

# Rapport du Comité de Suivi Individuel

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- **Affiliation**

School : École Centrale de Nantes (ECN)

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Team : H2I (Hydrodynamique, Interfaces et Interactions)

- **Date of admission**

01/01/2018 (1 year 10 months)

- **Financement**

CIFRE contract from Bureau Veritas (BV) and ECN

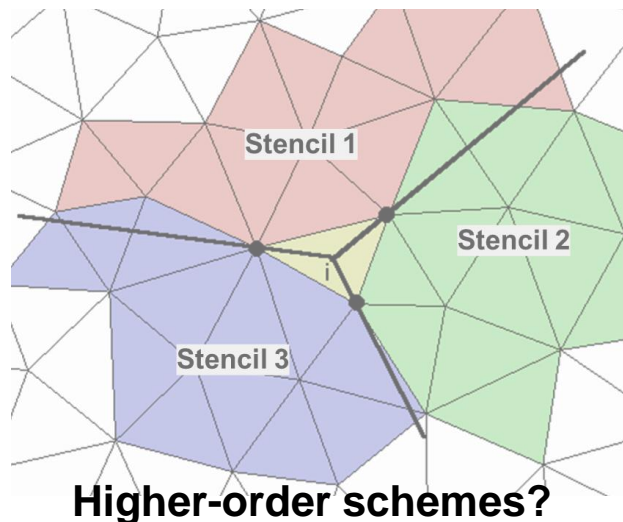
- **Encadrants de thèse**

David Le Touzé (Directeur)

Benjamin Bouscasse (Co-encadrant)

**Numerical improvement and validation** of a naval hydrodynamics CFD solver in view of performing **fast and accurate** simulation of complex **ship-wave interaction**.

## Numerical Improvement



## Efficiency



$$\text{Efficiency} = \frac{\text{Accuracy}}{\text{Computational cost}}$$

## Naval applications

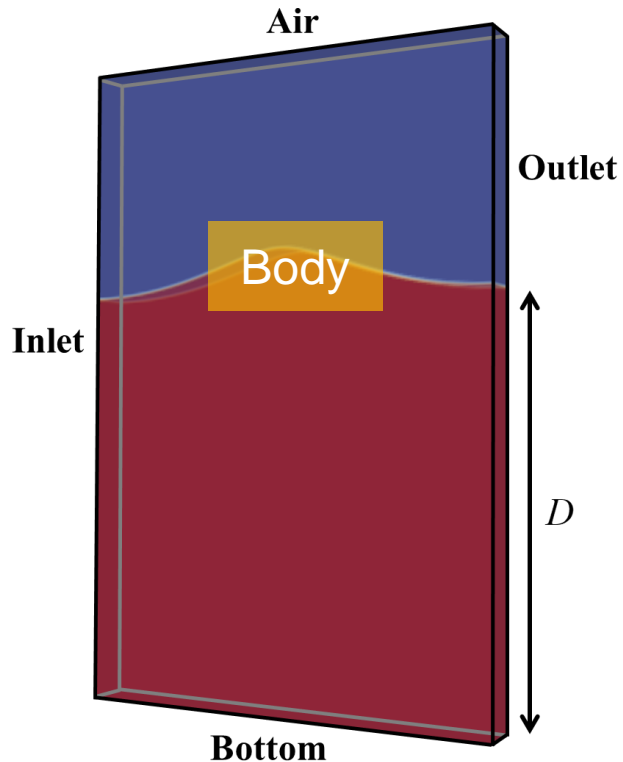


# What makes the problem complicated?

## Two-phase incompressible viscous (Newtonian) flow solver.

There are many important issues.

The most critical issue is interface (discontinuity).



Governing equations

$$\frac{\partial \alpha}{\partial t} + \nabla \cdot (\mathbf{u} \alpha) + \nabla \cdot (\mathbf{u}_r \alpha (1 - \alpha)) = 0$$

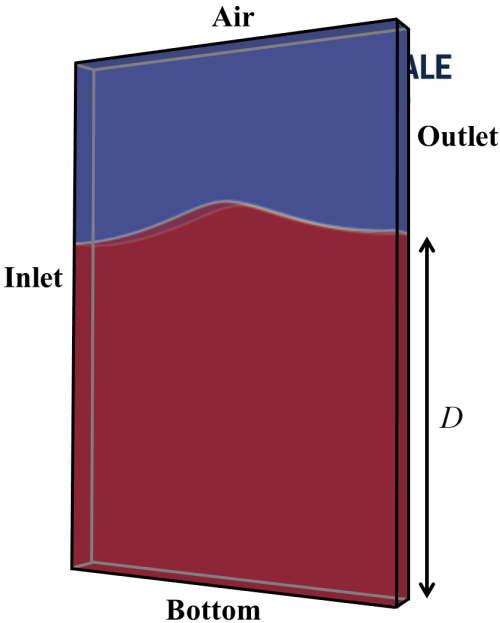
$$\frac{\partial (\rho \mathbf{u})}{\partial t} + \nabla \cdot (\rho \mathbf{u} \mathbf{u}) - \nabla \cdot (\mu (\nabla \mathbf{u})) - \nabla \mathbf{u} \cdot \nabla \mu = \nabla p_d - (\mathbf{g} \cdot \mathbf{x}) \nabla \rho$$

*VOF, density, mass flux, dynamic pressure, viscosity*

# Preliminary study: Interface treatment

## The interface treatment schemes

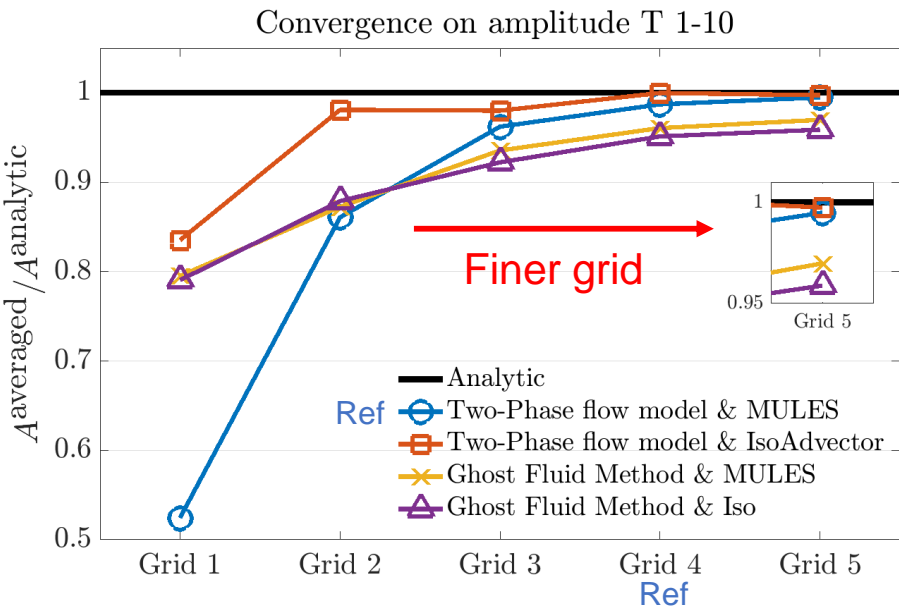
- Interface capturing scheme: How to define(**capture**) the free surface.
- Interface advection scheme: How to **move** interface in time.
- Interface boundary condition: How to define the **physical properties** at the interface.



### Periodic wave propagation test

The interface capturing scheme is VOF.

Interface boundary conditions	Interface advection
Averaged <b>T</b> wo- <b>P</b> hase <b>M</b> odel	Compressive VOF+ <b>MULES</b>
Averaged <b>T</b> wo- <b>P</b> hase <b>M</b> odel	<b>Iso</b> Advectord
GFM ( <b>G</b> host <b>F</b> luid <b>M</b> ethod)	Compressive VOF+ <b>MULES</b>
GFM ( <b>G</b> host <b>F</b> luid <b>M</b> ethod)	<b>Iso</b> Advectord



# Preliminary study: Waves

## Wave generation and absorption.

$$\chi = (1 - w)\chi + w\chi^{Target}$$

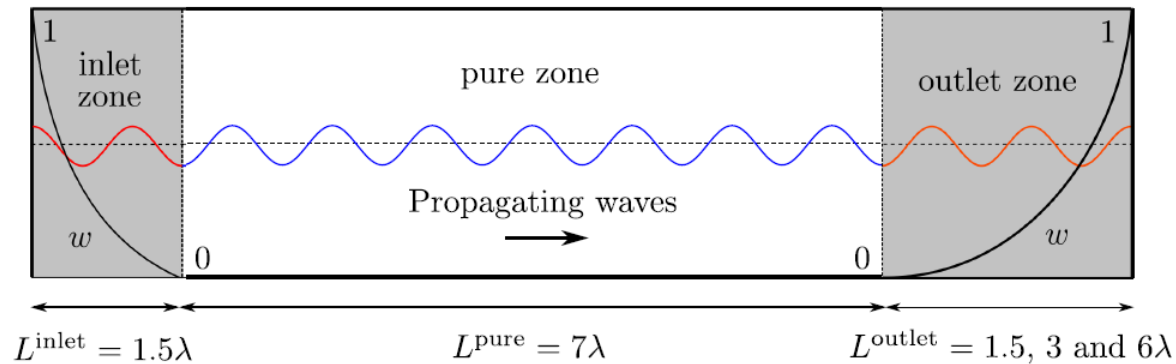


Figure 1.1. Schematic view of the NWT for a parametric study on the relaxation schemes.

Explicit Relaxation method is used to generate wave.

