

Theorem (Rank-Nullity theorem)

Let $T: V \rightarrow W$ be a linear transformation from V into W . If V is finite-dimensional, then

$$\text{rank}(T) + \text{nullity}(T) = \dim V.$$

Proof.

Let $\{v_1, v_2, \dots, v_k\}$ be a basis for $N(T)$.

Choose $v_{k+1}, v_{k+2}, \dots, v_n$ such that $\{v_1, v_2, \dots, v_k, v_{k+1}, \dots, v_n\}$ is a basis for V .

Claim $S = \{Tv_{k+1}, Tv_{k+2}, \dots, Tv_n\}$ is a basis for $R(T)$.

S is linearly independent:

Let $c_{k+1}Tv_{k+1} + \dots + c_nTv_n = 0$. Then

$$T(c_{k+1}v_{k+1} + \dots + c_nv_n) = 0.$$

$$\Rightarrow c_{k+1}v_{k+1} + \dots + c_nv_n \in N(T).$$

\therefore there exists ~~v_1, v_2, \dots, v_k~~ scalar c_1, c_2, \dots, c_k such that

$$c_{k+1}v_{k+1} + \dots + c_nv_n = c_1v_1 + c_2v_2 + \dots + c_kv_k.$$

$$\Rightarrow c_1v_1 + c_2v_2 + \dots + c_nv_n - c_{k+1}v_{k+1} - \dots - c_nv_n = 0$$

Since $\{v_1, v_2, \dots, v_n\}$ is a basis for V ,

$$c_1 = c_2 = \dots = c_k = c_{k+1} = \dots = c_n = 0.$$

In particular, $c_{k+1} = \dots = c_n = 0$.

S spans $R(T)$: (i.e., $\text{span}(S) = R(T)$).

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Let $w \in \text{span}(S)$. Then

$$w = d_{k+1}T(v_{k+1}) + \dots + d_n T(v_n)$$

$$= T(d_{k+1}v_{k+1} + \dots + d_nv_n) \in R(T).$$

$$\therefore \text{span}(S) \subseteq R(T) \longrightarrow \textcircled{1}$$

Let $w_1 \in R(T)$. Then

$$w_1 = T(v), \text{ for some } v \in V.$$

$$\Rightarrow w_1 = T(c_1v_1 + \dots + c_nv_n)$$

$$\Rightarrow w_1 = T(c_1v_1 + \dots + c_kv_k) + T(c_{k+1}v_{k+1} + \dots + c_nv_n)$$

$$= c_1T(v_1) + \dots + c_kT(v_k) + c_{k+1}T(v_{k+1}) + \dots + c_nT(v_n)$$

$$= c_{k+1}T(v_{k+1}) + \dots + c_nT(v_n) \quad (\because v_1, v_2, \dots, v_k \in N(T))$$

$$\in \text{span}(S).$$

$$\therefore R(T) \subseteq \text{span}(S) \longrightarrow \textcircled{2}$$

From $\textcircled{1}$ & $\textcircled{2}$, $R(T) = \text{span}(S)$.

$$\therefore \text{rank}(T) = \dim(R(T))$$

$$= n - k$$

$$\Rightarrow \text{rank}(T) + \text{nullity}(T) = \dim V.$$

Theorem

Let V and W be finite dimensional vector spaces over K such that $\dim V = \dim W$. If T is a linear transformation from V into W , then TFAE.

(i) T is invertible.

(ii) T is one-one.

(iii) T is onto.

Proof. Use rank-nullity theorem.

Representation of ~~vectors~~ linear transformation by matrices.

Definition (Ordered basis)

If V is a finite dimensional vector space, an ordered basis for V is a finite sequence of vectors which is a basis for V .

Let $B = \{v_1, v_2, \dots, v_n\}$ be an ~~any~~ ordered basis for V .

Let $v \in V$. Then there exist unique scalars c_1, c_2, \dots, c_n such that

$$v = c_1 v_1 + c_2 v_2 + \dots + c_n v_n.$$

We call c_i the i th coordinate of v with respect to the ordered basis B . The matrix

$[v]_B = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$ is called the coordinate matrix of v w.r. to B .

Let V be an n -dimensional vector space over \mathbb{K} and let W be an m -dimensional vector space over \mathbb{K} .

