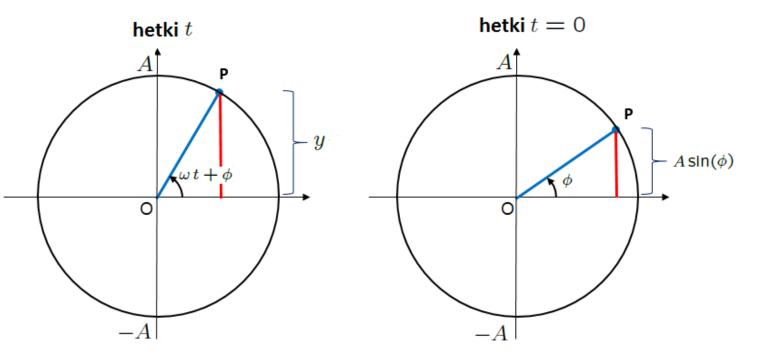
#### Sinikäyrä $y = A \sin(\omega t + \phi)$



kertoo pisteen P korkeuden hetkellä t, kun se pyörii A-säteistä ympyrää vastapäivään nopeudella  $\omega$  **rad**iaania sekunnissa ja kiertokulma on  $\phi$  hetkellä t=0.

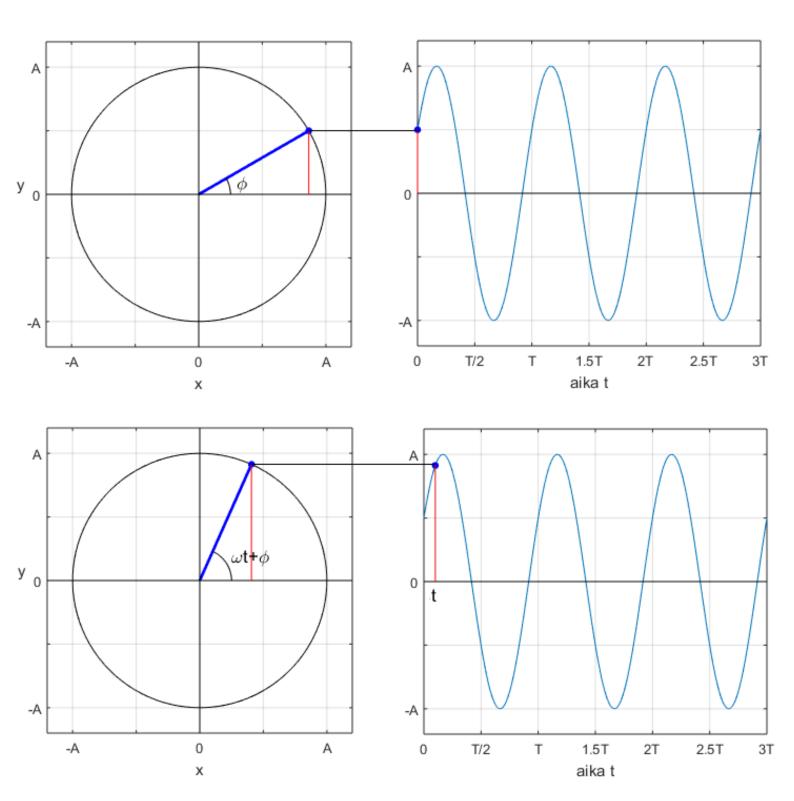
Kosinikäyrä  $x = A\cos(\omega t + \phi)$  kertoo P:n vaakasuoran paikan. A = amplitudi