Various outlet conditions are studied

Increased viscosity & artificial damping source

$$\frac{\partial(\rho \mathbf{u})}{\partial t} + \nabla \cdot (\rho \mathbf{u} \mathbf{u}) - \nabla \cdot ((\mu + \mu_{add})(\nabla \mathbf{u})) - \nabla \mathbf{u} \cdot \nabla \mu = \nabla p_d - (\mathbf{g} \cdot \mathbf{x}) \nabla \rho + \mathbf{S}$$

$$\mathbf{S} = (0, 0, \rho(C_1 + C_2 u_z) w u_z)$$

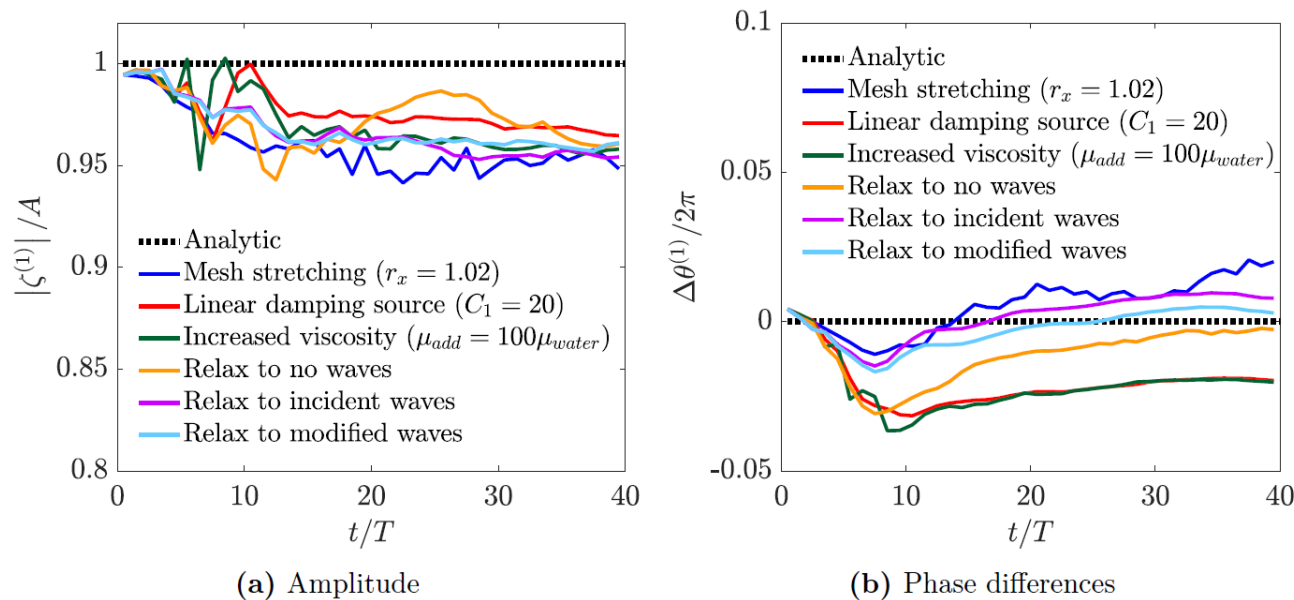
Relaxation to incident wave & no wave (calm water).

Mesh stretched outlet

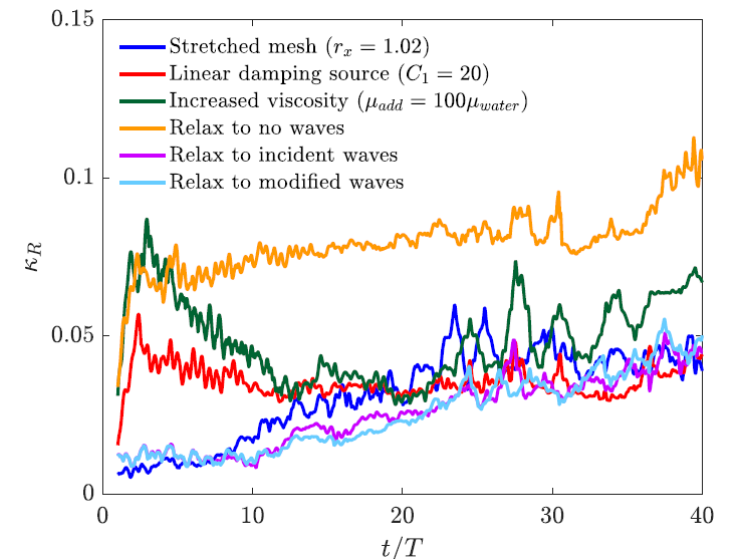
## Wave generation and absorption.

If the condition of outlet is different to the incoming wave, it makes wave reflection and phase shift.

**Indicent wave outlet condition** gives most stable and precise wave propagation.



**Figure 2.1.** The first-order harmonic amplitudes and phase differences with respect to different outlet.

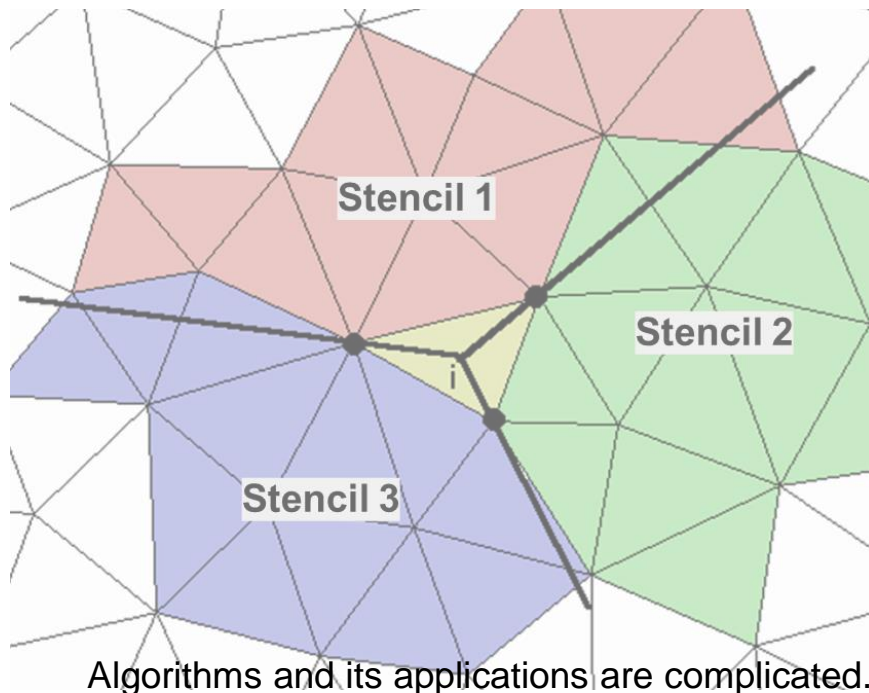


**Figure 2.2.** Evolution of reflection coefficients for different outlets.

## Higher-order scheme.

The higher-order schemes are believed to have the advantage on high-order accuracy

### Spatial scheme



### Temporal scheme

$$\frac{dy}{dt} = f(t, y)$$

$$y^{n+1} = y^n + hf(t^{n+1}, y^{n+1})$$

$$y^{n+1} = y^n + C_{CN} hf(t^{n+1}, y^{n+1}) + (1 - C_{CN}) hf(t^n, y^n)$$

$$C \frac{V}{h} \alpha^{t+h} + F(\phi, \alpha)^{t+h} = C_o \frac{V_o}{h} \alpha^t - C_{oo} \frac{V_{oo}}{h} \alpha^{t-h}$$

$$C = 1 + \frac{h}{h+h_o} \quad C_o = C + C_{oo} \quad C_o = \frac{h^2}{h_o(h+h_o)}$$

Consider an ODE

Implicit Euler

Crank Nicolson

Second order Backward difference  
(Second order Backward differentiation formula (BDF2))

Other ODE Solvers:  
Runge Kutta, El...

The temporal schemes are studied first, because it is more simple.



# Higher-order temporal schemes

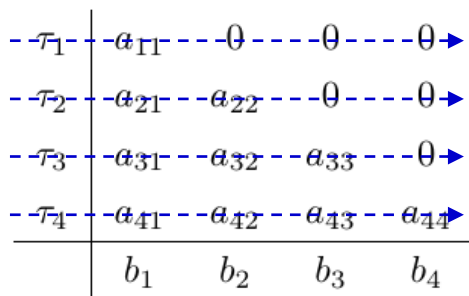
## Diagonally Implicit Runge-Kutta (DIRK) method

$$\dot{y} = f(t, y(t)) \quad (1)$$

$$y(t^{(n,i)}) = y^{(i)} = y^{(n)} + \underbrace{h a_{ii} f(t^{(n,i)}, y(t^{(n,i)}))}_{\text{Diagonally implicit}} + h \sum_{j=1}^{i-1} \underbrace{a_{ij} f(t^{(n,j)}, y(t^{(n,j)}))}_{\text{Explicit}} \quad (2)$$

$$t^{(n,i)} = t^{(n)} + h \tau_i$$

$$y^{(n+1)} = y^{(n)} + h \sum_{j=1}^s \underbrace{b_j}_{\text{Diagonally implicit}} f(t^{(n,j)}, y(t^{(n,j)})) \quad (3)$$



$-\tau_1$	$a_{11}$	$0$	$0$	$0$
$-\tau_2$	$a_{21}$	$a_{22}$	$0$	$0$
$-\tau_3$	$a_{31}$	$a_{32}$	$a_{33}$	$0$
$-\tau_4$	$a_{41}$	$a_{42}$	$a_{43}$	$a_{44}$
	$b_1$	$b_2$	$b_3$	$b_4$

Butcher matrix

Singly Diagonally IRK

$\tau_1$	$\gamma$	$0$	$0$	$0$
$\tau_2$	$a_{21}$	$\gamma$	$0$	$0$
$\tau_3$	$a_{31}$	$a_{32}$	$\gamma$	$0$
$\tau_4$	$a_{41}$	$a_{42}$	$a_{43}$	$\gamma$
	$b_1$	$b_2$	$b_3$	$b_4$

$0$	$0$	$0$	$0$	$0$
$\tau_2$	$a_{21}$	$\gamma$	$0$	$0$
$\tau_3$	$a_{31}$	$a_{32}$	$\gamma$	$0$
$\tau_4$	$a_{41}$	$a_{42}$	$a_{43}$	$\gamma$
	$b_1$	$b_2$	$b_3$	$b_4$

Explicit first SDIRK

Only SA DIRKs are used.

