Writing OS



Writing an OS in Rust

https://os.phil-opp.com/

-opp.com

Writing an OS in Rust Philipp Oppermann's blog

This blog series creates a small operating system in the Rust programming language. Each post is a small tutorial and includes all needed code, so you can follow along if you like. The source code is also available in the corresponding Github repository.

Latest post: Async/Await

BARE BONES

A Freestanding Rust Binary

The first step in creating our own operating system kernel is to create a Rust executable that does not link the standard library. This makes it possible to run Rust code on the bare metal without an underlying operating system. *read more »*

A Minimal Rust Kernel

In this post we create a minimal 64-bit Rust kernel for the x86 architecture. We build upon the freestanding Rust binary from the previous post to create a bootable disk image, that prints something to the screen. *read more »*

VGA Text Mode

The VGA text mode is a simple way to print text to the screen. In this post, we create an interface that makes its usage safe and simple, by encapsulating all unsafety in a separate module. We also implement support for Rust's formatting macros. read more »

Testing

This post explores unit and integration testing in no_std executables. We will use Rust's support for custom test frameworks to execute test functions inside our kernel. To report the results out of QEMU, we will use different features of QEMU and the bootimage tool.

Other Languages

B 7

- PersianJapanese
- Japanesi
- Russian
- Chinese (simplified)
- Chinese (traditional)

Recent Updates

No notable updates recently.

Repository







Write operating system from scratch

https://learningos.github.io/rcore_step_by_step_webdoc/



Course Review

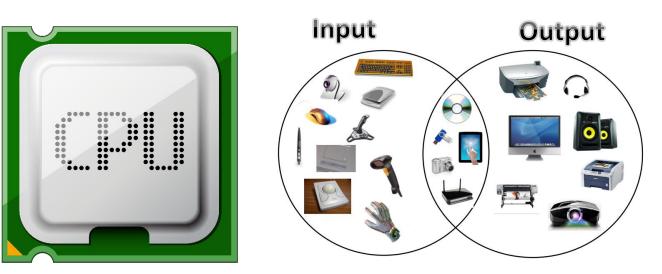


- •What is OS?
- OS components
- OS services
- OS design goals
- OS characteristics
- Early OSs

Manage Execution of Applications Mixing

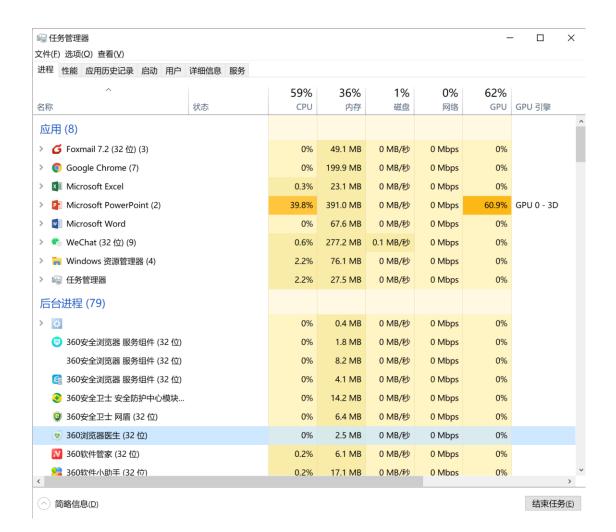
- Resources are made available to multiple applications
- Processor is switched among multiple applications
- The processor and I/O devices can be used

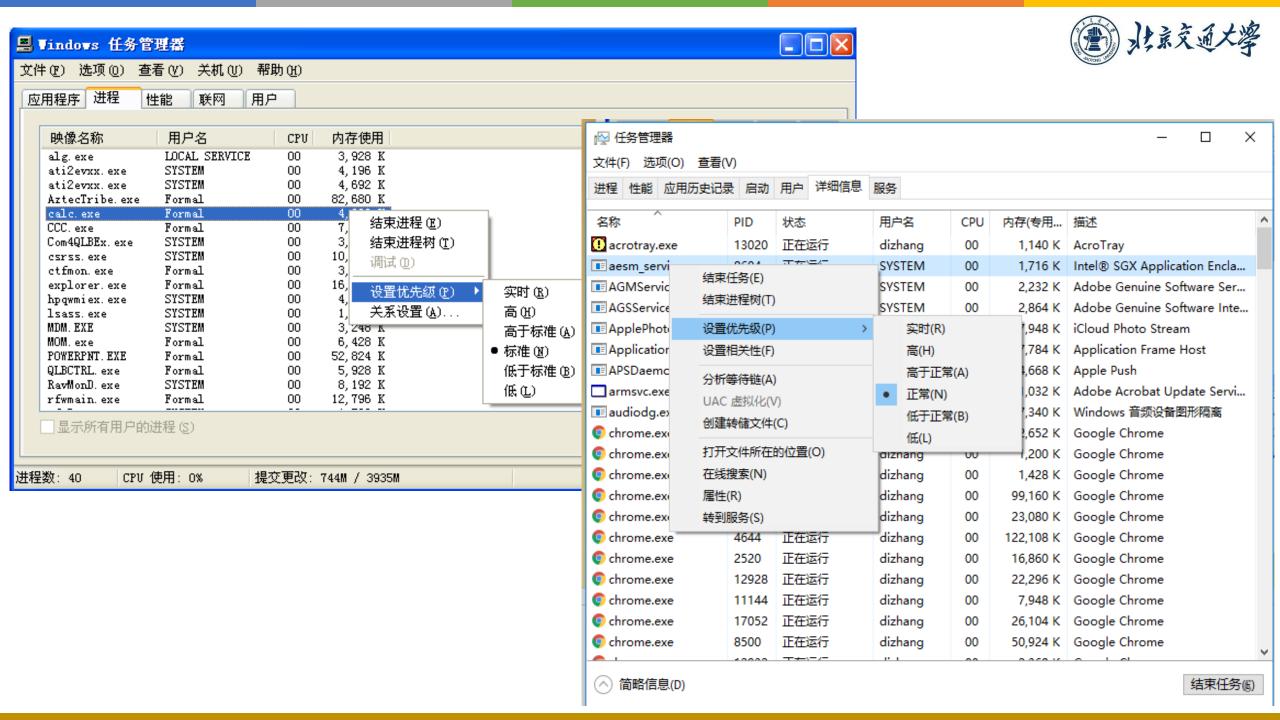
efficiently













Processes





- Process Concept
- Process Scheduling
- Operations on Processes
- Interprocess Communication
- Communication in Client-Server Systems





What is a Process?

