

# Introduction

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topIivol meshing tool provides sequential/parallel tools for creating volumetric tetrahedral meshes from a given topology (point-cloud `*.xyz`). The volumetric meshes can be extracted in Gmsh's `*.msh` format or medit's `*.mesh` format. The framework is written in C++, and uses MPI I/O and MPI for parallelization. One could produce distributed meshes suitable for domain-decomposition based solvers or simply non distributed meshes (single mesh) suitable for a sequential/parallel solver.

topIivol consists a total of four tools:

## 1. `topIivol_PreProc`

This tool is a point-cloud preprocessor. Often point-cloud data is huge and requires some alterations. This tool takes in a point-cloud as an input (`.xyz`). It can be used to coarsen a structured point cloud, by skipping a specified n number of points.

## 2. `topIivol_Mesher`

This is a sequential computing tool. This tool takes in a point-cloud as an input (`.xyz`) and generates volumetric meshes that can be extracted in Gmsh's `*.msh` format or medit's `*.mesh` and `*.meshb` format.

## 3. `topIivol_ParMesher`

This is a parallel computing tool. This tool takes in a point-cloud as an input (`.xyz`) and generates volumetric meshes that can be extracted in medit's `*.mesh` format.

## 4. `topIivol_DistMesher`

This is a tool to create embarrassingly parallel distributed meshes. The mesher takes in a point-cloud as an input (`.xyz`) and outputs distributed mesh.

# Installation process

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Before you begin installing topIivol please check if your system meets the dependencies.

## Dependencies

- [automake](#)
- [C++](#)
- [MPI](#)

### Now that I have all the dependencies what next

Goto `top-ii-vol-Source` folder and

- step 1

```
autoreconf -i
```

- step 2

```
./configure
```

Note: `./configure` will install `topIIVol` in `/usr/local/bin` or `/usr/bin`, you generally need to be a superuser (sudoer) to have access to these directories. If you prefer to install at any other directory of choice `--prefix=Your/Own/Path` with `./configure`:

```
./configure --prefix=Your/Own/Path
```

- step 3

```
make
```

- step 4

```
make check
```

- step 5

```
sudo make install
```

Note: if you used `--prefix` during the configure phase, you can avoid using `sudo` for this step and simply `make install`.

## Running topIIVol

If the compilation went successful you should have three tools at your disposal

`topIIVol_ParMesher`, `topIIVol_Mesher`, `topIIVol_PreProc`, and `topIIVol_DistMesher`. These tools can be worked with command line inputs. Normally, these tools should be present in `/usr/local/bin` or `/usr/bin` folder, or else if you used `--prefix=your/directory` at the time of configure then these tools should be present in `your/directory/bin`.

### How to use topIIVol\_PreProc ?

- If you wish to coarsen your mesh by skipping 10 points in x and y direction

```
topIIVol_PreProc --xpoints 500 --ypoints 451 --xskip 10 --yskip 10 \
--in ../../etc/DEM_10m.xyz --out out-coarse.xyz
```

*Command-line option definitions*

Option	Type	Comment
<code>--xpoints</code>	[int]	These are # of x points present in your point cloud.
<code>--ypoints</code>	[int]	These are # of y points present in your point cloud.
<code>--xskip</code>	[int]	These are # of periodic x points you would like to skip.
<code>--yskip</code>	[int]	These are # of periodic y points you would like to skip.
<code>--in</code>	[string]	String to provide the input point cloud file <code>.xyz</code>
<code>--out</code>	[string]	String to provide the output coarsened/stripped point cloud file <code>.xyz</code>

Note that after successfully running `./topIvol_PreProc` there will be a info file `info-<out-coarse.xyz>.txt` that give the number of x and y points in the coarsened mesh cloud.

### How to use topIvol\_Mesher ?

This is the sequential mesher

- For sequential mesher producing `*.mesh` mesh.

```
topIvol_Mesher --xpoints 32 --ypoints 29 --zpoints 15 --depth -1000 \
--in ../../etc/DEM_160m.xyz --out out-mesh.mesh --mesh mesh
```

- For sequential mesher producing `*.msh` mesh.

```
topIvol_Mesher --xpoints 32 --ypoints 29 --zpoints 15 --depth -1000 \
--in ../../etc/DEM_160m.xyz --out out-mesh.msh --mesh msh
```