SDIRK Stiffly accurate

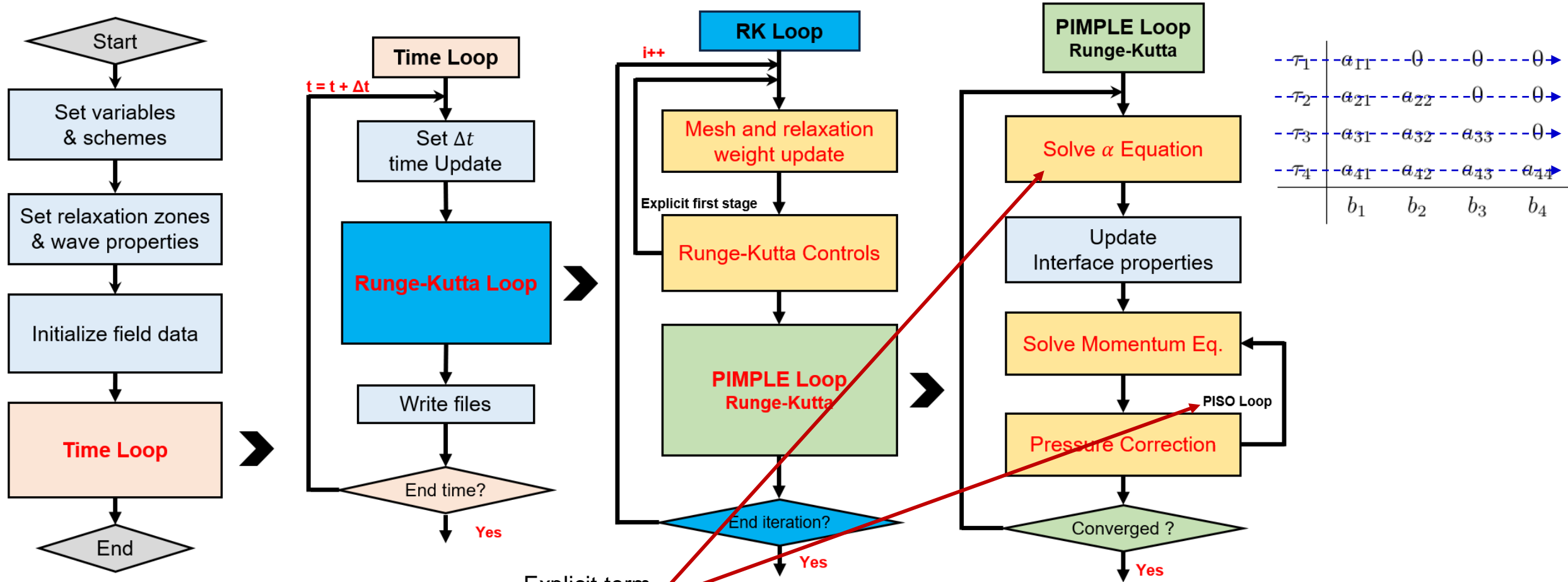
$\tau_1$	$\gamma$	$0$	$0$	$0$
$\tau_2$	$a_{21}$	$\gamma$	$0$	$0$
$\tau_3$	$a_{31}$	$a_{32}$	$\gamma$	$0$
$1$	$a_{41}$	$a_{42}$	$a_{43}$	$\gamma$
	$a_{41}$	$a_{42}$	$a_{43}$	$\gamma$

$0$	$0$	$0$	$0$	$0$
$\tau_2$	$a_{21}$	$\gamma$	$0$	$0$
$\tau_3$	$a_{31}$	$a_{32}$	$\gamma$	$0$
$1$	$a_{41}$	$a_{42}$	$a_{43}$	$\gamma$
	$a_{41}$	$a_{42}$	$a_{43}$	$\gamma$

ESDIRK SA

Fig. 1. Four-stage SDIRK, SDIRK\_SA, ESDIRK and ESDIRK\_SA [\[14\]](#)

# Higher-order temporal schemes



$-\tau_1$	$-a_{11}$	$-\theta$	$-\theta$	$-\theta$
$-\tau_2$	$-a_{21}$	$-a_{22}$	$-\theta$	$-\theta$
$-\tau_3$	$-a_{31}$	$-a_{32}$	$-a_{33}$	$-\theta$
$-\tau_4$	$-a_{41}$	$-a_{42}$	$-a_{43}$	$-a_{44}$
	$b_1$	$b_2$	$b_3$	$b_4$

Explicit term

$$y(t^{(n,i)}) = y^{(i)} = y^{(n)} + h a_{ii} f(t^{(n,i)}, y(t^{(n,i)})) + h \sum_{j=1}^{i-1} a_{ij} f(t^{(n,j)}, y(t^{(n,j)}))$$

$$t^{(n,i)} = t^{(n)} + h \tau_i$$

(2) Previous RK iteration data must be used.  
Thus, each governing equations must change.

# Higher-order temporal schemes

**Table 2**  
Names and the properties of solvers

Code name	Identification name	Order	Implicit stage
Euler	Implicit Euler	1	1
OFCN	OpenFOAM CN	2	1
RKCN	ESDIRK[2](2)_SA	2	1
RK221	SDIRK[2](2)_S	2	2
RK331	SDIRK[3](3)_SA	3	3
RK334	ESDIRK[3](3)_SA	3	2
RK431	ESDIRK[3](4)_SA	3	3

RKCN			RK221		
0	0	0	$\gamma$	$\gamma$	0
1	0.5	0.5	1	$1 - \gamma$	$\gamma$
	0.5	0.5		$1 - \gamma$	$\gamma$

$$\gamma = (2 - \sqrt{2})/2$$

RK331				
$\gamma$	$\gamma$	0	0	
$\frac{(1+\gamma)}{2}$	$\frac{(1+\gamma)}{2} - \gamma$	$\gamma$	0	
1	$-\frac{(6\gamma^2 - 16\gamma + 1)}{4}$	$\frac{(6\gamma^2 - 20\gamma + 5)}{4}$	$\gamma$	
	$-\frac{(6\gamma^2 - 16\gamma + 1)}{4}$	$\frac{(6\gamma^2 - 20\gamma + 5)}{4}$	$\gamma$	

$$\gamma = 0.43586652150845899941601945.$$

RK431				
0	0	0	0	0
$2\gamma$	$\gamma$	$\gamma$	0	0
$c_3$	$(c_3 - a_{32} - \gamma)$	$a_{32}$	$\gamma$	0
1	$(1 - b_2 - b_3 - \gamma)$	$b_2$	$b_3$	$\gamma$
	$(1 - b_2 - b_3 - \gamma)$	$b_2$	$b_3$	$\gamma$

$$a_{32} = \frac{c_3(c_3 - 2\gamma)}{4\gamma} \quad b_2 = \frac{-2 + 3c_3 + 6\gamma(1 - c_3)}{12\gamma(c_3 - 2\gamma)} \quad b_3 = \frac{1 - 6\gamma + 6\gamma^2}{3c_3(c_3 - 2\gamma)} \quad c_3 = \frac{3 - 20\gamma + 24\gamma^2}{4 - 24\gamma + 24\gamma^2}$$

RK334			
0	0	0	0
$2\gamma$	$\gamma$	$\gamma$	0
1	$(1 - b_2 - \gamma)$	$b_2$	$\gamma$
	$(1 - b_2 - \gamma)$	$b_2$	$\gamma$

$$b_2 = (1 - 2\gamma)/(4\gamma) \text{ and } \gamma = (3 + \sqrt{3})/6.$$

## Taylor-Green vortex simulation

Analytic solution

$$-\pi \leq x, y \leq \pi$$

$$u = -\sin(x)\cos(y)e^{-2\nu t}$$

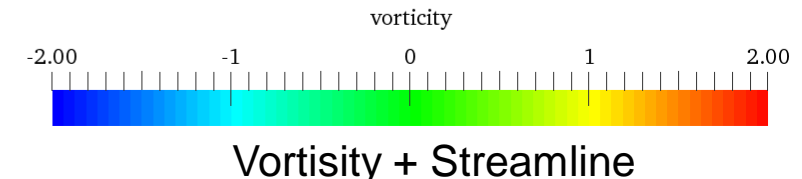
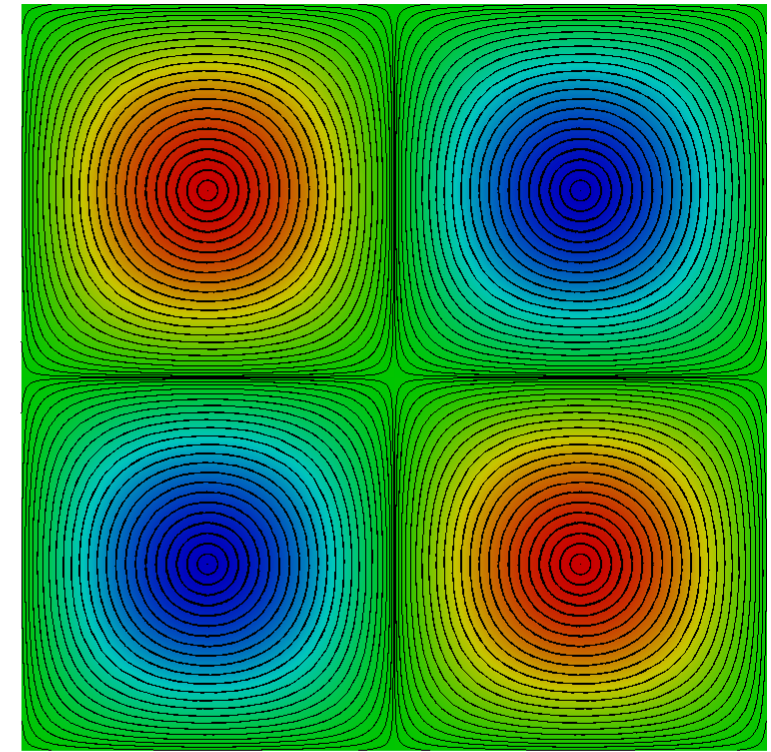
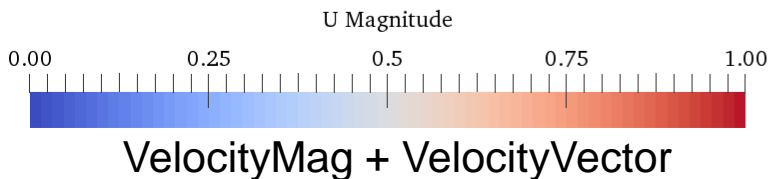
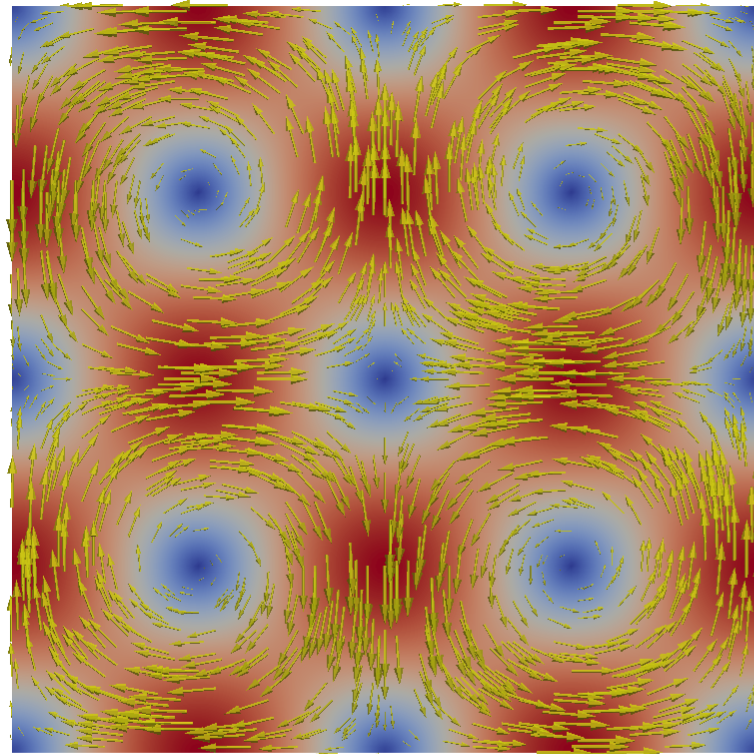
$$v = \cos(x)\sin(y)e^{-2\nu t}$$

