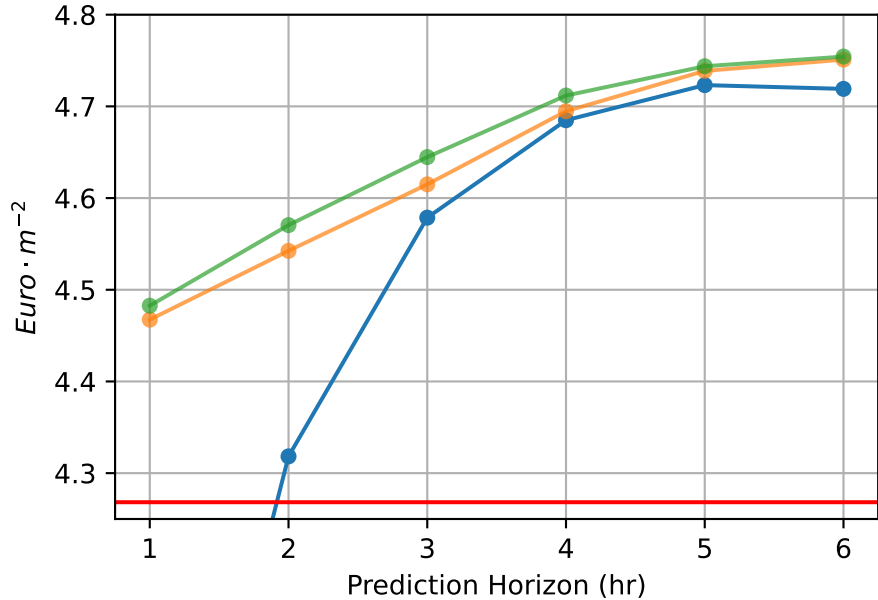
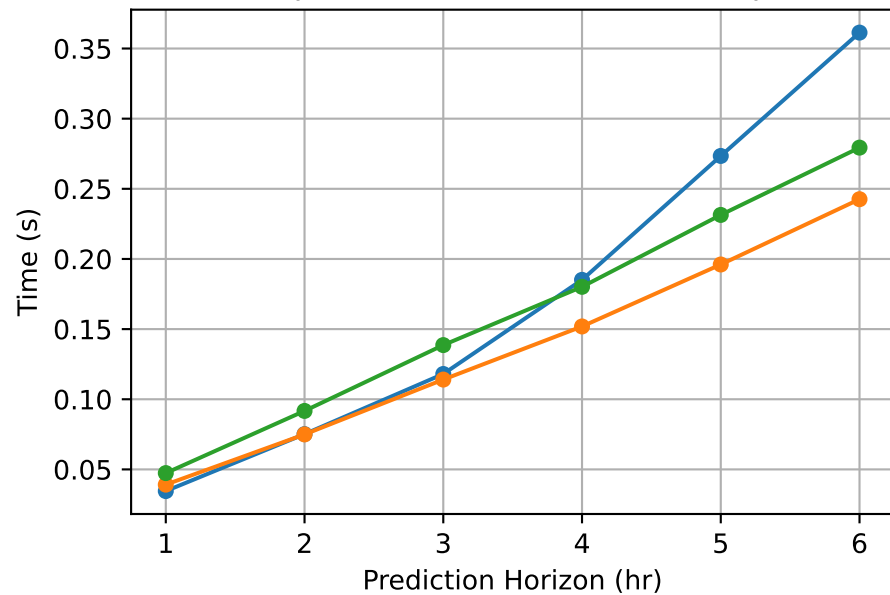


Final Cumulative Reward



Computational Time of Control Input



—●— Nominal MPC      —●— RL-MPC with only terminal region constraint      —●— RL-MPC with terminal region constraint and cost function