### Command-line option definitions

Option	Type	Comment
<code>--xpoints</code>	[int]	These are # of x points present in your point cloud.
<code>--ypoints</code>	[int]	These are # of y points present in your point cloud.
<code>--zpoints</code>	[int]	These are # of z points intended in the z direction.
<code>--in</code>	[string]	String to provide the input point cloud file <code>.xyz</code>
<code>--out</code>	[string]	String to provide the output mesh file <code>.mesh</code>
<code>--depth</code>	[int]	This is the depth of the mesh needed.
<code>--mesh</code>	[string]	To specify the kind of mesh needed

## How to use topIivol\_ParMesher ?

This is the parallel mesher (still under heavy development)

- For parallel mesher producing \*.mesh mesh with 2 MPI ranks.

```
mpirun -n 2 topIivol_ParMesher --xpoints 32 --ypoints 29 --zpoints 15 \  
--depth -2000 --in ../../etc/DEM_160m.xyz --out Parallel-out-mesh.mesh
```

### Command-line option definitions

Option	Type	Comment
--xpoints	[int]	These are # of x points present in your point cloud.
--ypoints	[int]	These are # of y points present in your point cloud.
--zpoints	[int]	These are # of z points intended in the z direction.
--in	[string]	String to provide the input point cloud file .xyz
--out	[string]	String to provide the output mesh file .mesh
-n	[int]	Provide the # of MPI ranks.

## How to use topIivol\_DistMesher ?

This is tool to create distributed mesh from partitioned point cloud

- Examples 3D partitioning of distributed mesher producing \*.mesh mesh with 24 MPI ranks (with 24 subdomains divided between x, y and z directions):

```
mpirun -n 24 topIivol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --partition_x 2 --partition_y 3 --partition_z 4 \  
--out top-ii-vol-mesh --in ../../etc/DEM_160m
```

or

```
mpirun -n 24 topIivol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --partition_x 3 --partition_y 2 --partition_z 4 \  
--out top-ii-vol-mesh --in ../../etc/DEM_160m
```

or

```
mpirun -n 24 topIivol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --partition_x 2 --partition_y 2 --partition_z 6 \  
--out top-ii-vol-mesh --in ../../etc/DEM_160m
```

- Examples 2D partitioning of distributed mesher producing \*.mesh mesh with 8 MPI ranks (with the 8 subdomains divided between x and y directions):

```
mpirun -n 8 topIIvol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --partition_x 2 --partition_y 4 --partition_z 1 \  
--out top-ii-vol-mesh --in ../../etc/DEM_160m
```

or

```
mpirun -n 8 topIIvol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --partition_x 4 --partition_y 2 --partition_z 1 \  
--out top-ii-vol-mesh --in ../../etc/DEM_160m
```

- Examples 2D partitioning of distributed mesher producing \*.mesh mesh with 6 MPI ranks (with the 6 subdomains divided between x and z directions):

```
mpirun -n 6 topIIvol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --partition_x 2 --partition_y 1 --partition_z 3 \  
--out top-ii-vol-mesh --in ../../etc/DEM_160m
```

or

```
mpirun -n 6 topIIvol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --partition_x 3 --partition_y 1 --partition_z 2 \  
--out top-ii-vol-mesh --in ../../etc/DEM_160m
```

- Examples 2D partitioning of distributed mesher producing \*.mesh mesh with 16 MPI ranks (with the 16 subdomains divided between y and z directions):

```
mpirun -n 16 topIIvol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --partition_x 1 --partition_y 8 --partition_z 2 \  
--out top-ii-vol-mesh --in ../../etc/DEM_160m
```

or

```
mpirun -n 16 topIIvol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --partition_x 1 --partition_y 2 --partition_z 8 \  
--out top-ii-vol-mesh --in ../../etc/DEM_160m
```

or

```
mpirun -n 16 topIIvol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --partition_x 1 --partition_y 4 --partition_z 4 \  
--out top-ii-vol-mesh --in ../../etc/DEM_160m
```

- Examples 1D partitioning of distributed mesher producing \*.mesh mesh with 4 MPI ranks (letting the algorithm decide the partition direction):

```
mpirun -n 4 topIIvol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --out top-ii-vol-mesh --in ../../etc/DEM_160m
```

- Examples 1D partitioning of distributed mesher producing \*.mesh mesh with 4 MPI ranks (enforced partitioning in x direction):

```
mpirun -n 4 topIIVol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --partition_x 4 --partition_y 1 --partition_z 1 \  
--out top-ii-vol-mesh --in ../../etc/DEM_160m
```

- Examples 1D partitioning of distributed mesher producing \*.mesh mesh with 8 MPI ranks (enforced partitioning in y direction):

```
mpirun -n 8 topIIVol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --partition_x 1 --partition_y 8 --partition_z 1 \  
--out top-ii-vol-mesh --in ../../etc/DEM_160m
```