Let $B = \{v_1, v_2, \dots, v_n\}$ be an ordered basis for V and let $B' = \{w_1, w_2, \dots, w_m\}$ be an ordered basis for W .

Let $T: V \rightarrow W$ be a linear transformation from V into W .

For each $v_j \in V$, $T(v_j)$ is uniquely written as

$$Tv_j = \sum_{i=1}^m A_{ij} w_i, \text{ where } A_{ij} \in \mathbb{K}.$$

The $m \times n$ matrix $A = (A_{ij})$ is called the matrix of T with respect to the ordered bases B and B' . We denote A by $[T]_{B, B'}$. If $V = W$ and $B = B'$, we write simply $[T]_B$ instead of $[T]_{B, B'}$.

Example 1

Let $T: \mathbb{K}^2 \rightarrow \mathbb{K}^2$ be a linear transformation defined

by $T(v_1, v_2) = (v_1, 0)$.

Find the matrix of T w.r. to the standard basis $\{e_1, e_2\}$.

$$\begin{matrix} e_1 & e_2 \\ \swarrow & \searrow \\ (1, 0) & (0, 1) \end{matrix}$$

Soln

(i) Verify that T is linear.

$$\therefore [T]_B = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

Now $T(1, 0) = (1, 0) = 1e_1 + 0e_2$

$$T(0, 1) = (0, 0) = 0e_1 + 0e_2$$

Example 2.

Take $V = P_3(\mathbb{R})$, $W = P_3(\mathbb{R})$

$$B = \left\{ \underset{f_0}{1}, \underset{f_1}{x}, \underset{f_2}{x^2}, \underset{f_3}{x^3} \right\}, \quad B' = \{1, x, x^2, x^3\}$$

Define $D: P_3(\mathbb{R}) \rightarrow P_3(\mathbb{R})$ by

$$Df = f'$$

$$\text{i.e., } (Df)(x) = f'(x), \quad x \in \mathbb{R}$$

Then D is linear.

$$Df_0 = 0 = 0f_0 + 0f_1 + 0f_2 + 0f_3$$

$$Df_1 = f_0 = 1f_0 + 0f_1 + 1f_2 + 1f_3$$

$$Df_2 = 2f_1 = 0f_0 + 2f_1 + 0f_2 + 0f_3$$

$$Df_3 = 3f_2 = 0f_0 + 0f_1 + 3f_2 + 0f_3$$

$$\therefore [D]_B = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Theorem. Let V be a vector space over \mathbb{K} . Let ~~and~~

$B = \{v_1, v_2, \dots, v_n\}$ and $B' = \{v'_1, v'_2, \dots, v'_n\}$ be two ordered bases for V . Suppose T is a linear transformation from V into V . If $P = [P_1, P_2, \dots, P_n]$ is the $n \times n$ matrix with columns $P_j = [v'_j]_{B'}$,

$$\text{Then } [T]_{B'} = P^{-1} [T]_B P.$$

Example

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Take Example 1 (Page 41).

Choose $B = \{(1,0), (0,1)\}$ and $B' = \{(1,1), (2,1)\}$.

Prove that B' is a basis for \mathbb{R}^2 .

$$(1,1) = 1e_1 + 1e_2 \Rightarrow P_1 = [(1,1)]_B = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$(2,1) = 2e_1 + 1e_2 \Rightarrow P_2 = [(2,1)]_B = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$\therefore P = \begin{pmatrix} 1 & 2 \\ 1 & 1 \end{pmatrix} \quad \left(\text{Show that } P^{-1} = \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} \right)$$

$$\begin{aligned} T(1,1) &= (1,0) = \alpha_1(1,1) + \alpha_2(2,1) \\ &= 1(1,1) + (-1)(2,1) \end{aligned}$$

$$\begin{aligned} T(2,1) &= (2,0) \\ &= \alpha_1(1,1) + \alpha_2(2,1) \\ &= -2(1,1) + 2(2,1) \end{aligned}$$

$$\therefore [T]_{B'} = \begin{pmatrix} 1 & -2 \\ -1 & 2 \end{pmatrix}$$

To find α_1, α_2 ,

$$\alpha_1 + 2\alpha_2 = 1$$

$$\alpha_1 + \alpha_2 = 0$$

$$\Rightarrow \alpha_2 = 1, \alpha_1 = -1$$

Verify that

$$[T]_{B'} = P^{-1} [T]_B P.$$