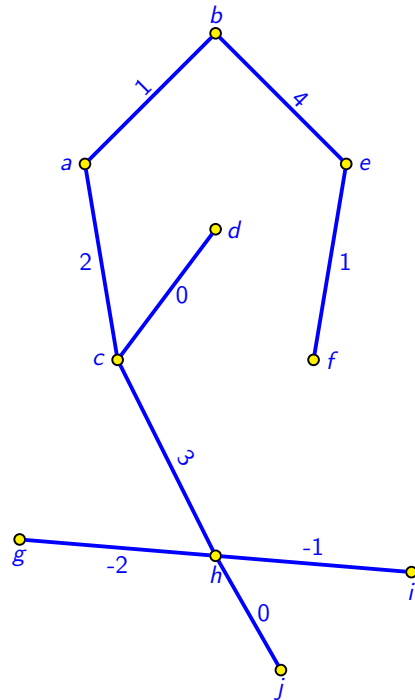
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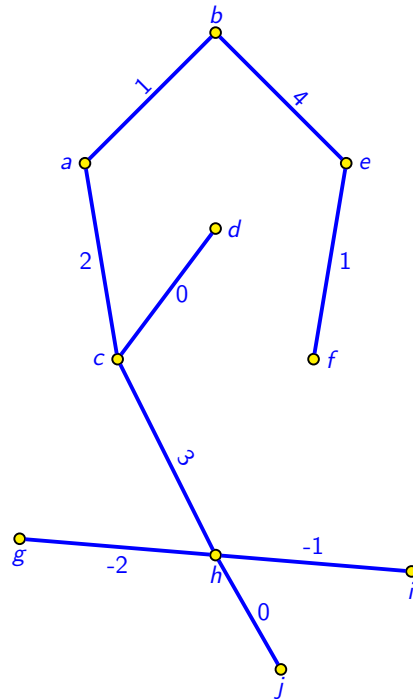
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$$w(G) = \sum_{e \in E'} w(e) = 8.$$

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$$w(G) = \sum_{e \in E'} w(e) = 8.$$

Question: How to check whether $T \cup \{e\}$ creates a cycle or not?

Correctness

Theorem

The spanning tree returned by Kruskal's algorithm is a MST.

Proof of the Theorem

Let T be returned by the algorithm and let S be a MST of G .

If T is equal to S then there is nothing to prove.

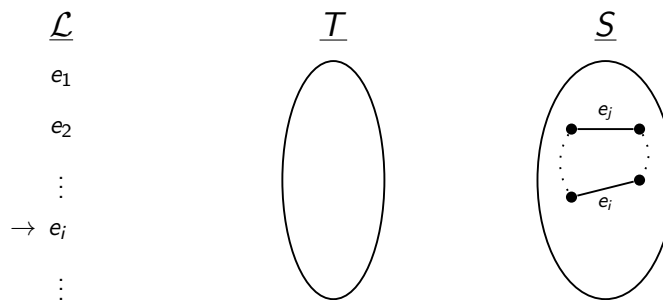
So, let $T \neq S$.

Strategy: From S form a spanning tree S' s.t., $w(S') \leq w(S)$ and S' has one more edge in common to T than S does.

Repeat the strategy at most $n - 1$ times to obtain a tree S_0 which is equal to T and

$$w(T) = w(S_0) \leq \dots \leq w(S') \leq w(S).$$

Proof of the Theorem



Since $S \neq T$, let $e_i \in \mathcal{L}$ be the first i , s.t., $e_i \in T$ but $e_i \notin S$. Consider $S \cup \{e_i\}$.

- This must have created a **cycle** in S .
- Then there must be an edge e_j on this cycle which is not in T .
- **Modify S :**

$$S' \leftarrow (S \setminus \{e_j\}) \cup \{e_i\}.$$

So S' has one more edge in common to T than S and

$$w(S') = w(S) - w(e_j) + w(e_i).$$

Proof of the Theorem

Can e'_j 's position in \mathcal{L} be earlier to e_i ?

Proof of the Theorem

Can e_j 's position in \mathcal{L} be earlier to e_i ? No.

- Notice that $e_j \notin T$ because it must have formed a cycle with edges in T which are earlier to e_j in \mathcal{L} .
- By definition of e_i , if $j < i$, then all these edges must be in S .
- Hence with e_j they form a cycle in S ! $\Rightarrow \times$

$\therefore j > i$, which implies that $w(S') < w(S)$. Hence the theorem.

An Implementation Using Disjoint-set Data Structure

MST-KRUSKAL(G, w)

I/P: A connected, weighted undirected graph $G = (V, E)$ and the corresponding weight function w .

O/P: A list of edges of the MST.

1. $A \leftarrow \emptyset$
2. **for** each vertex $v \in V$
3. MAKE-SET(v)
4. sort the edges of E into non-decreasing order of weight w
5. **for** each edge $(u, v) \in E$, taken in non-decreasing order of weight
6. **if** (FIND-SET(u) \neq FIND-SET(v))
7. $A \leftarrow A \cup \{(u, v)\}$
8. UNION(u, v)
9. **return** A

Time Complexity

- The running time depends on the implementation of the disjoint-set data structure.
- Assume the **disjoint-set-forest implementation** with the **union-by-rank** and **path-compression** heuristics.
- Recall that it is the asymptotically **fastest implementation known**.

Time Complexity

- **Line 1:** Initializing the set A takes $\mathcal{O}(1)$ time.
- **Line 4:** Sort the list of edges takes $\mathcal{O}(|E| \log |E|)$ times.
- **Lines 2-3:** Performs $|V|$ MAKE-SET operations.
- **Lines 5-8:** Performs $\mathcal{O}(|E|)$ FIND-SET and UNION operations.
- **Lines 2-3 + Lines 5-8:** Takes a total of

$$\begin{aligned} & \mathcal{O}((|V| + |E|)\alpha(|V|)) \\ &= \mathcal{O}(|E| \cdot \alpha(|V|)) \quad [\because |E| \geq |V| - 1 \text{ (} G \text{ is connected)}] \end{aligned}$$

time, where α is the very slowly growing function.

- Moreover, since $\alpha(|V|) = \mathcal{O}(\log |V|)$ (slowly growing w.r.t. V), the running time of Kruskal's algorithms is

$$\mathcal{O}(|E| \log |V|).$$

Prim's Algorithm

History

- 1st developed in 1930 by Czech mathematician [Vojtěch Jarník](#).
- Rediscovered and republished later by computer scientists
 - [Robert C. Prim](#) in 1957 and
 - [Edsger W. Dijkstra](#) in 1959.
- **Other Names:**
 - [Jarník's algorithm](#),
 - [Prim-Jarník algorithm](#),
 - [Prim-Dijkstra algorithm](#) or
 - the [DJP algorithm](#).

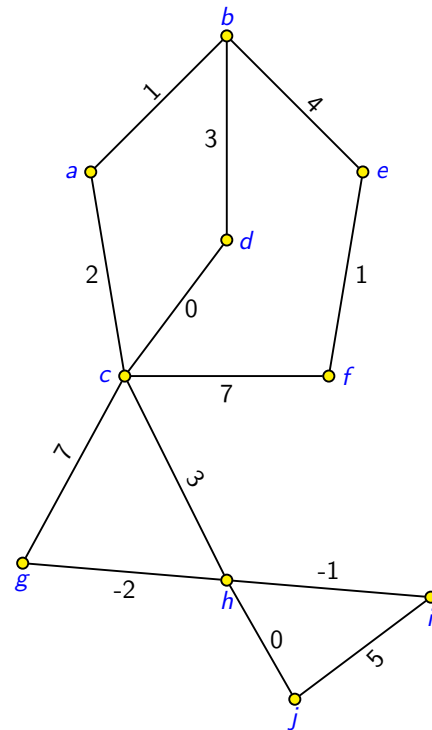
Introduction

- Operates much like Dijkstra's algorithm for finding shortest paths in a graph.
- **Property:** The edges in the set A always form a single tree.
- **Key Idea:**
 - Starts from an arbitrary root vertex r .
 - Grows until the tree spans all the vertices in V .
- **Strategy:**
 - At each step, a **light edge** is added to the tree A that connects A to an isolated vertex of $G_A = (V, A)$.
 - **Greedy:** The tree is augmented at each step with an edge that contributes the **minimum amount possible to the tree's weight**.

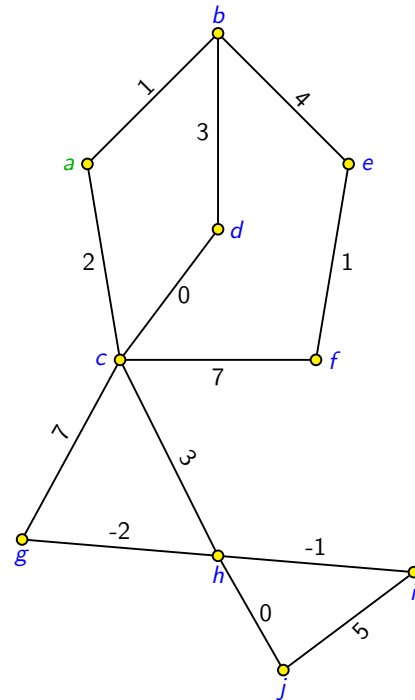
The Algorithm

- **Efficiency:** Depends on how easy it is to select a new edge to be added to the tree formed by the edges in A .
- **I/P:** A connected graph $G = (V, E)$ and the root r .
- All vertices that are **not** in the tree reside in a MIN-PRIORITY queue Q based on a **key field**.
- For each vertex v , $key[v]$ is the minimum weight of any edge connecting v to a vertex in the tree.
- By convention, $key[v] = \infty$ if there is no such edge.
- The field $\pi[v]$ names the parent of v in the tree.
- **During execution:** $A = \{(\pi[v], v) : v \in \{V \setminus \{r\}\} \setminus Q\}$.
- **Termination:** When the MIN-PRIORITY queue Q is **empty**.
 - $A = \{(\pi[v], v) : v \in V \setminus \{r\}\}$.

MST-PRIM(G, w, r)



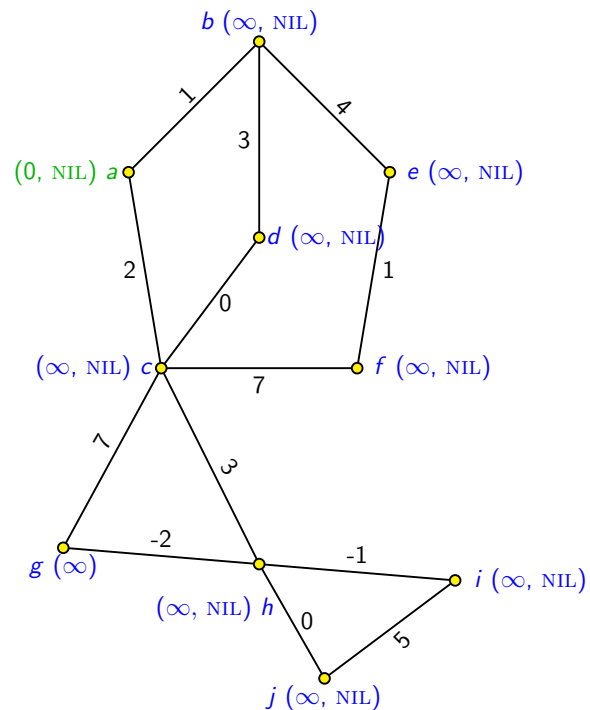
MST-PRIM(G, w, r)



I/P: A weighted connected undirected graph $G = (V, E, w)$ and a root vertex r .

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MST-PRIM(G, w, r)

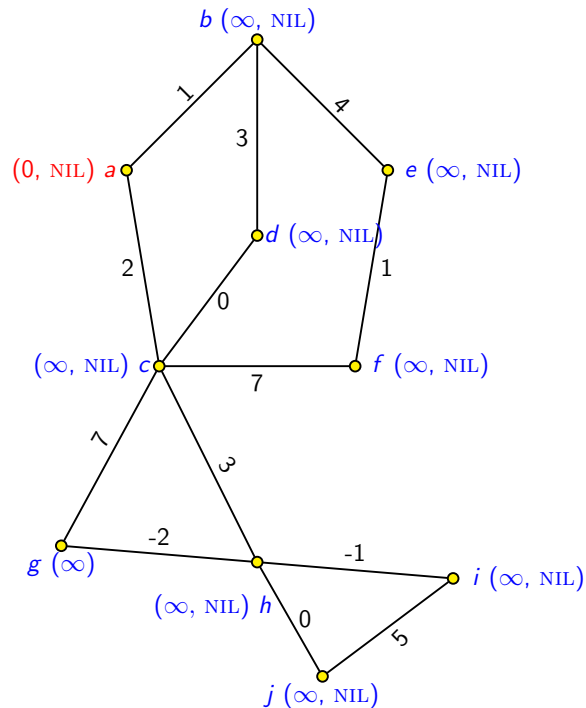


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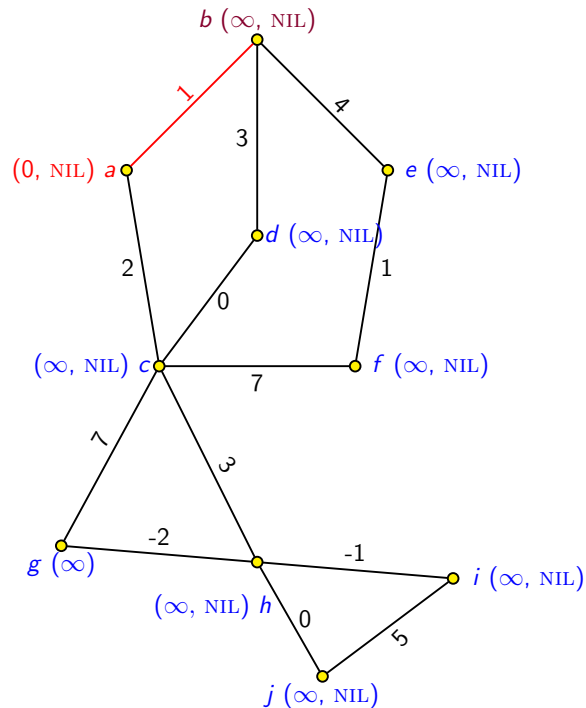


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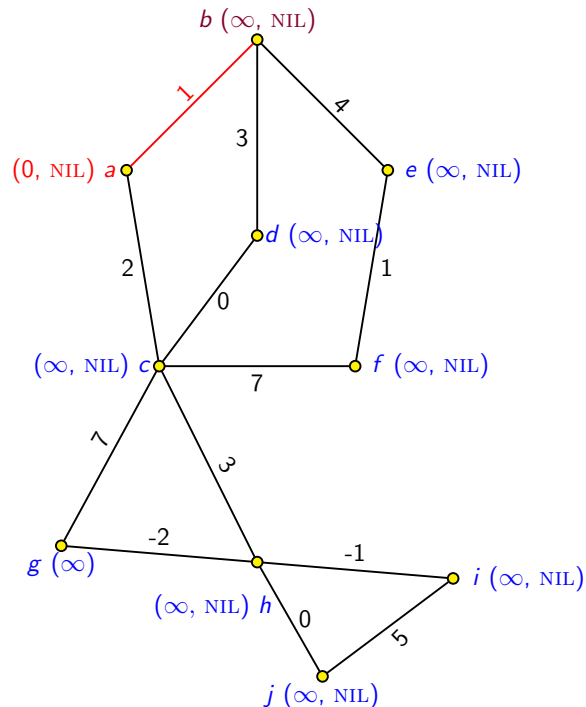


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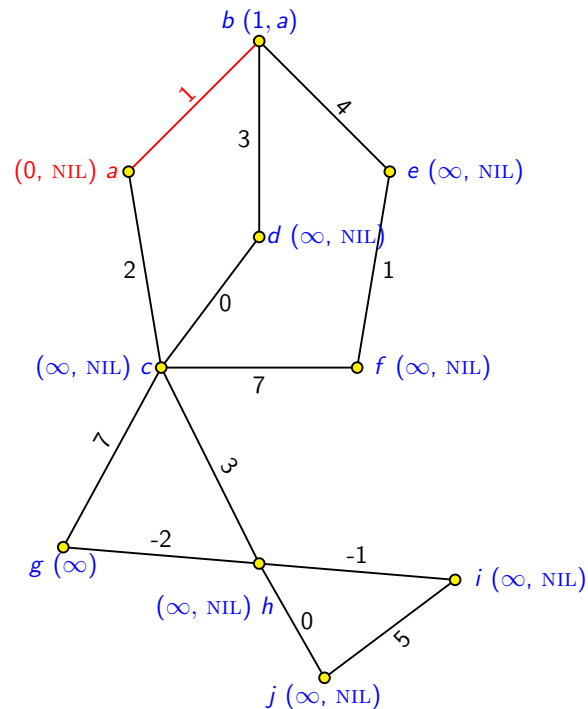


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MST-PRIM(G, w, r)

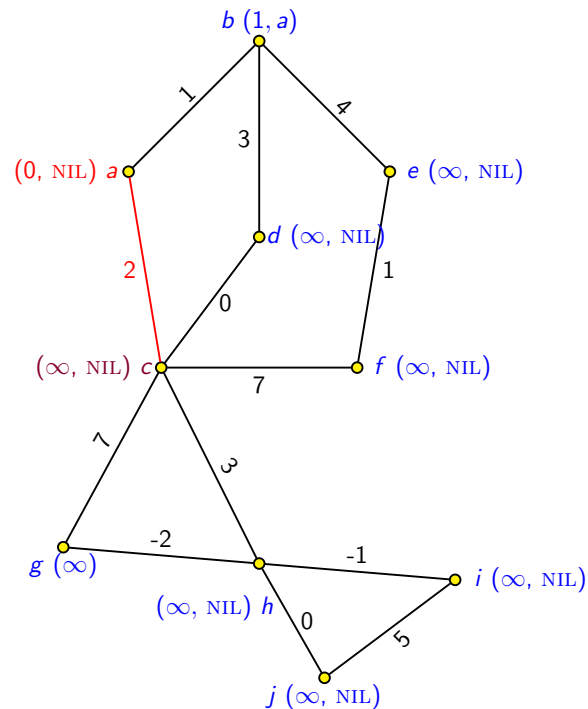


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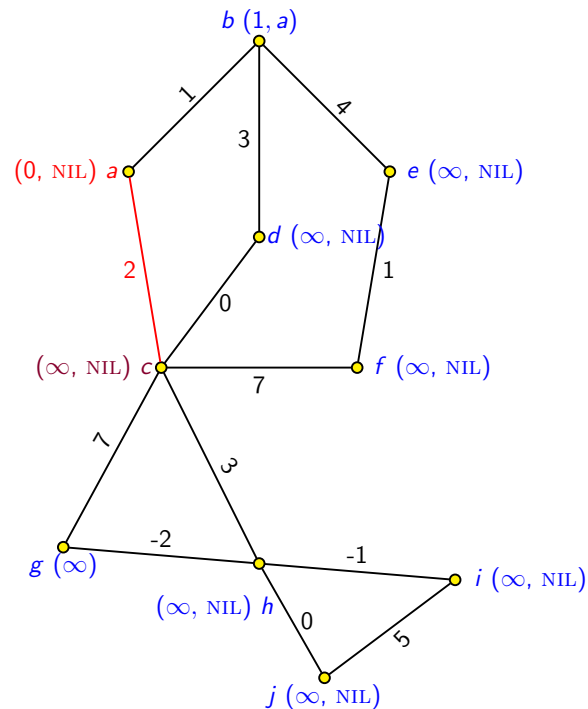