How to describe a Process?



Process Concept



What is a process?

- One program which has an independent function works on certain data set dynamically and allocates resources dynamically
- Process is a program in execution
- An instance of a program running on a computer

Difference Between Process & Program

- A program is a passive entity but a process is an active entity
- Process is dynamic, and the program is static
- Process is temporary, the program is permanent
- The elements of process and program is different
 - Process: Process Control Block
 - Program: Code and Data
- Two processes may be associated with the same program, they are considered as separate execution sequences

Processes

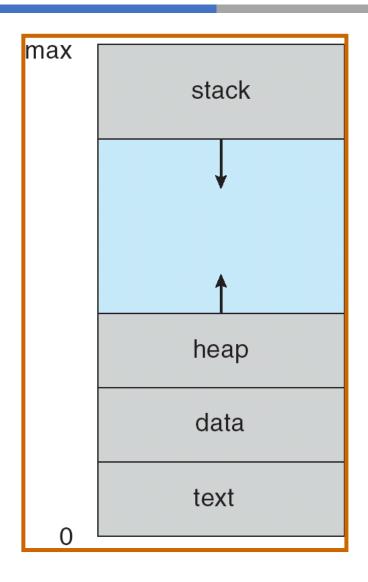


- A system therefore consists of a collection of processes:
 - Operating system processes execute system code, and
 - User processes execute user code.

System Process & User Process



Process Structure in Memory



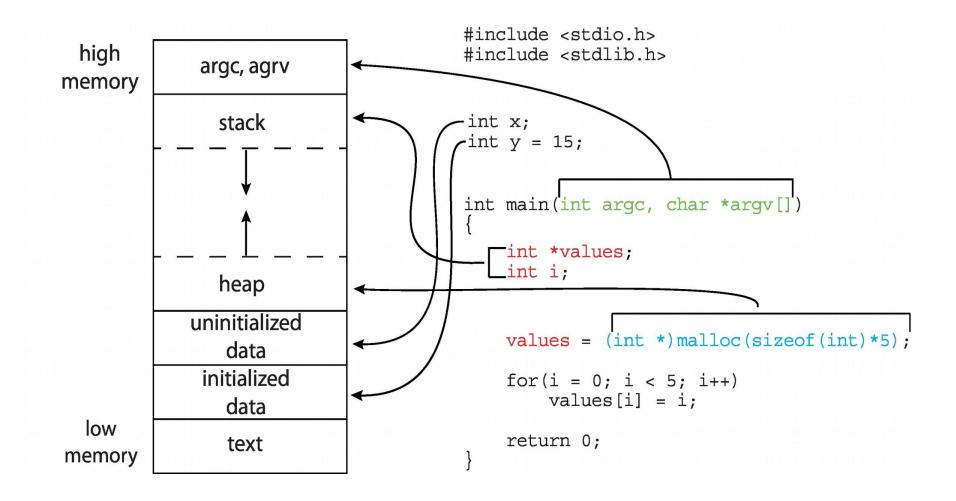
Temporary data (function parameters, return addresses, local variables)

Dynamically allocated memory at runtime
Global variables

Value of program counter; Contents of processor's registers



Memory Layout of a C Program



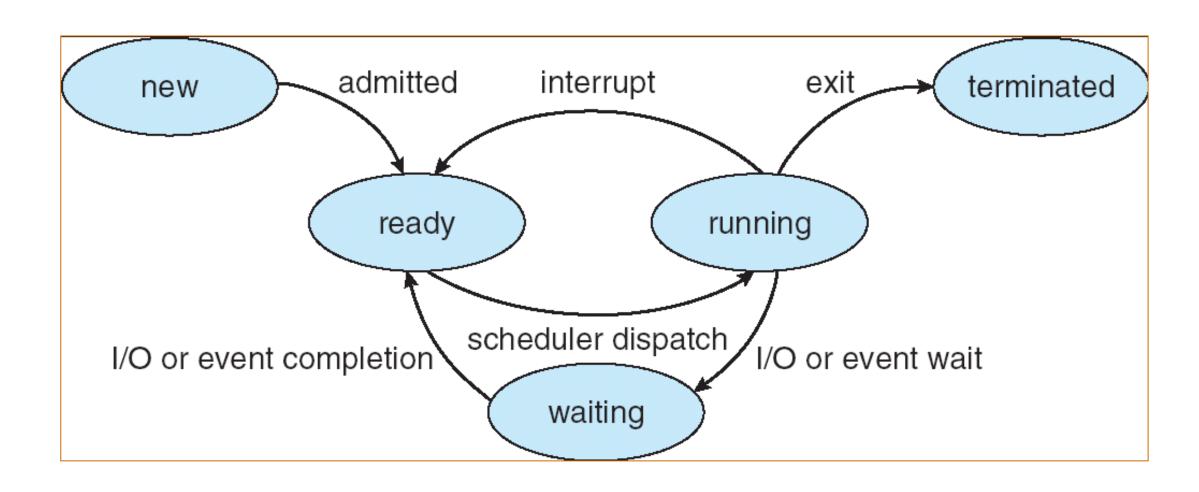
Process State



- Process state
 - new: the process is being created
 - running: instructions are being executed
 - waiting: the process is waiting for some event to occur (such as an I/O completion or reception of a signal)
 - ready: the process is waiting to be assigned to a processor
 - terminated: the process has finished execution
- As a process executes, it changes state
- Only one process is running on one processor at any instant. However, many processes may be ready or waiting



