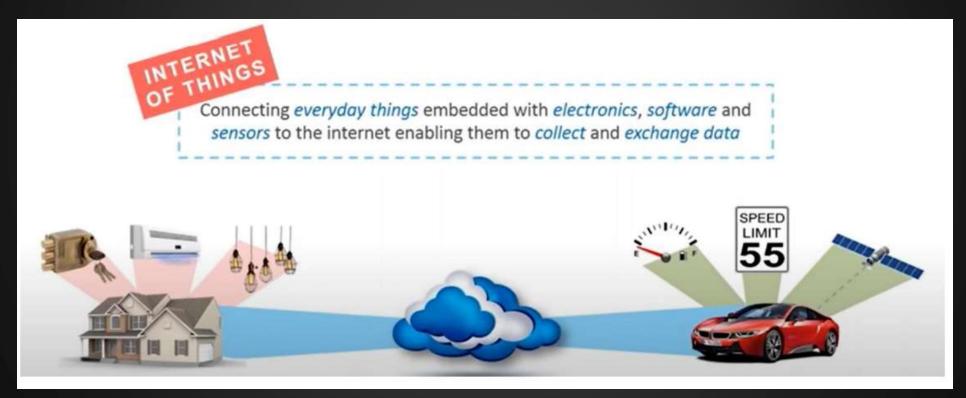




# What you will Learn Today?

✓ IoT Based Data Monitoring System using ARM CORTEX M4 & ESP8266 —Thingspeak Cloud

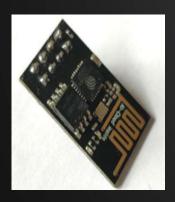
### What is Internet of Things



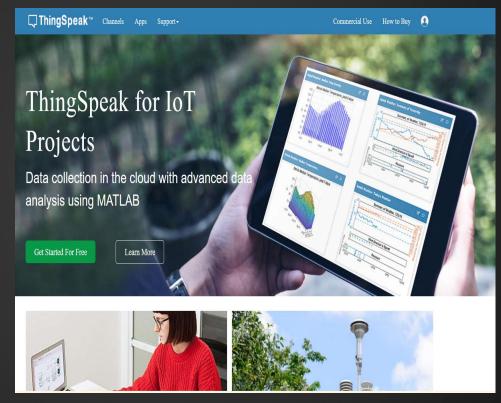
# Hardware Required











### SOFTWARE REQUIRED

- STM2CUBE IDE
- SALEA LOGIC ANALYZER
- Thingspeak

### What is Thingspeak

#### Analytic IoT platform

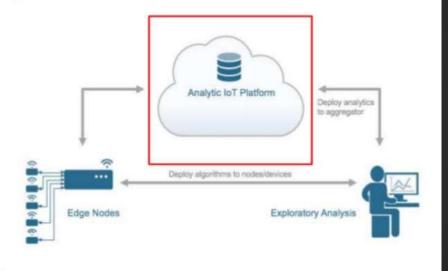
- Collect data from sensors, "things"
- Visualize data instantly
- Has more than 60,000 users

#### Analyze data

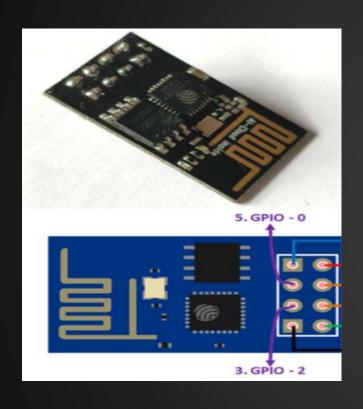
 MATLAB integration allows users to run scheduled code on data coming into ThingSpeak