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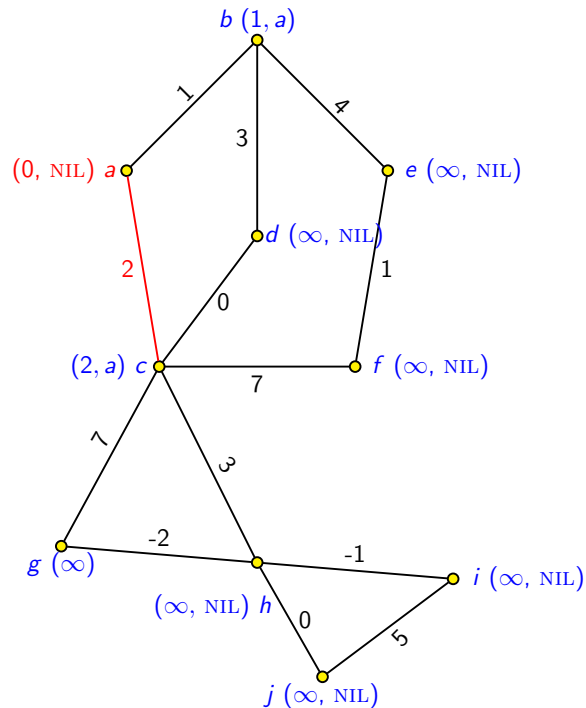


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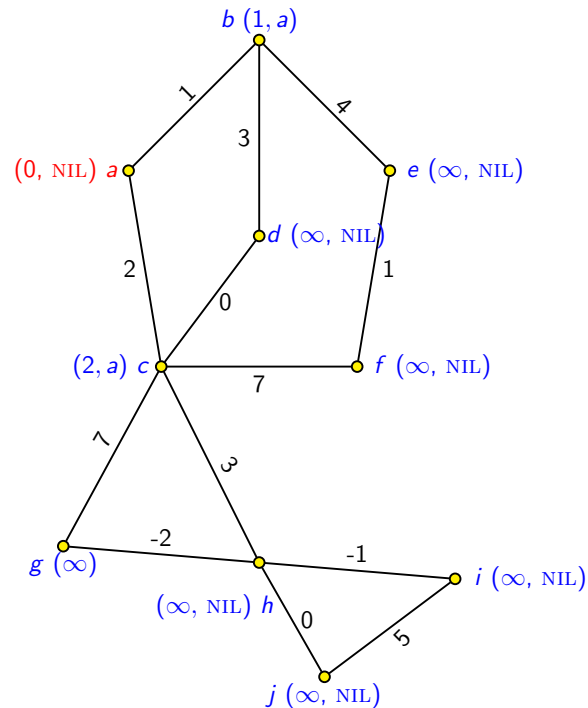


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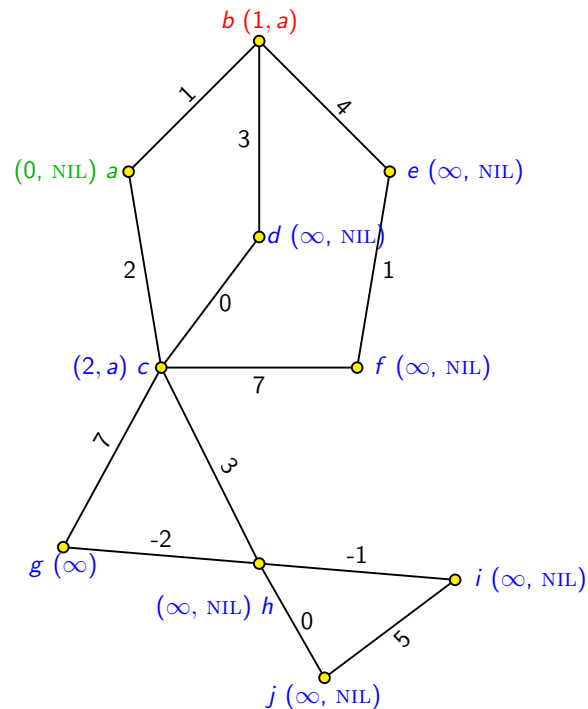


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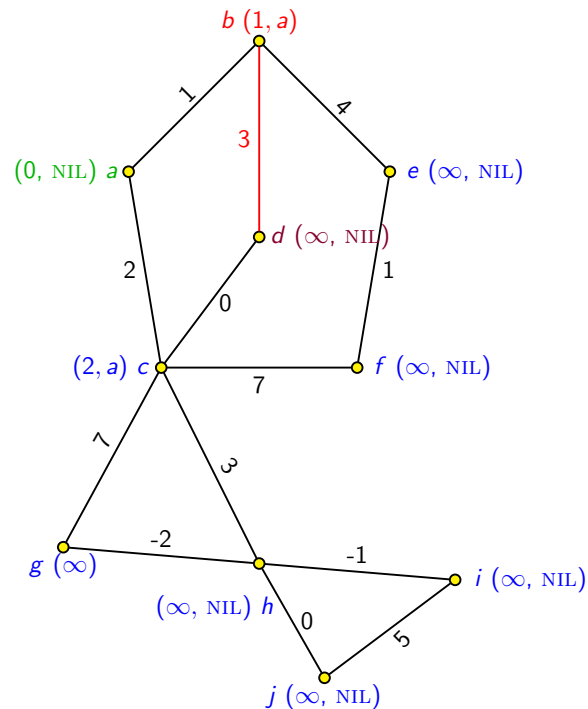


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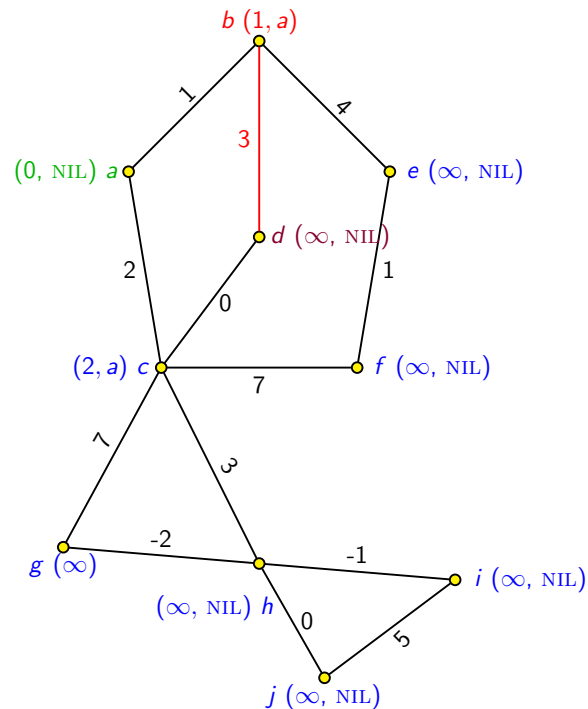


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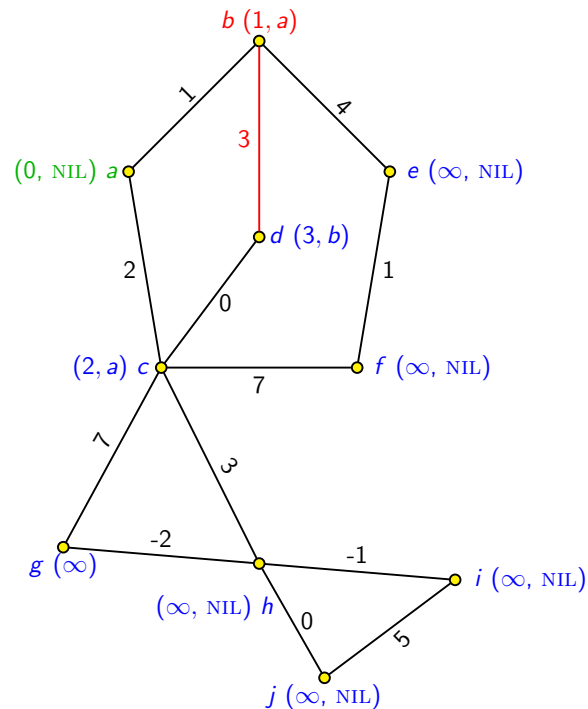


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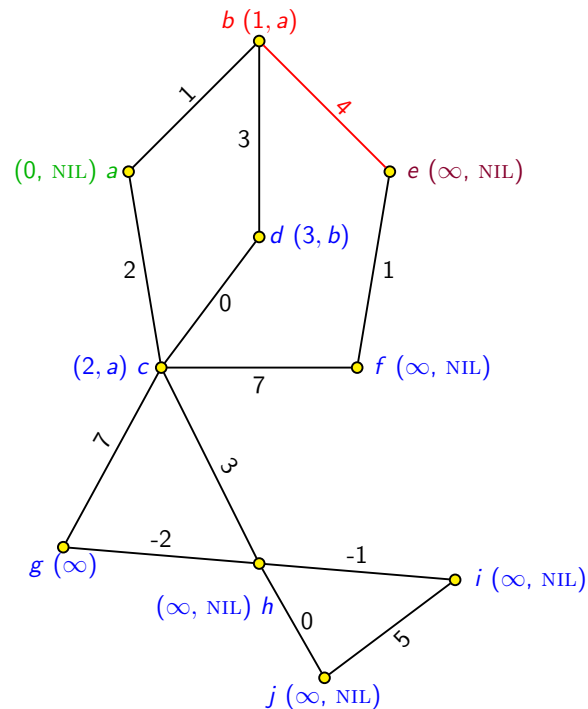


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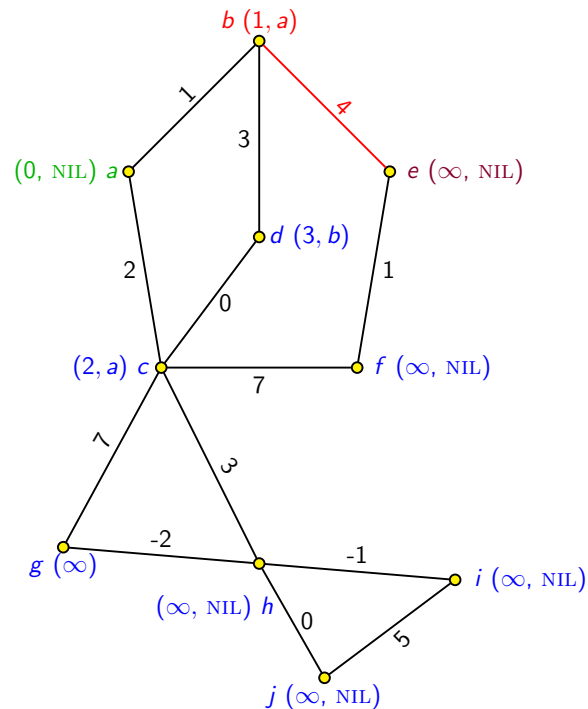


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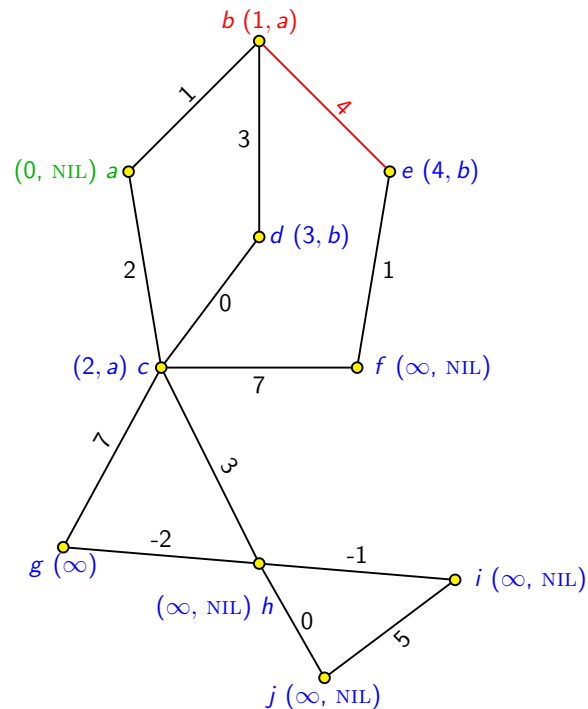


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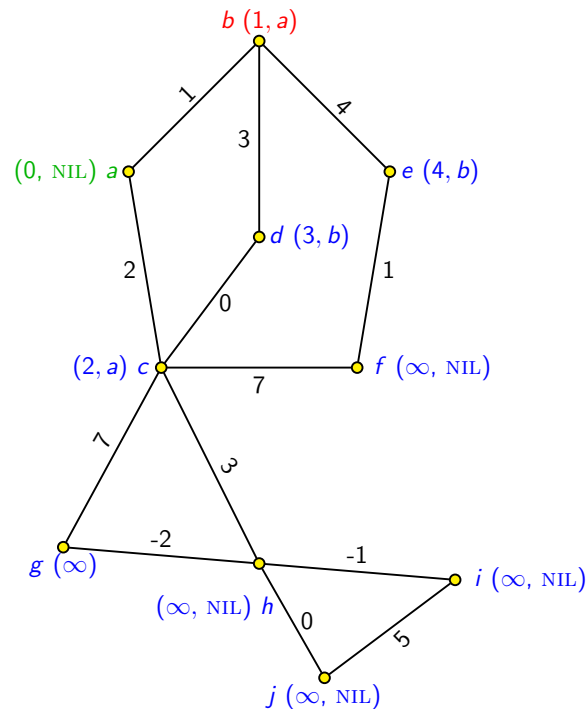


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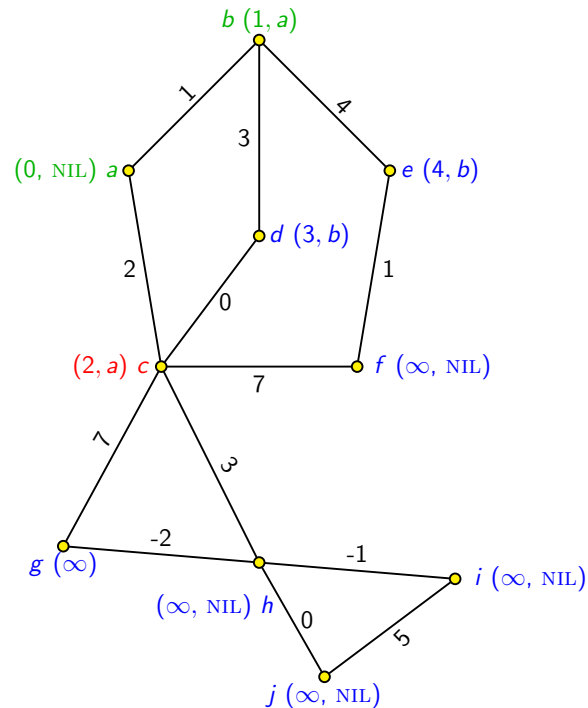


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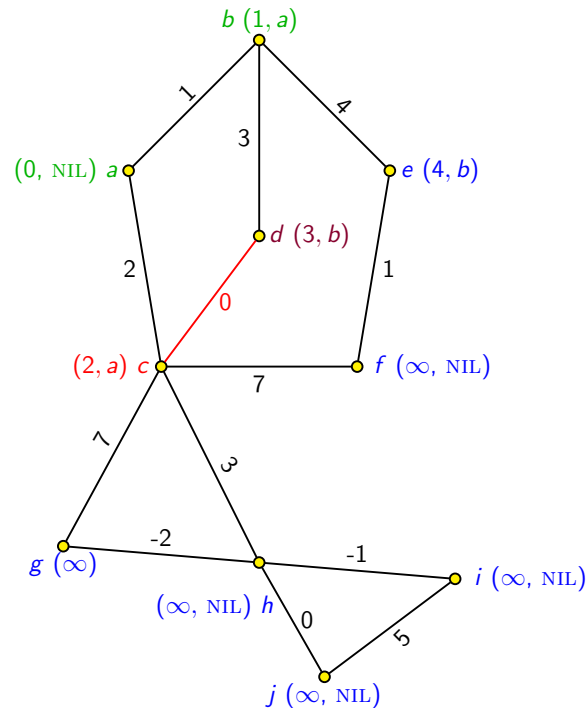


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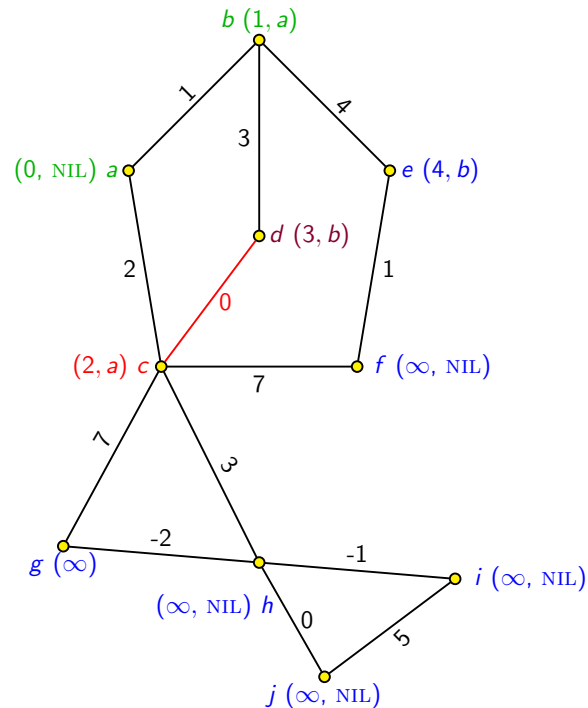