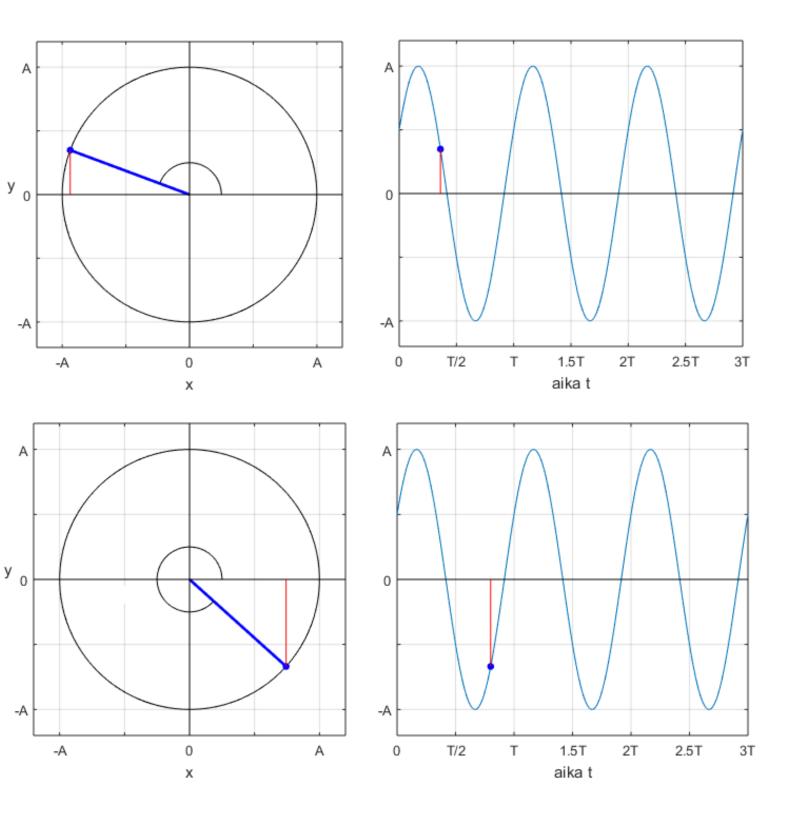
 $\omega = 2\pi f = \text{kulmataajuus (rad/sek)}$ 

f = taajuus (kierrosta/sek)

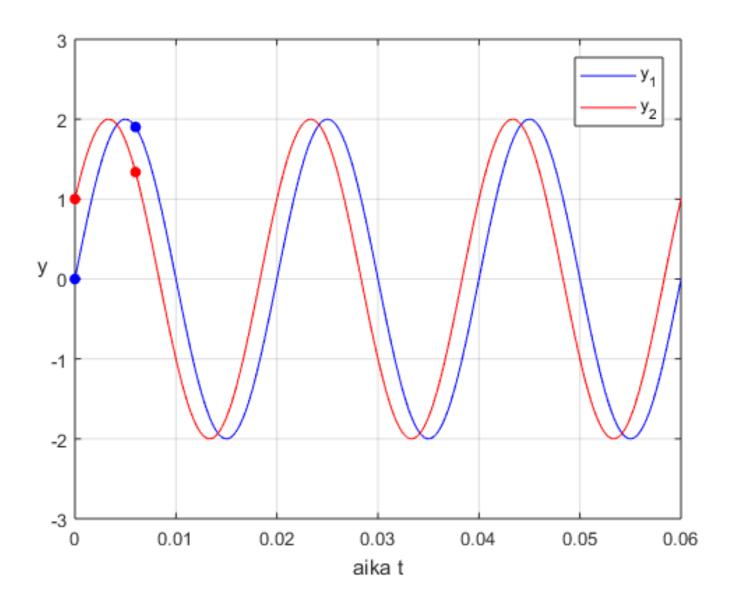
 $T=2\pi/\omega=1/f=$  jakso = yhteen kierrokseen kuluva aika

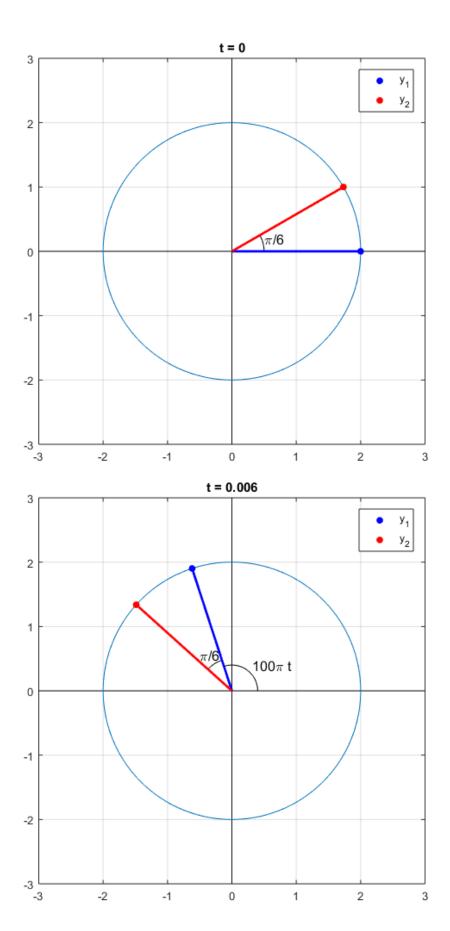
 $\phi = \text{vaihekulma (rad, yleensä välillä } -\pi \dots \pi)$ 