Diagram of Process State





Process Control Block (PCB)

- Information associated with each process
 - Identifier
 - Process state
 - CPU scheduling information (e.g., priority)
 - Program counter: next instruction to be executed
 - CPU registers
 - Memory-management information (e.g., base/limit register, page or segment tables)
 - Accounting information
 - I/O status information





- The current state of process is held in a process control block (PCB):
 - This is a "snapshot" of the execution and protection environment
 - Only one PCB is active at a time
- Created and managed by the operating system

process state process number program counter registers memory limits list of open files

Process Control Block



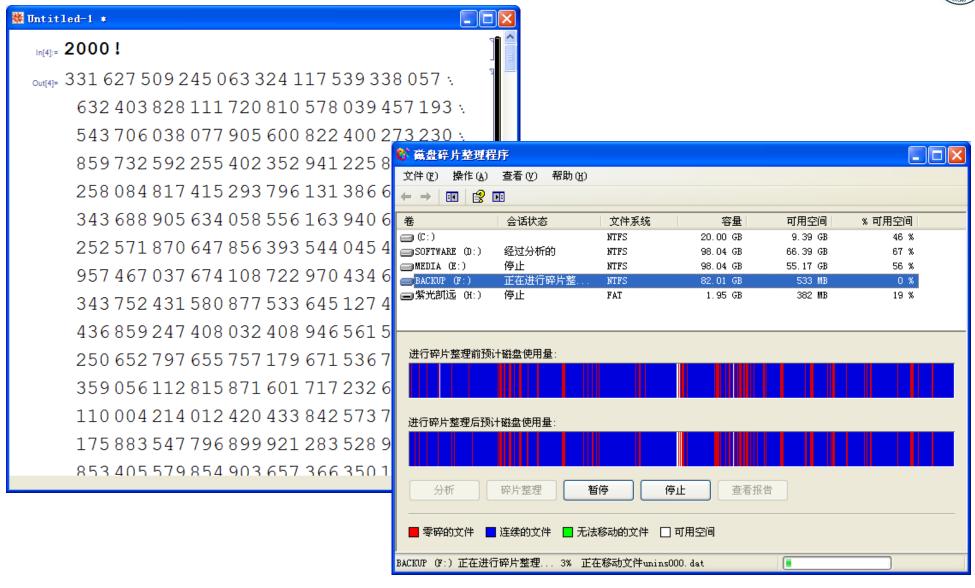
Implementation of Processes

- •OS creates process, allocates memory, I/O devices, files, and so on to user program.
- Create the PCB
 - the number is limited



Process Scheduling

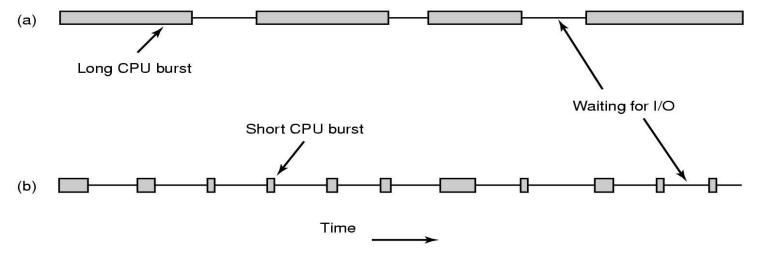




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Introduction to Scheduling

- Bursts of CPU usage alternate with periods of I/O wait
- Processes can be described as either:
 - I/O-bound process spends more time doing I/O than computations, many short CPU bursts
 - CPU-bound process spends more time doing computations; many long CPU bursts





Introduction to Scheduling

- Why Scheduling?
- For a uni-processor system, there is only one running process. The rest should wait until CPU free and is rescheduled





Process Scheduling Queues

- Job queue
 - set of all processes in the system
- Ready queue
 - set of all processes residing in main memory, ready and waiting to execute
- Device queues
 - set of processes waiting for an I/O device
- Processes migrate among the various queues



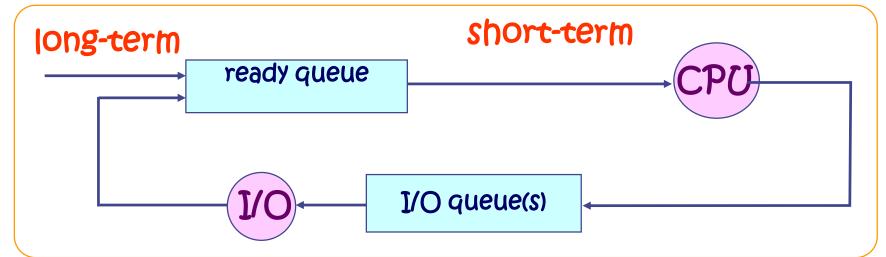


- Long-term scheduler (or job scheduler) selects which processes should be brought into the ready queue
 - Execute less frequently (e.g., once several minutes)
 - Control the degree of multiprogramming
 - Select a good process mix of I/O-bound processes and CPU-bound processes

Schedulers



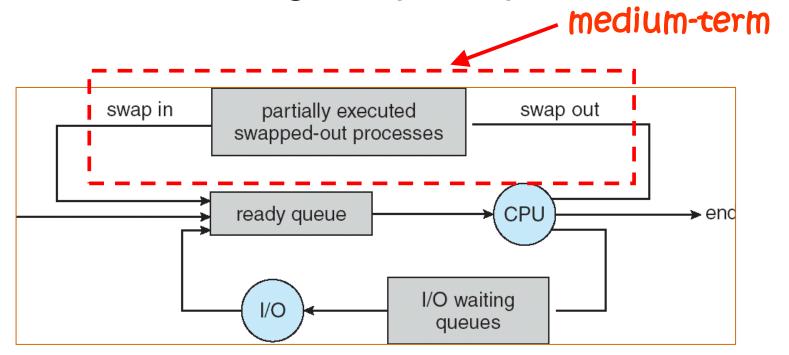
- Short-term scheduler (or CPU scheduler) selects which process should be executed next and allocates CPU
 - Execute quite frequently (e.g., once per 100ms)
 - Must be very fast
 - e.g., if it takes 10 ms, then 10/(100+10) percent of CPU is wasted.