$$p = \frac{\rho}{4} [\cos(2x) + \cos(2y)] e^{-4\nu t}$$

$$w = -2\sin(x)\sin(y)e^{-2\nu t} \quad \text{vorticity}$$

Computational conditions

$$\text{Re} = \frac{U_{\max} L}{\nu} = 10 \quad L = 2\pi \quad U_{\max} = 1$$



## Taylor-Green vortex simulation

$t_{end} = 2\text{sec}$

maximum error of velocity magintude

maximum error of pressure

### Spatial Convergence of velocity

All spatial schemes are **linear**

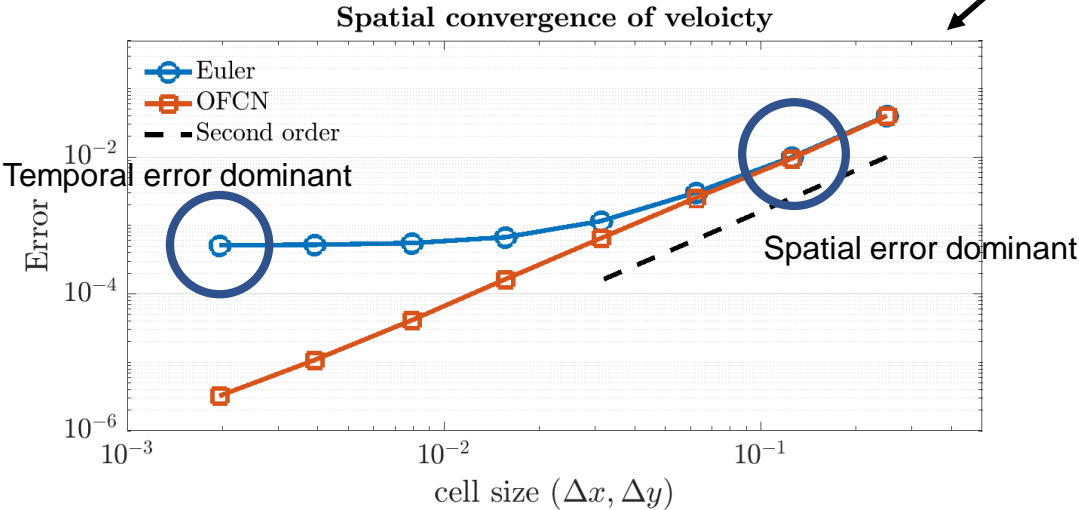


Table 3  
The computational conditions of Taylor-Green vortex benchmark,  $Re = 10$

Time-step	Number of cell per reference length $L$			
	Dx04 ~ Dx64	Dx128	Dx256	Dx512
0.004	---	---	---	---
0.01		O	O	
0.02		O	O	
0.04		O	O	
0.08		O	O	
0.1		O	O	
0.125		O	O	
0.2		O	O	
0.25		O	O	
0.4		O	O	

Temporal

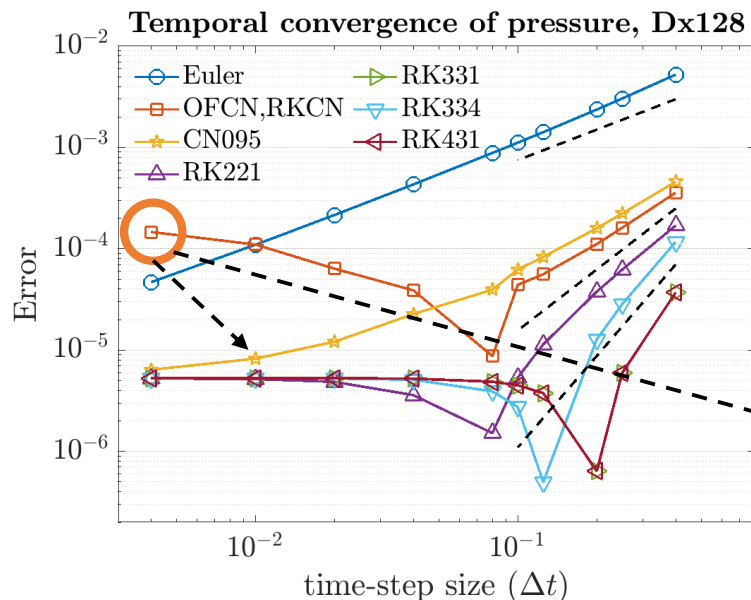
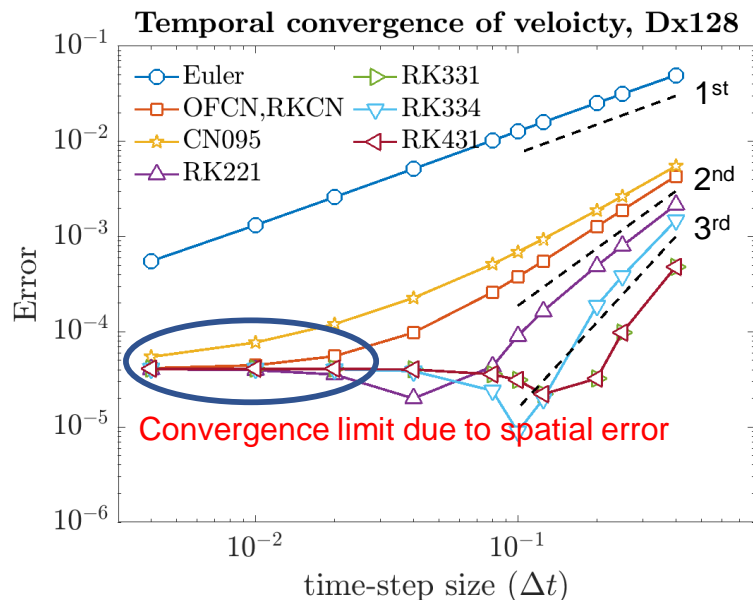
# Higher-order temporal schemes

Table 3

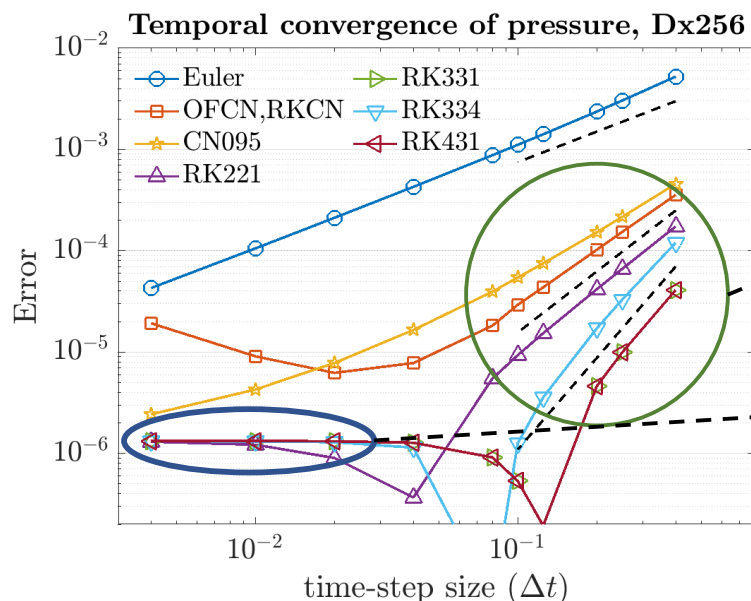
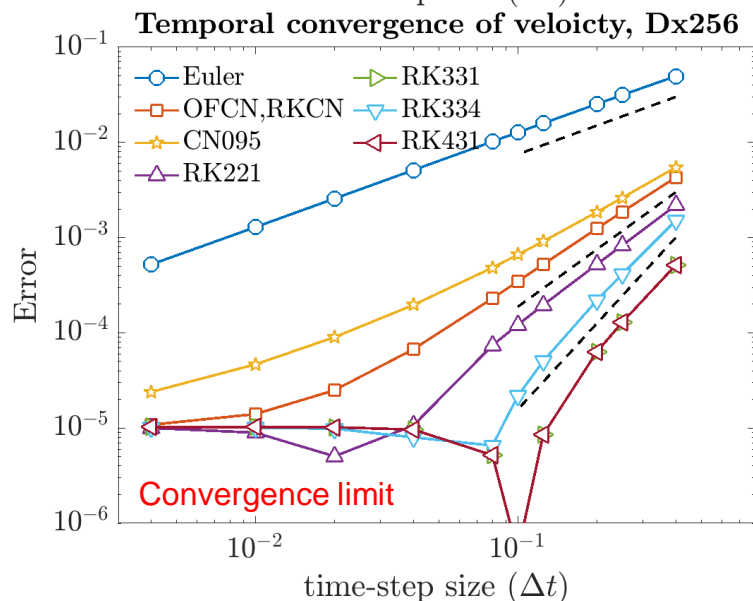
The computational conditions of Taylor-Green vortex benchmark,  $Re = 10$

Time-step	Number of cell per reference length $L$			
	Dx04 ~ Dx64	Dx128	Dx256	Dx512
0.004	—○—	—○—	—○—	—○— Spatial
0.01		○	○	
0.02		○	○	
0.04		○	○	
0.08		○	○	
0.1		○	○	
0.125		○	○	
0.2		○	○	
0.25		○	○	
0.4		○	○	

Temporal



This can be remedied using off-centering



$$\frac{y^{(n+1)} - y^{(n)}}{h} = C_{CN} f(t^{(n+1)}, y(t^{(n+1)})) + (1 - C_{CN}) f(t^{(n)}, y(t^{(n)})) \quad (37)$$

$$C_{CN} = 1/(1 + C_{oc})$$

Temporal error dominant condition  
The order of convergence is achieved.