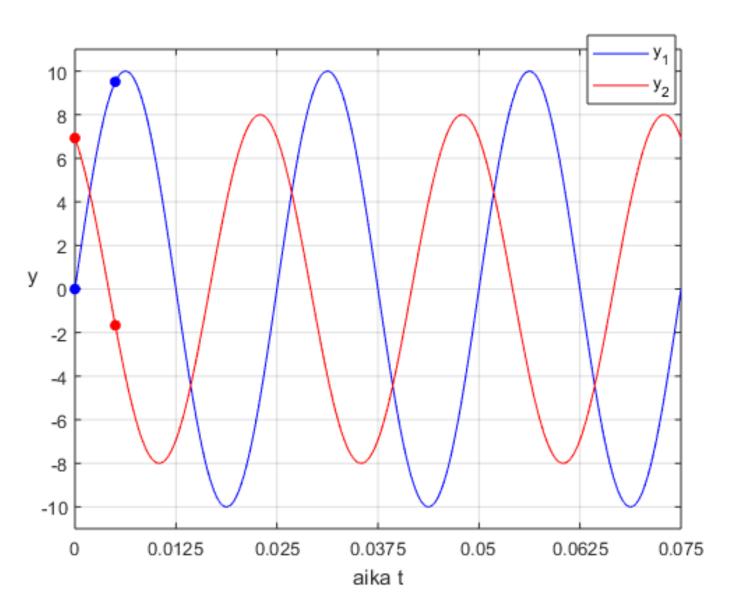


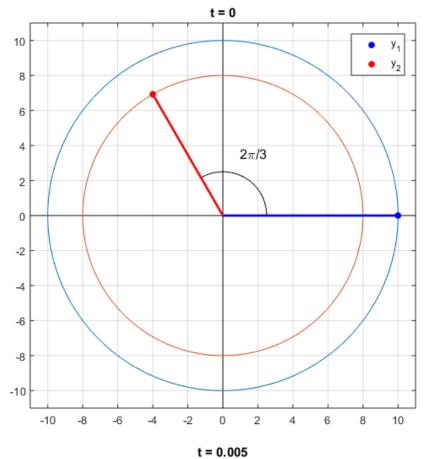
$$y_1 = 2\sin(100\pi t)$$
  
 $y_2 = 2\sin(100\pi t + \pi/6)$ 

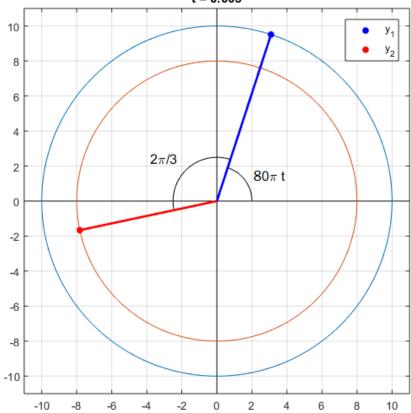




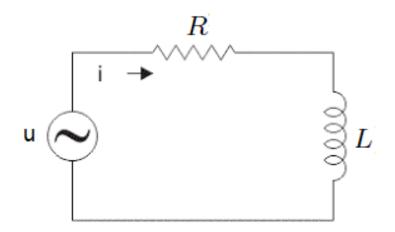
$$y_1 = 10\sin(80\pi t)$$
  
 $y_2 = 8\sin(80\pi t + 2\pi/3)$ 







#### RL-piiri $\cdot$

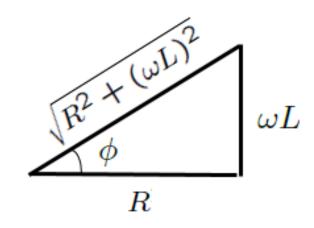


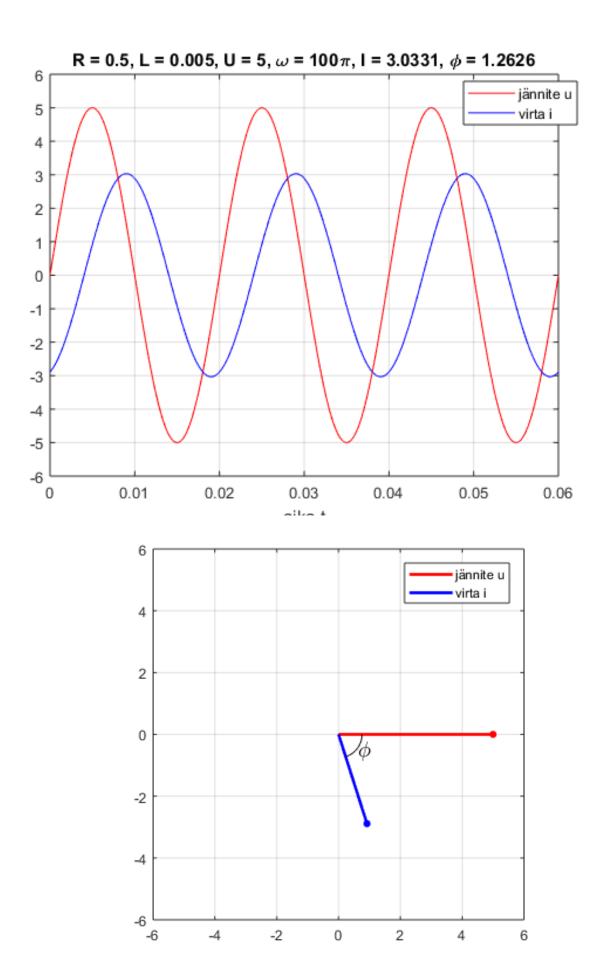
