Kruskal's algorithm to find MST of a network

a)

Kruskal's algorithm is a greedy algorithm used to find the minimum spanning tree (MST) of a connected, undirected graph. It works by sorting the edges in non-decreasing order of their weights and then adding edges to the MST while ensuring no cycles are formed. Here are the steps and algorithms needed:

1. Disjoint Set (Union-Find) Data Structure:

The Union-Find data structure is crucial for Kruskal's algorithm to efficiently manage and merge disjoint sets of nodes while checking for cycles.

- **Find Operation**: This operation finds the root of the set containing the element. It uses path compression to optimize future queries.
- **Union Operation**: This operation merges two sets. It uses union by rank to keep the tree shallow, making future operations faster.

2. Kruskal's Algorithm:

- Sort all the edges in the graph in increasing order of their weights.
- Initialize a disjoint set data structure to manage connected components.
- Iterate through the sorted edges and for each edge, check if it forms a cycle:
 - ✓ If it doesn't form a cycle (i.e., the two vertices are in different components), include this edge in the MST and perform a union operation.
 - ✓ If it forms a cycle, discard the edge.
- Repeat until you have included (n 1) edges (where n is the number of vertices in the graph). At this point, the MST is complete.

b)

Time Complexity Analysis:

1. Sorting the edges:

Sorting the edges takes **O(ElogE)**, where E is the number of edges.

2. Union-Find Operations:

The time complexity of each union and find operation using path compression and union by rank is almost constant, specifically $O(\alpha(n))$, where $\alpha(n)$ is the inverse Ackermann function, which grows extremely slowly and is nearly constant for all practical values of n.

 \checkmark For **E** edges, the total complexity of union and find operations is **O**(**E**α(**n**)).

3. Overall Complexity:

Therefore, the total time complexity of Kruskal's algorithm is dominated by the sorting step, resulting in:

 $O(ElogE + E\alpha(n)) \approx O(ElogE)$

This is efficient for sparse graphs (where E is much less than n^2).

Space Complexity Analysis:

1. Disjoint Set:

The space complexity for the Union-Find data structure is **O(n)**, where n is the number of nodes (vertices).

2. Edges:

The space complexity for storing the edges is **O(E)**, where **E** is the number of edges in the graph.

3. Overall Complexity:

The space complexity is O(n+E), which is efficient.

Correctness:

- Kruskal's algorithm ensures that no cycles are formed because the algorithm only adds an edge if the two vertices of the edge are in different connected components (checked using the Union-Find data structure).
- The algorithm guarantees that the MST is optimal because it always adds the next smallest edge that doesn't form a cycle, following the greedy approach.

c)



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