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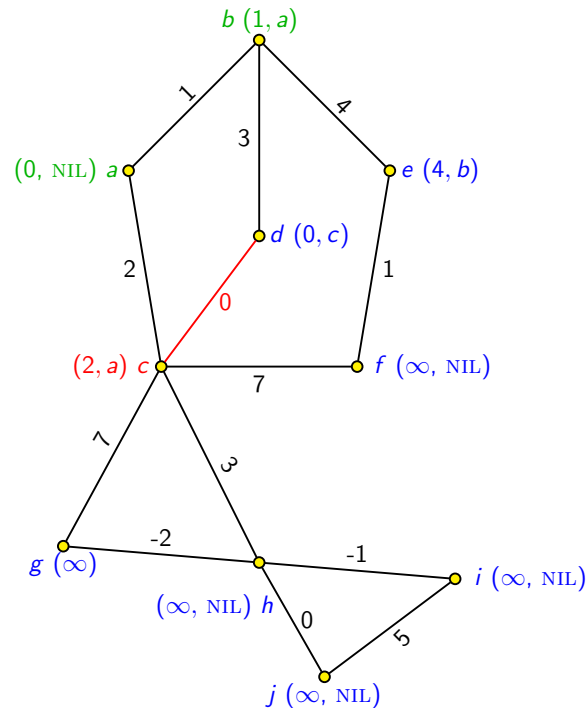


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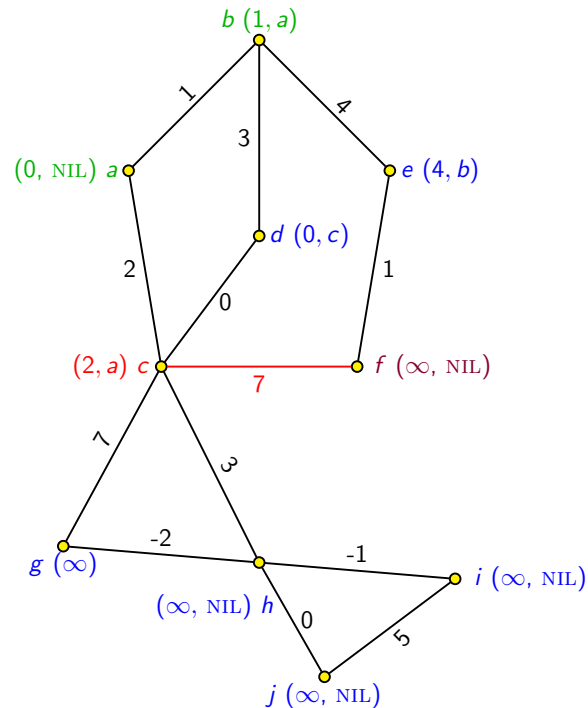


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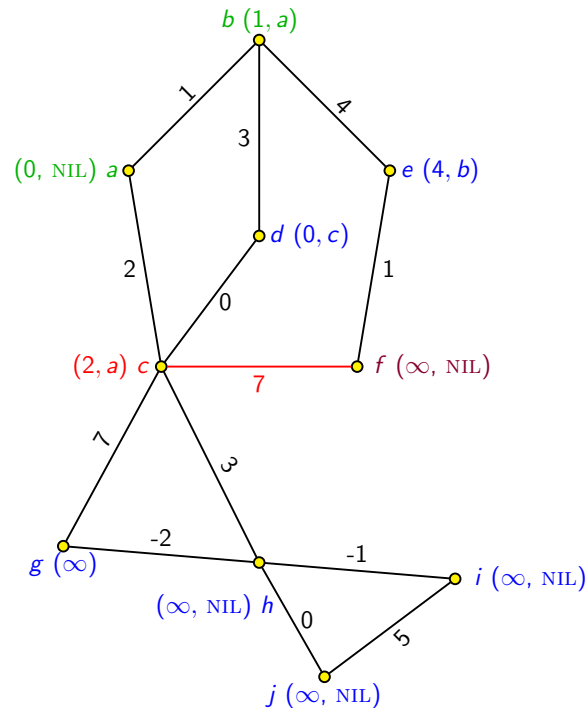


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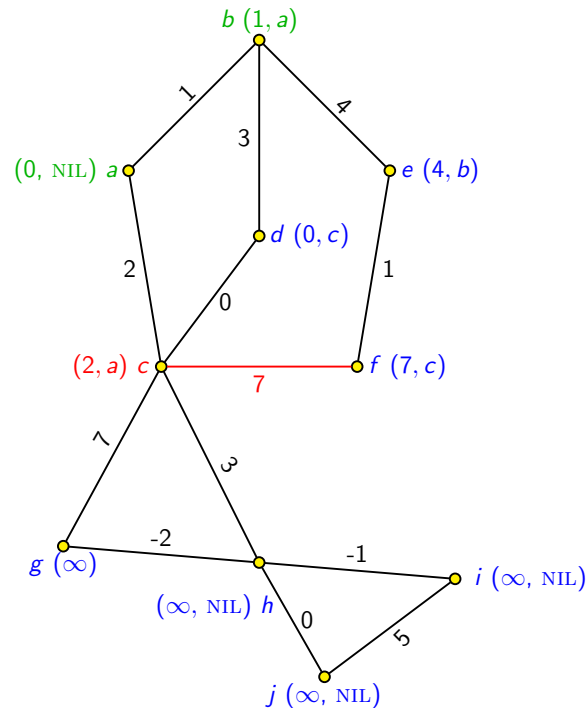


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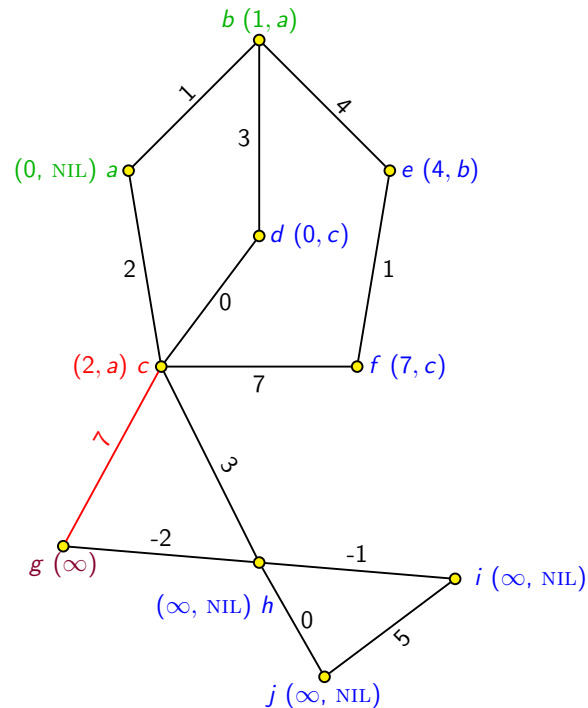


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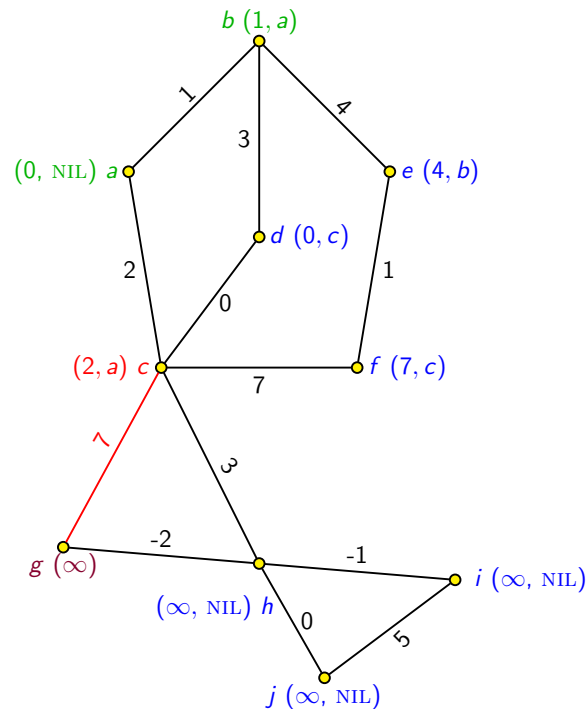


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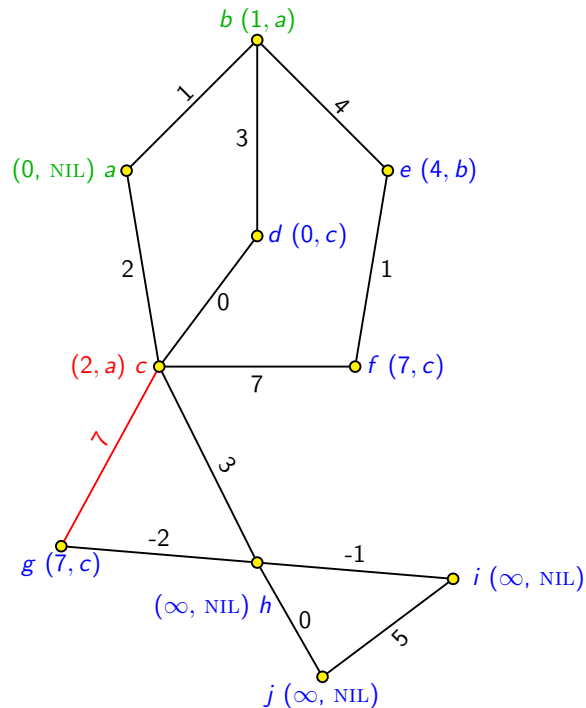


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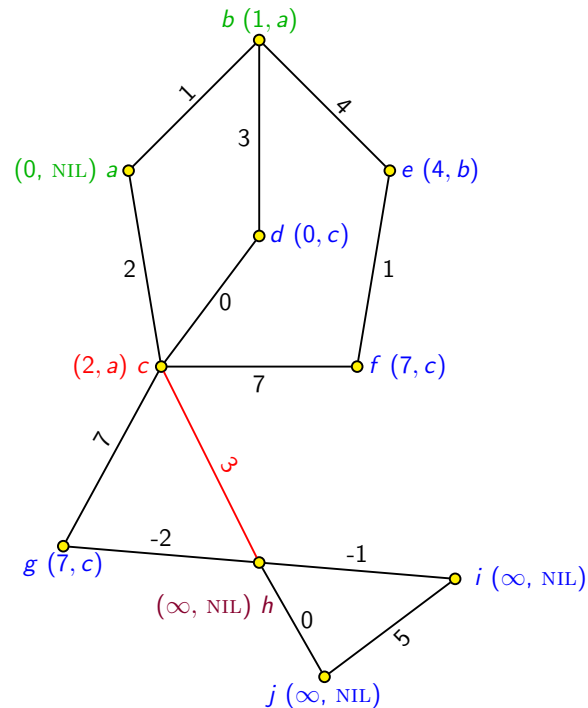


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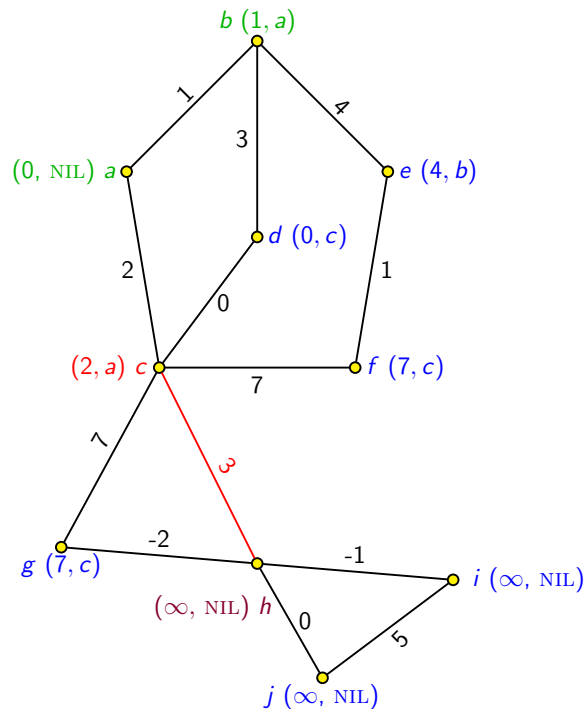


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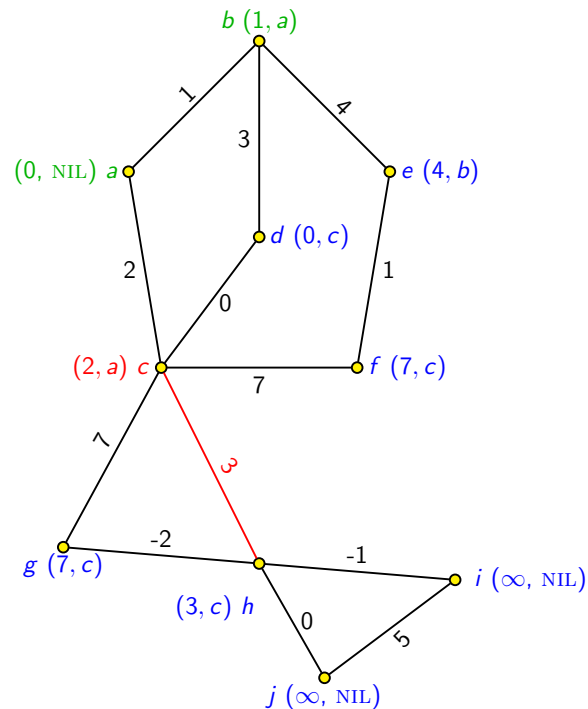


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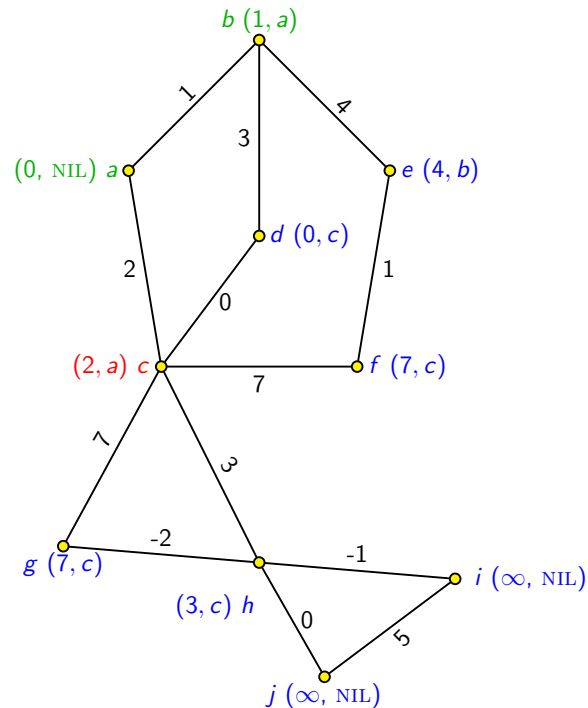


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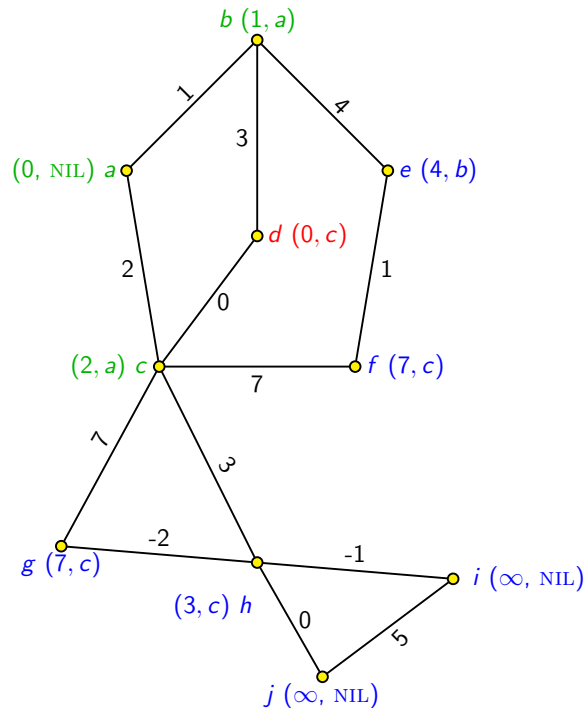


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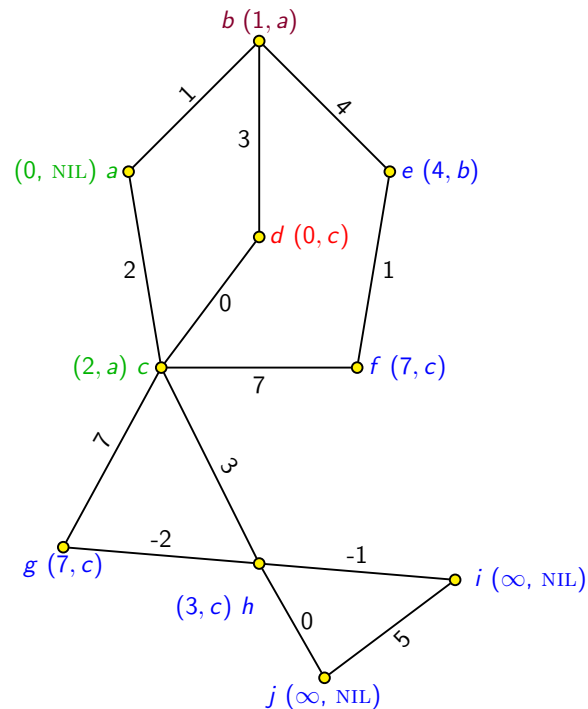


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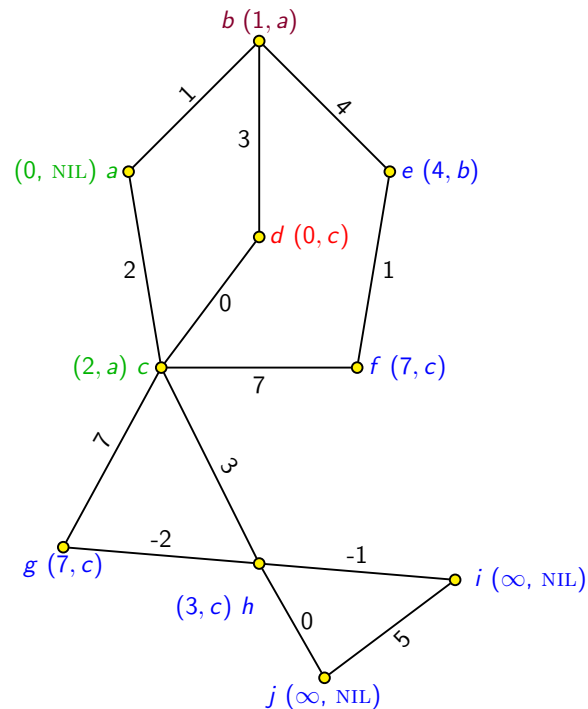


