Dataset Exploration Report

1. Introduction

- Dataset Source: COCO (Common Objects in Context)
- **Purpose:** Object detection in autonomous driving scenarios, aiming to identify and classify objects like pedestrians, vehicles, traffic signs, and obstacles in real-time.

2. Dataset Composition

- Number of Images: 26300 (deleted unannotated images).
- Number of Objects (Bounding Boxes): 11.
- Classes:

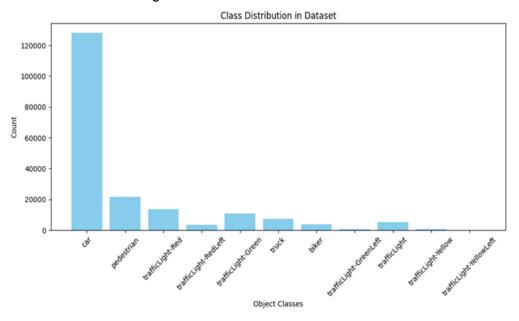
```
Reys: dict_keys(['info', 'licenses', 'categories', 'images', 'annotations'])
Sample Image Entry:
('id': 0, 'license': 1, 'file_name': '1478897926627294775 jpg.rf.6828a46821cbab4c2c277d7ddf291f00.jpg', 'height': 512, 'width': 512, 'date_captured': '2921-06-09712:24:25+00:00']
('id': 0, 'license': 1, 'file_name': '14788999899174870_jpg.rf.6828a48821432f9513dad8d91c54a1346.jpg', 'height': 512, 'width': 512, 'date_captured': '2921-06-09712:24:25+00:00']
Sample Annotation Entry:
('id': 0, 'image_id': 0, 'category_id': 2, 'bbox': [140, 262, 21, 25.5], 'area': 535.5, 'segmentation': [], 'iscrowd': 0)
('id': 0, 'image_id': 0, 'category_id': 2, 'bbox': [266, 231, 24, 95.5], 'area': 2922, 'segmentation': [], 'iscrowd': 0)
('id': 2, 'image_id': 0, 'category_id': 2, 'bbox': [271, 241, 17, 76], 'area': 1292, 'segmentation': [], 'iscrowd': 0)

Categories:
('id': 0, 'name': 'obstacles', 'supercategory': 'obstacles')
('id': 1, 'name': 'biker', 'supercategory': 'obstacles')
('id': 3, 'name': 'traffic.ight-Green, 's upercategory': 'obstacles')
('id': 4, 'name': 'traffic.ight-Green.id', 'supercategory': 'obstacles')
('id': 7, 'name': 'traffic.ight-Green.id', 'supercategory': 'obstacles')
('id': 7, 'name': 'traffic.ight-Green.id', 'supercategory': 'obstacles')
('id': 9, 'name': 'traffic.ight-Groundert', 'supercategory': 'obstacles')
('id': 1, 'name': 'traffic.ight-Groundert', 'supercategory': 'obstacles')
('id': 1, 'name': 'traffic.ight-Groundert', 'supercategory': 'obstacles')
('id': 1, 'name': 'traffic.ight-Groundert', 'supercategory': 'obstacles')
```

• Bounding Box Format: COCO format [x_min, y_min, width, height].

3. Class Distribution Analysis (

 Histogram of Object Categories: A visualization showing the distribution of object categories to check for class imbalances.



4. Image Quality & Metadata Analysis

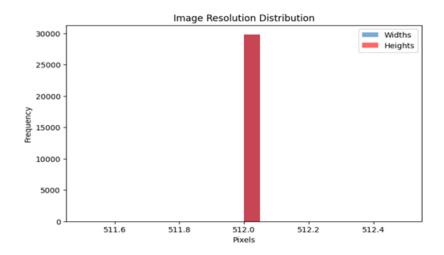
• Resolution Distribution:

Image Resolution Stats:

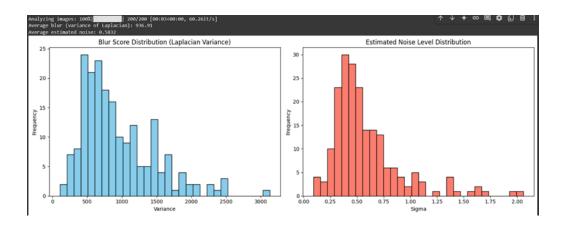
Min size: 512x512

Max size: 512x512

Avg size: 512x512

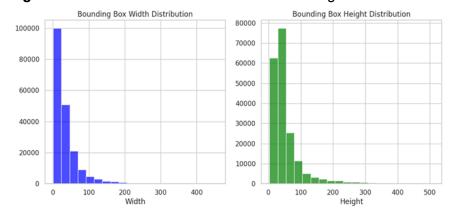


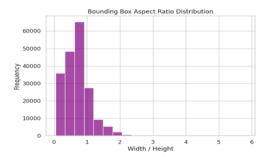
• **Blur & Noise Analysis:** Identification of images with low quality due to motion blur, poor lighting, or noise.



5. Bounding Box Validity Check

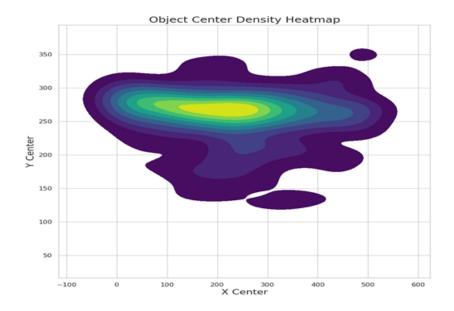
- Total Bounding Boxes: 194539
- **Invalid Bounding Boxes:** Zero (number and percentage of bounding boxes exceeding image dimensions or having negative coordinates).
 - Bounding Box Size Distribution: Statistics on bounding box widths and heights.



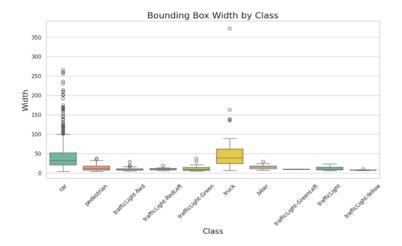


6. Spatial Distribution Analysis

Spatial Distribution Analysis



Bounding Box Width by Class



7. Bias Detection & Visualization:

	class	count	percentage	avg_size
0	car	127873	65.731293	4087.007779
1	pedestrian	21491	11.047142	1426.195942
2	trafficLight-Red	13673	7.028411	396.755713
4	trafficLight-Green	10838	5.571119	308.702008
5	truck	7194	3.697973	8258.766767
8	trafficLight	5101	2.622096	630.617981
6	biker	3704	1.903988	1567.550964
3	trafficLight-RedLeft	3482	1.789872	308.634486
7	trafficLight-GreenLeft	614	0.315618	330.293338
9	trafficLight-Yellow	541	0.278093	347.246753
10	trafficLight-YellowLeft	28	0.014393	311.580579