Schedulers



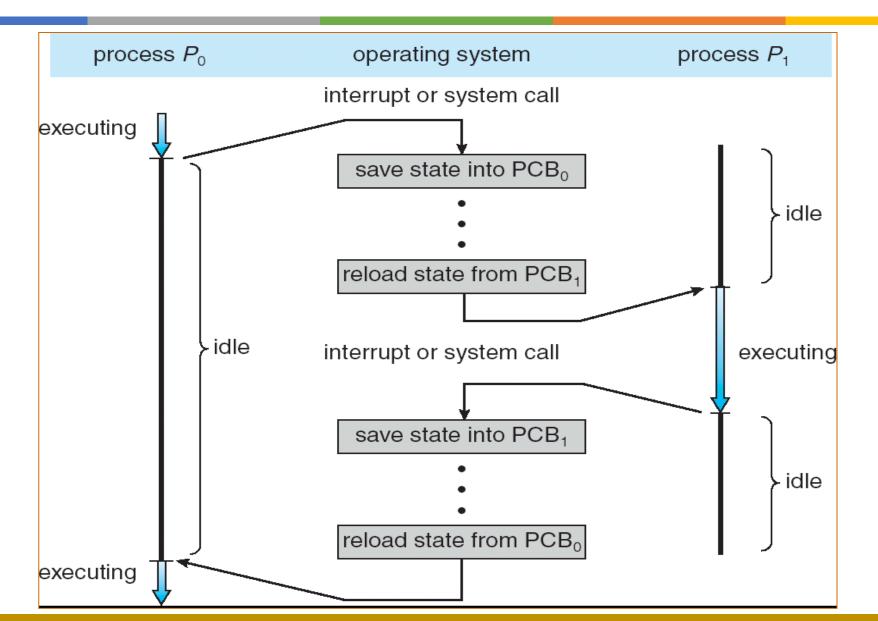
- Medium-term Scheduler (Swapping)
 - swap out: removing processes from memory to reduce the degree of multiprogramming.
 - swap in: reintroducing swap-out processes into memory



Differences between These Schedulers

- Long-term scheduling job scheduling, select job from external storage to memory and create a process
 - invoked very infrequently (seconds, minutes) ⇒ (may be slow)
- Short-term scheduling process scheduling, select the ready process to run on the processor
 - invoked very frequently (milliseconds) ⇒ (must be fast)
- Medium-term scheduling solves the problem of insufficient memory, using secondary storage to alleviate (controls the degree of multiprogramming)

CPU Switch from Process to Process



Context Switch



- When CPU switches to another process, the system must save the state of the old process and load the saved state for the new process
- This is also called a "context switch"
- Context-switch time is overhead; the system does no useful work while switching



Operations on Processes



Operations on Processes

- Five major activities of an operating system in regard to process management
 - The creation and deletion of both user and system processes
 - The suspension and resumption of processes
 - The provision of mechanisms for process synchronization
 - The provision of mechanisms for process communication
 - The provision of mechanisms for deadlock handling

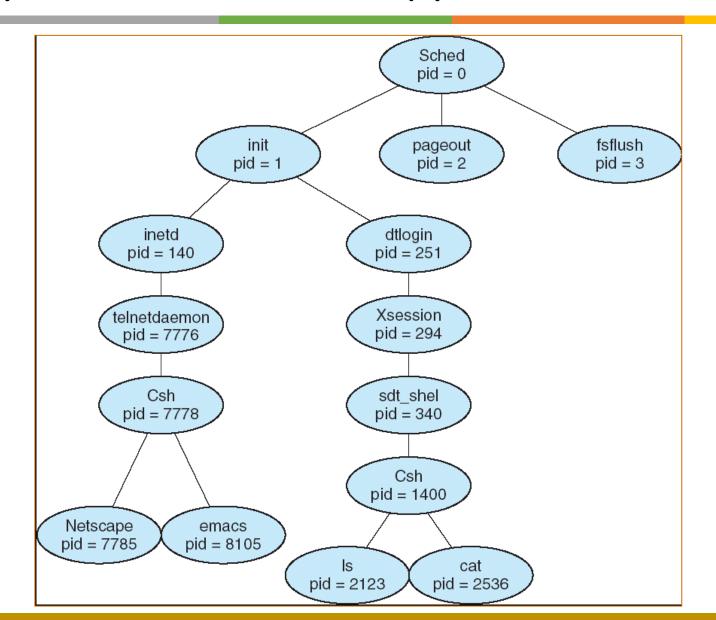
Process



- A process may spawn many processes as it runs
- Parent process create children processes, which, in turn create other processes, forming a tree of processes
- Forms a hierarchy
 - UNIX calls this a "process group"
- Windows has no concept of process hierarchy
 - all processes are created equally (by using handle)



A tree of processes on a typical Solaris



Process Creation



- Parent process create children processes, thus forming a tree of processes
- Resource sharing
 - Parent and children share all resources
 - Children share subset of parent's resources
 - Parent and child share no resources
- Execution
 - Parent and children execute concurrently
 - Parent waits until children terminate

Process Termination



- Conditions which terminate processes
 - Normal exit (voluntary)
 - Error exit (voluntary)
 - Fatal error (involuntary)
 - Killed by another process (involuntary)

CreateProcessA



BOOL CreateProcessA()

CreateProcessA function (processthreadsapi.h)

• 13 minutes to read

Creates a new process and its primary thread. The new process runs in the security context of the calling process.