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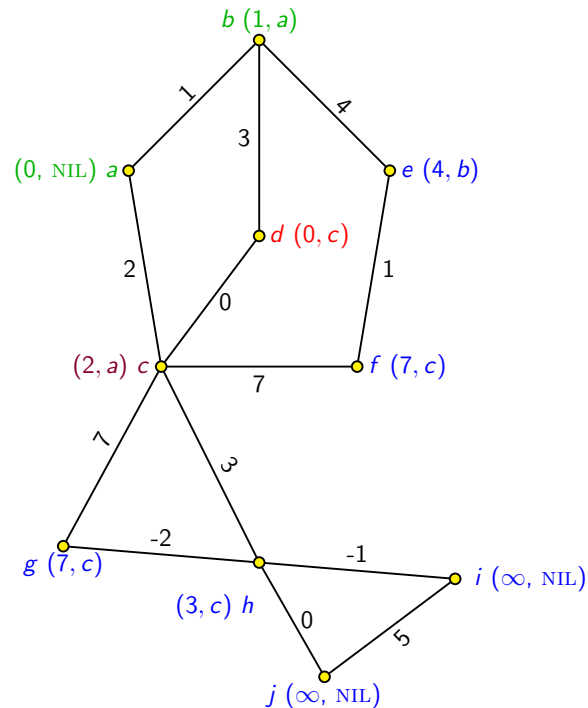


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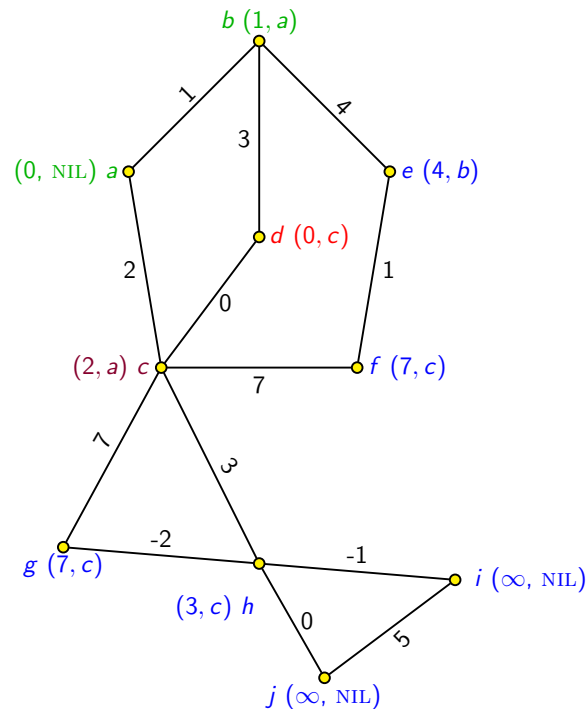


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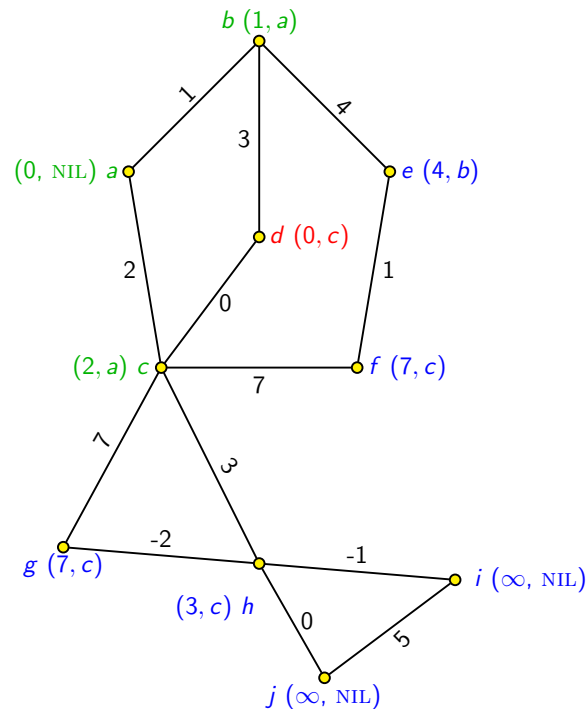


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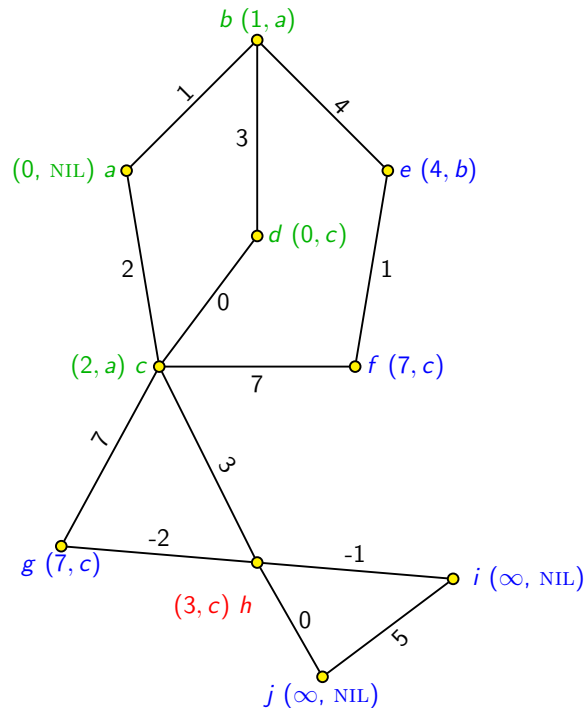


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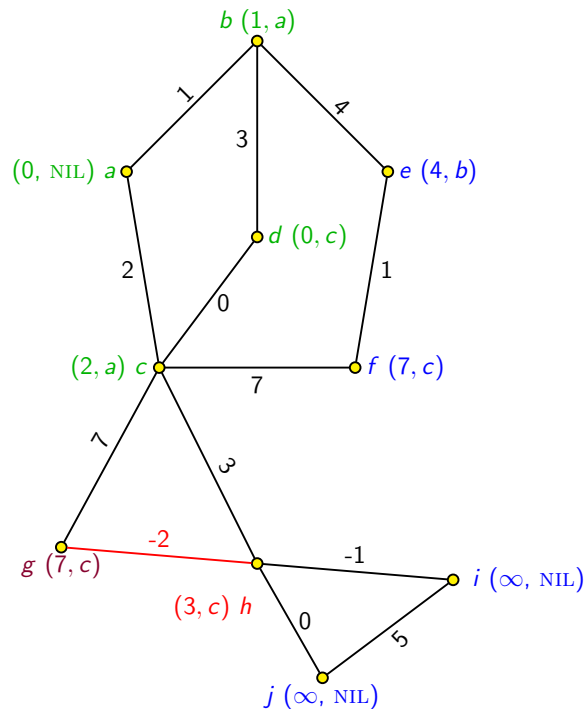


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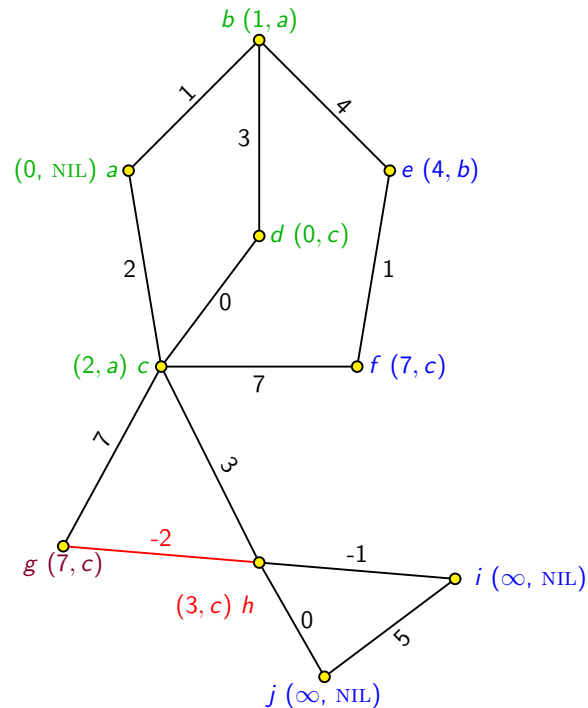


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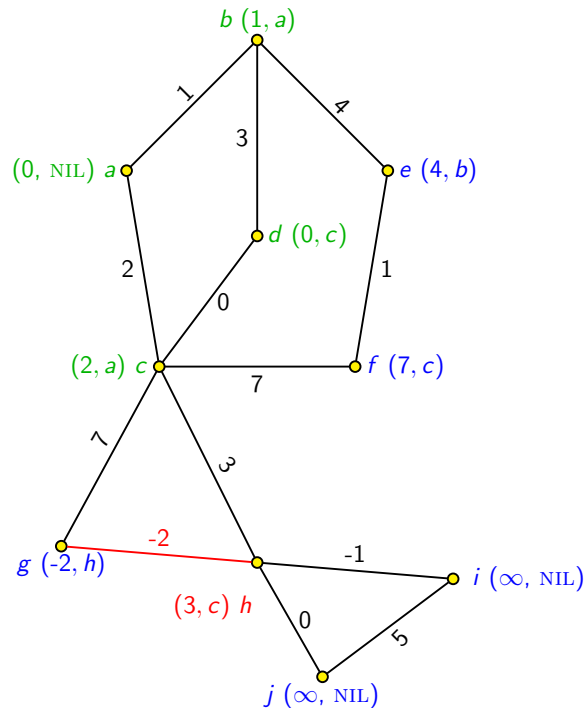


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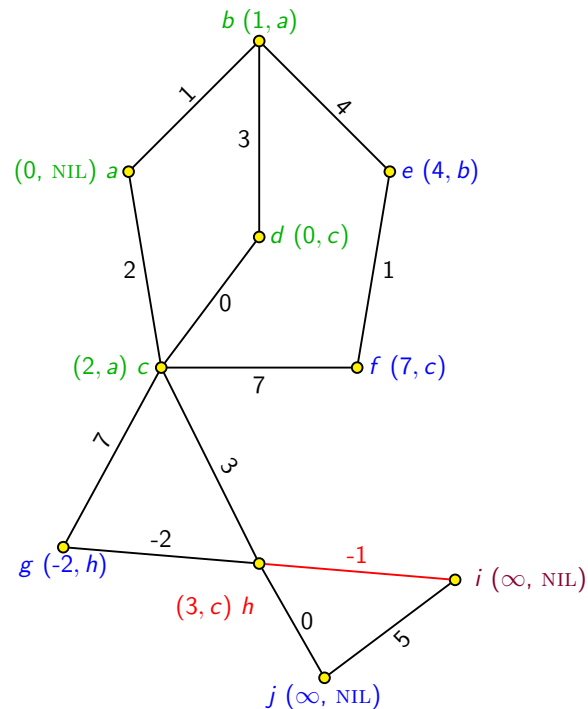


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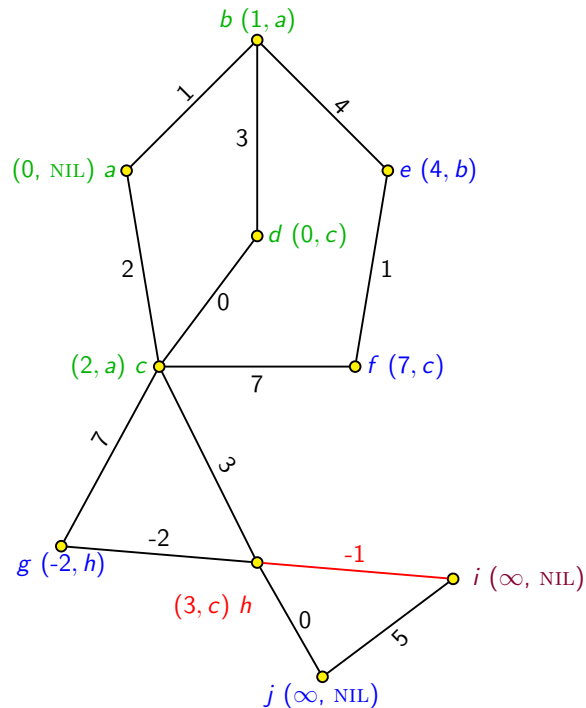


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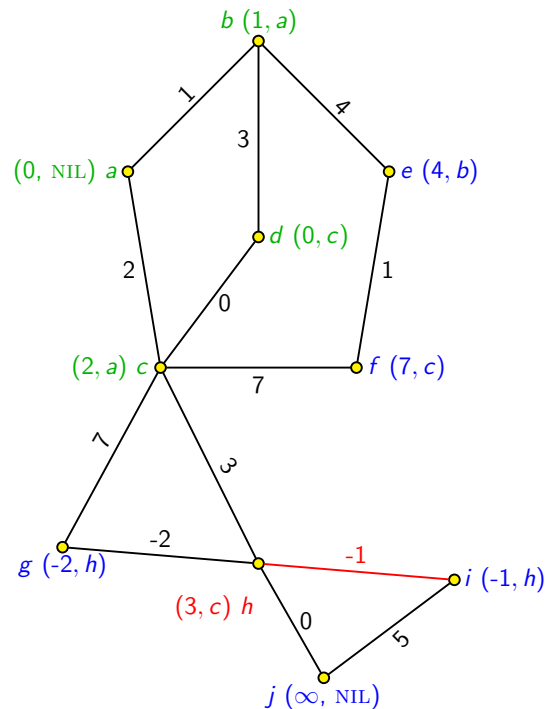


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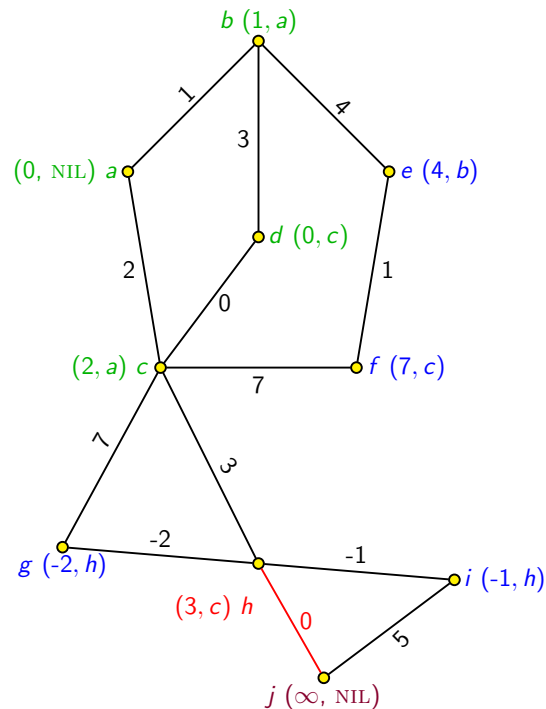


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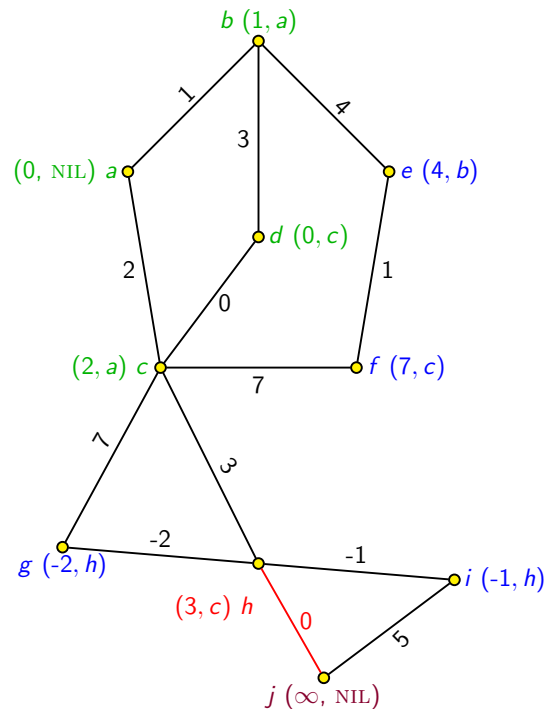


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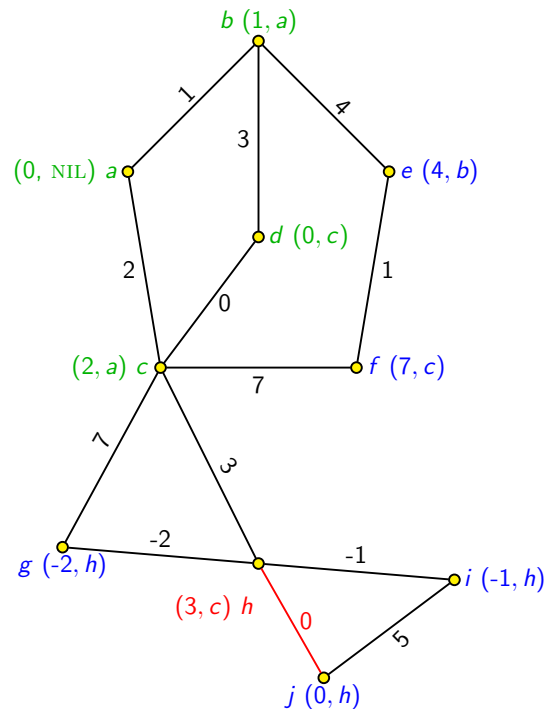


