# EE2703: Assignment 7: The Laplace Transform

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### 1 Abstract:

In this assignment, we will,

- 1. solve for the time response of a spring with different decays and frequencies
- 2. solve for a coupled spring problem
- 3. obtain the magnitude and phase response of the Steady State Transfer function of a two-port network
- 4. obtain the  $v_o(t)$  for the said two-port network

### 2 Introduction:

In this assignment, we will make use of Laplace Transform to solve 'continuous time' systems. We will analyse the LTI systems using the python library, scipy.signal.

## 3 Time Response of a Spring:

We need to find the response of a spring, whose equation is given by,

$$\ddot{x} + 2.25x = f(t)$$

Here f(t) is given by,

$$f(t) = e^{-at}cos(\omega t)u(t)$$

where, 'a' represents decay and takes values 0.5 and 0.05.  $\omega$  takes values 1.4, 1.45, 1.5, 1.55 and 1.6. We will use the **Laplace Transform** to solve the problem.

The Laplace transform of  $f(t) = e^{-at}cos(\omega t)u(t)$  is given as:

$$\mathcal{L}\{f(t)\} = \frac{s+a}{(s+a)^2 + \omega^2}$$

From the property of Laplace transforms, we know:

$$x(t) \longleftrightarrow \mathcal{X}(s)$$

$$\implies \dot{x}(t) \longleftrightarrow s\mathcal{X}(s) - x(0^{-})$$

$$\implies \ddot{x}(t) \longleftrightarrow s^{2}\mathcal{X}(s) - sx(0^{-}) - \dot{x}(0^{-})$$

From the above equations, we get, for a = 0.5 and  $\omega = 1.5$ :

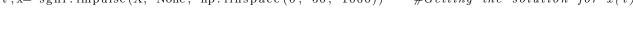
$$F(s) = \frac{s + 0.5}{(s + 0.5)^2 + 2.25}$$

Substituting the given ICs x(0) and  $\dot{x}(0)$  are 0, we get:

$$X(s) = \frac{s + 0.5}{((s + 0.5)^2 + 2.25)(s^2 + 2.25)}$$

Using scipy.signal.impulse to find the x(t) by the following code, and plotting it (for 0 < t < 50s), we get:

#### Python Code:



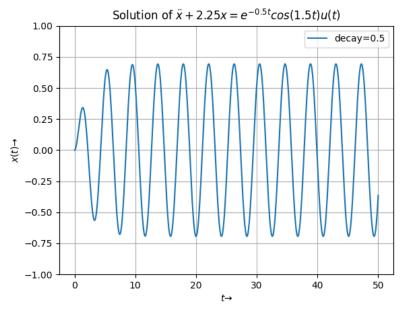


Figure 1: x(t) for a = 0.5 and  $\omega = 1.5$ 

Now, we use a smaller decay of a = 0.05, we get:

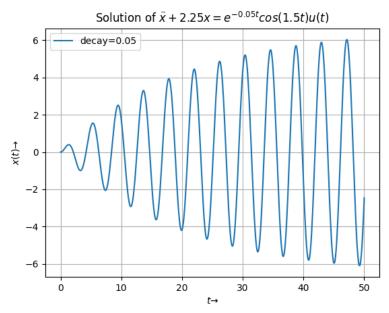


Figure 2: x(t) for a = 0.05 and  $\omega = 1.5$ 

Now, we obtain the response for different frequencies, using  ${\tt signal.lsim}, {\it Python~Code:}$ 

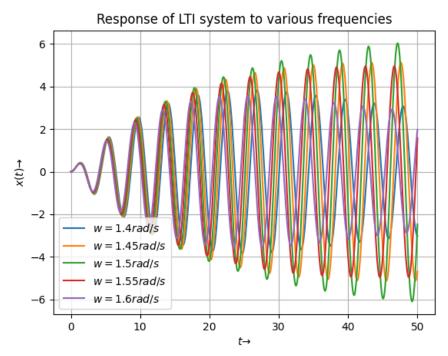


Figure 3: x(t) for a = 0.05 and varying  $\omega$ 

We can see the maximum amplitude of oscillations is obtained when the frequency of f(t) is  $1.5 \; rad/s$ . We can also see that  $\omega = 1.5 \; rad/s$  is the natural frequency. Therefore, at  $\omega = 1.5 \; rad/s$ , it is in resonance.