If the calling process is impersonating another user, the new process uses the token for the calling process, not the impersonation token. To run the new process in the security context of the user represented by the impersonation token, use the CreateProcessAsUser or CreateProcessWithLogonW function.

Syntax

```
BOOL CreateProcessA(

LPCSTR lpApplicationName,

LPSTR lpCommandLine,

LPSECURITY_ATTRIBUTES lpProcessAttributes,

LPSECURITY_ATTRIBUTES lpThreadAttributes,

BOOL bInheritHandles,

DWORD dwCreationFlags,

LPVOID lpEnvironment,

LPCSTR lpCurrentDirectory,

LPSTARTUPINFOA lpStartupInfo,

LPPROCESS_INFORMATION lpProcessInformation
);
```

ExitProcess



void ExitProcess(UINT uExitCode);

ExitProcess function (processthreadsapi.h)

· 2 minutes to read

Ends the calling process and all its threads.

Syntax

void ExitProcess(
 UINT uExitCode
);

Parameters

uExitCode

The exit code for the process and all threads.

Return value

None

Remarks

Use the GetExitCodeProcess function to retrieve the process's exit value. Use the GetExitCodeThread function to retrieve a thread's exit value.

TerminateProcess



- BOOL TerminateProcess(HANDLE hProcess,UINT uExitCode);
 - GetCurrentProcess()

TerminateProcess function (processthreadsapi.h)

• 2 minutes to read

Terminates the specified process and all of its threads.

Syntax

```
BOOL TerminateProcess(
HANDLE hProcess,
UINT uExitCode
);
```

Parameters

hProcess

A handle to the process to be terminated.

The handle must have the PROCESS_TERMINATE access right. For more information, see Process Security and Access Rights.

uExitCode

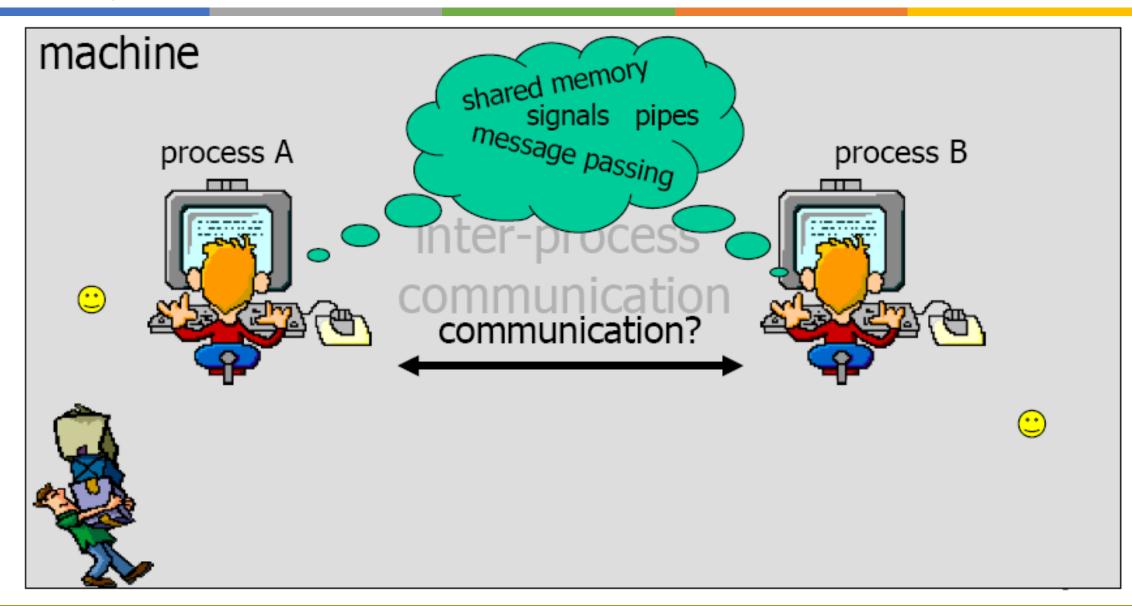
The exit code to be used by the process and threads terminated as a result of this call. Use the GetExitCodeProcess function to retrieve a process's exit value. Use the GetExitCodeThread function to retrieve a thread's exit value.



Interprocess Communication



Cooperating Processes





Cooperating Processes

- Independent process cannot affect or be affected by the execution of another process
- Cooperating process can affect or be affected by the execution of another process
- Advantages of process cooperation
 - Information sharing
 - Computation speed-up
 - Modularity
 - Convenience, e.g., A user can performs several tasks at the same time (editing, printing, compiling)

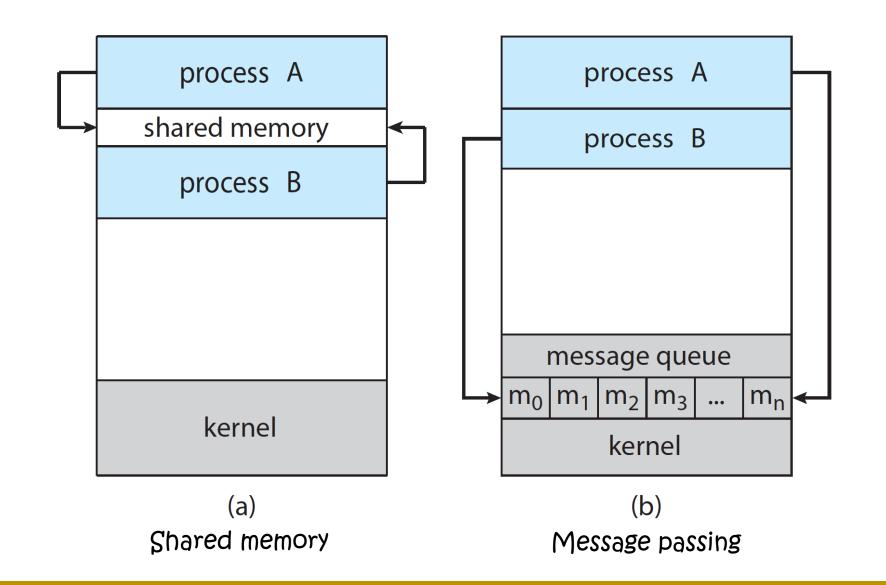
 Mechanism for processes to communicate and to synchronize their actions