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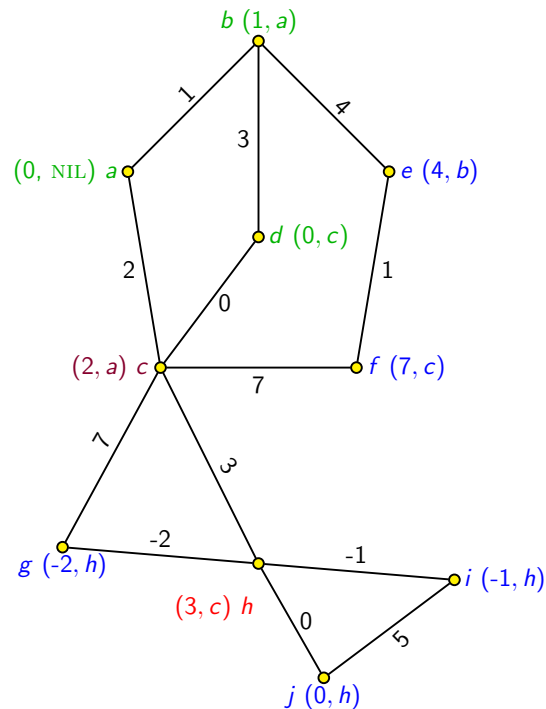


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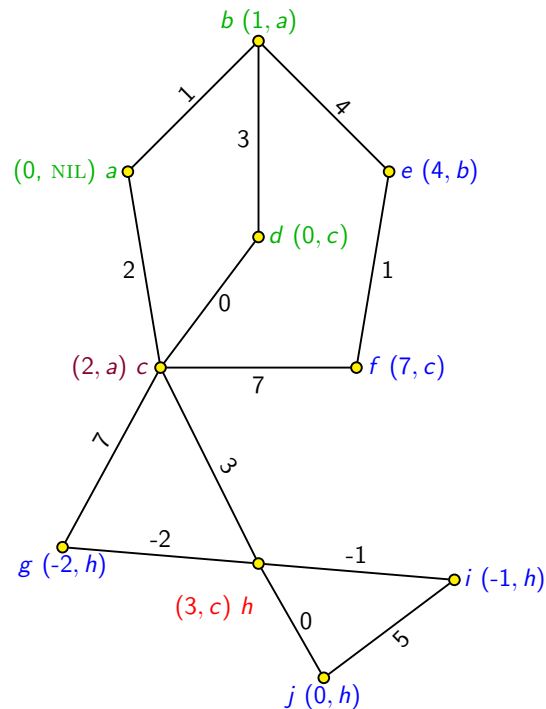


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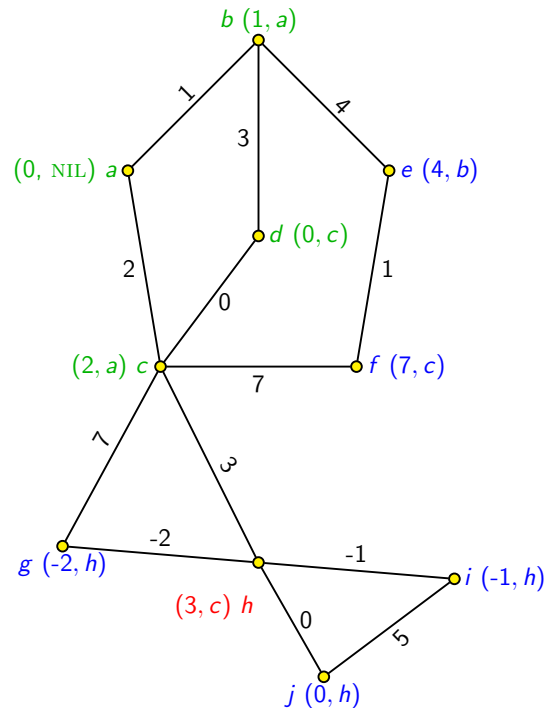


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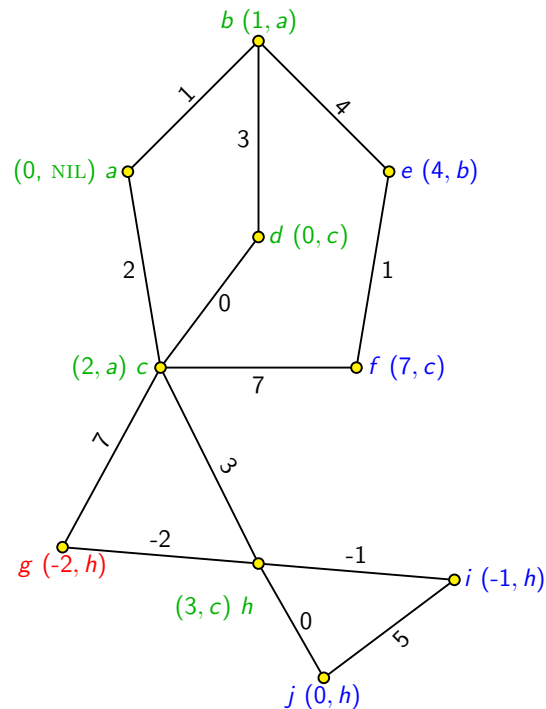


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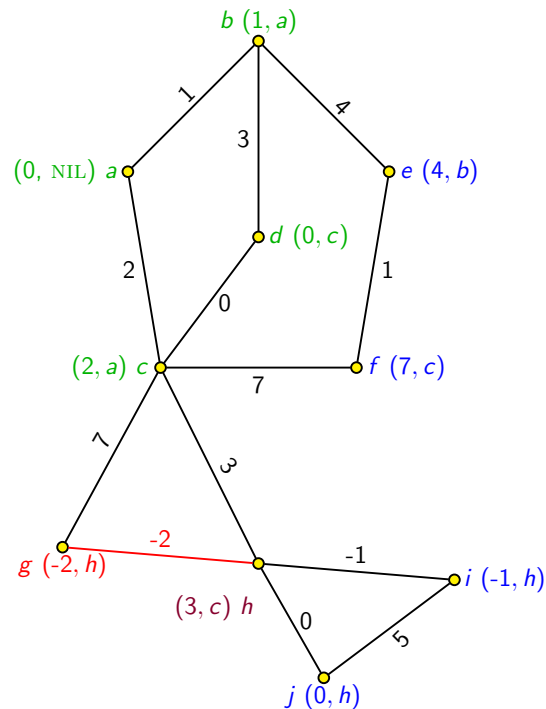


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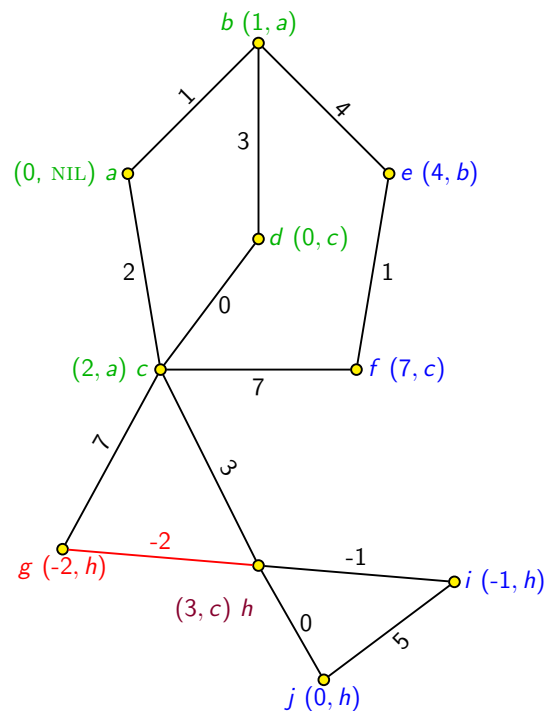


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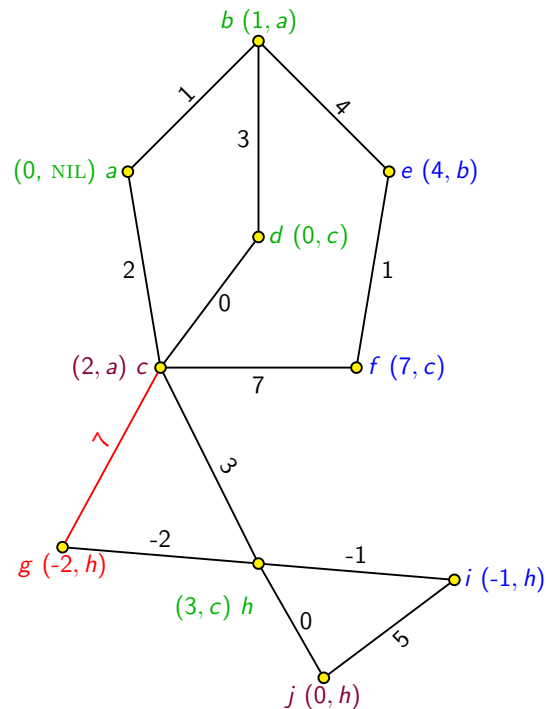


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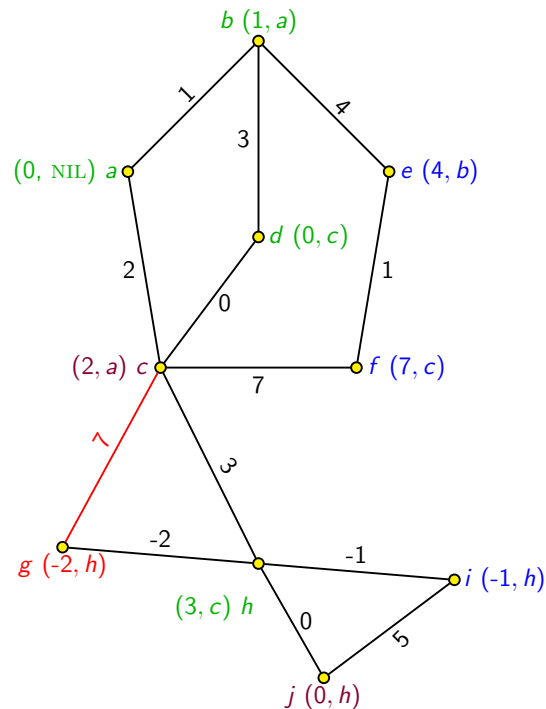


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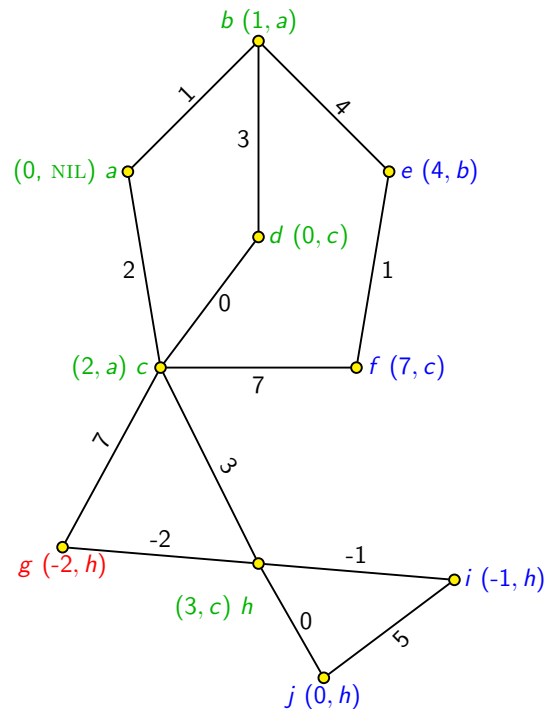


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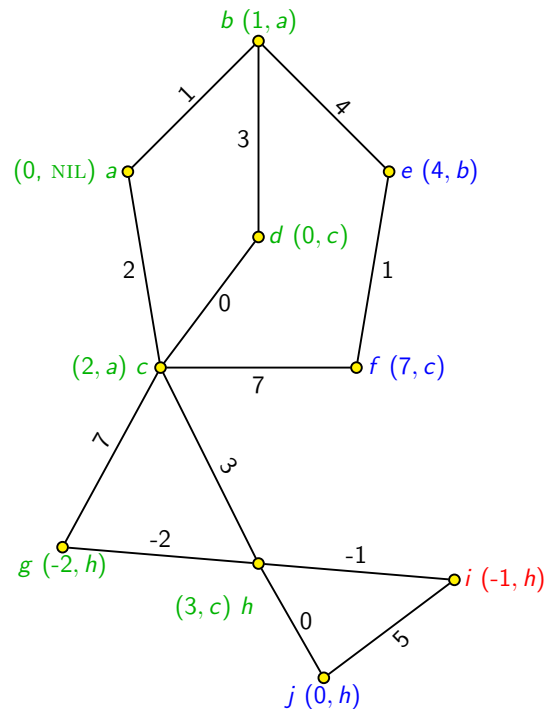


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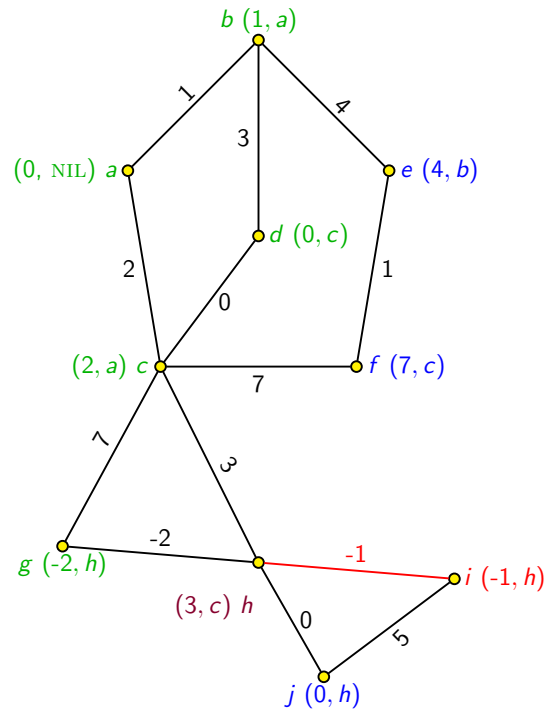


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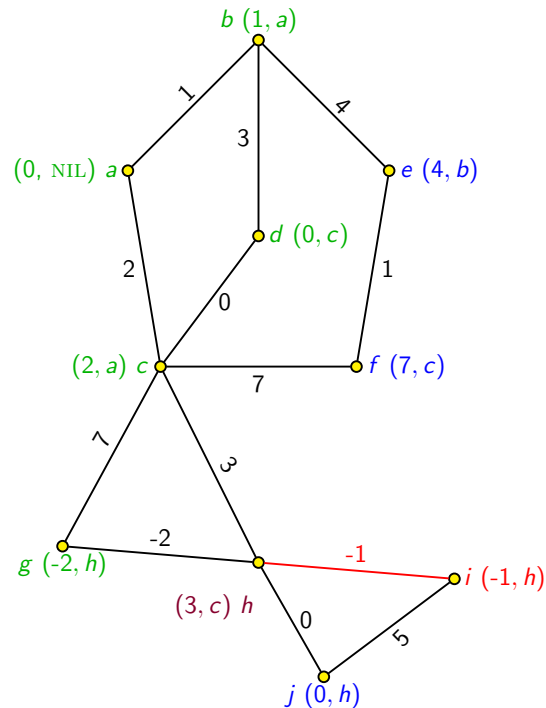


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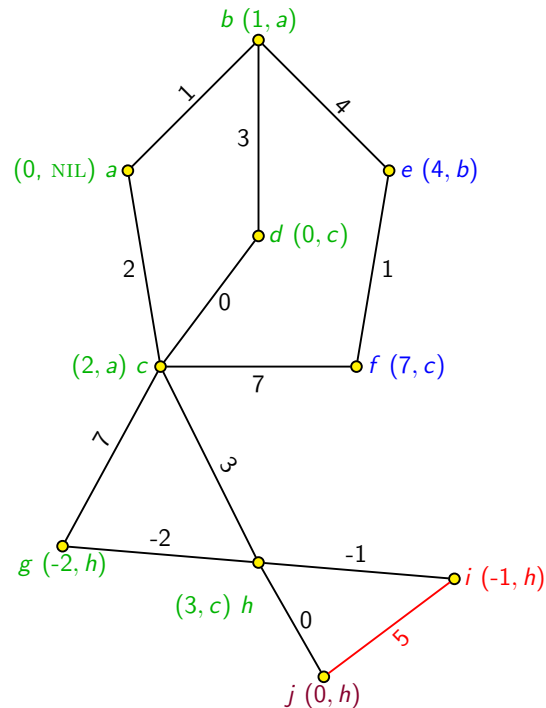


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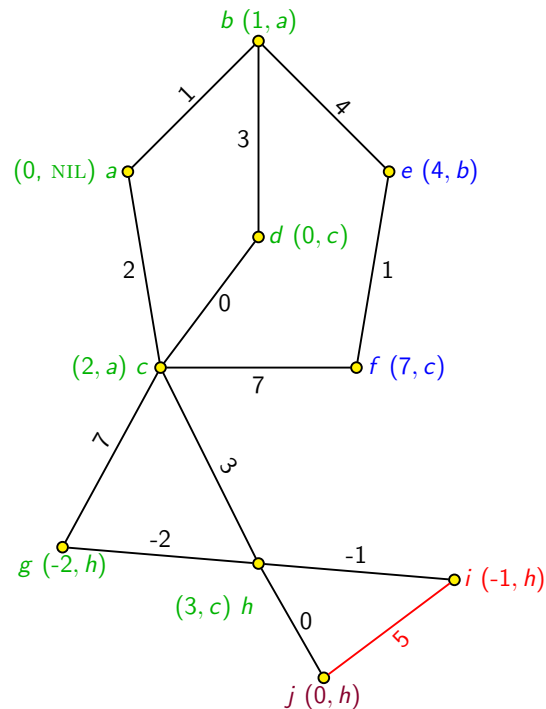


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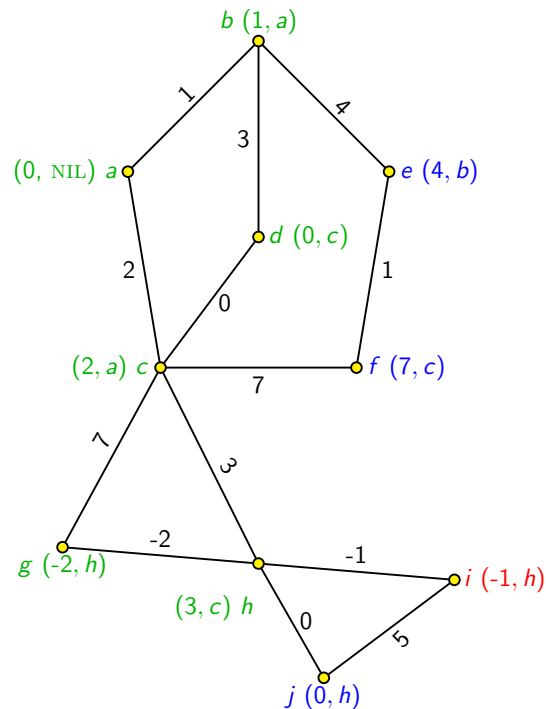


