Local Search

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Outlines

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- Examples
- •Hill Climbing Pros/Cons
- Hill Climbing Types
- Simulated Annealing

Local Search and Optimization Problems

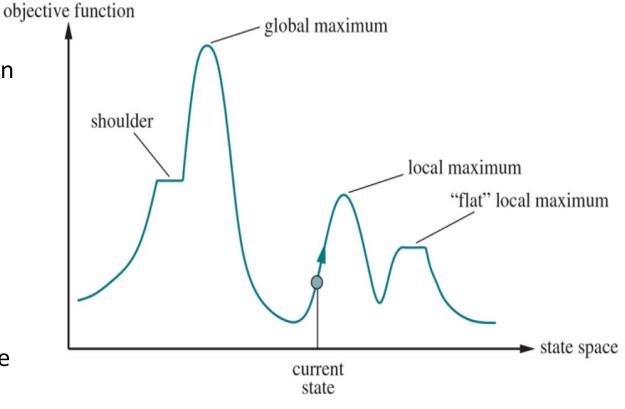
- •Local Search algorithms operate by searching from a start state to neighbouring states, without keeping track of the paths, nor the set of states that have been reached.
- might never explore a portion of the search space where a solution actually resides.
- •solve **optimization problems**, in which the aim is to **find the best state** according to an objective function.

Key advantages:

- 1. use very little memory
- 2. often find reasonable solutions in large or infinite state spaces for where systematic algorithms are unsuitable.

Local Search

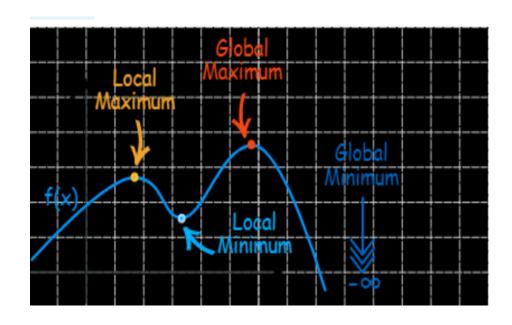
- Each point (state) in the landscape has an "elevation," defined by the value of the objective function.
- If elevation corresponds to an objective function, then the aim is to find the highest peak—a global maximum—and we call the process hill climbing.
- If elevation corresponds to cost, then the aim is to find the lowest valley—a global minimum—and we call it gradient descent.



A one-dimensional state-space landscape in which elevation corresponds to the objective function. The aim is to find the global maximum.

Terminologies

- •A high point is called a maximum (plural maxima).
- •A low point is called a minimum (plural minima).
- •We say **local maximum (or minimum)** when there may be higher (or lower) points elsewhere but not nearby.
- •The maximum or minimum over the entire function is called an "Absolute" or "Global" maximum or minimum.



Find the maxima and minima for a function: $y = 5x^3 + 2x^2 - 3x$ (1)

Solution:

1) Apply first derivative to equation (1)

$$y' = 15x^2 + 4x - 3 (2)$$

2) Find the value of x

```
15x^2+9x-5x-3=0

3x(5x+3)-1(5x+3)=0 using factorization

(3x-1)(5x+3)=0

x=1/3, x=-3/5

At x=1/3:

y'=15(1/3)^2+4(1/3)-3=0

At x=-3/5:

y'=15(-3/5)^2+4(-3/5)-3=0
```

3) Apply derivative once more to equation (2), the second derivative

$$y'' = 30x + 4$$
 (3)

At x = -3/5:

$$y'' = 30(-3/5) + 4 = -14$$

it is less than 0, so -3/5 is a local maximum

At
$$x = +1/3$$
:

$$y'' = 30(+1/3) + 4 = +14$$

it is greater than 0, so +1/3 is a local minimum

Hill-Climbing Search

- •The hill-climbing search algorithm keeps track of one current state and on each iteration moves to the neighbouring state with highest value.
- •heads in the direction that provides the **steepest ascent**.
- •terminates when it reaches a "peak" where no neighbour has a higher value.
- does not look ahead beyond the immediate neighbours of the current state.
- •one way to use hill-climbing search is to use the negative of a heuristic cost function as the objective function; that will climb locally to the state with smallest heuristic distance to the goal.
- •sometimes called greedy local search because it grabs a good neighbour state without thinking ahead about where to go next.

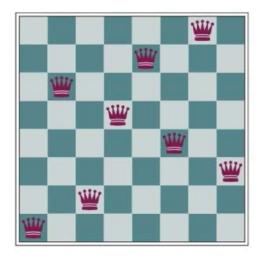
Hill-Climbing Search

The hill-climbing search algorithm, which is the most basic local search technique. At each step the current node is replaced by the best neighbour.

```
function HILL-CLIMBING(problem) returns a state that is a local maximum
    current ← problem.INITIAL
    while true do
        neighbor ← a highest-valued successor state of current
        if VALUE(neighbor) ≤ VALUE(current) then return current
        current ← neighbor
```

8 Queens

- The goal is to minimize the number of queens attacking each other.
- Heuristic cost estimate, h=number of queens (Q) attacking each others directly or indirectly.
- Successors are all possible states moving one Q in the same column.
- 8 * 7= 56 possible successors.
- ∘ (a) h=1
- ∘ (b) h= 17

