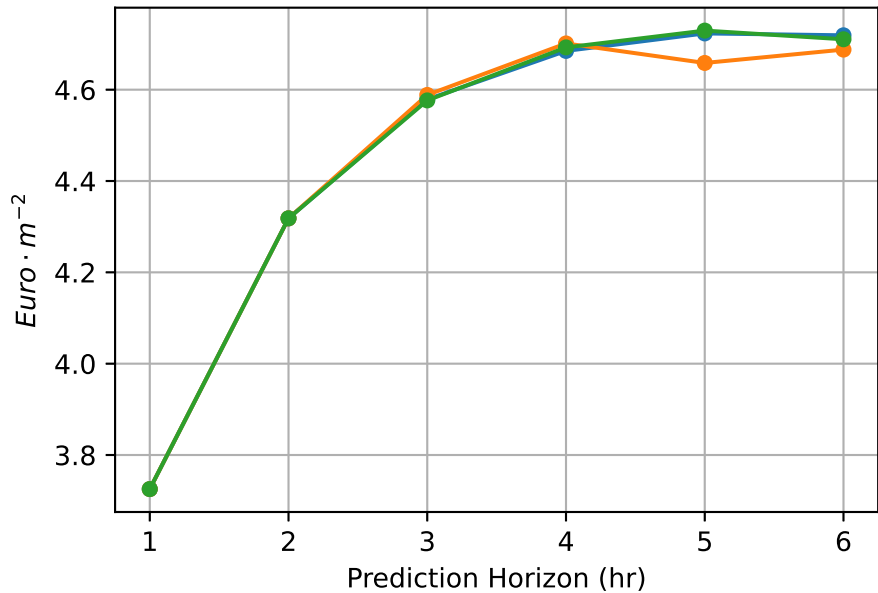
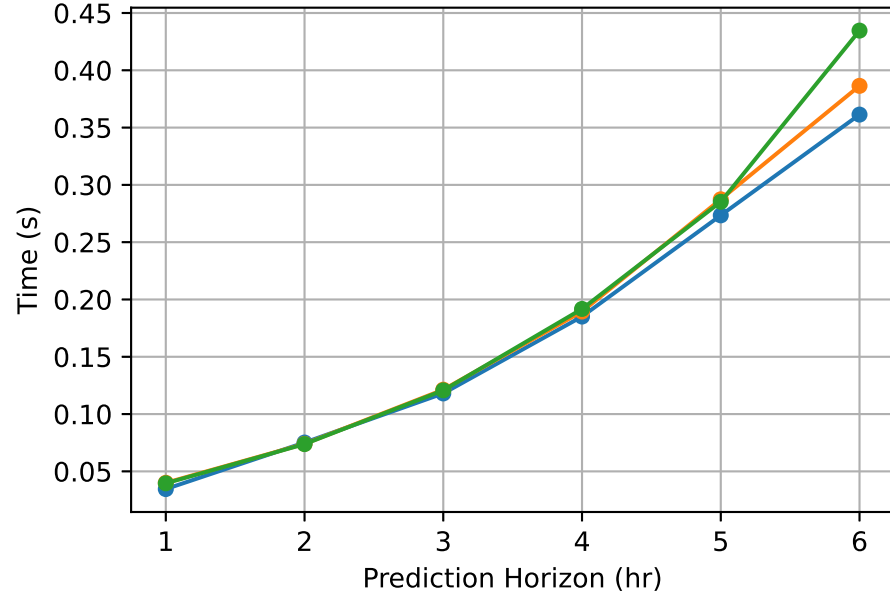


Final Cumulative Reward



Computational Time of Control Input



—●— Nominal MPC —●— MPC with $(\tilde{x}_{k|k}, \tilde{u}_{k|k})$ —●— MPC with $(\hat{x}_{k|k}, \hat{u}_{k|k})$