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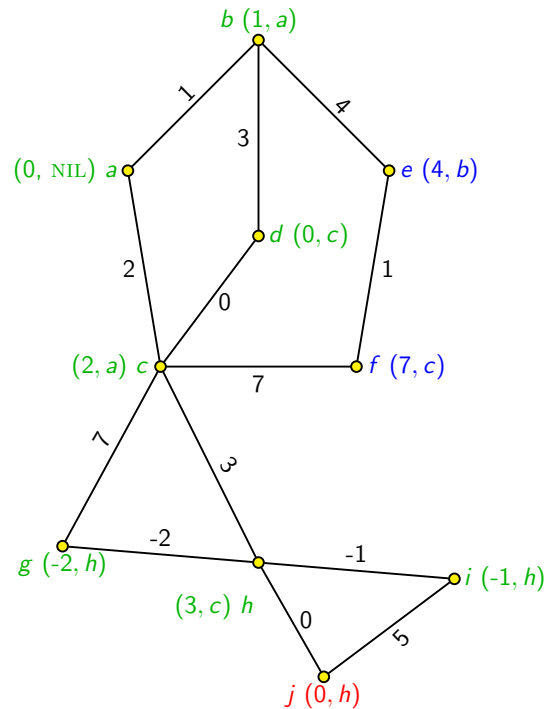


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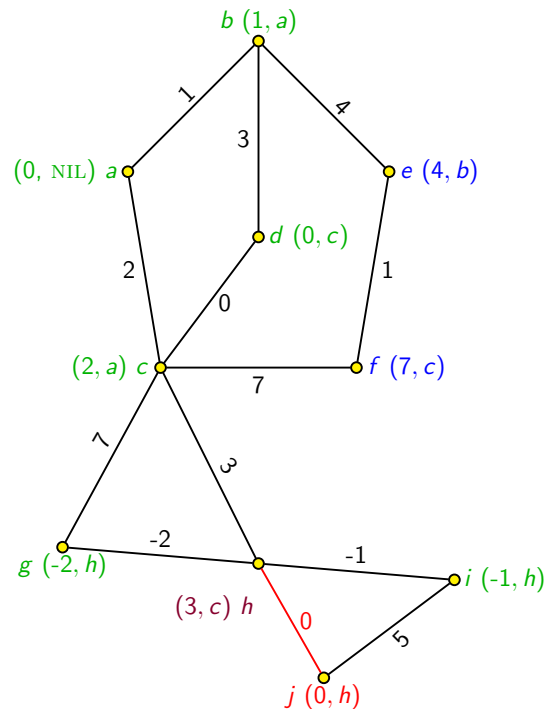


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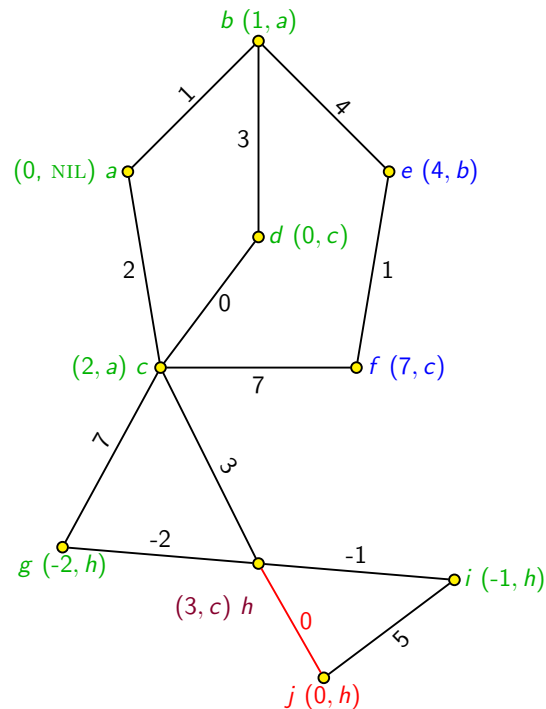


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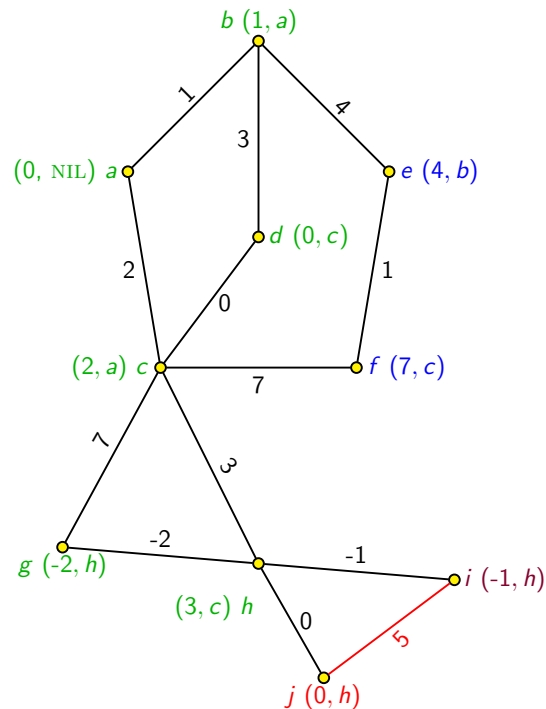


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MST-PRIM(G, w, r)

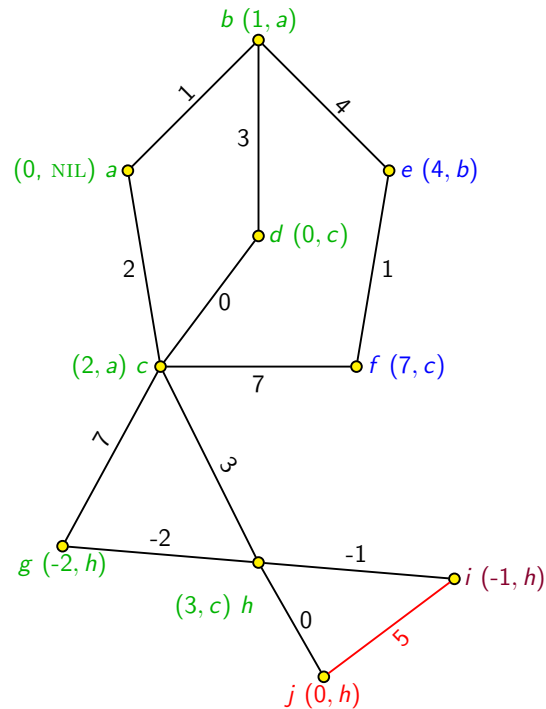


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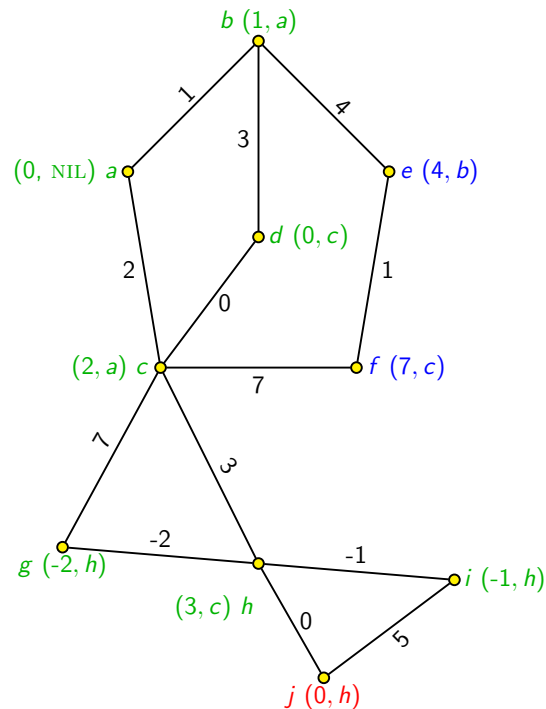


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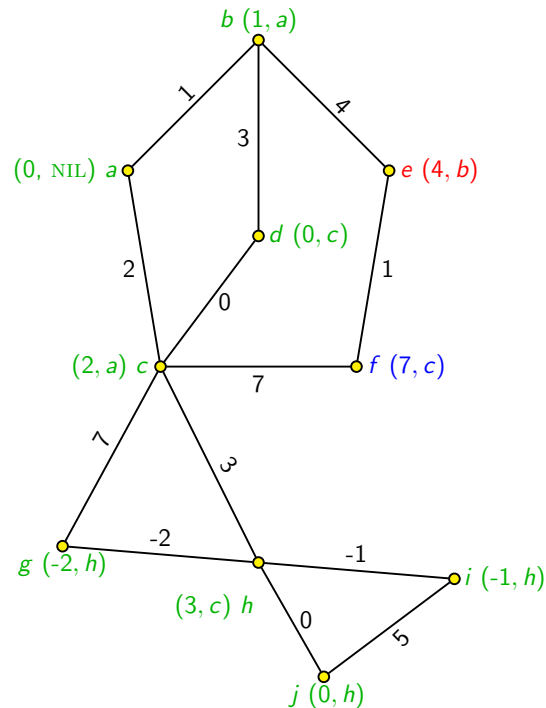


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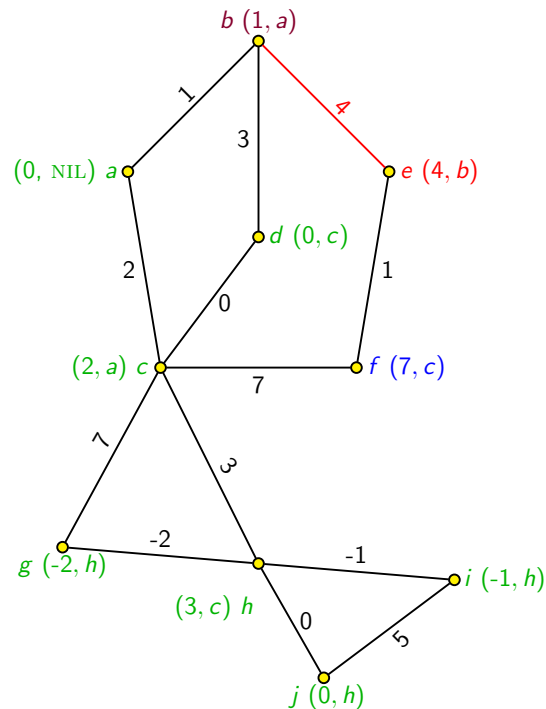


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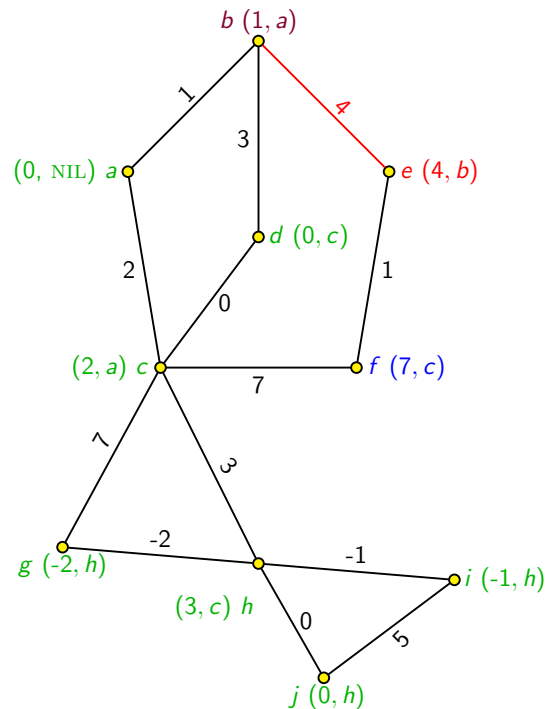


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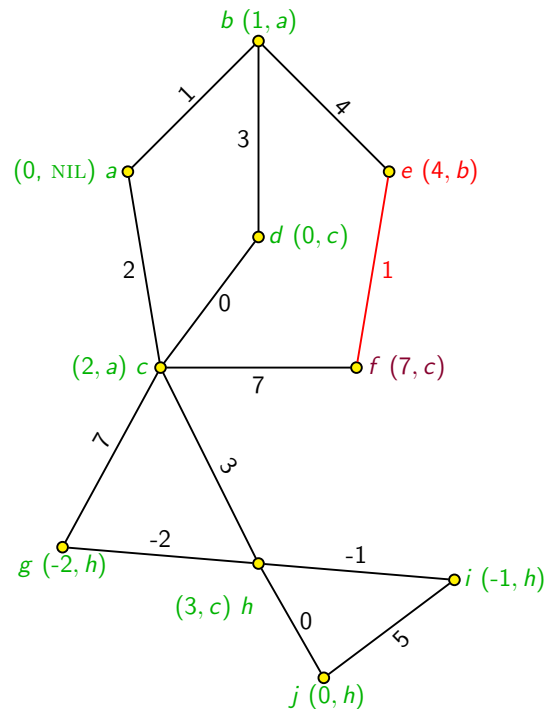


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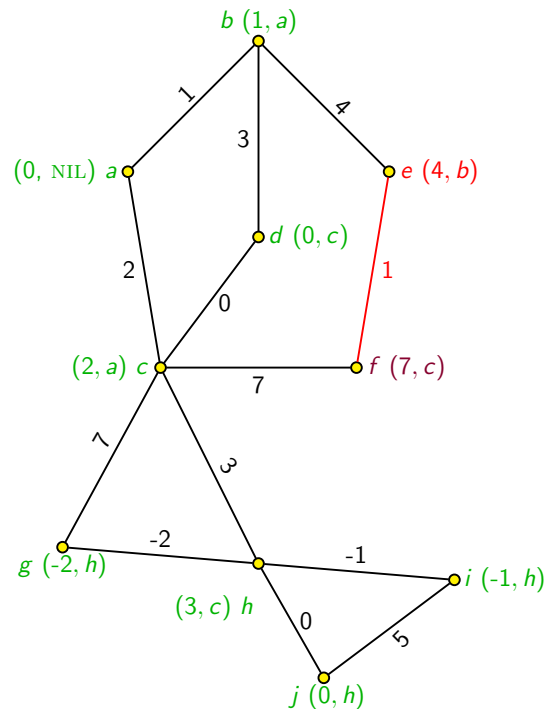


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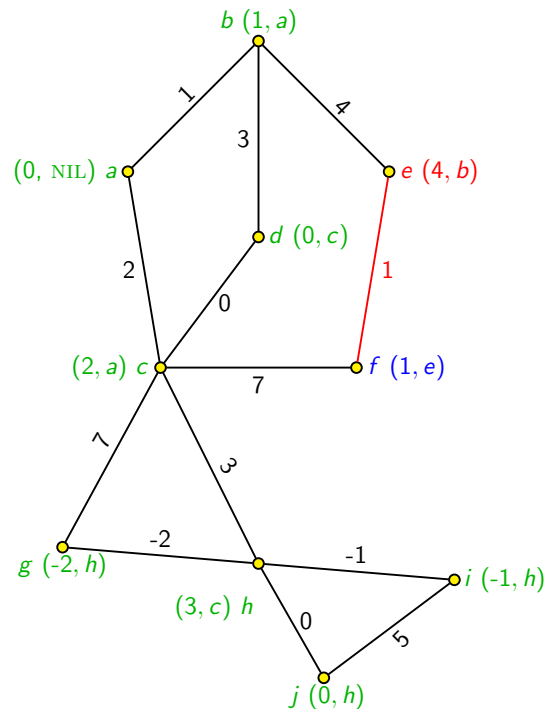


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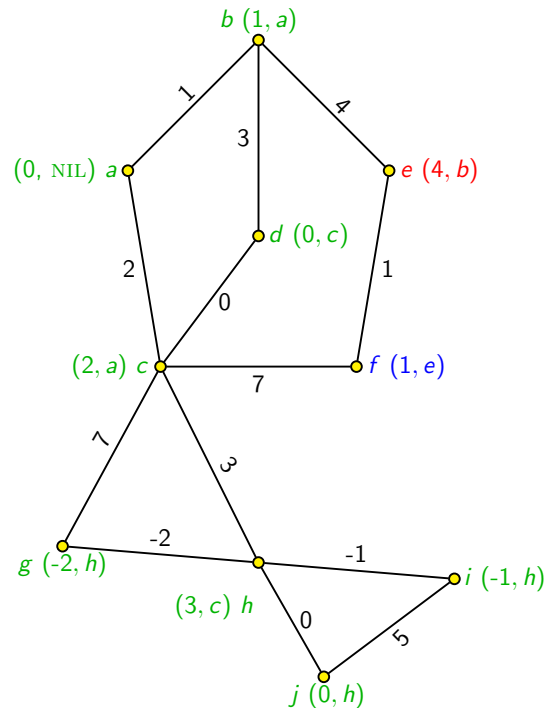


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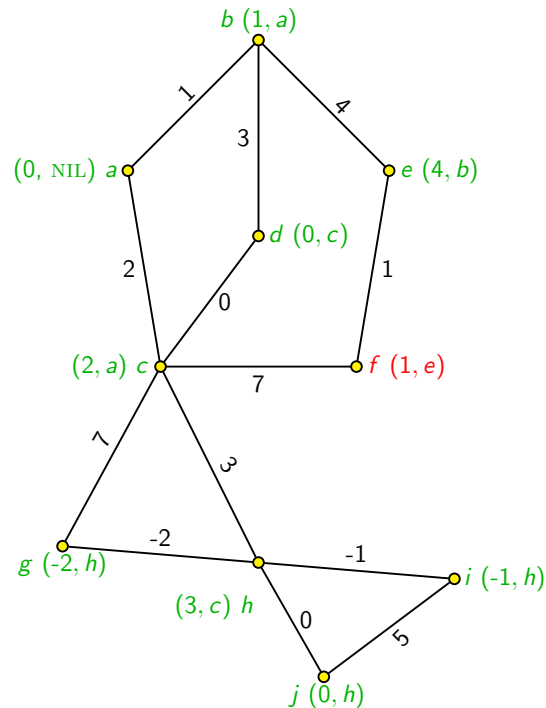