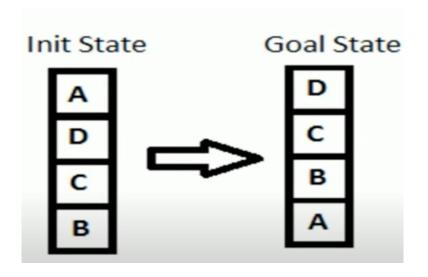


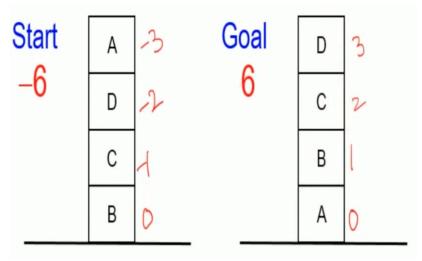


(a) (b)

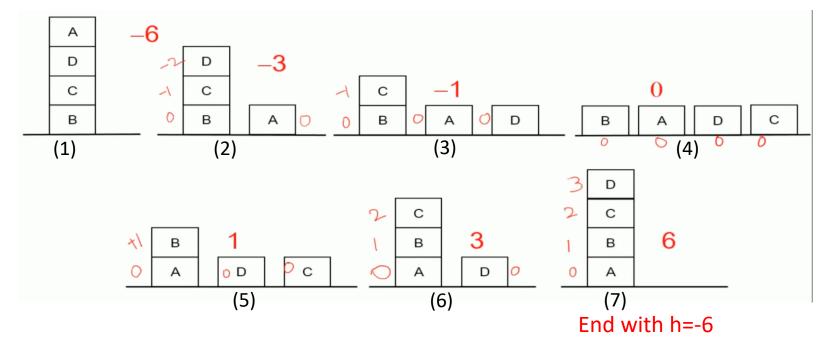
4-Blocks: global heuristic function

- h= +1 for all the blocks in the support structure if the block is correctly positioned
- otherwise h= -1





Start with h= -6



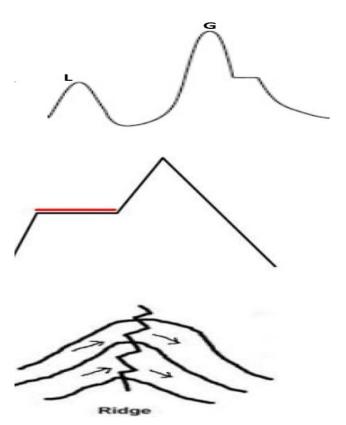
Hill-Climbing Search Pros/Cons

Pros:

- It can make rapid progress toward a solution because it is usually quite easy to improve a bad state.
- No backtracking

Cons:

- LOCAL MAXIMA: a peak that is higher than each of its neighbouring states but lower than the global maximum.
- PLATEAUS: a flat area of the state-space landscape. It can be a flat local maximum, from which no uphill exit exists, or a shoulder, from which progress is possible.
- RIDGES: result in a sequence of local maxima that is very difficult for greedy algorithms to navigate.



Hill Climbing Types

1. Stochastic hill climbing

- chooses at random from among the uphill moves
- the probability of selection can vary with the steepness of the uphill move
- converges more slowly than steepest ascent
- finds better solutions in some state

2. First-choice hill climbing

- implements stochastic hill that generates successors randomly until one is generated that is better than the current state
- a good strategy when a state has many (e.g., thousands) of successors.

3. Random-restart hill climbing

- conducts a series of hill-climbing searches from randomly generated initial states, until a goal is found
- complete with probability 1, because it will eventually generate a goal state as the initial state

- •Key Idea: escape local maxima by allowing some "bad" moves but gradually decrease their frequency
- •Take some uphill steps to escape the local minimum
- •Instead of picking the best move, it picks a random move
- •If the move improves the situation, it is executed. Otherwise, move with some probability less than 1.
- Physical analogy with the annealing process:
 - Allowing liquid to gradually cool until it freezes
- •The heuristic value is the energy, E
- •Temperature parameter, T, controls speed of convergence.

- **Basic inspiration**: What is annealing?
- In mettallurgy, annealing is the physical process used to temper or harden metals or glass by heating them to a high temperature and then gradually cooling them, thus allowing the material to coalesce into a low energy cristalline state.
 - •Heating then slowly cooling a substance to obtain a strong cristalline structure.
- **Key idea:** Simulated Annealing combines Hill Climbing with a random walk in some way that yields both efficiency and completeness.
- Used to solve VLSI layout problems in the early 1980

```
function SIMULATED-ANNEALING (problem, schedule) returns a solution state
   inputs: problem, a problem
              schedule, a mapping from time to "temperature"
   local variables: current, a node
                         next. a node
                         T, a "temperature" controlling prob. of downward steps
   current \leftarrow Make-Node(Initial-State[problem])
   for t \leftarrow 1 to \infty do
         T \leftarrow schedule[t]
         if T = 0 then return current
         next \leftarrow a randomly selected successor of current
         \Delta E \leftarrow \text{Value}[next] - \text{Value}[current]
        if \Delta E > 0 then current \leftarrow next
        else \mathit{current} \leftarrow \mathit{next} only with probability e^{\Delta E/T}
```

Temperature T

- Used to determine the probability
- High T : large changes
- Low T : small changes

Cooling Schedule

- Determines rate at which the temperature T is lowered
- Lowers T slowly enough, the algorithm will find a global optimum

In the beginning, aggressive for searching alternatives, become conservative when time goes by