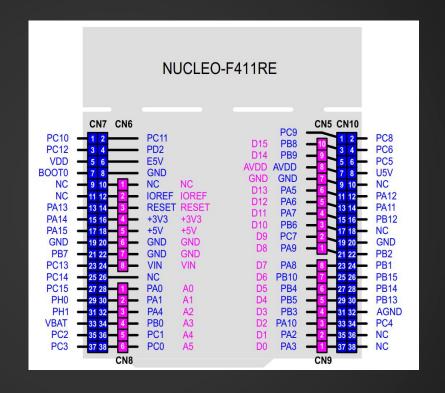
#### Act on data

 E.g. send a tweet when the temperature in your backyard reaches 32 degrees



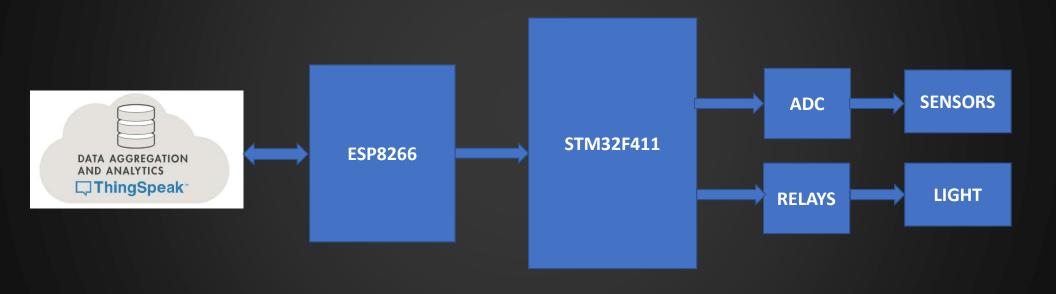
### SCHEMATIC DESIGN





//PB6->TX //PB7->RX ->ESP8266 TX //RELAY -PA5

## **Block Diagram**



### **UART Parameters**

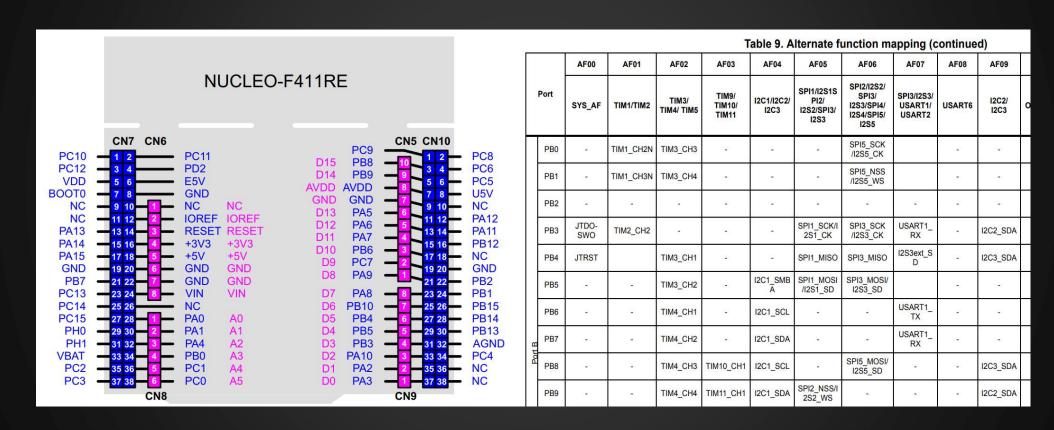
- Baud Rate 115200
- Number of Data Bits (7, 8)
- Parity Bit (On, Off)
- Stop Bits (0, 1, 2)
- Flow Control (None, On, Hardware)