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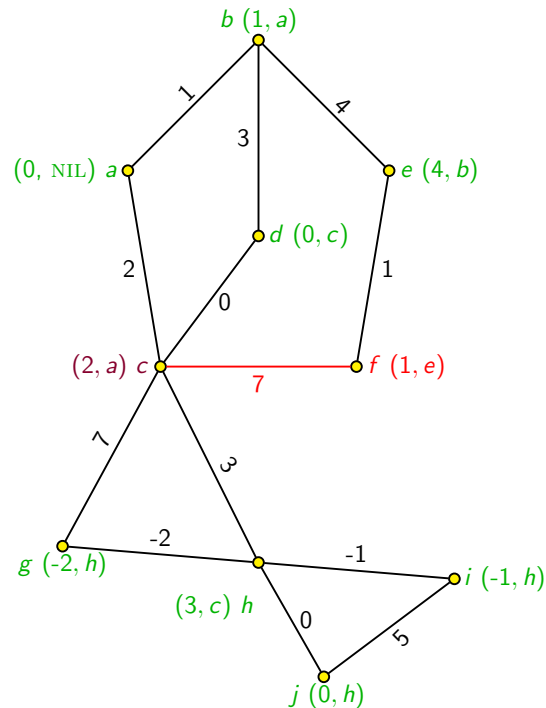


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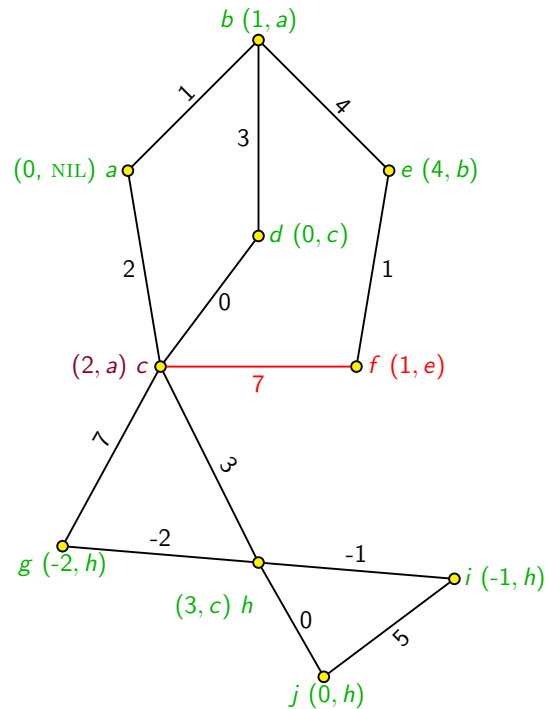


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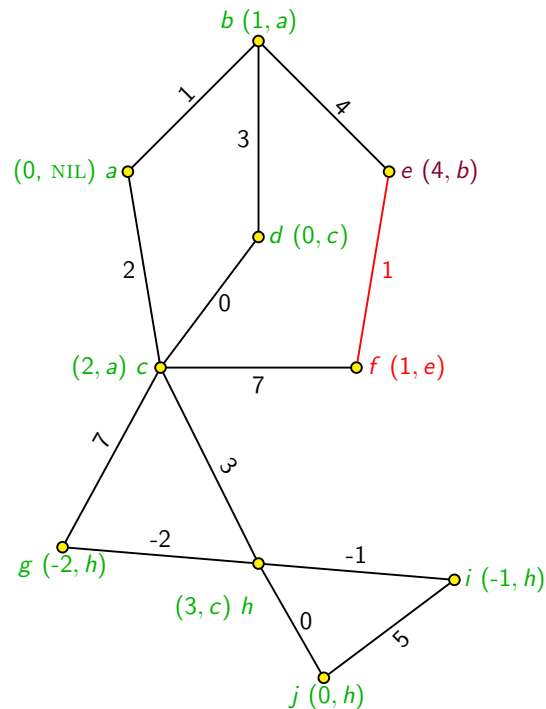


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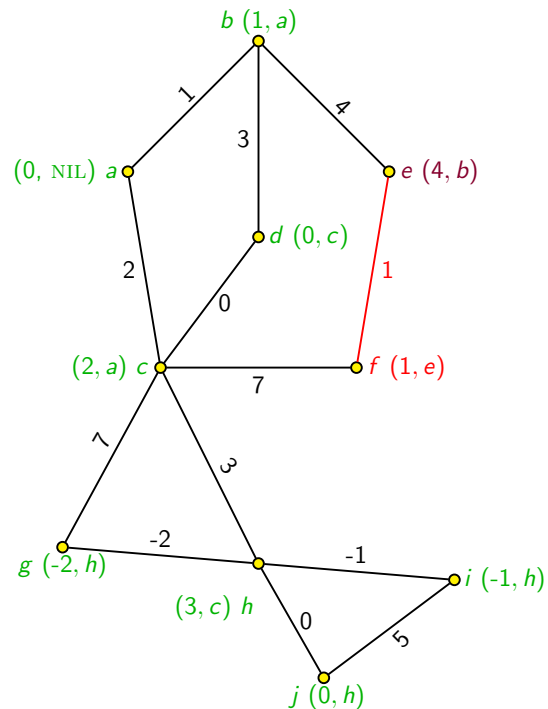


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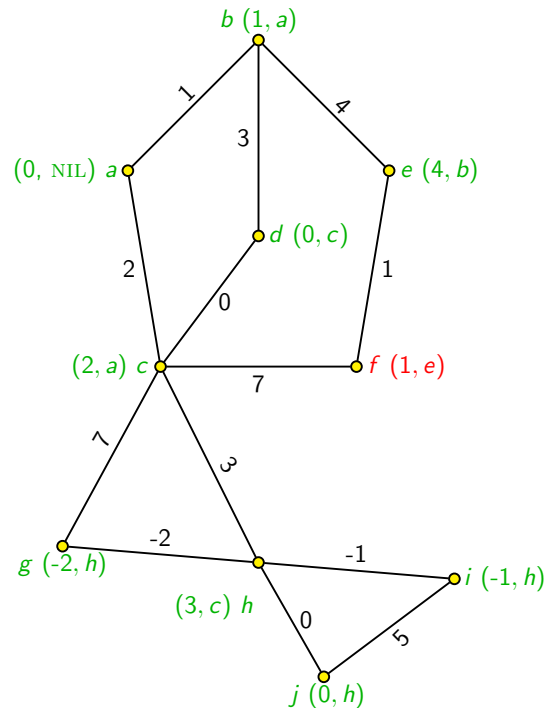


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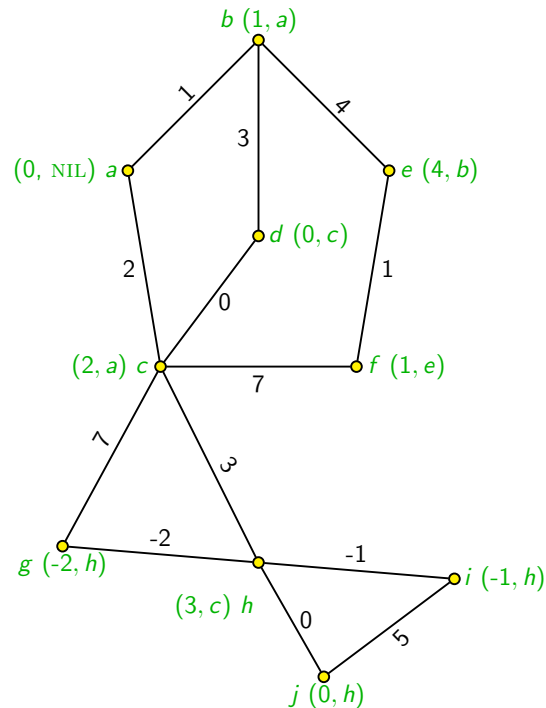


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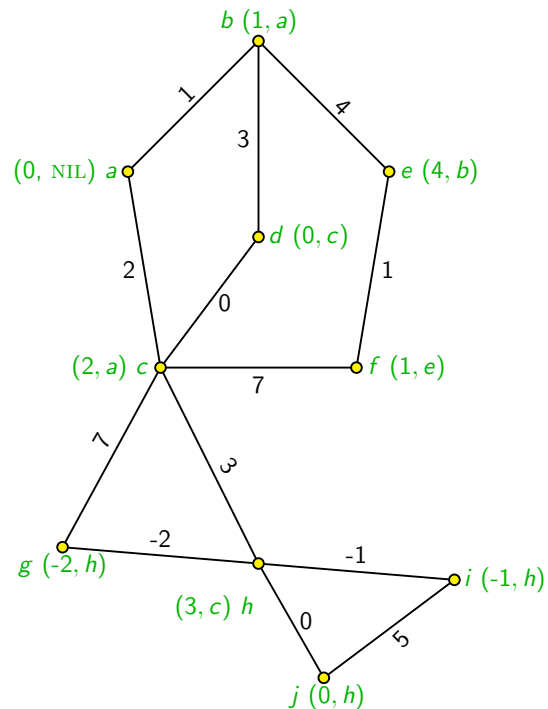


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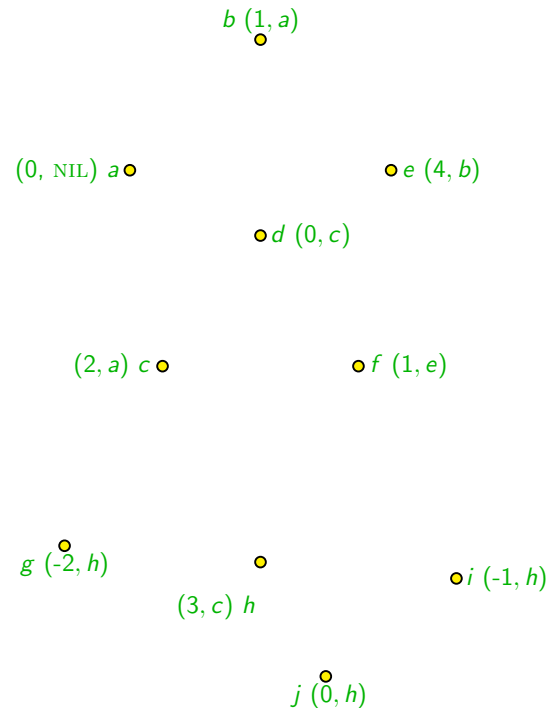


