MAPM312 Project - Parabolic PDEs

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1 Introduction

1.1 Problem Statement

The following set of coupled partial differential equations will be analyised at the hand of the Crank-Nicolson model:

$$\begin{split} \frac{\partial u}{\partial t} &= D_u \frac{\partial^2 u}{\partial x^2} + u(1-u) - \frac{auv}{1+\lambda u} \\ \frac{\partial v}{\partial t} &= D_v \frac{\partial^2 v}{\partial x^2} - \frac{v}{ab} + \frac{auv}{b(1+\lambda u)} \end{split}$$

$$a \le x \le b, \quad 0 \le t$$

$$u_x(a,t) = 0, \quad u_x(b,t) = 0$$

2 Derivation

From the problem statement we have the following system of PDEs.

$$u_t = D_u u_{xx} + f(u, v) \tag{1a}$$

$$v_t = D_v v_{xx} + g(u, v) \tag{1b}$$

where $a \le x \le b$, $0 \le t \le T$, and

$$f(u,v) = u(1-u) - \frac{auv}{1+\lambda u}$$
(2a)

$$f(u,v) = u(1-u) - \frac{auv}{1+\lambda u}$$

$$g(u,v) = -\frac{v}{ab} + \frac{auv}{b(1+\lambda u)}$$
(2a)

We use the following finite difference approximations, derived from the Taylor series expansion, in place of the u_t , u_{xx} , v_t , and v_{xx} in equations (1). The spacial and temporal domains are descretized using N and M points respectively and h and k are the related step lengths.

$$u_{t} = \frac{u(x, t+k) - u(x, t)}{k} - \frac{k}{2}u_{tt}(x, \tau)$$
(3a)

$$v_t = \frac{v(x, t+k) - v(x, t)}{k} - \frac{k}{2}v_{tt}(x, \sigma)$$
 (3b)

$$u_{xx} = \frac{u(x-h,t) - 2u(x,t) + u(x+h,t)}{h^2} - \frac{h^2}{12} u_{xxxx}(\xi,t)$$
 (3c)

$$v_{xx} = \frac{v(x-h,t) - 2v(x,t) + v(x+h,t)}{h^2} - \frac{h^2}{12}v_{xxxx}(\epsilon,t)$$
 (3d)

Let $n = 1 \dots N$ and $m = 1 \dots M$. Discard the truncation terms from equations (3) and let U_n^m and V_n^m approximate the true solutions $u(x_n, t_m)$ and $v(x_n, t_m)$. We can then replace equations (1) with the following system of equations. We also write $f(u_n^m, v_n^m) = f_n^m$ and $g(u_n^m, v_n^m) = g_n^m$.

$$\frac{U_n^{m+1} - U_n^m}{k} = \frac{D_u}{2} \left\{ \left[\frac{U_{n-1}^{m+1} - 2U_n^{m+1} + U_{n+1}^{m+1}}{h^2} \right] + \left[\frac{U_{n-1}^m - 2U_n^m + U_{n+1}^m}{h^2} \right] \right\} + f_n^m$$
 (4a)

$$\frac{V_n^{m+1} - V_n^m}{k} = \frac{D_v}{2} \left\{ \left[\frac{V_{n-1}^{m+1} - 2V_n^{m+1} + V_{n+1}^{m+1}}{h^2} \right] + \left[\frac{V_{n-1}^m - 2V_n^m + V_{n+1}^m}{h^2} \right] \right\} + g_n^m$$
 (4b)

Multiplying equations (4) throughout by 2k and rearranging the terms yields the following with $r = D_u k/h^2$ and $s = D_v k/h^2$.

$$(2+2r)U_n^{m+1} - rU_{n-1}^{m+1} - rU_{n+1}^{m+1} = (2-2r)U_n^m + rU_{n-1}^m + rU_{n+1}^m + 2kf_n^m$$

$$(2+2s)V_n^{m+1} - sV_{n-1}^{m+1} - sV_{n+1}^{m+1} = (2-2s)V_n^m + sV_{n-1}^m + sV_{n+1}^m + 2kg_n^m$$
(5a)

$$(2+2s)V_n^{m+1} - sV_{n-1}^{m+1} - sV_{n+1}^{m+1} = (2-2s)V_n^m + sV_{n-1}^m + sV_{n+1}^m + 2kg_n^m$$
(5b)

We now investigate the boundary conditions. When n=1 we have may use the central difference formula for the first derivatives as follows:

$$U_x(a,t) = 0 = \frac{U_2 - U_0}{2h}$$
 (6a)

$$V_x(a,t) = 0 = \frac{V_2 - V_0}{2h} \tag{6b}$$

Since the derivatives at the boundaries are given as 0 this implies that:

$$U_2 = U_0 \tag{7a}$$

$$V_2 = V_0 \tag{7b}$$

The same argument follows for the right endpoint where n = N and we have:

$$U_x(b,t) = 0 = \frac{U_{N+1} - U_{N-1}}{2h}$$
(8a)

$$V_x(b,t) = 0 = \frac{V_{N+1} - V_{N-1}}{2h}$$
(8b)