Inter-Process
Communication
(IPC)





IPC Communication Models

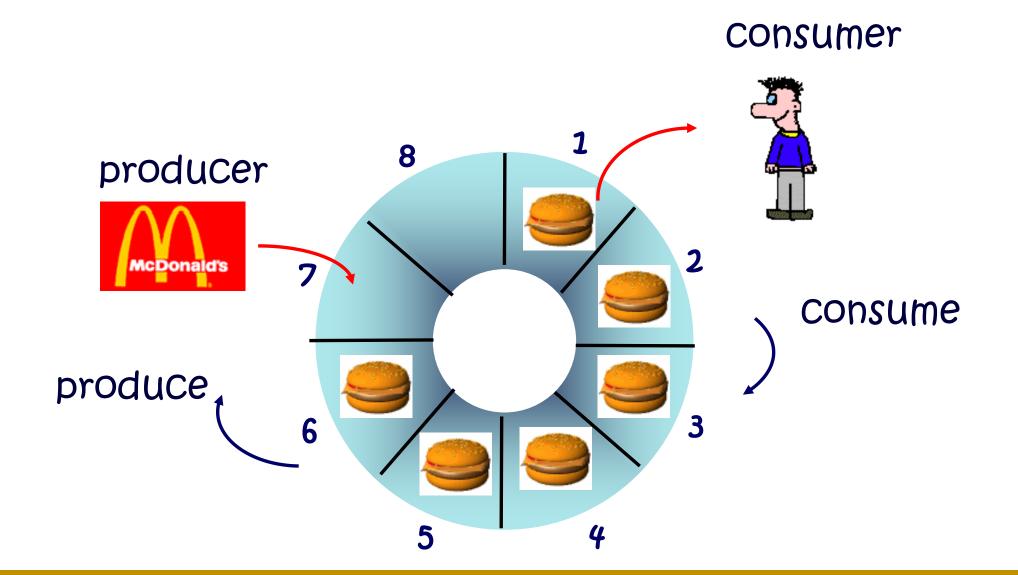


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Producer-Consumer Problem

- Paradigm for cooperating processes, producer process produces information that is consumed by a consumer process
 - unbounded-buffer places no practical limit on the size of the buffer
 - producer: no wait
 - consumer: wait when buffer is empty
 - bounded-buffer assumes that there is a fixed buffer size
 - producer: wait when buffer is full
 - consumer: wait when buffer is empty

Example of Producer-Consumer Problem

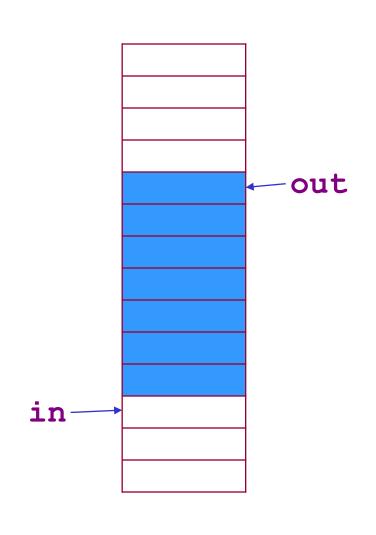




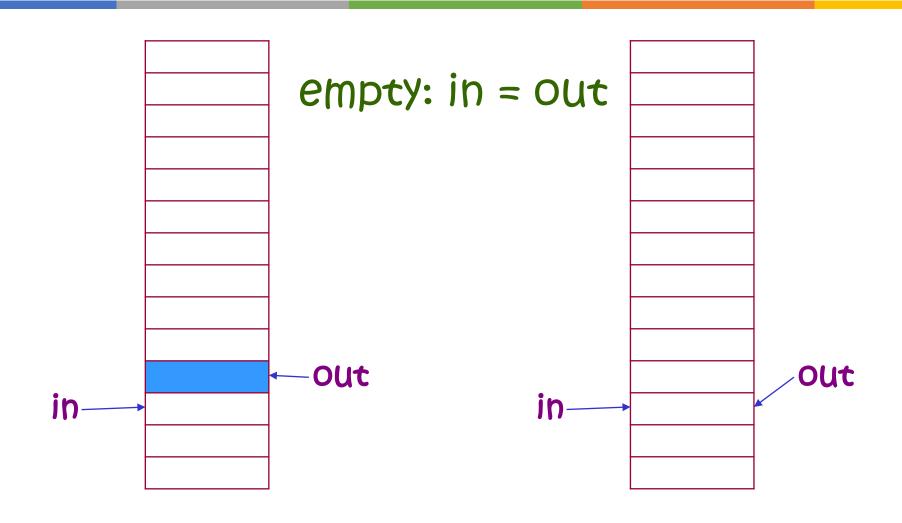
Shared data: Buffer as a circular array

```
#define BUFFER SIZE 10
typedef struct {
} item;
item buffer[BUFFER SIZE];
int in = 0;
int out = 0;
```