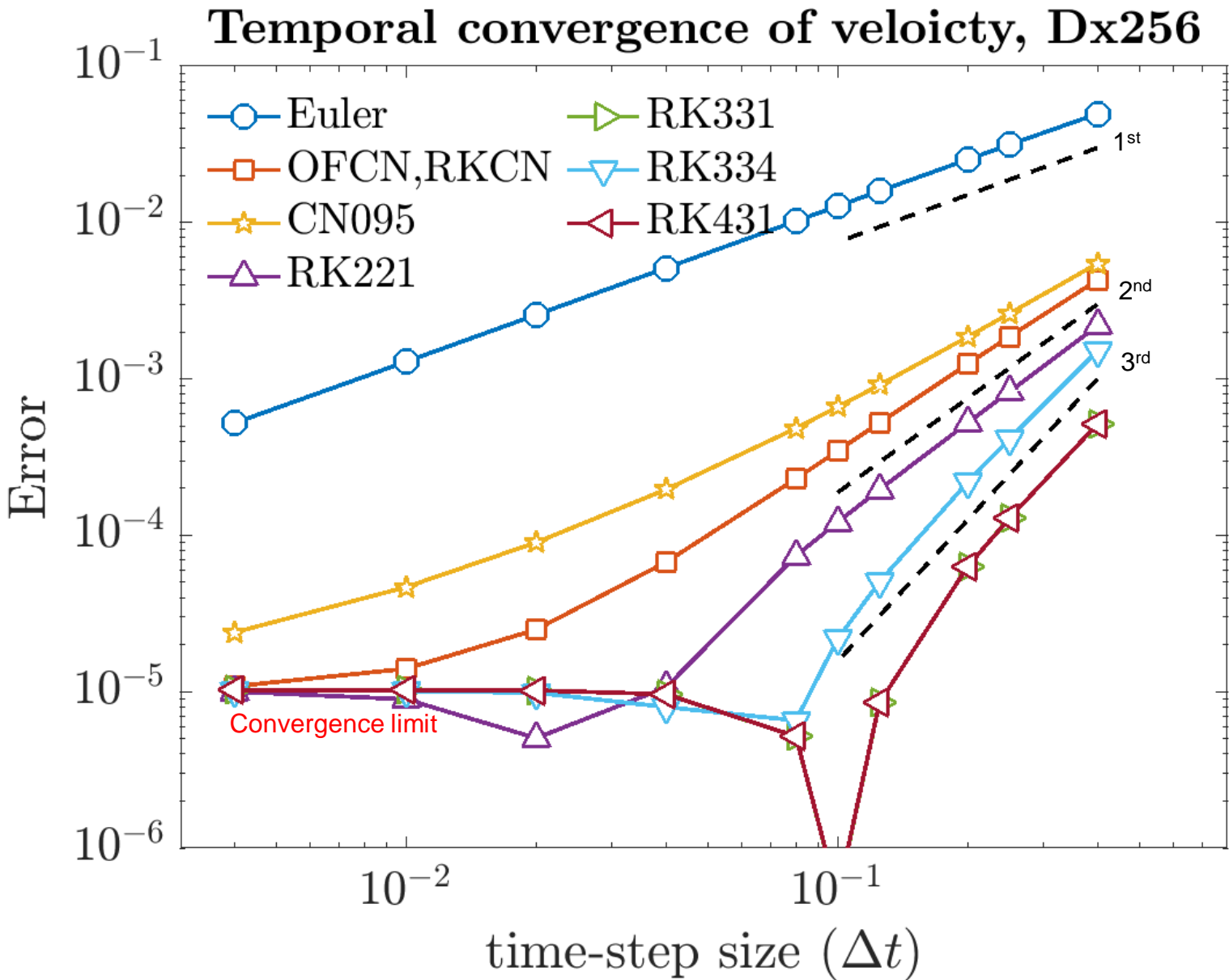
Spatial error dominant condition



# Higher-order temporal schemes

Table 3  
The computational conditions of Taylor-Green vortex benchmark,  $Re = 10$

Time-step	Number of cell per reference length $L$			
	Dx04 ~ Dx64	Dx128	Dx256	Dx512
0.004	—○—	—○—	—○—	—○—
0.01		○	○	
0.02		○	○	
0.04		○	○	
0.08		○	○	
0.1		○	○	
0.125		○	○	
0.2		○	○	
0.25		○	○	
0.4		○	○	



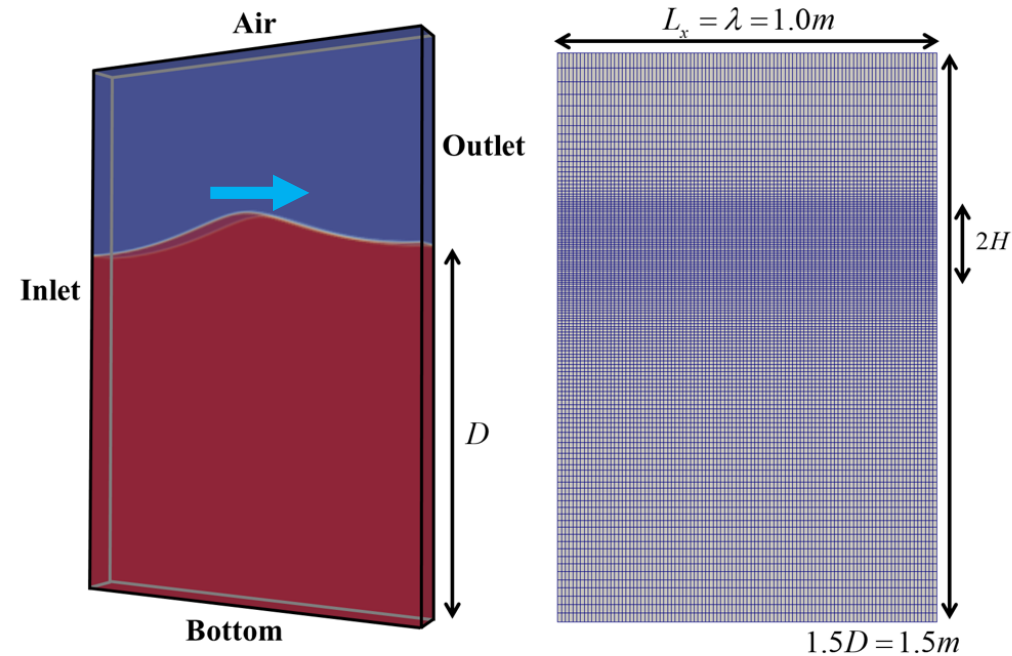
Temporal

# Higher-order temporal schemes

## Periodic wave propagation

Reference

Case	$\lambda/\Delta x$	$H/\Delta z$	$T/\Delta t$
Grid 1	25	5	100
Grid 2	50	10	200
Grid 3	100	20	400
Grid 4	200	40	800
Grid 3 dt100	100	20	100
Grid 3 dt200	100	20	200
Grid 3 dt400	100	20	400
Grid 3 dt800	100	20	800
Grid 3 dt1600	100	20	1600



$$\text{Efficiency} = \frac{\text{Accuracy}}{\text{Computational cost}}$$

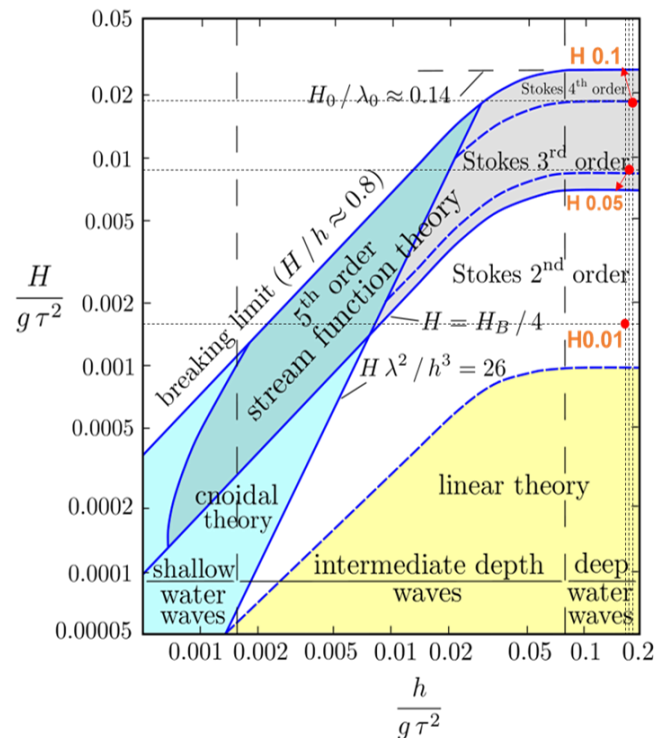


Averaged normalized wave amplitude from 1-10 periods  
(Computation time) x (nCore)



# Higher-order temporal schemes

## Periodic wave propagation



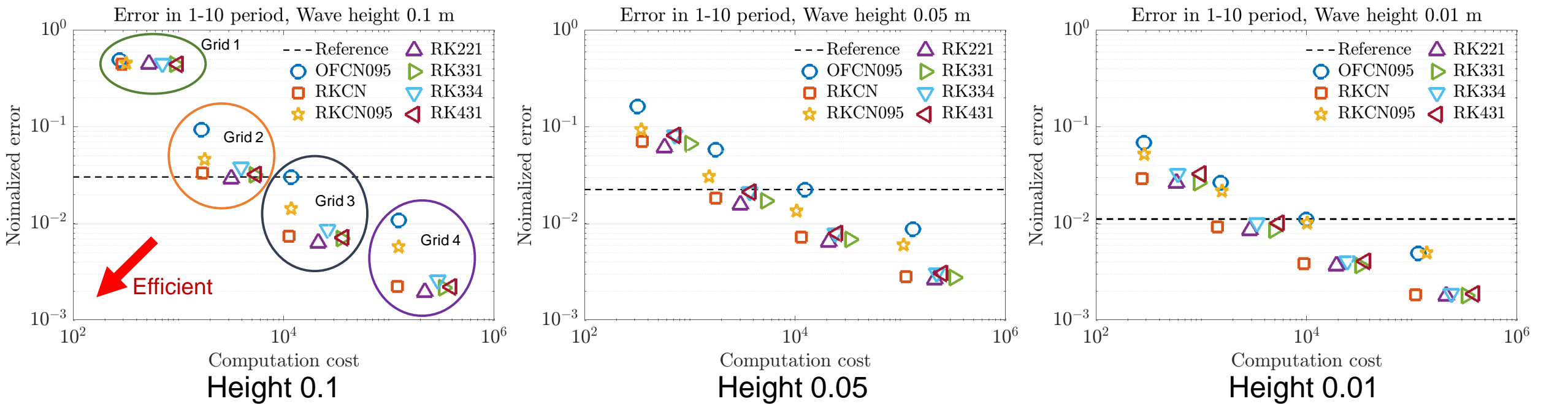
Item	Unit	H0.1	H0.05	H0.01
Depth (D)	[m]	1.0	1.0	1.0
Wave length	[m]	1.0	1.0	1.0
Wave period (T)	[sec]	0.76179	0.79049	0.79991
Wave height (H)	[m]	0.1	0.05	0.01
Wave steepness	H/L	10%	5%	1%
1 <sup>st</sup> order Amp	[m]	0.047413	0.024751	0.004998
2 <sup>nd</sup> order Amp	[m]	0.008294	0.001995	0.000079
3 <sup>rd</sup> order Amp	[m]	0.002263	0.000243	0.000002
4 <sup>th</sup> order Amp	[m]	0.000744	0.000035	-

$$\text{Efficiency} = \frac{\text{Accuracy}}{\text{Computational cost}} \rightarrow \frac{\text{Averaged normalized wave amplitude from 1-10 periods}}{(\text{Computation time}) \times (\text{nCore})}$$