### AT COMMANDS

AT commands used for data transmission

- AT+RST
- AT+CWJAP="WIFINAME", "Password"
- AT+CIPSTART="TCP","184.106.153.149",80
- AT+CIPSEND=49
- AT+CLOSE

### **Connection Details**



### STEPS FOR UART TRANSMIT

```
//Enable clock access to GPIOA

//SET PA2,PA3 MODE TO Alternate function Mode

//SET PA2 ,PA3 Alternative function type to UART_TX (AF07)

//CONFIGURE UART MODULE

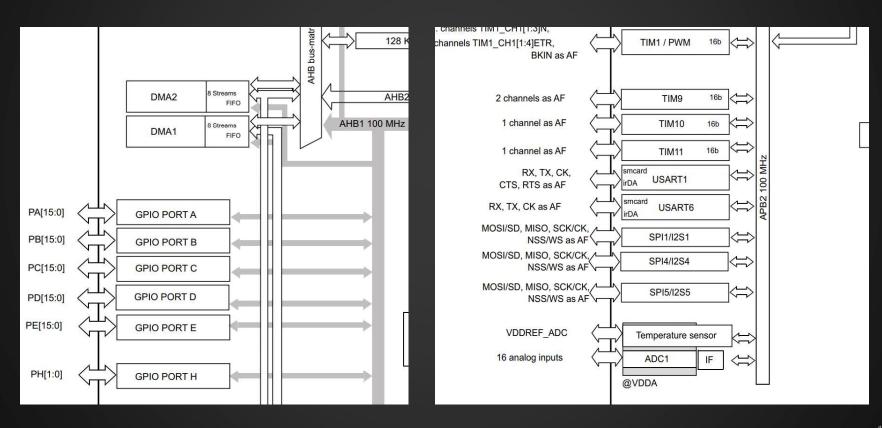
//ENABLE CLOCK ACCESS TO UART2

//CONFIGURE BAUDRATE

//CONFIGURE TRANSFER DIRECTION

//ENABLE UART MODULE
```

### **Block Diagram**



### **USART1-FUNCTIONAL MAPPING**

| -    |   |      | AF00           | AF01      | AF02                | AF03                     | AF04               | AF05                                     | AF06   | AF07                            | -  |
|------|---|------|----------------|-----------|---------------------|--------------------------|--------------------|--|--|---------------------------------|----|
| Port |   | Port | SYS_AF         | TIM1/TIM2 | TIM3/<br>TIM4/ TIM5 | TIM9/<br>TIM10/<br>TIM11 | I2C1/I2C2/<br>I2C3 | SPI1/I2S1S<br>PI2/<br>I2S2/SPI3/<br>I2S3 | SPI2/I28 2/<br>SPI3/<br>I2S3/SPI4/<br>I2S4/SPI5/<br>I2S5 | SPI3/I2S3/<br>USART1/<br>USART2 | US |
|      |   | PB0  |                | TIM1_CH2N | TIM3_CH3            | <b>2</b> (               | -                  | 4  | SPI5_SCK<br>/I2S5_CK                                     |                                 |    |
|      |   | PB1  | 9              | TIM1_CH3N | TIM3_CH4            | <b>2</b> 1               | ( <del>2</del> )   | 121                                      | SPI5_NSS<br>/I2S5_WS                                     |                                 |    |
|      |   | PB2  | 6              | 26        | - 4                 | 24                       | ~                  | -  | ē  | 3 <u>2</u>                      |    |
|      |   | PB3  | JTDO-<br>SWO   | TIM2_CH2  | - B                 | 100                      |                    | SPI1_SCK/I<br>2S1_CK                     | SPI3_SCK<br>/I2S3_CK                                     | USART1_<br>RX                   |    |
|      |   | PB4  | JTRST          | 2         | TIM3_CH1            | 57.                      | (A)                | SPI1_MISO                                | SPI3_MISO  | I2S3ext_S<br>D                  |    |
|      |   | PB5  |                |           | Tilvi3_CH2          | <b>=</b> 2               | A A                | SPI1 MOSI<br>/I2S1_SD                    | SPI3_MOSI/   |                                 |    |
|      |   | PB6  | ( <del>.</del> | •         | TIM4_CH1            | -                        | I2C1_SCL           | a#1                                      | i.e.   | USART1_<br>TX                   |    |
|      | В | РВ7  | -              | -1        | TIM4_CH2            | <b>=</b> 3               | I2C1_SDA           | .=                                       | :-   | USART1_<br>RX                   |    |
|      | ō |      | X              | **        | - 20                |                          |                    | *  |  |                                 | T  |