Jos jännite  $u = U \sin(\omega t)$ , niin virta

 $i = I\sin(\omega t - \phi)$ , missä

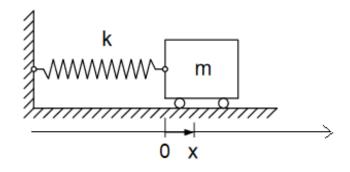
$$I = \frac{U}{\sqrt{R^2 + (\omega L)^2}}$$

$$\phi = \tan^{-1}(\omega L/R)$$





# Mekaaninen värähtelijä: massa m, jousivakio k, alkupaikka $x_0$ ja -nopeus $v_0$

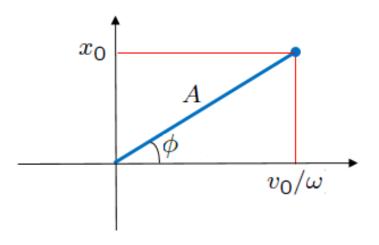


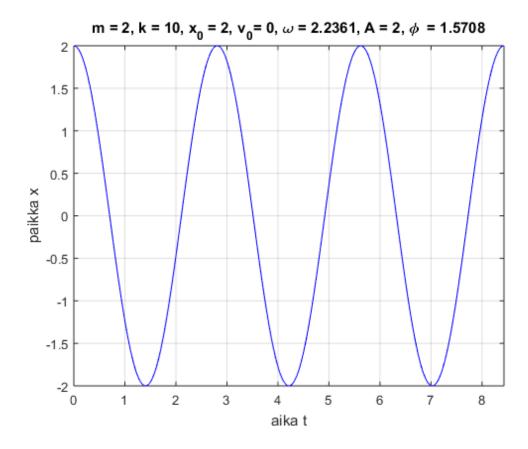
Paikka  $x = A\sin(\omega t + \phi)$ , missä