# Higher-order temporal schemes

## Periodic wave propagation

Case	$\lambda/\Delta x$	$H/\Delta z$	$T/\Delta t$
Grid 1	25	5	100
Grid 2	50	10	200
Grid 3	100	20	400
Grid 4	200	40	800
Grid 3 dt100	100	20	100
Grid 3 dt200	100	20	200
Grid 3 dt400	100	20	400
Grid 3 dt800	100	20	800
Grid 3 dt1600	100	20	1600



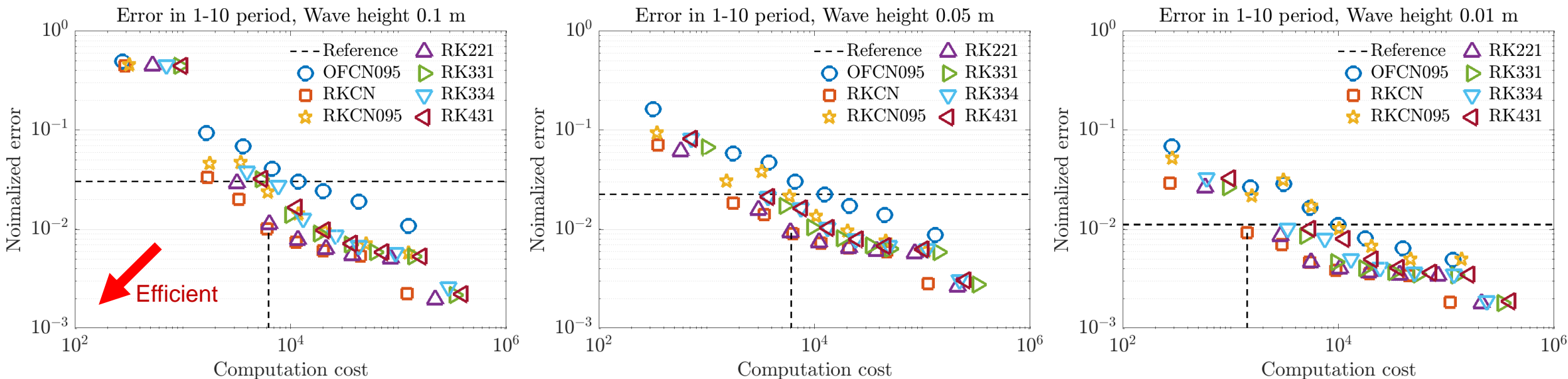
Black dotted line is reference OFCN095 case

Only spatial convergence cases are plotted here to estimate the spatial error.

# Higher-order temporal schemes

## Periodic wave propagation

Case	$\lambda/\Delta x$	$H/\Delta z$	$T/\Delta t$
Grid 1	25	5	100
Grid 2	50	10	200
Grid 3	100	20	400
Grid 4	200	40	800
Grid 3 dt100	100	20	100
Grid 3 dt200	100	20	200
Grid 3 dt400	100	20	400
Grid 3 dt800	100	20	800
Grid 3 dt1600	100	20	1600



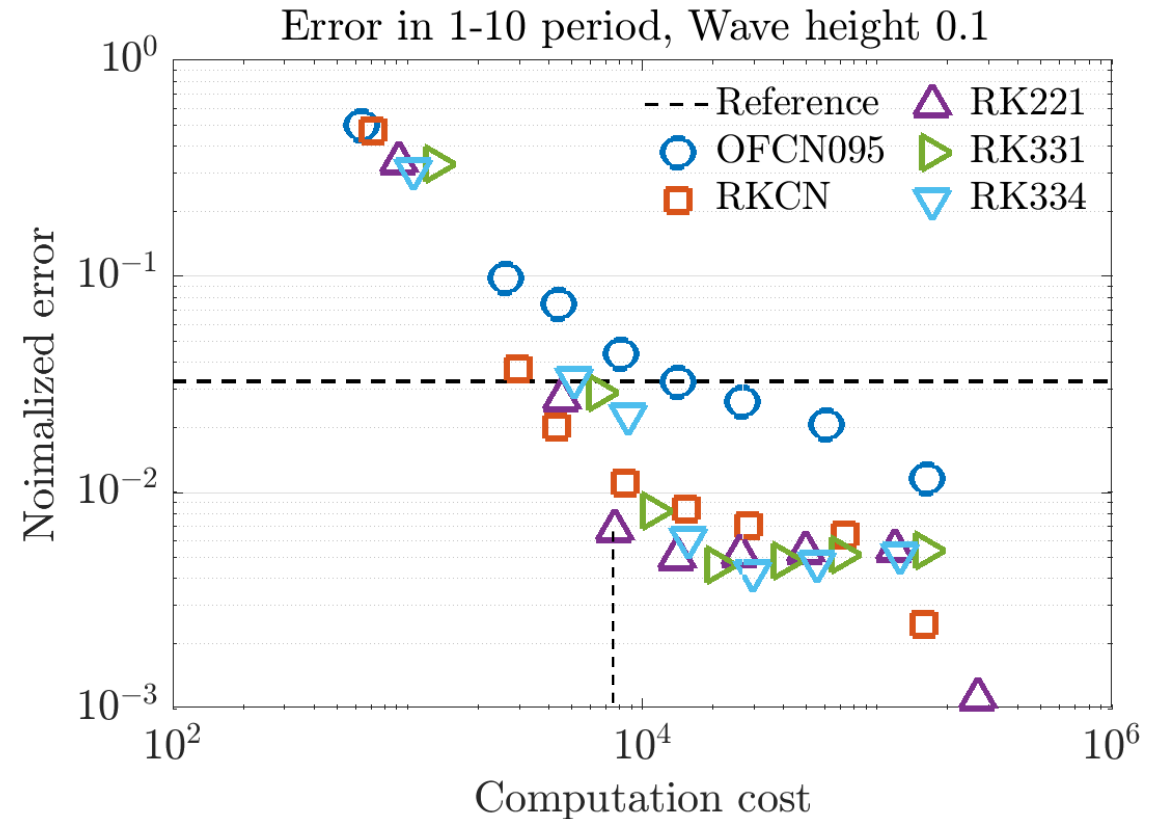
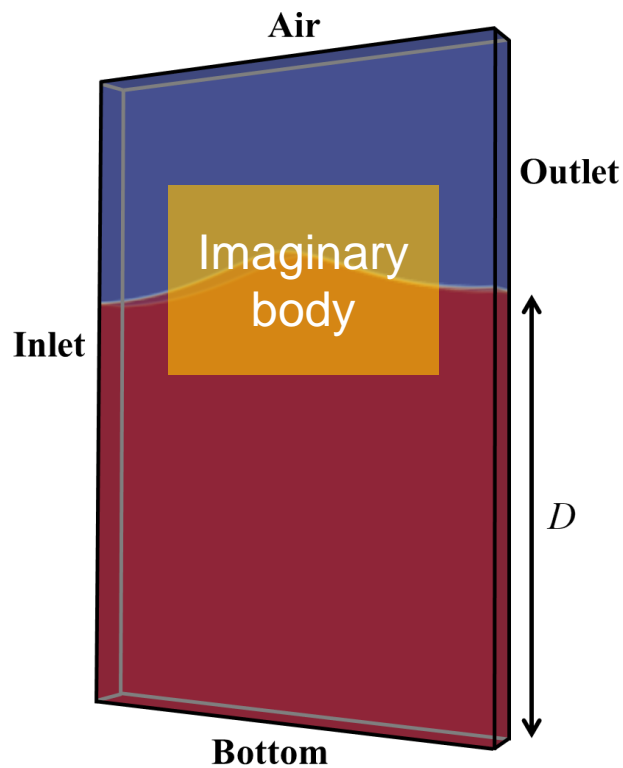
The efficient solvers are RKCEN and RK221  
Higher-order rate of convergences are not observed.  
Better stability is observed with SDIRK\_SA type methods  
If the wave amplitudes are small, we can use courser mesh

Code name	Identification name	Order	Implicit stage
Euler	Implicit Euler	1	1
OFCN	OpenFOAM CN	2	1
RKCEN	ESDIRK[2](2)_SA	2	1
RK221	SDIRK[2](2)_S	2	2
RK331	SDIRK[3](3)_SA	3	3
RK334	ESDIRK[3](3)_SA	3	2
RK431	ESDIRK[3](4)_SA	3	3

# Higher-order temporal schemes

## Periodic wave propagation with **moving mesh**

Case	$\lambda/\Delta x$	$H/\Delta z$	$T/\Delta t$
Grid 1	25	5	100
Grid 2	50	10	200
Grid 3	100	20	400
Grid 4	200	40	800
Grid 3 dt100	100	20	100
Grid 3 dt200	100	20	200
Grid 3 dt400	100	20	400
Grid 3 dt800	100	20	800
Grid 3 dt1600	100	20	1600