### **FUNCTIONAL MAPPING**

|   | ١ |
|---|---|
| ŀ | ı |
| ľ | ı |

Table 9. Alternate function mapping

DocID026289 Rev 7

|        |     | AF00   | AF01                  | AF02                | AF03                     | AF04               | AF05                                     | AF06  | AF07                            | AF08   | AF09          | AF10            | AF11 | AF12         | AF13 | AF14 | AF15         |
|--------|-----|--------|-----------------------|---------------------|--------------------------|--------------------|--|---|---------------------------------|--------|---------------|-----------------|------|--------------|------|------|--------------|
| Port   |     | SYS_AF | TIM1/TIM2             | TIM3/<br>TIM4/ TIM5 | TIM9/<br>TIM10/<br>TIM11 | 12C1/I2C2/<br>I2C3 | SPI1/I2S1S<br>PI2/<br>I2S2/SPI3/<br>I2S3 | SPI2/I2S2/<br>SPI3/<br>I2S3/SPI4/<br>I2S4/SPI5/<br>I2S5 | SPI3/I2S3/<br>USART1/<br>USART2 | USART6 | 12C2/<br>12C3 | OTG1_FS         |      | SDIO         |      |      |              |
|        | PA0 |        | TIM2_CH1/<br>TIM2_ETR | TIM5_CH1            |                          | S48                | •  | 9   | USART2_<br>CTS                  |        |               | -               | -    | -            | -    | 36   | EVENT<br>OUT |
|        | PA1 | 9      | TIM2_CH2              | TIM5_CH2            | 40                       | 2                  | SPI4_MOSI<br>/I2S4_SD                    | -   | USART2_<br>RTS                  | -      |               | -               | -    | 127          | -    |      | EVENT<br>OUT |
| ĺ      | PA2 |        | TIM2_CH3              | TIM5_CH3            | TIM9_CH1                 | -                  | I2S2_CKIN                                | *   | USART2_<br>TX                   | (#)    |               | *               | -    | -            | -    |      | EVENT<br>OUT |
|        | PA3 |        | TIM2_CH4              | TIM5_CH4            | TIM9_CH2                 |                    | I2S2_MCK                                 | ž.  | USART2_<br>RX                   | (7)    |               |                 |      | m)           | 2    |      | EVENT<br>OUT |
|        | PA4 | 300    |                       |                     |                          | S48                | SPI1_NSS/I<br>2S1_WS                     | SPI3_NSS/I2<br>S3_WS                                    | USART2_<br>CK                   |        |               | -               |      | -            | -    | 36   | EVENT<br>OUT |
|        | PA5 | 9      | TIM2_CH1/<br>TIM2_ETR |                     | 49                       | 2                  | SPI1_SCK/I<br>2S1_CK                     | 9   | 4                               | -      |               | -               | -    | - 127        | -    |      | EVENT<br>OUT |
|        | PA6 |        | TIM1_BKIN             | TIM3_CH1            |                          |                    | SPI1_MISO                                | I2S2_MCK  |                                 | (#)    |               | ( <del>-</del>  | -    | SDIO_<br>CMD | -    |      | EVENT<br>OUT |
| Port A | PA7 | z.     | TIM1_CH1N             | TIM3_CH2            |                          |                    | SPI1_MOSI<br>/I2S1_SD                    | *   | 7.                              | (7)    | -             | 185             |      | .70          |      |      | EVENT<br>OUT |
| Por    | PA8 | MCO_1  | TIM1_CH1              |                     |                          | I2C3_<br>SCL       |  | 340   | USART1_<br>CK                   | •      | *             | USB_FS_<br>SOF  |      | SDIO_<br>D1  | ÷    | 30   | EVENT<br>OUT |
|        | PA9 | 4      | TIM1_CH2              | Heli                | (#C)                     | I2C3_<br>SMBA      | *  | *   | USART1_<br>TX                   | (4)    |               | USB_FS_<br>VBUS | -    | SDIO_<br>D2  | *    |      | EVENT<br>OUT |

