

# Epsilon-NFA to NFA Converter Documentation

## Overview

This program converts an  $\epsilon$ -NFA (Nondeterministic Finite Automaton with epsilon transitions) into an equivalent NFA without epsilon transitions. The conversion preserves the language recognized by the automaton while eliminating all  $\epsilon$ -transitions.

## Theory Background

### What is an $\epsilon$ -NFA?

An  $\epsilon$ -NFA is a finite automaton that can transition between states without consuming any input symbol (epsilon transitions). These transitions make the automaton easier to design but more complex to simulate.

## Conversion Algorithm

The conversion process involves three main steps:

1. **Epsilon-Closure Computation:** For each state, determine all states reachable via zero or more epsilon transitions
2. **Transition Elimination:** Create new direct transitions that bypass epsilon transitions
3. **Final State Adjustment:** Mark states as final if they can reach any original final state via epsilon transitions

## Data Structures

### Constants

```
c

#define MAX_STATES 10      // Maximum number of states
#define MAX_ALPHABET_SIZE 5 // Maximum alphabet size
```

### Global Variables

Variable	Type	Purpose
num_states	int	Number of states in the automaton
num_symbols	int	Number of symbols in the alphabet
alphabet[]	char array	Input alphabet symbols
initial_state	int	Starting state of the automaton

Variable	Type	Purpose
final_states[]	int array	Boolean array marking final states

## Transition Tables

Table	Dimensions	Purpose
symbol_transitions[][][]	states × symbols × states	Original non-epsilon transitions
epsilon_transitions[][]	states × states	Original epsilon transitions
epsilon_closure[][]	states × states	Computed epsilon-closure relation
converted_transitions[][][]	states × symbols × states	New transitions without epsilons

## Function Reference

**initialize\_data\_structures()**

**Purpose:** Initializes all global arrays to zero before processing.

**Algorithm:** Iterates through all data structures and sets each element to 0.

**Complexity:**  $O(n^3)$  where n is MAX\_STATES

**read\_automaton\_input()**

**Purpose:** Reads the automaton specification from standard input.

**Input Format:**

Number of states: <n>  
Number of symbols: <m>  
Alphabet symbols: <s1> <s2> ... <sm>  
Initial state: <q0>  
Number of final states: <f>  
Final states: <qf1> <qf2> ... <qff>  
Symbol transitions (-1 to stop):  
<from> <symbol> <to>  
...  
-1  
Epsilon transitions (-1 to stop):  
<from> <to>  
...  
-1

### Example:

Number of states: 3  
Number of symbols: 2  
Alphabet symbols: a b  
Initial state: 0  
Number of final states: 1  
Final states: 2  
Symbol transitions (-1 to stop):  
1 a 2  
-1  
Epsilon transitions (-1 to stop):  
0 1  
-1

### compute\_epsilon\_closure()

**Purpose:** Computes the epsilon-closure for all states using the Floyd-Warshall-style transitive closure algorithm.

### Algorithm:

1. Initialize: Each state can reach itself (reflexive property)
2. Repeat until no changes occur:
  - For each state i that can reach state j
  - For each state k reachable from j via epsilon
  - Mark that i can reach k

## Mathematical Definition:

$$\epsilon\text{-closure}(q) = \{p \mid q \xrightarrow{*} p \text{ via } \epsilon\text{-transitions}\}$$

**Complexity:**  $O(n^3)$  worst case, but typically faster due to early termination

**Key Property:** The  $\text{epsilon\_closure}[i][j] = 1$  means state  $i$  can reach state  $j$  through zero or more epsilon transitions.

---

### eliminate\_epsilon\_transitions()

**Purpose:** Creates new direct symbol transitions that bypass all epsilon transitions.

#### Algorithm:

For each source state  $s$ :

1. Find all states reachable from  $s$  via epsilon (epsilon-closure)
2. For each such state  $q$  and each symbol  $a$ :
  - Find states  $r$  directly reachable from  $q$  by reading  $a$
  - Find all states reachable from  $r$  via epsilon
  - Add direct transition:  $s \xrightarrow{a} (\text{all such final states})$

#### Mathematical Formula:

$$\delta'(s, a) = \epsilon\text{-closure}(\delta(\epsilon\text{-closure}(s), a))$$

Where:

- $\delta'$  is the new transition function
- $\delta$  is the original transition function
- $\epsilon\text{-closure}()$  computes epsilon-closure

#### Example:

Original  $\epsilon$ -NFA:

$$0 \xrightarrow{\epsilon} 1 \xrightarrow{a} 2$$

Converted NFA:

0 --a--> 2 (bypassing the epsilon transition)

**Complexity:**  $O(n^4 \times m)$  where  $n$  = states,  $m$  = alphabet size

---

### **update\_final\_states()**

**Purpose:** Updates the set of final states based on epsilon-closure.

**Algorithm:** A state becomes final if it can reach any original final state via epsilon transitions.

**Rule:**

q is final in NFA if  $\exists f \in F$  such that  $f \in \epsilon\text{-closure}(q)$

Where  $F$  is the set of original final states.