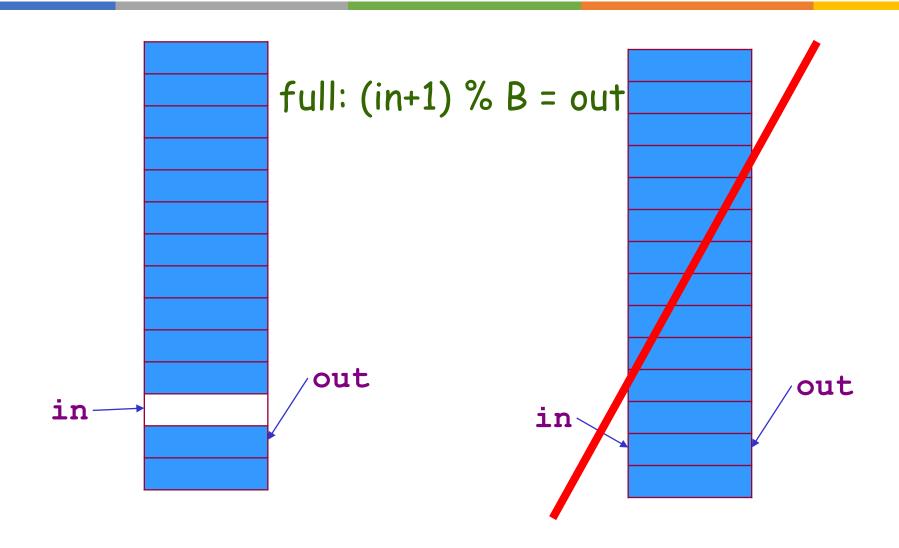
- Shared data: Buffer as a circular array
 - next free: in
 - first available: out
 - empty: in = out
 - full: (in+1) % B = out



Bounded-Buffer: Shared-Memory Solution



Bounded-Buffer: Shared-Memory Solution



Bounded-Buffer: Producer Process-Insert()

```
while (true) {
 /* Produce an item */
  while (((in+1) % BUFFER SIZE) == out)
   ;/*do nothing--no free buffers */
 buffer[in] = item;
 in = (in + 1) % BUFFER SIZE;
```

Bounded Buffer: Consumer Process - Remove()

```
while (true) {
  while (in == out)
    ; // do nothing -- nothing to consume
 // remove an item from the buffer
 item = buffer[out];
 out = (out + 1) % BUFFER SIZE;
 return item;
```



Message system

- Message system processes communicate with each other without resorting to shared variables
- IPC facility provides two operations:
 - send(message) message size fixed or variable
 - receive(message)
- If P and Q wish to communicate, they need to:
 - establish a communication link between them
 - exchange messages via send/receive



Direct Communication



- Processes must name each other explicitly:
 - send (P, message) send a message to process P
 - receive (Q, message) receive a message from process Q
- •limited modularity: if the name of a process is changed, all old names should be found. It is not easy for separate compilation.





- Messages are sent and received from mailboxes (also referred to as ports)
 - Each mailbox has a unique id
 - Processes can communicate only if they share a mailbox



Indirect Communication



- Operations
 - create a new mailbox
 - send and receive messages through mailbox
 - destroy a mailbox
- Primitives are defined as:

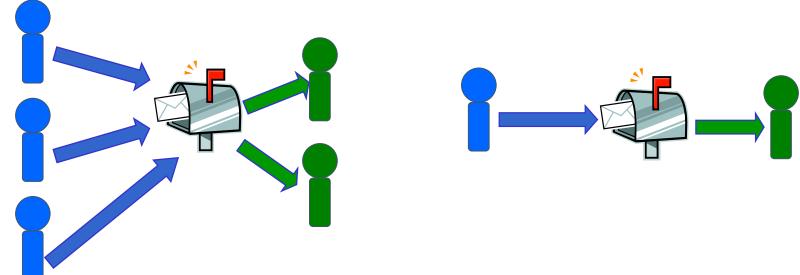
send(A, message) – send a message to mailbox A
receive(A, message) – receive a message from mailbox A







- Properties of communication link
 - Link established only if processes share a common mailbox
 - A link may be associated with many processes
 - Each pair of processes may share several communication links
 - Link may be unidirectional or bi-directional





Synchronization

- Message passing may be either blocking or non-blocking
- Blocking is considered synchronous
 - Blocking send: the sender is blocked until the message is received
 - Blocking receive: the receiver is blocked until a message is available
- Non-blocking is considered asynchronous
 - Non-blocking send: the sender sends the message and continue
 - Non-blocking receive: the receiver receives a valid message or null





 Mailslots are supported by three specialized functions: CreateMailslot, GetMailslotInfo, and SetMailslotInfo.

