## Time Serjes: Theory and Methods

Reter J. Brockwell & Richard A. Davis

April 23, 2020

## Contents

1	Stationary Time Series	3
	1.1 Stochastic Processes	3

## 1 Stationary Time Series

## 1.1 Stochastic Processes

**Definition 1.1.** A **stochastic process** is a family of random variables  $\{X_t, t \in T\}$  defined on a probability space  $(\Omega, \mathcal{F}, P)$ 

A probability space or a probability triple  $(\Omega, \mathcal{F}, P)$  consists of three elements

- 1. The sample space  $\Omega$  an arbitrary non-empty set
- 2. The  $\sigma$ -algebra  $\mathcal{F} \in 2^{\Omega}$  called events, s.t.
  - $\mathcal{F}$  contains the sample space:  $\Omega \in \mathcal{F}$
  - ullet  $\mathcal F$  is closed under complements
  - $\bullet$   $\mathcal{F}$  is closed under countable unions
- 3. The probability measure  $P: \mathcal{F} \to [0,1]$  a function on  $\mathcal{F}$  s.t.
  - P is countably additive: if  $\{A_i\}_{i=1}^{\infty} \subseteq \mathcal{F}$  is a countable collection of pairwise disjoint sets, then  $P(\bigcup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} P(A_i)$
  - the measure of entire sample space is equal to one

A **random variable** is a measurable function  $X:\Omega\to E$  from a set of possible outcomes  $\Omega$  to a measurable space E. The probability that X takes on a value in a measurable set  $S\subseteq E$  is written as

$$P(X \in S) = P(\omega \in \Omega \mid X(\omega) \in S)$$

*Remark.* In time series analysis, the index set T is a set of time points, very often  $\{0, \pm 1, \pm 2, \dots\}, \{1, 2, 3, \dots\}, [0, \infty)$  or  $(-\infty, \infty)$ 

**Definition 1.2** (Realizations of a Stochastic Process). The functions  $\{X(\omega), \omega \in \Omega\}$  on T are known as the **realizations** or **sample-paths** of the process  $\{X_t, t \in T\}$ 

**Example 1.1** (Sinusoid with Random Phase and Amplitude). Let A and  $\Theta$  be independent random variable with  $A \geq 0$  and  $\Theta$  distributed uniformly on  $[0,2\pi)$ . A stochastic process  $\{X(t),t\in\mathbb{R}\}$  can then be defined in terms of A and  $\Theta$  for any given  $\nu\geq 0$  and r>0 by

$$X_t = r^{-1}A\cos(\nu t + \Theta)$$

or more explicitly

$$X_t(\omega) = r^{-1}A(\omega)\cos(\nu t + \Theta(\omega))$$