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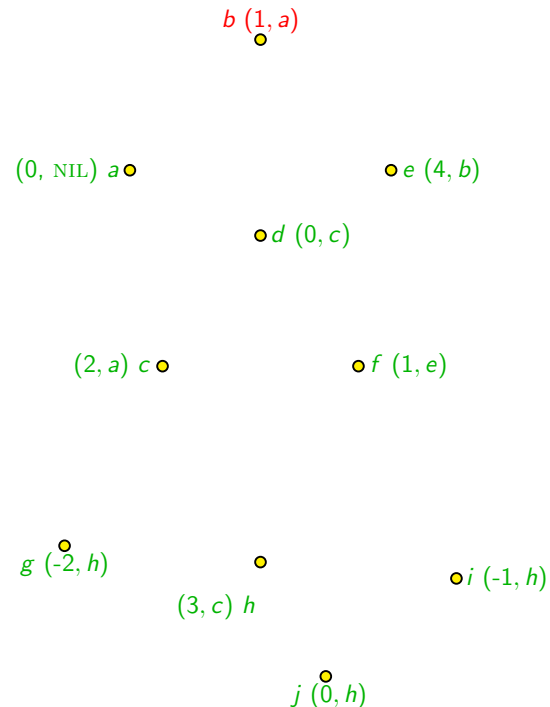
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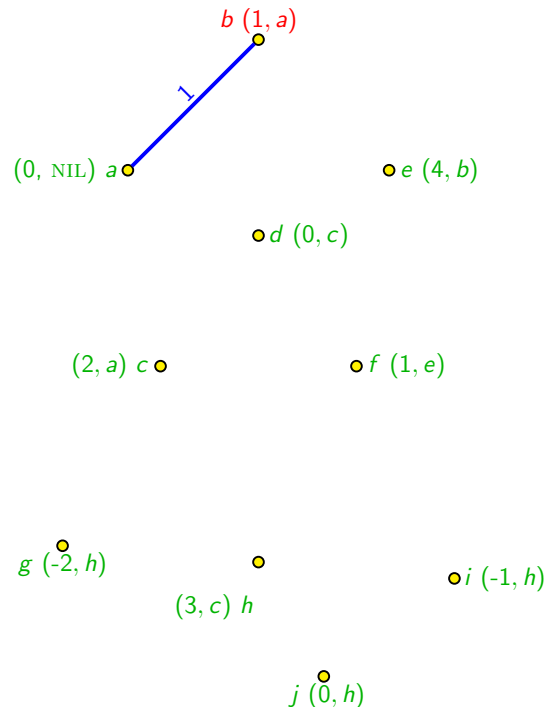
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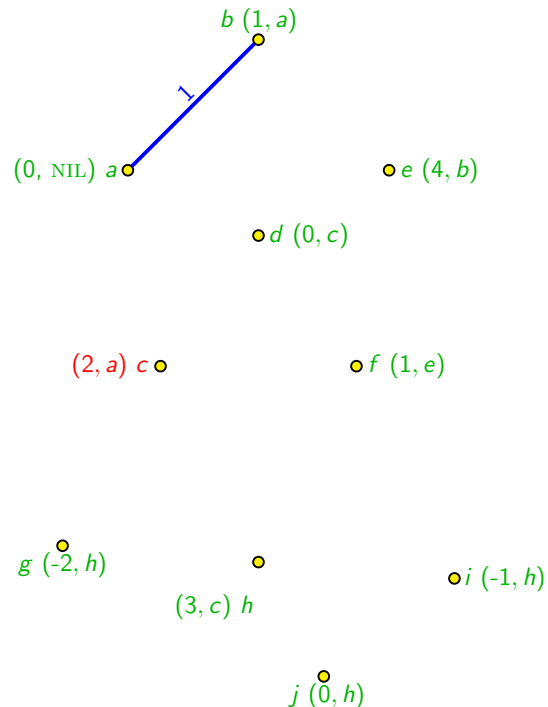
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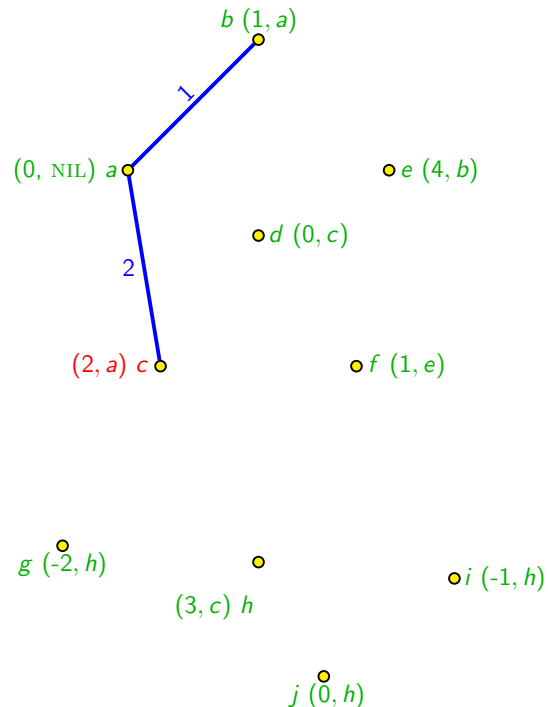
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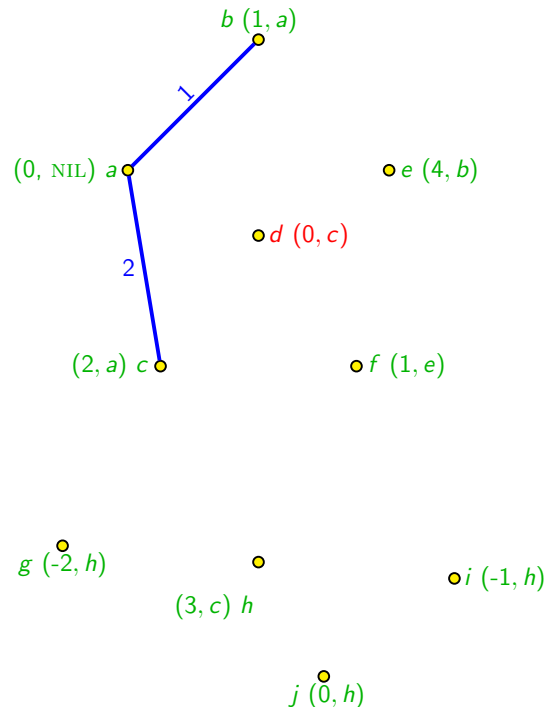
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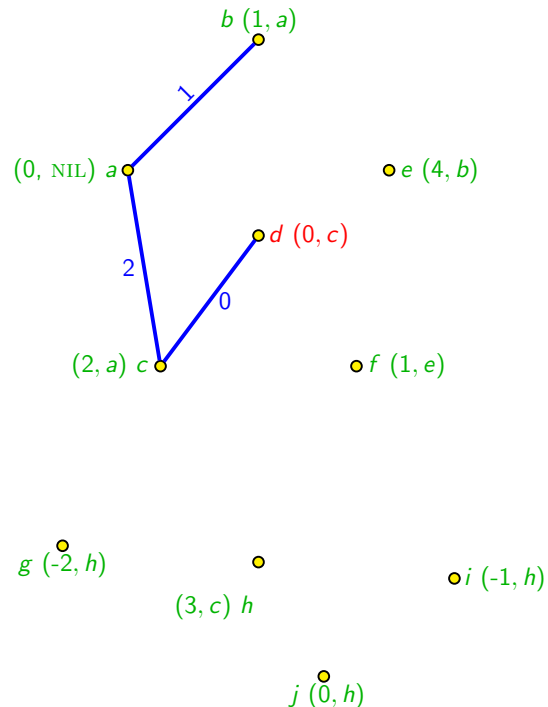
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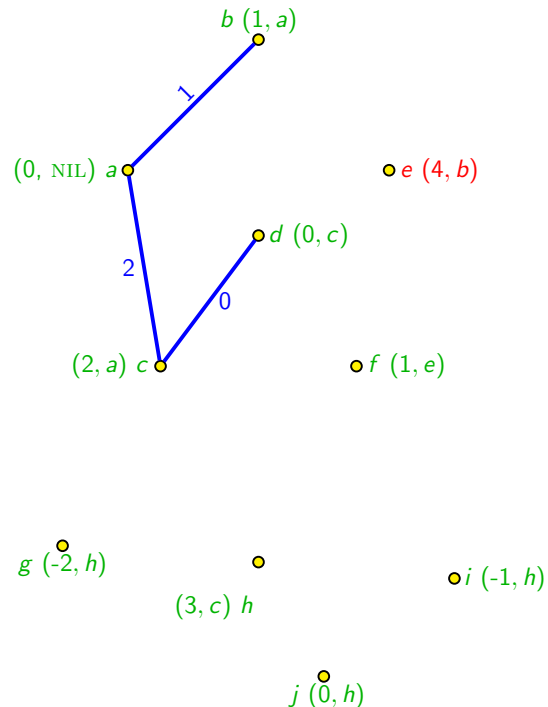
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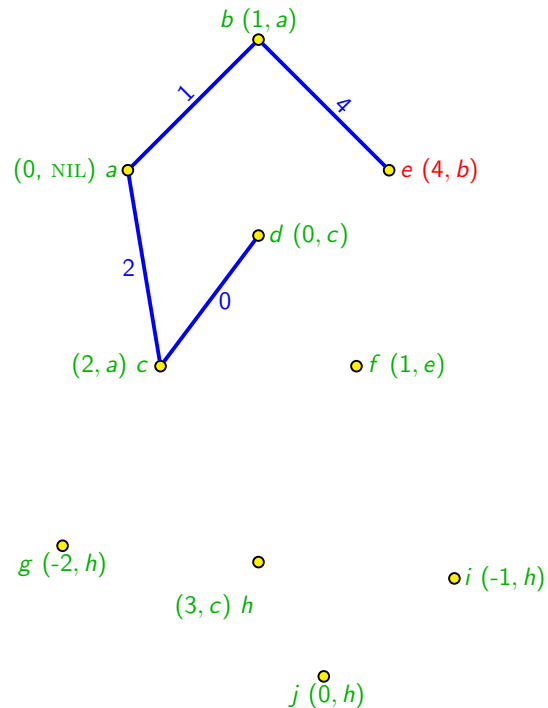
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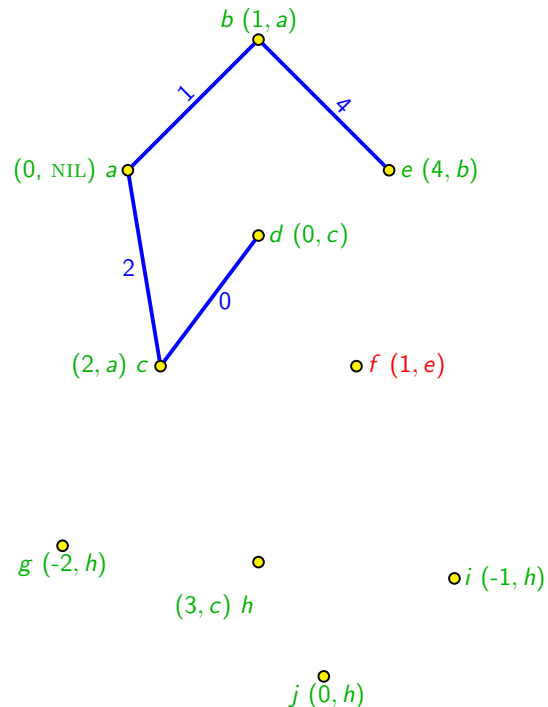
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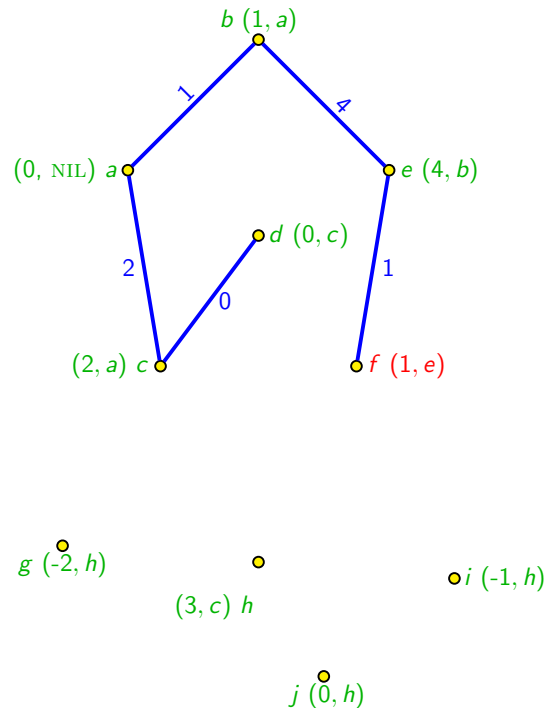
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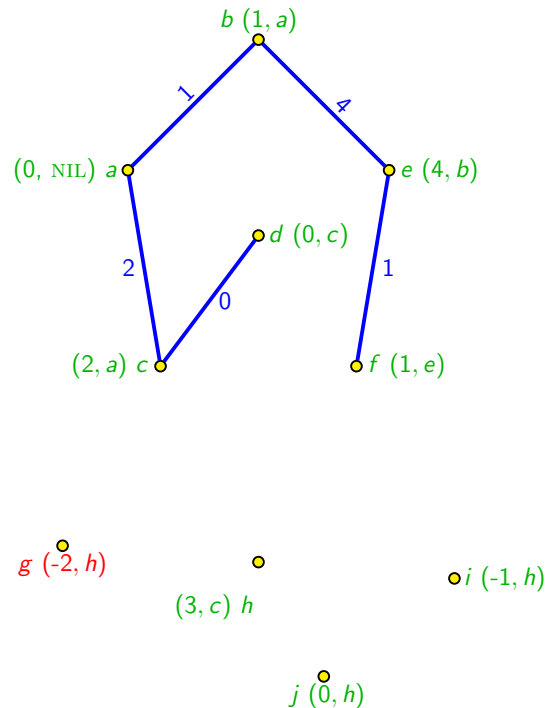
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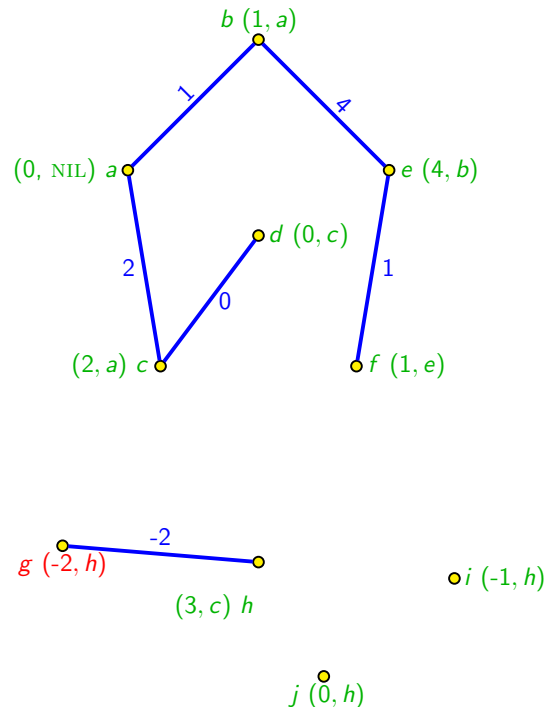
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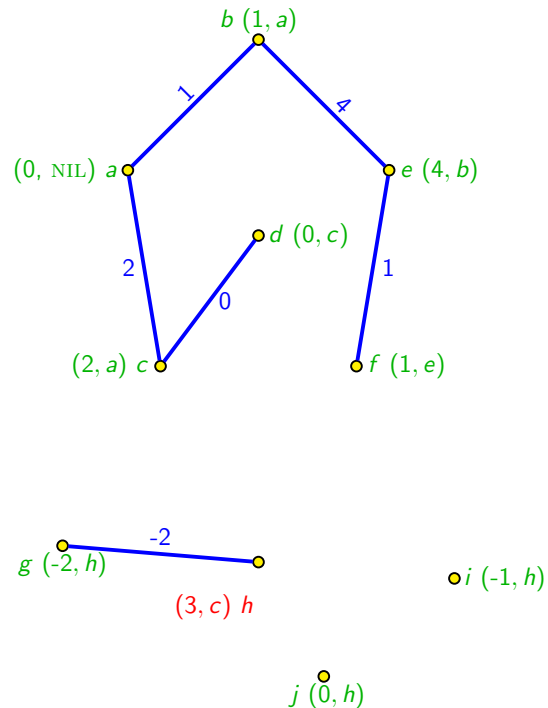
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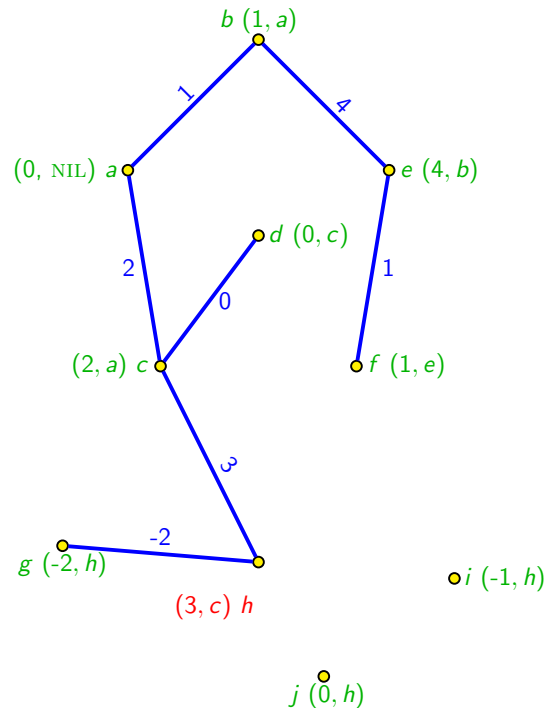
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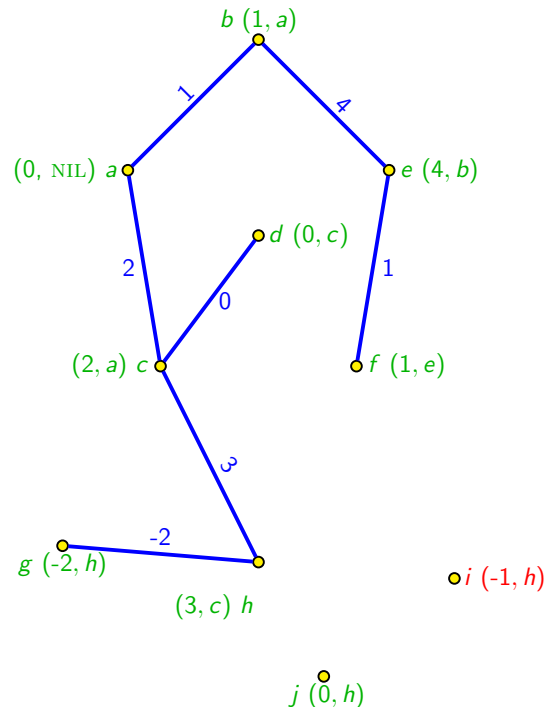
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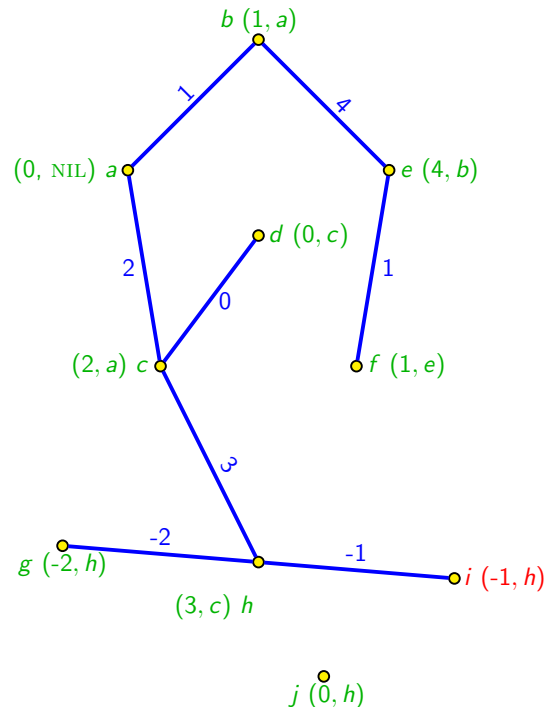
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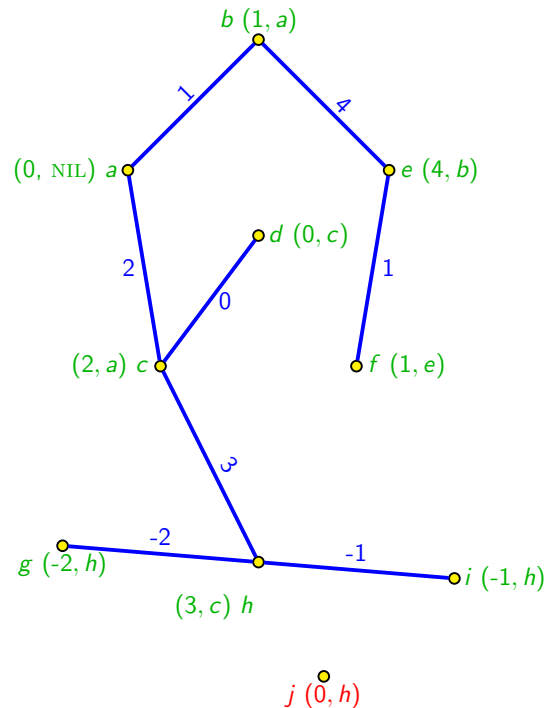
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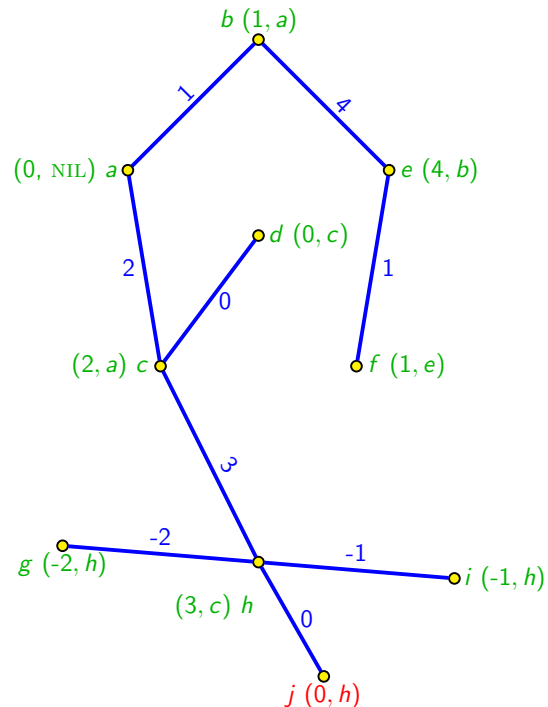
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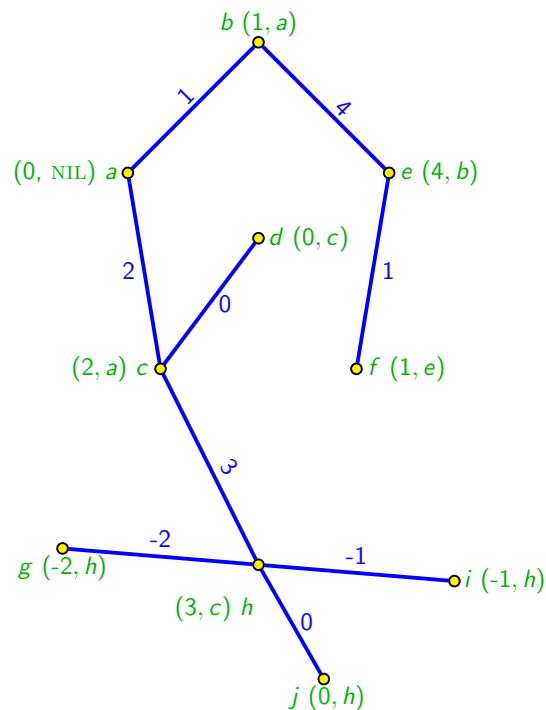
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$$w(G) = \sum_{e \in A} w(e) = 8.$$

Correctness

The correctness follows from the following 3-part loop invariant:

- $A = \{(v, \pi[v]) : v \in \{V \setminus \{r\}\} \setminus Q\}$.
- The vertices already placed into the MST are those in $V \setminus Q$.
- For all vertices $v \in Q$, if $\pi[v] \neq \text{NIL}$, then $\text{key}[v] < \infty$ and $\text{key}[v]$ is the weight of a **light edge** $(v, \pi[v])$ connecting v to some vertex already placed into the minimum spanning tree.

Cut: A **cut** $(S, V \setminus S)$ of an undirected graph $G = (V, E)$ is a partition of V .

Light edge: An edge is a **light edge** crossing a **cut** if its weight is the minimum of any edge crossing the cut.

Note: There can be more than one light edge crossing a cut in the case of ties.

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Homework: Read the proof the correctness of Prim's algorithm!

Complexity

- Depends on how the MIN-PRIORITY queue Q is implemented.
- Assume that Q is implemented as a binary MIN-HEAP.
- **Lines 1-5:** BUILD-MIN-HEAP procedure can be used to perform the initialization in $\mathcal{O}(|V|)$ time.
- **Note:** The body of the **while** loop is executed $|V|$ times.
 - Each EXTRACT-MIN operation takes $\mathcal{O}(\log |V|)$ time.

$\therefore |V|$ calls to EXTRACT-MIN takes $\mathcal{O}(|V| \log |V|)$ time.

Complexity

- **Lines 8-11:** The **for** loop is executed $\mathcal{O}(|E|)$ times.
 - Recall that the sum of the lengths of all adjacency lists is $2|E|$.
 - **Line 9:** Test for membership in Q takes constant time.
 - Keep a bit for each vertex v to denote whether $v \in Q$ or not.
 - Update the bit when the vertex is removed from Q .
 - **Line 11:** Involves an implicit DECREASE-KEY operation.
 - Takes $\mathcal{O}(\log |V|)$ time in a binary MIN-HEAP.
- **Total time:** $\mathcal{O}(|V| \log |V| + |E| \log |V|) = \mathcal{O}(|E| \log |V|)$.

Books and Other Materials Consulted

- ① [Definitions and Krushkal's Algorithm](#) taken from Discrete Mathematics Lecture Notes (M. Tech (CS), Monsoon Semester, 2007) taught by [Prof. Palash Sarkar](#) (ASU, ISI Kolkata).
- ② *Introduction to Algorithms* by [Thomas H Cormen](#), [Charles E Leiserson](#), [Ronald L Rivest](#), [Clifford Stein](#).

Thank You for your kind attention!



Questions!!