Error increased compare to the static mesh cases

DIRK type methods are more efficient then classical OFCN

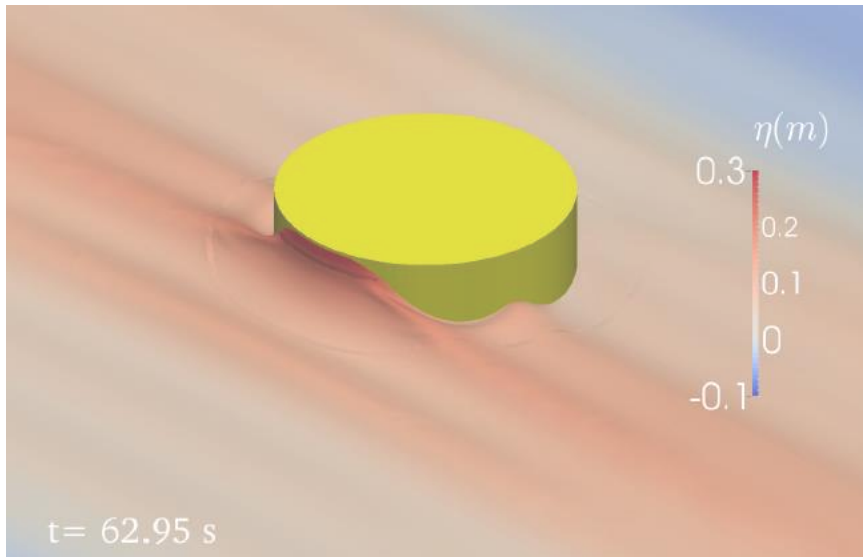
## Future works

To do a FSI simulation it is good to use **SWENSE** to control the number of cell.

$$\chi = \chi_I + \chi_C$$

= incident wave component + complimentary component

1. CALM buoy in regular / irregular wave



2. KCS with waves & with forward speed

### MOERI Container Ship (KCS)

[| Description](#) | [| Geometry and Conditions](#) | [| Test Program](#) | [| Links and References](#) |

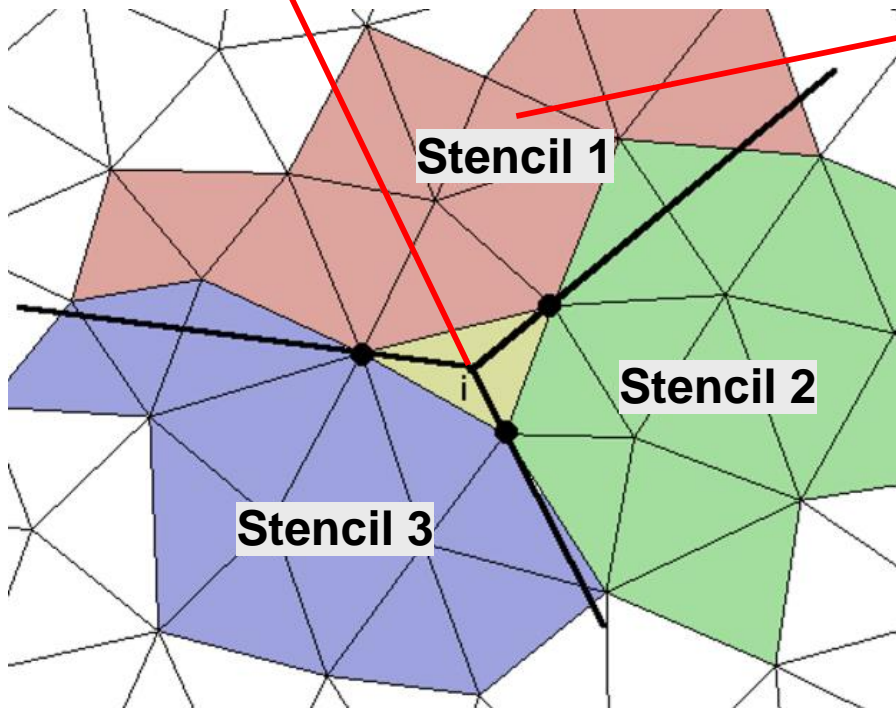


## Future works

**WENO** & WENO reconstruction method.

$$p_{WENO,i} = \bar{\Phi}_i + \sum_{k=1}^K \tilde{a}_k \Omega_k \quad \leftarrow \quad p_{weno} = \sum_{m=1}^{N_{si}} w_m p_i^{(m)} \quad \leftarrow \quad p_i^{(m)} = \bar{\Phi}_i + \sum_{k=1}^K a_k^{(m)} \Omega_k$$

$N_{si} = \text{stencils}$



**Need careful formulation  
also needs to estimate its efficiency.**

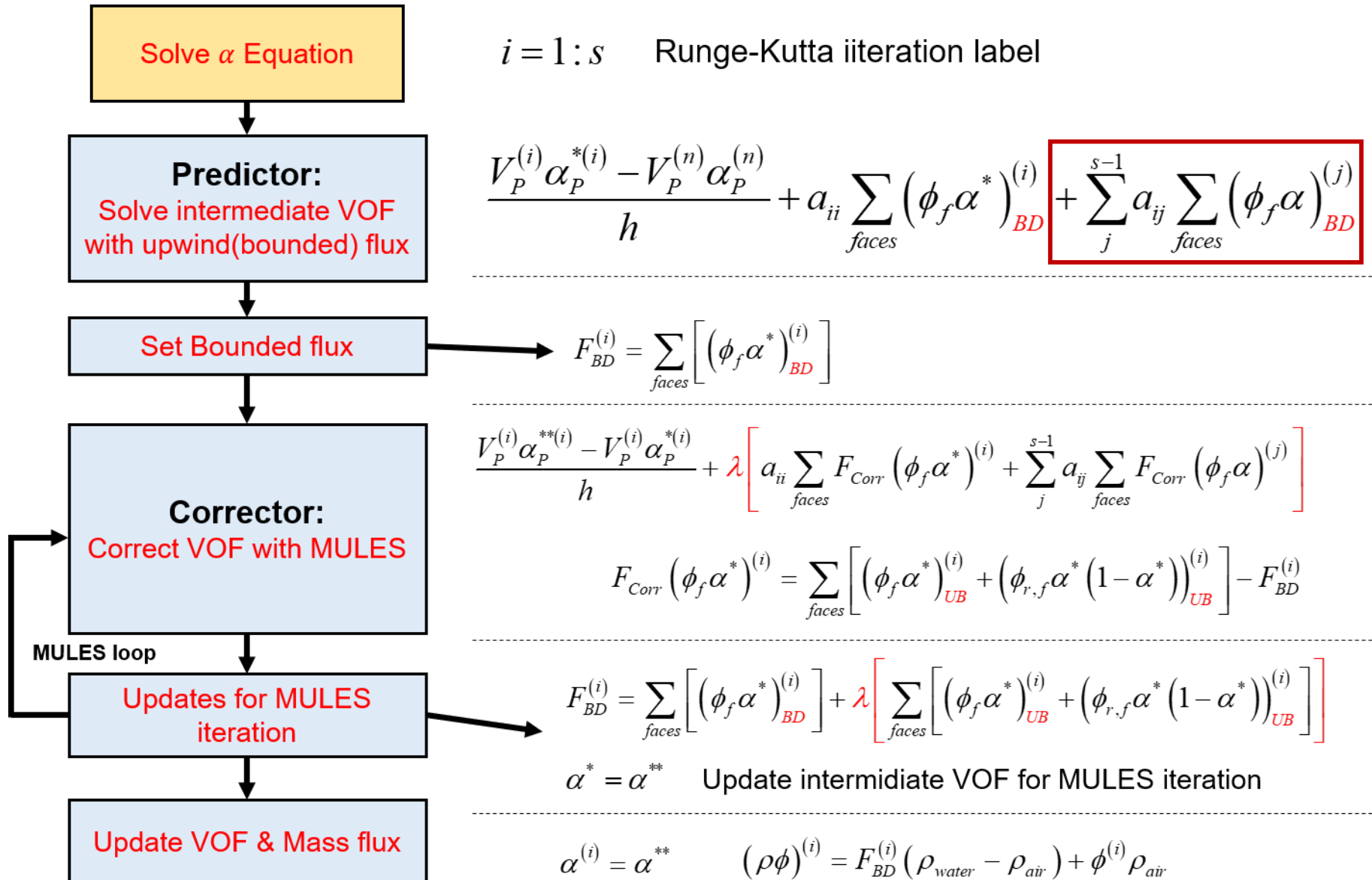
## Articles

1. A paper on the higher-order temporal scheme (ongoing).
2. A paper on the interface treatment schemes (Not ready yet).

*Thank you*



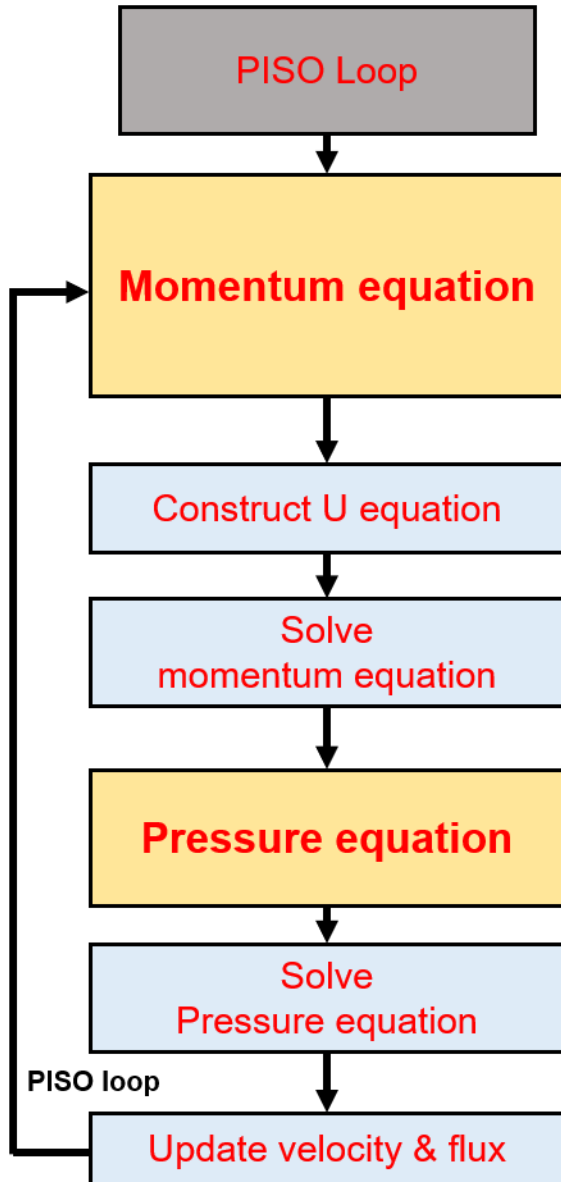
# Higher-order temporal schemes



$-\tau_1$	$\alpha_{11}$	$\theta$	$\theta$	$\theta$
$-\tau_2$	$\alpha_{21}$	$\alpha_{22}$	$\theta$	$\theta$
$-\tau_3$	$\alpha_{31}$	$\alpha_{32}$	$\alpha_{33}$	$\theta$
$-\tau_4$	$\alpha_{41}$	$\alpha_{42}$	$\alpha_{43}$	$\alpha_{44}$
	$b_1$	$b_2$	$b_3$	$b_4$



