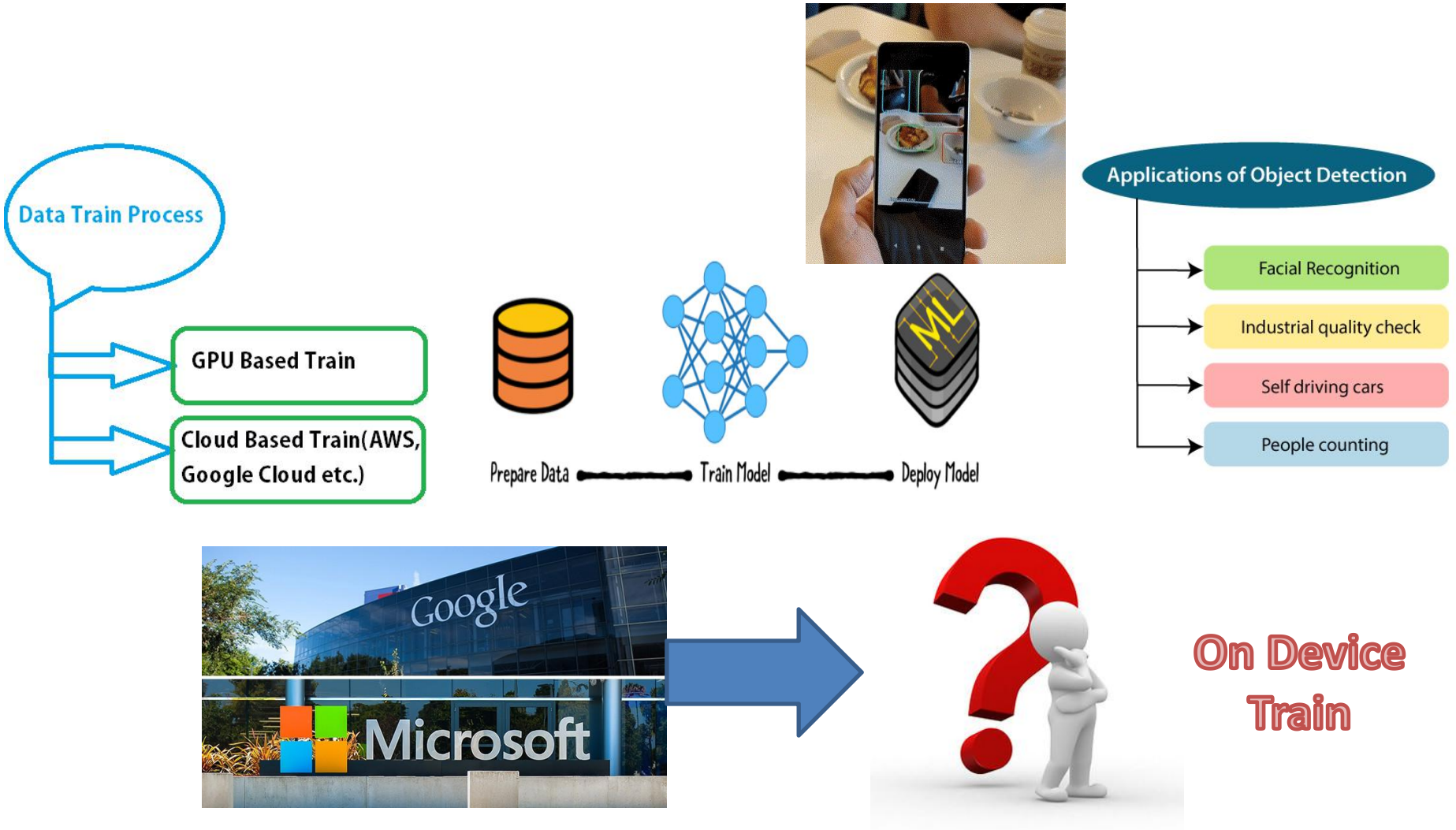


On Device Object Train and Recognition

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Problem



Solution

Step 0. Initialize weights: to small random values;

Step 1. Apply a sample: apply to the input a sample vector \mathbf{u}^k having desired output vector \mathbf{y}^k ;

Step 2. Forward Phase:

Starting from the first hidden layer and propagating towards the output layer:

Calculate the activation values for the units at layer L as:

If $L-1$ is the input layer

$$a_{h_L}^k = \sum_{j=0}^N w_{jh_L} u_j^k$$

If $L-1$ is a hidden layer

$$a_{h_L}^k = \sum_{j_{L-1}=0}^{N_{L-1}} w_{j_{L-1}h_L} x_{j_{L-1}}^k$$

Calculate the output values for the units at layer L as:

$$x_{h_L}^k = f_L(a_{h_L}^k)$$

in which use i_o instead of h_L if it is an output layer

Step 4. Output errors: Calculate the error terms at the output layer as:

$$\delta_{i_o}^k = (y_{i_o}^k - x_{i_o}^k) f'_o(a_{i_o}^k)$$

Step 5. Backward Phase Propagate error backward to the input layer through each layer L using the error term

$$\delta_{h_L}^k = f'_L(a_{h_L}^k) \sum_{i_{L+1}=1}^{N_{L+1}} \delta_{i_{L+1}}^k w_{h_L i_{L+1}}^k$$

in which, use i_o instead of i_{L+1} if $L+1$ is an output layer;

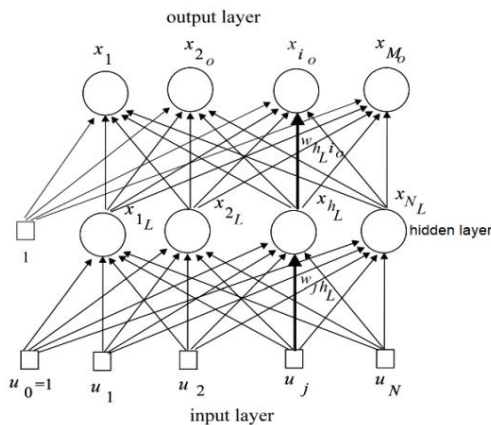
Step 6. Weight update: Update weights according to the formula

$$w_{j_{L-1}h_L}(t+1) = w_{j_{L-1}h_L}(t) + \eta \delta_{h_L}^k x_{j_{L-1}}^k$$

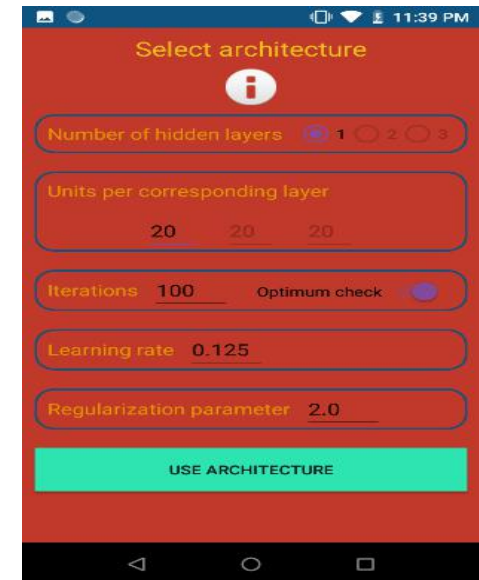
Step 7. Repeat steps 1-6 until the stop criterion is satisfied, which may be chosen as the mean of the total error

$$\langle e^k \rangle = \frac{1}{2} \sum_{i_o=1}^M (y_{i_o}^k - x_{i_o}^k)^2$$

Neural Network Algorithm



Neural Network Architecture



Developed Application

Product



Pocket Code: Learn programming your own game apps!

Catrobat Education

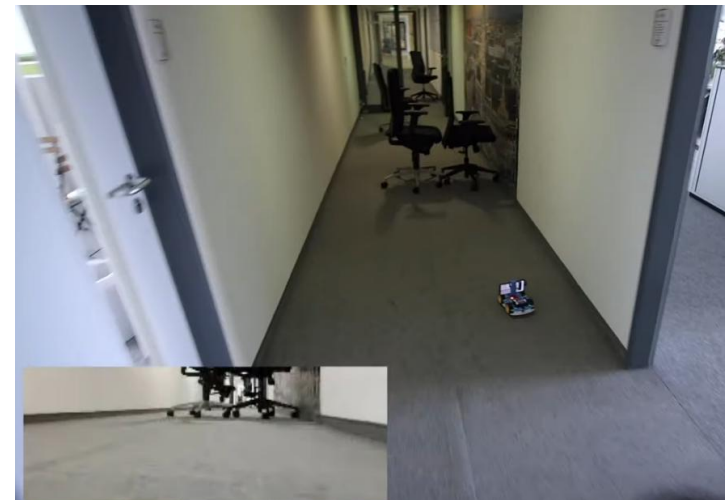
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I have no fund just working as a contributor to increase students learning.

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