### **ALTERNATE FUNCTIONS**

Address offset: 0x20 Reset value: 0x0000 0000

| 31 | 30   | 29      | 28 | 27 | 26   | 25      | 24 | 23 | 22   | 21      | 20    | 19         | 18   | 17 | 16 |  |  |
|----|------|---------|----|----|------|---------|----|----|------|---------|-------|------------|------|----|----|--|--|
|    | AFRL | 7[3:0]  |    |    | AFRL | .6[3:0] |    |    | AFRI | _5[3:0] |       | AFRL4[3:0] |      |    |    |  |  |
| rw | rw   | rw      | rw | rw | rw   | rw      | rw | rw | rw   | rw      | rw    | rw         | rw   | rw | rw |  |  |
| 15 | 14   | 13      | 12 | 11 | 10   | 9       | 8  | 7  | 6    | 5       | 4     | 3          | 2    | 1  | 0  |  |  |
|    | AFRL | .3[3:0] |    |    | AFRL | 2[3:0]  |    |    | AFRI | _1[3:0] | [3:0] |            | AFRI |    |    |  |  |
| rw | rw   | rw      | rw | rw | rw   | rw      | rw | rw | rw   | rw      | rw    | rw         | rw   | rw | rw |  |  |
|    |      |         |    | 0  | 1    | 1       | 1  |    | 01)  |         | , e   |            |      | P  | -  |  |  |

Bits 31:0 **AFRLy:** Alternate function selection for port x bit y (y = 0..7)

These bits are written by software to configure alternate function I/Os

#### AFRLy selection:

0000: AF0 1000: AF8 1001: AF9 0001: AF1 0010: AF2 1010: AF10 0011: AF3 1011: AF11 0100: AF4 1100: AF12 0101: AF5 1101: AF13 0110: AF6 1110: AF14 0111: AF7 1111: AF15

### **BAUD RATE CALCULATION**

- Peripheral Clock =16000000
- BAUDRATE=9600
- BRR =((16000000+(9600/2))/9600)
- BRR= 1667
- HEX VALUE OF BRR =0X0683
- BAUDRATE=115200
- BRR = ((16000000+(115200/2))/115200)
- BRR= 139
- HEX VALUE OF BRR =0X008B

### **UART WRITE**

```
7 void uart2_write(int ch)
8 {
9     //Make sure the transmit data register is empty
9     while(!(*USART2_SR & 0x0080)){}
1     //write to transmit data register
2     *USART2_DR =(ch&0XFF);
8 }
```

#### TXE: Transmit data register empty

This bit is set by hardware when the content of the TDR register has been transferred into the shift register. An interrupt is generated if the TXEIE bit =1 in the USART\_CR1 register. It is cleared by a write to the USART\_DR register.

0: Data is not transferred to the shift register

1: Data is transferred to the shift register)

#### 26.6.1 Status register (USART\_SR)

Address offset: 0x00

Reset value: 0x00C0 0000

| 31 | 30       | 29   | 28    | 27 | 26 | 25    | 24    | 23    | 22    | 21    | 20   | 19  | 18 | 17 | 16 |
|----|----------|------|-------|----|----|-------|-------|-------|-------|-------|------|-----|----|----|----|
|    |          |      |       |    |    |       | Rese  | erved |       |       |      |     |    |    |    |
| 15 | 14       | 13   | 12    | 11 | 10 | 9     | 8     | 7     | 6     | 5     | 4    | 3   | 2  | 1  | 0  |
|    | Reserved |      |       |    |    | CTS   | LBD   | TXE   | TC    | RXNE  | IDLE | ORE | NF | FE | PE |
|    |          | nese | erved |    |    | rc_w0 | rc_w0 | r     | rc_w0 | rc_w0 | r    | r   | r  | r  | r  |

### **USART DATA REGISTER**

#### Data register (USART\_DR)

Address offset: 0x04

Reset value: 0xXXXX XXXX

Bits 31:9 Reserved, must be kept at reset value

Bits 8:0 DR[8:0]: Data value

Contains the Received or Transmitted data character, depending on whether it is read from or written to.