# Higher-order temporal schemes



$$\frac{\partial(V_P \rho \mathbf{u})}{\partial t} + \sum_{faces} ((\rho \phi)_f \mathbf{u}_f) - \sum_{faces} (\mu_f (\nabla \mathbf{u}_f)) - \nabla \mathbf{u} \cdot \nabla \mu V_P = \nabla p_d V_P - (\mathbf{g} \cdot \mathbf{x}) \nabla \rho V_P$$

$$RKi = i = 1 : s$$

$$\frac{(V_P \rho \mathbf{u})^{(i)} - (V_P \rho \mathbf{u})^{(n)}}{h} + a_{ii} \mathbf{R}^{(i)} + \sum_{j=1}^{i-1} a_{ij} \mathbf{R}^{(j)} = 0$$

$$\mathbf{R}^{(i)} = \sum_{faces} ((\rho \phi)_f^{(i)} \mathbf{u}_f^{(i)}) - \sum_{faces} (\mu_f^{(i)} (\nabla \mathbf{u}_f^{(i)})) - \nabla \mathbf{u}^{(i)} \cdot \nabla \mu^{(i)} V_P^{(i)} + \nabla p_d^{(i)} V_P^{(i)} + (\mathbf{g} \cdot \mathbf{x}) \nabla \rho^{(i)} V_P^{(i)}$$

$-\tau_1$	$a_{11}$	$0$	$0$	$0$
$-\tau_2$	$a_{21}$	$a_{22}$	$0$	$0$
$-\tau_3$	$a_{31}$	$a_{32}$	$a_{33}$	$0$
$-\tau_4$	$a_{41}$	$a_{42}$	$a_{43}$	$a_{44}$
	$b_1$	$b_2$	$b_3$	$b_4$

$$UEq^{(i)} = a_p^{(i)} \mathbf{u}^{(i)} - \mathbf{H}^{(i)} = -a_{ii} \nabla p_d^{(i)} - a_{ii} \nabla \rho^{(i)} (\mathbf{g} \cdot \mathbf{x})^{(i)}$$

$$\text{Get } \mathbf{u}^{(i)}$$

$$\nabla \mathbf{u}^{(i)} = 0 = \nabla \frac{1}{a_p^{(i)}} \left[ \mathbf{H}^{(i)} - a_{ii} \nabla p_d^{(i)} - a_{ii} \nabla \rho^{(i)} (\mathbf{g} \cdot \mathbf{x})^{(i)} \right]$$

$$\sum_{faces} \left[ \frac{1}{a_p^{(i)}} a_{ii} \nabla p_d^{(i)} \right]_f = \sum_{faces} \left( \frac{1}{a_p^{(i)}} \left[ \mathbf{H}^{(i)} - a_{ii} \nabla \rho^{(i)} (\mathbf{g} \cdot \mathbf{x})^{(i)} \right] \right)_f$$

$$\mathbf{u}^{(i)} = \frac{1}{a_p^{(i)}} \left[ \mathbf{H}^{(i)} - a_{ii} \nabla p_d^{(i)} - a_{ii} \nabla \rho^{(i)} (\mathbf{g} \cdot \mathbf{x})^{(i)} \right]$$

## 3.4.1. Application of ALE formulation

The consideration of moving mesh to VOF convection equation write: The additional term, mesh flux ( $\phi_{mesh}$ ), is also adapted to *Predictor & Corrector* algorithm.

$$\begin{aligned} \frac{V_{P(n+1)}^{(i)} \alpha_{P(n+1)}^{(i)} - V_{P(n+1)}^{(n)} \alpha_{P(n+1)}^{(n)}}{h} + \sum_f (\phi_{mesh} \alpha_f)^{(i)} + a_{ii} \sum_f (\phi_f \alpha_f)^{(i)} \\ + \sum_{j=1}^{i-1} a_{ij} \sum_f (\phi_f \alpha_f)^{(j)} = 0. \end{aligned} \quad (32)$$

The application of SCL formulation to momentum equation yields Eq.(33), where the  $\mathbf{R}$  is equal to Eq.(24).

$$\frac{(V \rho \mathbf{u})_P^{(i)} - (V \rho \mathbf{u})_P^{(n)}}{h} + \sum_f [(\rho \phi_{mesh})^{(i)} \mathbf{u}_f^{(i)}] + a_{ii} \mathbf{R}^{(i)} + \sum_{j=1}^{i-1} a_{ij} \mathbf{R}^{(j)} \quad (33)$$

# Preliminary study: Waves

## Wave generation and absorption.

$$\chi = (1 - w)\chi + w\chi^{Target}$$

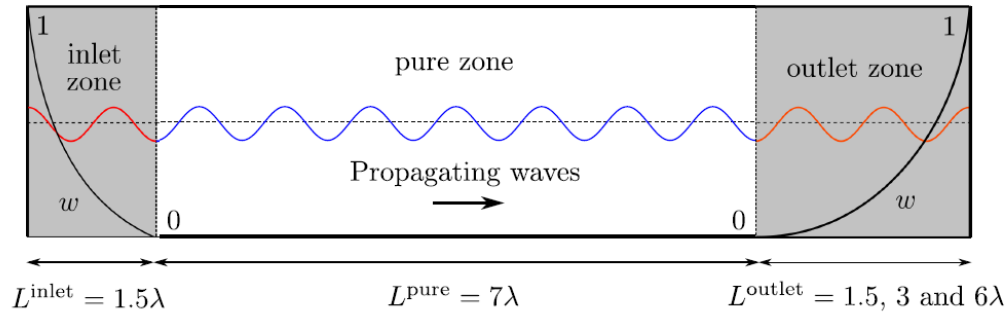


Figure 1.1. Schematic view of the NWT for a parametric study on the relaxation schemes.

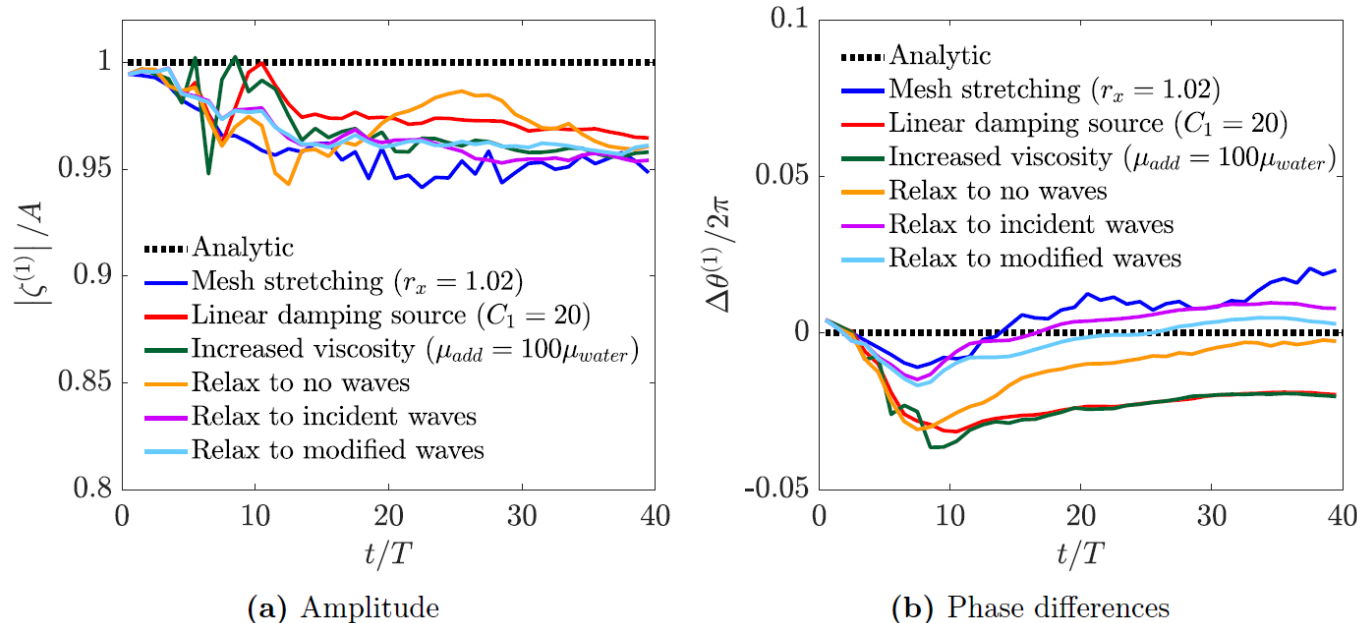


Figure 2.1. The first-order harmonic amplitudes and phase differences with respect to different outlet.

Explicit Relaxation method (to incident wave & no wave).  
Increased viscosity & artificial damping source

$$\frac{\partial(\rho u)}{\partial t} + \nabla \cdot (\rho u u) - \nabla \cdot ((\mu + \mu_{add})(\nabla u)) - \nabla u \cdot \nabla \mu = \nabla p_d - (\mathbf{g} \cdot \mathbf{x}) \nabla \rho + \mathbf{S}$$

$$\mathbf{S} = (0, 0, \rho(C_1 + C_2 u_z) w u_z)$$

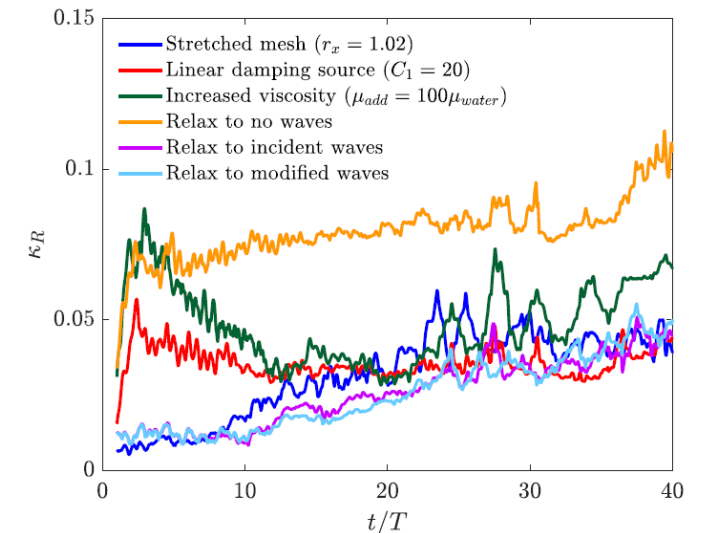


Figure 2.2. Evolution of reflection coefficients for different outlets.