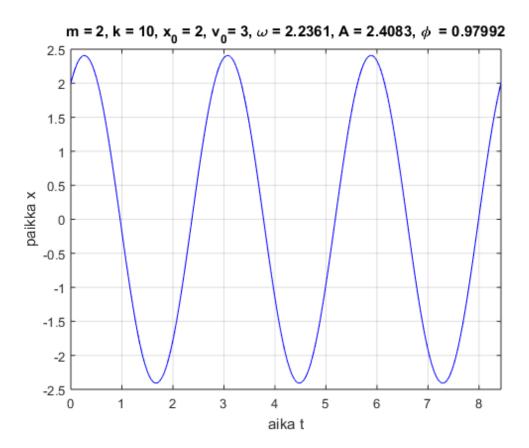
$$\omega = \sqrt{k/m}$$

$$A = \sqrt{x_0^2 + (v_0/\omega)^2}$$

$$\phi = \operatorname{atan2}(x_0, v_0/\omega).$$



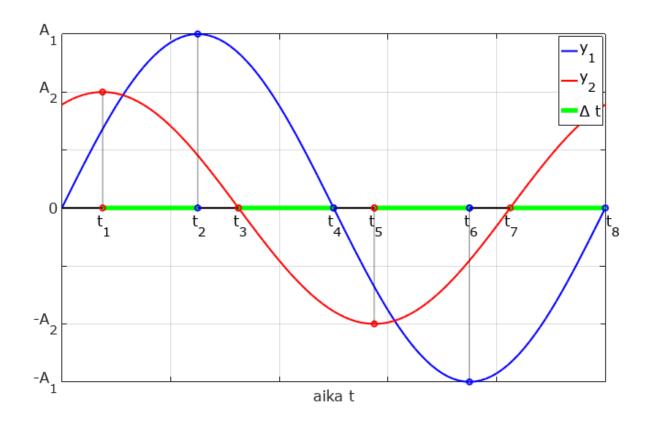


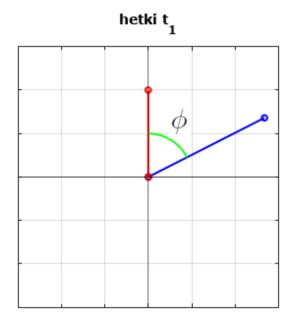


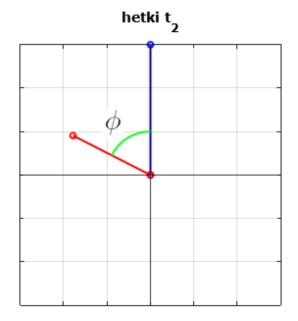
#### Samantaajuisten sinikäyrien

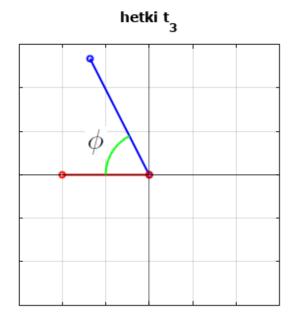
$$y_1 = A_1 \sin(\omega t)$$
 ja  $y_2 = A_2 \sin(\omega t + \phi)$ 

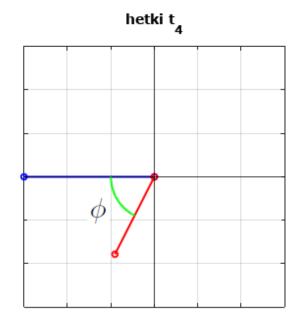
vaihe-ero  $\phi = \omega \cdot \Delta t$ , missä  $\Delta t$  on sinikäyrien huippu- tai nollakohtien aika-ero.