## 4 Coupled Spring Problem:

We have to solve the Coupled equations given by,

$$\ddot{x} + (x - y) = 0$$
$$\ddot{y} + 2(y - x) = 0$$

Given the ICs x(0) = 1 and  $\dot{x}(0) = y(0) = \dot{y}(0) = 0$ . After solving ,we get the X(s) and Y(s) as,

$$X(s) = \frac{s^{2} + 3}{s^{3} + 3s}$$
$$Y(s) = \frac{2}{s^{3} + 3s}$$

Now, we get the graph of x(t) and y(t) by using signal.impulse.

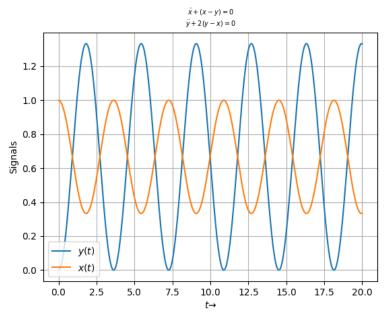


Figure 4: x(t) and y(t) for the coupled spring problem

# 5 Two-port Network:

The transfer function of the given two-port network can be written as:

$$H(s) = \frac{V_o(s)}{V_i(s)} = \frac{1}{s^2 LC + sRC + 1}$$

The Bode magnitude and phase plots can be found using the method scipy.signal.bode(). The plots are shown below:

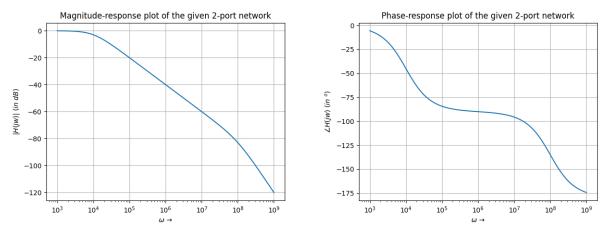


Figure 5: Bode Plots of the RLC Network's Transfer function

Now, when the input to the network,  $v_i(t)$  is  $cos(10^3t)u(t) - cos(10^6t)u(t)$ , the output is given by:

$$V_o(s) = V_i(s).H(s)$$

We will use scipy.signal.lsim to find  $v_o(t)$  from  $V_o(s)$ . Plotting the obtained  $v_o(t)$ , we get:

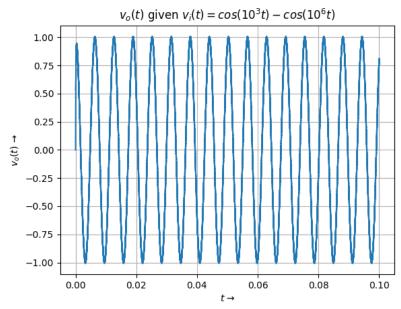


Figure 6:  $v_o(t)$  of the RLC network, when  $v_i(t) = (cos(10^3t) - cos(10^6t))u(t)$ 

We can see it to be varying as a sinusoid of frequency approximately 160 Hz, which is expected, as the RLC network acts as a low pass filter - it allows low frequencies to pass through unchanged, while damping high frequencies to huge extent.

We notice that in the initial variation, When zoomed in, for 0 < t < 30 us, we get:

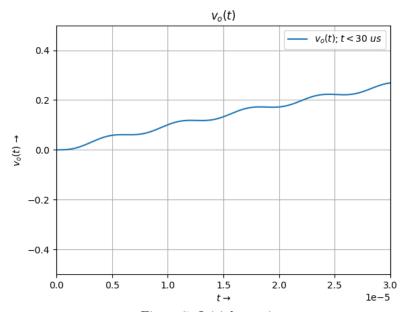


Figure 7: Initial transients

This is due to application of the step input, i.e., the input is suddenly turned on at t = 0.

## 6 Conclusion

In this assignment, we saw the power of Laplace Transform for the analysis of LTI systems. We used the scipy.signal python library to obtain various signals from functions. We solved for the time response of a spring, coupled spring equations, and a two-port problem.