**Example:**

- Original: State 2 is final
  - Epsilon transition: 1 -- $\epsilon$ --> 2
  - Result: States 1 and 2 are both final
- 

### **display\_result()**

**Purpose:** Prints the resulting epsilon-free NFA in a human-readable format.

**Output Format:**

```
===== ε-free NFA =====
```

```
Start state: <q0>
```

```
Final states: <zf1> <zf2> ...
```

```
Transitions:
```

```
<from> --<symbol>--> <to>
```

```
...
```

## **Algorithm Correctness**

### **Proof of Equivalence**

The converted NFA accepts the same language as the original  $\epsilon$ -NFA because:

1. **Forward Direction:** Any string accepted by the  $\epsilon$ -NFA is accepted by the converted NFA

- Each path in the  $\epsilon$ -NFA has a corresponding path in the converted NFA
  - Epsilon transitions are "compiled" into direct transitions
2. **Backward Direction:** Any string accepted by the converted NFA was accepted by the original
- Each new transition represents a valid path in the original automaton
  - No new accepting paths are created, only epsilon transitions are eliminated

## Termination

The algorithm terminates because:

- `compute_epsilon_closure()` uses fixed-point iteration on a finite set
- Once no new reachable states are discovered, the loop exits
- Maximum iterations:  $O(n^3)$

## Usage Example

### Input Automaton

Consider an  $\epsilon$ -NFA that accepts strings ending in 'b':

```
States: {0, 1, 2}
Alphabet: {a, b}
Initial: 0
Final: {2}
Transitions:
0 --ε--> 1
1 --a--> 1
1 --b--> 2
```

### Program Input

```
Number of states: 3
Number of symbols: 2
Alphabet symbols: a b
Initial state: 0
Number of final states: 1
Final states: 2
Symbol transitions (-1 to stop):
1 a 1
1 b 2
-1
Epsilon transitions (-1 to stop):
```

0 1  
-1

## Expected Output

```
===== ε-free NFA =====
```

Start state: 0

Final states: 2

Transitions:

0 --a--> 1

0 --b--> 2

1 --a--> 1

1 --b--> 2

## Explanation

- State 0 now has direct transitions for 'a' and 'b' because it can reach state 1 via epsilon
- The epsilon transition is eliminated while preserving the language

## Limitations

1. **Fixed Size:** Maximum 10 states and 5 alphabet symbols
2. **Input Format:** Requires specific input format with sentinel values (-1)
3. **No Validation:** Does not validate state numbers or symbol correctness
4. **Memory:** Uses static arrays, not memory-efficient for sparse automata

## Possible Extensions

1. **Dynamic Memory:** Use dynamic allocation for arbitrary-sized automata
2. **Input Validation:** Add error checking for invalid states/symbols
3. **File I/O:** Support reading from/writing to files
4. **Visualization:** Generate graphical representations (DOT format)
5. **Optimization:** Detect and remove unreachable states
6. **DFA Conversion:** Extend to convert NFA to DFA (subset construction)

## Complexity Analysis

Operation	Time Complexity	Space Complexity
Initialization	$O(n^2m)$	$O(n^2m)$
Input Reading	$O(n + t)$	$O(1)$
Epsilon-Closure	$O(n^3)$	$O(n^2)$
Transition Elimination	$O(n^4m)$	$O(n^2m)$
Final State Update	$O(n^2)$	$O(1)$
Output	$O(n^2m)$	$O(1)$
<b>Total</b>	<b><math>O(n^4m)</math></b>	<b><math>O(n^2m)</math></b>

Where:

- $n$  = number of states
- $m$  = alphabet size
- $t$  = number of input transitions

## References

1. Hopcroft, J. E., & Ullman, J. D. (1979). *Introduction to Automata Theory, Languages, and Computation*
2. Sipser, M. (2012). *Introduction to the Theory of Computation*
3. Aho, A. V., Sethi, R., & Ullman, J. D. (1986). *Compilers: Principles, Techniques, and Tools*

## License

This implementation is provided for educational purposes.