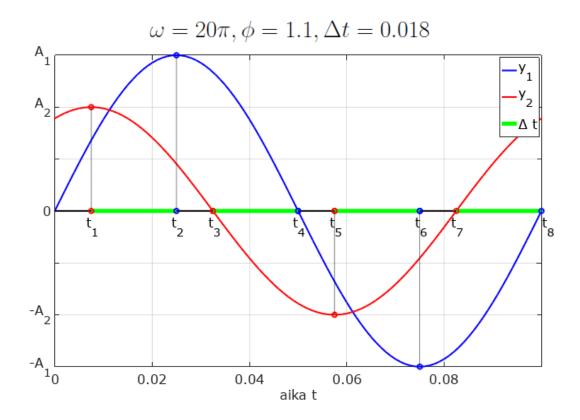


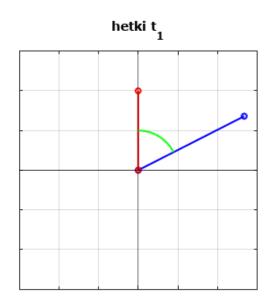


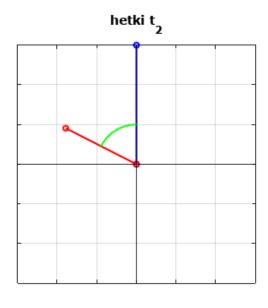


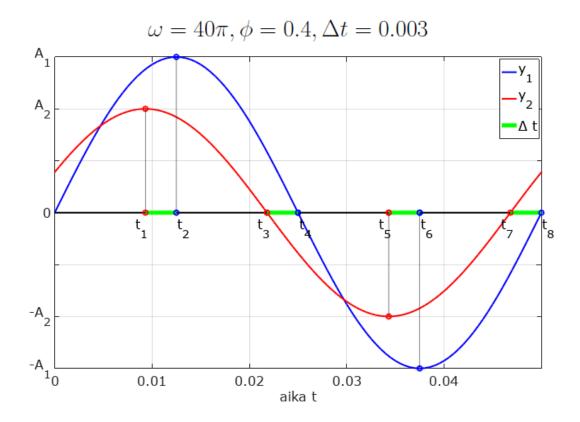


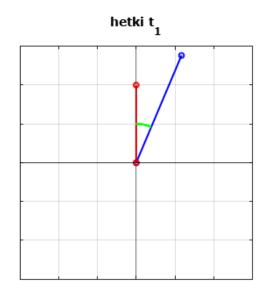


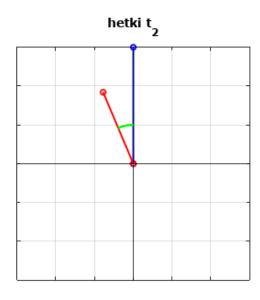












Samantaajuisten sinikäyrien summa on myös sinikäyrä, eli jos

$$y_1 = A_1 \sin(\omega t)$$
 ja  $y_2 = A_2 \sin(\omega t + \phi)$ , niin

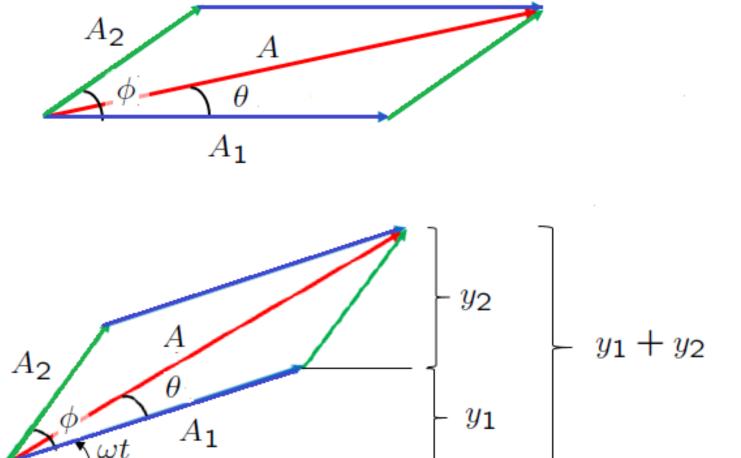
$$y_1 + y_2 = A\sin(\omega t + \theta)$$

missä amplitudi

$$A = \sqrt{(A_1 + A_2 \cos(\phi))^2 + (A_2 \sin(\phi))^2}$$

ja vaihekulma

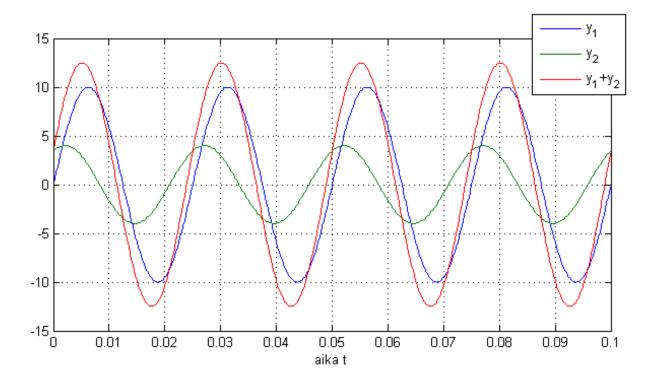
$$\theta = \operatorname{atan2}(A_2 \sin(\phi), A_1 + A_2 \cos(\phi))$$