The Data register performs a double function (read and write) since it is composed of two registers, one for transmission (TDR) and one for reception (RDR)

The TDR register provides the parallel interface between the internal bus and the output shift register (see Figure 1).

The RDR register provides the parallel interface between the input shift register and the internal bus.

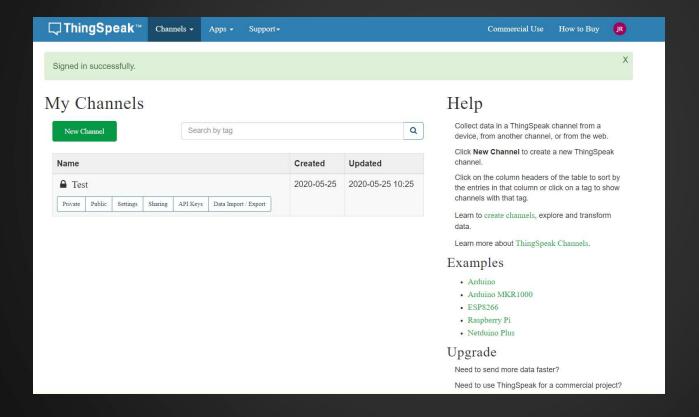
When transmitting with the parity enabled (PCE bit set to 1 in the USART\_CR1 register), the value written in the MSB (bit 7 or bit 8 depending on the data length) has no effect because it is replaced by the parity.

When receiving with the parity enabled, the value read in the MSB bit is the received parity bit.

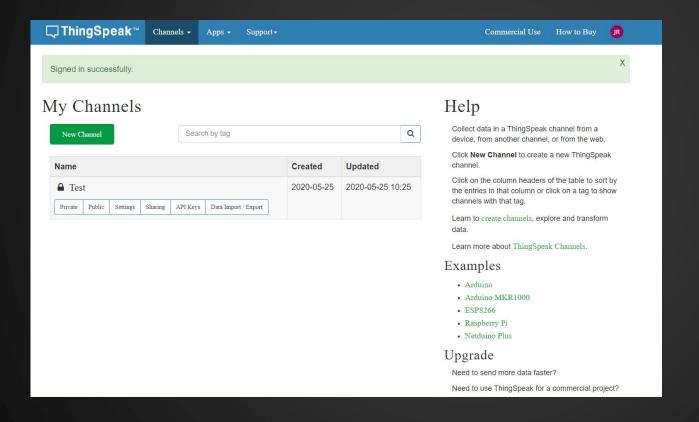
### **CONNECTION DETAILS**

```
//PB6->TX->ESP8266 RX
//PB7->RX ->ESP8266 TX
//RELAY -PA5
```

### **HOME PAGE**



### CHANNEL CREATION



### CREATE FIELDS

#### New Channel Arduino-IoT-Matlab Name Description MQ2 Field 1 V TEMP Field 2 DISTANCE Field 3 Field 4 Field 5 Field 6 Field 7 Field 8 Metadata

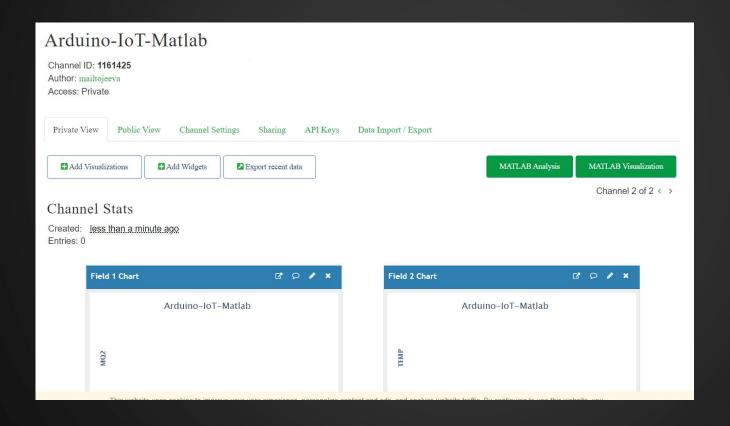
#### Help

Channels store all the data that a ThingSpeak application collects. Each channel includes eight fields that can hold any type of data, plus three fields for location data and one for status data. Once you collect data in a channel, you can use ThingSpeak apps to analyze and visualize it.