hence

$$U_{N+1} = U_{N-1} (9a)$$

$$V_{N+1} = V_{N-1} (9b)$$

We may then substitute (7) and (9) into their respective equations from (5) so that:

$$(2+2r)U_1^{m+1} - 2rU_2^{m+1} = (2-2r)U_1^m + 2rU_2^m + 2kf_1^m$$
(10a)

$$(2+2s)V_1^{m+1} - 2sV_2^{m+1} = (2-2s)V_1^m + 2sV_2^m + 2kg_1^m$$
(10b)

$$(2+2r)U_N^{m+1} - 2rU_{N-1}^{m+1} = (2-2r)U_N^m + 2rU_{N-1}^m + 2kf_N^m$$

$$(2+2s)V_N^{m+1} - 2sV_{N-1}^{m+1} = (2-2s)V_N^m + 2sV_{N-1}^m + 2kg_N^m$$

$$(10d)$$

$$(2+2s)V_N^{m+1} - 2sV_{N-1}^{m+1} = (2-2s)V_N^m + 2sV_{N-1}^m + 2kg_N^m$$
(10d)

rewritten into the following matrix equations:

$$\begin{bmatrix} 2+2r & -2r & \dots & 0 \\ -r & 2+2r & \dots & 0 \\ 0 & -r & \ddots & \vdots \\ \vdots & \vdots & \ddots & -r \\ 0 & 0 & -2r & 2+2r \end{bmatrix} \begin{bmatrix} U_1^{m+1} \\ U_2^{m+1} \\ \vdots \\ U_n^{m+1} \end{bmatrix} = \begin{bmatrix} 2-2r & 2r & \dots & 0 \\ r & 2-2r & \dots & 0 \\ 0 & r & \ddots & \vdots \\ \vdots & \vdots & \ddots & r \\ 0 & 0 & 2r & 2-2r \end{bmatrix} \begin{bmatrix} U_1^m \\ U_2^m \\ U_3^m \\ \vdots \\ U_n^m \end{bmatrix} + 2k \begin{bmatrix} f_1^m \\ f_2^m \\ f_3^m \\ \vdots \\ f_n^m \end{bmatrix}$$

$$\begin{bmatrix} 2+2s & -2s & \dots & 0 \\ -s & 2+2s & \dots & 0 \\ 0 & -s & \ddots & \vdots \\ \vdots & \vdots & \ddots & -s \\ 0 & 0 & -2s & 2+2s \end{bmatrix} \begin{bmatrix} V_1^{m+1} \\ V_2^{m+1} \\ V_3^{j+1} \\ \vdots \\ V_n^{m+1} \end{bmatrix} = \begin{bmatrix} 2-2s & 2s & \dots & 0 \\ s & 2-2s & \dots & 0 \\ 0 & s & \ddots & \vdots \\ \vdots & \vdots & \ddots & s \\ 0 & 0 & 2s & 2-2s \end{bmatrix} \begin{bmatrix} V_1^m \\ V_2^m \\ V_3^m \\ \vdots \\ V_n^m \end{bmatrix} + 2k \begin{bmatrix} g_1^m \\ g_2^m \\ g_3^m \\ \vdots \\ g_n^m \end{bmatrix}$$

3 Stability Analysis

We investigate the stability of the Crank-Nicolson method using the equation from (1a). A similar argument may be used to show the stability of the Crank-Nicolson method using the equation from (1b).

$$\frac{U_n^{m+1} - U_n^m}{k} = \frac{D_u}{2} \left(\frac{U_{n-1}^{m+1} - 2U_n^{m+1} + U_{n+1}^{m+1}}{h^2} + \frac{U_{n-1}^m - 2U_n^m + U_{n+1}^m}{h^2} \right)$$
(11)

We then substitute $U_n^m = \xi^m e^{iknh}$ and rearrange the terms in (11) such that:

$$\xi^{m+1}e^{iknh} - \xi^{m}e^{iknh} = \frac{D_{u}k}{2h^{2}} \left(\xi^{m+1}e^{ik(n+1)h} + \xi^{m}e^{ik(n+1)h} - 2\xi^{m+1}e^{iknh} - 2\xi^{m}e^{iknh} + \xi^{m+1}e^{ik(n-1)h} + \xi^{m}e^{ik(n-1)h} \right)$$
(12)

We may then divide throughout by $\xi^m e^{iknh}$ which gives the following:

$$\xi - 1 = \frac{D_u k}{2h^2} \left(\xi e^{ikh} + e^{ikh} - 2\xi - 2 + \xi e^{-ikh} + e^{-ikh} \right)$$
 (13)

Rearranging (13) and replacing the complex exponential gives:

$$\xi = 1 - \frac{D_u \tau}{2h^2} (\xi + 1) [1 - \cos(kh)] \tag{14}$$

Taking the absolute value of ξ gives:

$$|\xi| = \left| \frac{1 - D_u \tau / h^2 [1 - \cos(kh)]}{1 + D_u \tau / h^2 [1 - \cos(kh)]} \right| \le 1$$
 (15)

Since (15) is true for any value of k the Crank-Nicolson model is unconditionally stable.

4 Results

5 Discussion

6 Conclusion