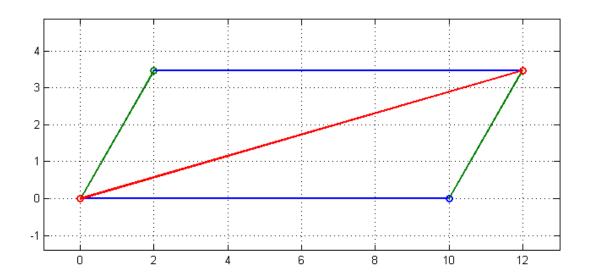


 $\langle \omega t \rangle$ 

 $y_1 = 10\sin(\omega t), \ y_2 = 4\sin(\omega t + \pi/3)$ 

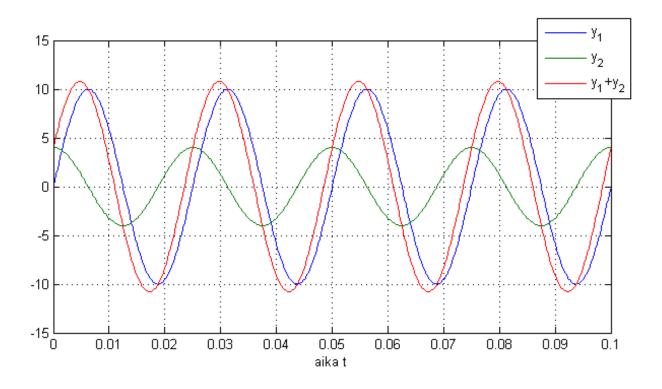
$$y_1 + y_2 = 12.5\sin(\omega t + 0.28)$$

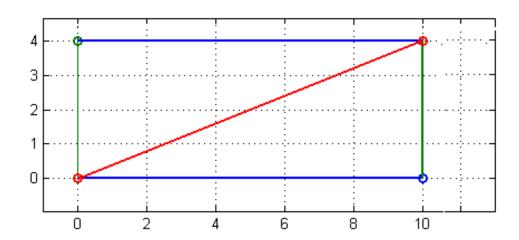




 $y_1 = 10\sin(\omega t), \ y_2 = 4\sin(\omega t + \pi/2)$ 

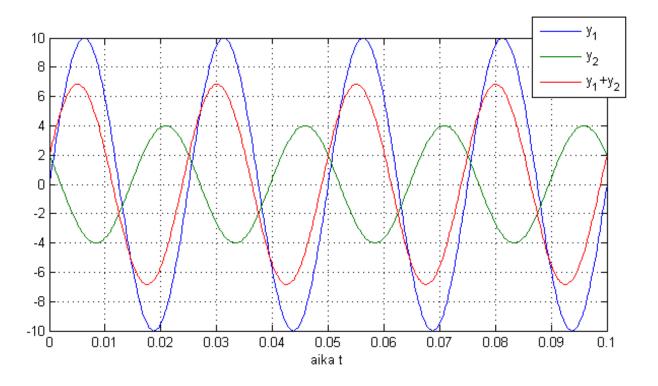
 $y_1 + y_2 = 10.8\sin(\omega t + 0.38)$ 

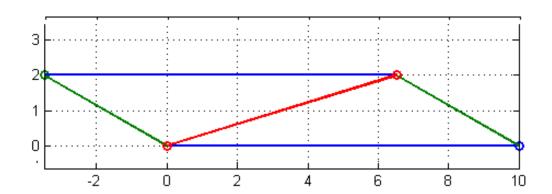




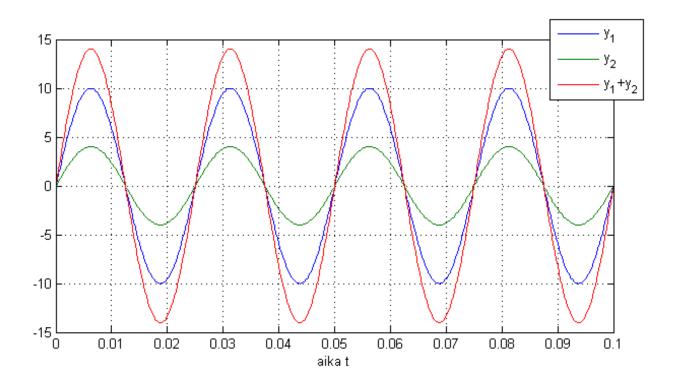
 $10\sin(\omega t) + 4\sin(\omega t + 5\pi/6)$ 