- Examples 1D partitioning of distributed mesher producing \*.mesh mesh with 3 MPI ranks (enforced partitioning in z direction):

```
mpirun -n 3 topIIVol_DistMesher --zpoints 50 --xpoints 32 --ypoints 29 \  
--depth -1000 --partition_x 1 --partition_y 1 --partition_z 3 \  
--out top-ii-vol-mesh --in ../../etc/DEM_160m
```

#### Command-line option definitions

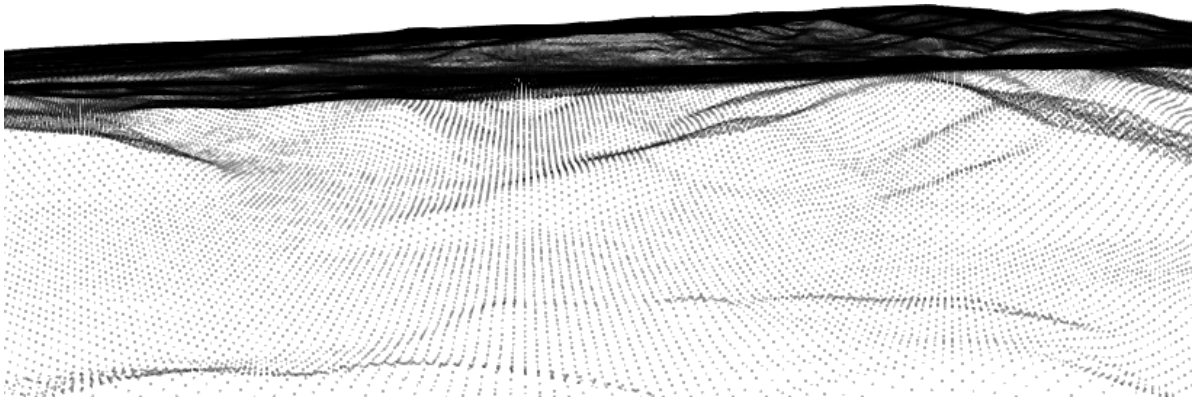
Option	Type	Comment
--xpoints	[int]	These are # of x points present in your point cloud.
--ypoints	[int]	These are # of y points present in your point cloud.
--zpoints	[int]	These are # of z points intended in the z direction.
--partition_x	[int]	These are # of x partitions in x direction.
--partition_y	[int]	These are # of y partitions in y direction.
--partition_z	[int]	These are # of z partitions in z direction.
--in	[string]	String to provide the input point cloud file .xyz
--out	[string]	String to provide the output mesh file .mesh
-np	[int]	Provide the # of MPI ranks.

To report bugs, issues, feature-requests contact:\*

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- [mohd-afeef.badri@etu.univ-nantes.fr](mailto:mohd-afeef.badri@etu.univ-nantes.fr)

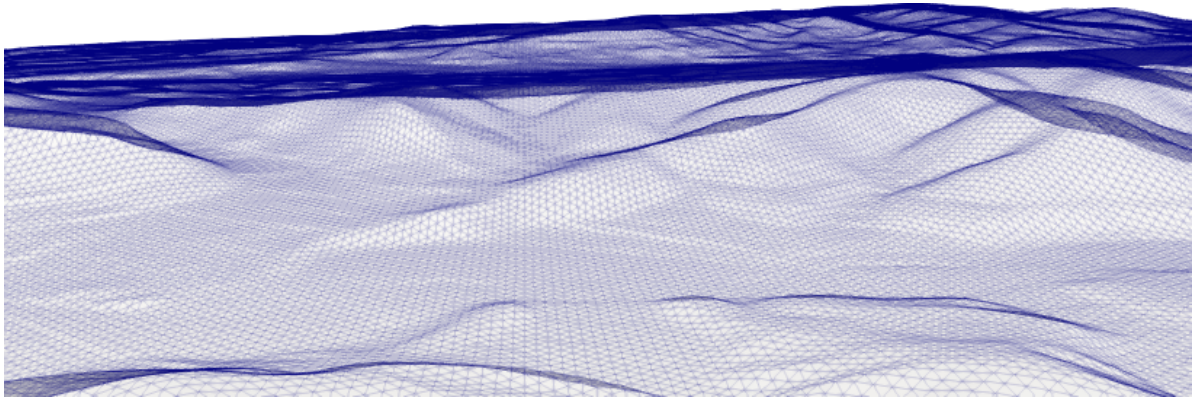
## Point cloud





**Surface triangulation of point cloud**

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**Finite element solution field**

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