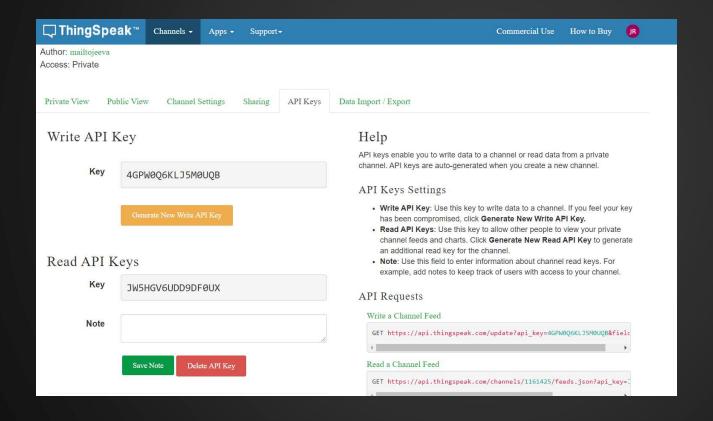
#### Channel Settings

- Percentage complete: Calculated based on data entered into the various fields
  of a channel. Enter the name, description, location, URL, video, and tags to
  complete your channel.
- Channel Name: Enter a unique name for the ThingSpeak channel.
- · Description: Enter a description of the ThingSpeak channel.
- Field#: Check the box to enable the field, and enter a field name. Each ThingSpeak channel can have up to 8 fields.
- Metadata: Enter information about channel data, including JSON, XML, or CSV data.
- Tags: Enter keywords that identify the channel. Separate tags with commas.
- Link to External Site: If you have a website that contains information about your ThingSpeak channel, specify the URL.
- . Show Channel Location:
  - Latitude: Specify the latitude position in decimal degrees. For example, the latitude of the city of London is 51.5072.
  - Longitude: Specify the longitude position in decimal degrees. For example, the longitude of the city of London is -0.1275.
  - o Elevation: Specify the elevation position meters. For example, the

### **CHANNEL CREATED**



### **READ AND WRITE API KEYS**



### **API KEY SETTINGS**

#### API Keys Settings . Write API Key: Use this key to write data to a channel. If you feel your key has been compromised, click Generate New Write API Key. . Read API Keys: Use this key to allow other people to view your private channel feeds and charts. Click Generate New Read API Key to generate an additional read key for the channel. . Note: Use this field to enter information about channel read keys. For example, add notes to keep track of users with access to your channel. API Requests Write a Channel Feed https://api.thingspeak.com/update?api\_key=4GPW0Q6KLJ5M0UQB&field1=0 Read a Channel Feed GET https://api.thingspeak.com/channels/1161425/feeds.json?api\_key=1 Read a Channel Field GET https://api.thingspeak.com/channels/1161425/fields/1.json?api\_ke Read Channel Status Updates GET https://api.thingspeak.com/channels/1161425/status.json?api\_key=

# **DEMO**

# Mindset Activity

- Write Down Your Top 10 Goals.(1 Mark)
- Write Down Your Top 10 Ideas to Achieve Your Goal. (1 Mark)
- 30 Minutes for Workout (5000-7000 Steps a Day)(2 Mark).
- 15 Minutes to Meditate (2 Mark)
- 10 Minutes to Visualize of Achieving Your Goals(1)
- 10 Minutes to Focus on the Day Plan (1)

2 Hr's for Learning and Take Notes. (2 Mark)

https://www.facebook.com/groups/embeddedsystemsandiot/

# THANK YOU