 $=6.8\sin(\omega t+0.30)$ 

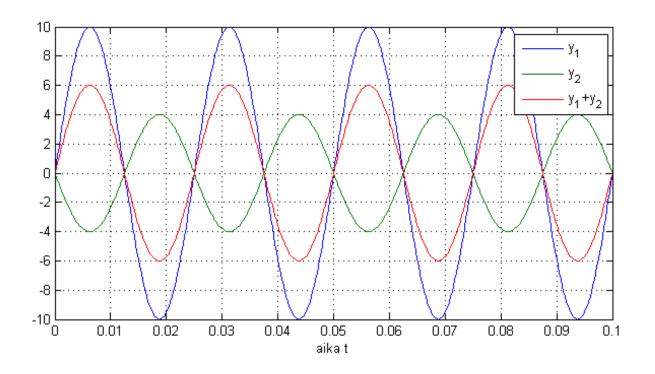




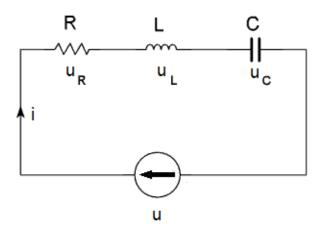
### $10\sin(\omega t) + 4\sin(\omega t) = 14\sin(\omega t)$



## $10\sin(\omega t) + 4\sin(\omega t + \pi) = 6\sin(\omega t)$



#### RLC-piiri:



jos virta  $i = I \sin(\omega t)$ , niin jännitteet

$$u_R = RI \sin(\omega t)$$

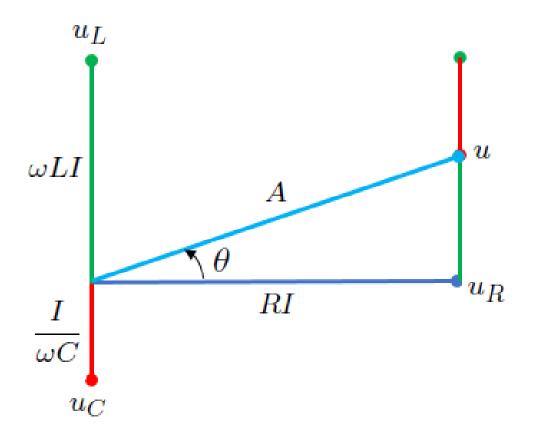
$$u_L = \omega L I \sin(\omega t + \pi/2)$$

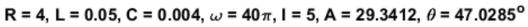
$$u_C = \frac{I}{\omega C} \sin(\omega t - \pi/2)$$

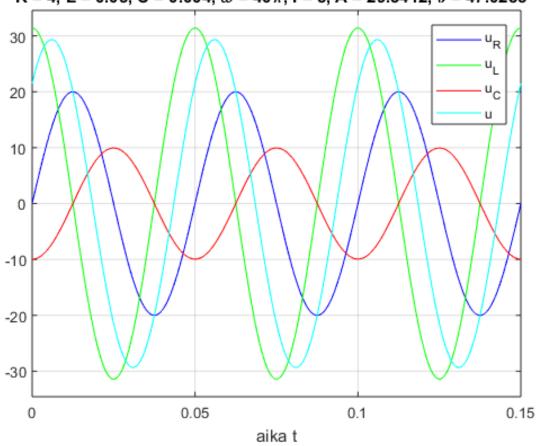
$$u = u_R + u_L + u_C = A\sin(\omega t + \theta)$$

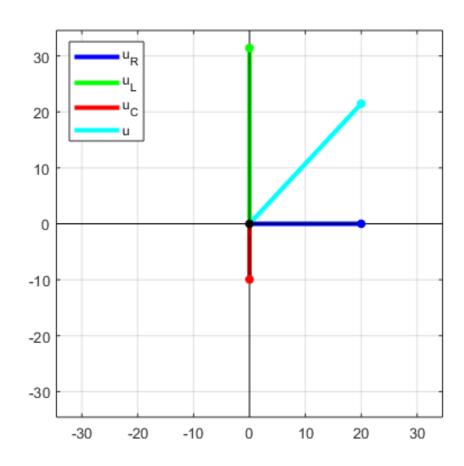
$$A = \sqrt{(RI)^2 + \left(\omega LI - \frac{I}{\omega C}\right)^2} = \sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2} I$$

$$\theta = \operatorname{atan2}\left(\omega LI - \frac{I}{\omega C}, RI\right) = \operatorname{atan2}\left(\omega L - \frac{1}{\omega C}, R\right)$$









R = 4, L = 0.005, C = 0.001,  $\omega$  = 100 $\pi$ , I = 5, A = 21.5636,  $\theta$  = -21.9532°