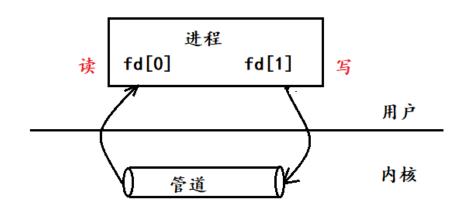
Pipe

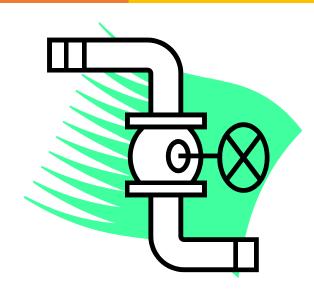


- CreatePipe
- CreateNamedPipe



WriteFile







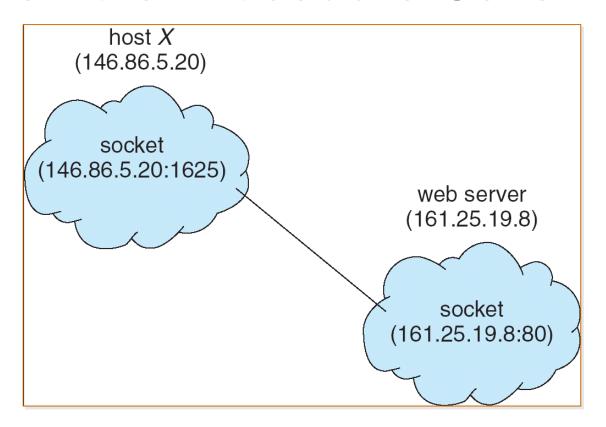
Communication in Client-Server Systems

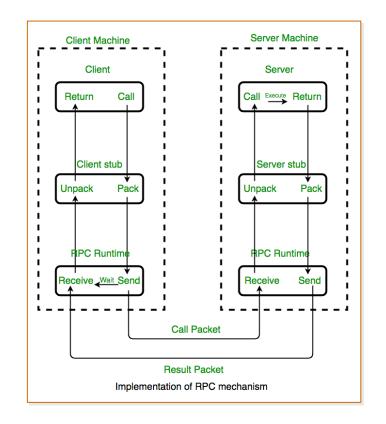


Client-Server Communication

- Sockets
- Remote Procedure Calls

https://www.cnblogs.com/swordfall/p/8683905.html



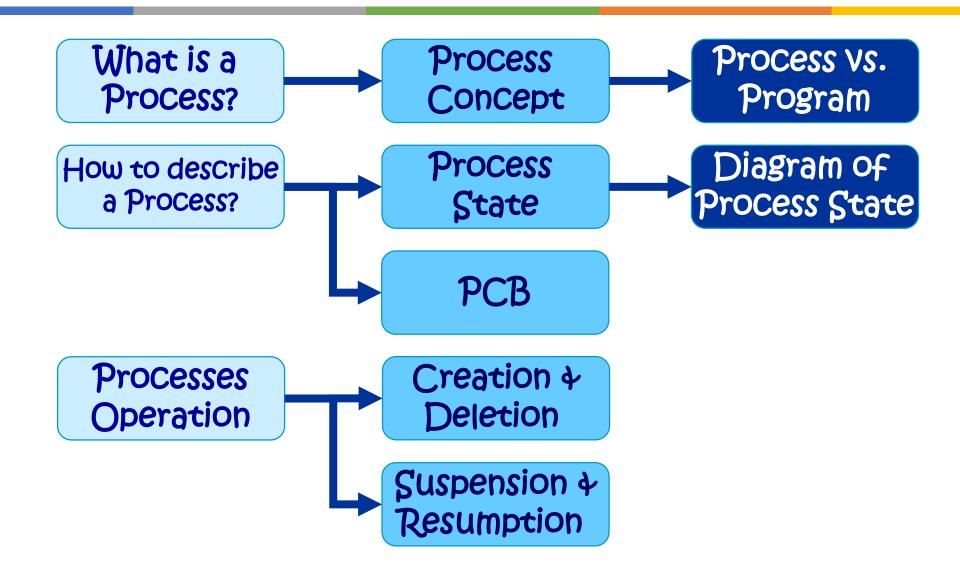




Summary

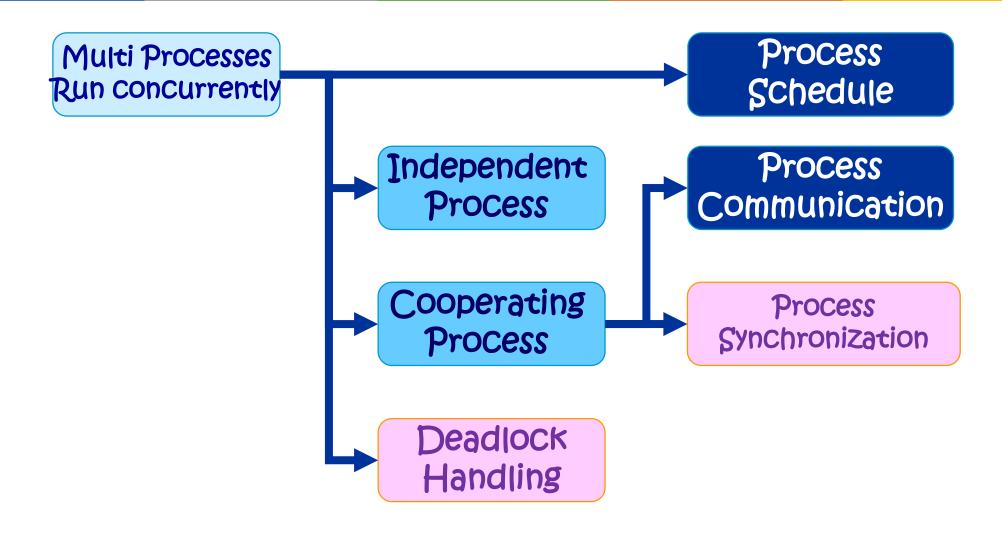






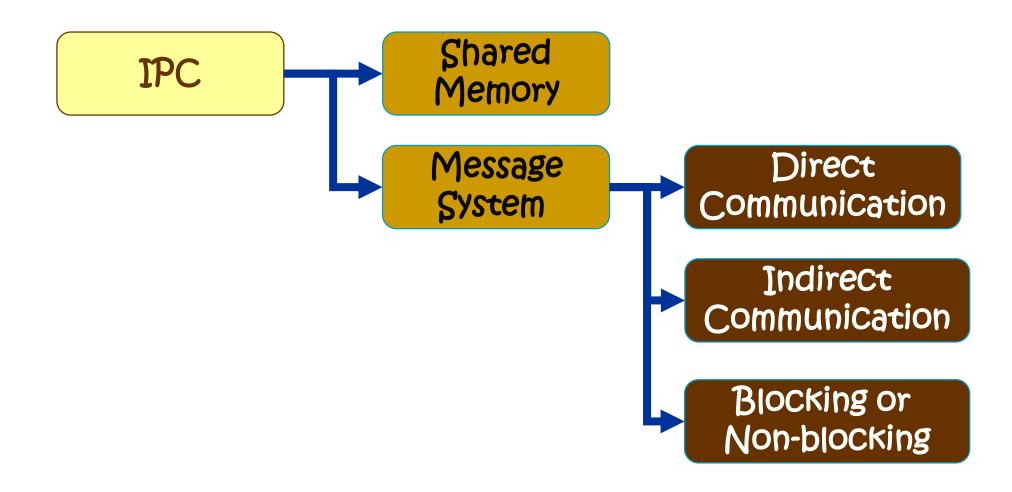








Interprocess Communication





Thank you! Q&A

