

Theorem.

Let V be a vector space which is spanned by a finite number of vectors, v_1, v_2, \dots, v_m . Then any independent set of vectors in V is finite and its cardinality is less than or equal to m .

Proof.

It is enough to prove that every subset S of V containing more than m vectors is linearly dependent.

Let $S = \{u_1, u_2, \dots, u_n\}$ be a such set, $n > m$.

Since $\{v_1, v_2, \dots, v_m\}$ spans V , \exists scalars $A_{ij} \in \mathbb{K}$ such that

$$u_j = \sum_{i=1}^m A_{ij} v_i.$$

For any scalars c_1, c_2, \dots, c_n , we have

$$c_1 u_1 + c_2 u_2 + \dots + c_n u_n = \sum_{j=1}^n c_j u_j$$

$$= \sum_{j=1}^n c_j \sum_{i=1}^m A_{ij} v_i$$

$$= \sum_{i=1}^m \left(\sum_{j=1}^n A_{ij} c_j \right) v_i$$

Since $m < n$, $AC = 0$ has at least one non-zero soln,

say, ^{that} $(c_1, c_2, \dots, c_n) = c$ is not zero-vector.

For this non-zero $c = (c_1, c_2, \dots, c_n)$, we have

$$c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0.$$

Corollary.

If V is a finite-dimensional vector space, then any two bases of V have the same (finite) number of elements.

Proof.

Since V is finite-dimensional, it has a finite basis.

Let $\{v_1, v_2, \dots, v_n\}$ and $\{u_1, u_2, \dots, u_m\}$ be two bases for V .

Since $\{v_1, v_2, \dots, v_n\}$ spans V and $\{u_1, u_2, \dots, u_m\}$ is linearly independent,

$$m \leq n \longrightarrow \textcircled{1} \quad (\text{by previous thm})$$

Similarly $\{u_1, u_2, \dots, u_m\}$ spans V and $\{v_1, v_2, \dots, v_n\}$ is linearly independent,

$$n \leq m \longrightarrow \textcircled{2}$$

From $\textcircled{1}$ & $\textcircled{2}$ $m = n$.

Definition

$\dim V :=$ the number of elements in a basis.

Corollary.

Let V be a finite dimensional vector space of dimension n . Then

(i) any subset of V which contains more than n elements is linearly dependent.

(ii) Any subset of V which contains fewer than n elements cannot span V .

Subspaces.

Let V be a vector space over \mathbb{K} . A subset W of V is said to be a subspace of V if W is a vector space over \mathbb{K} with respect to vector addition and scalar multiplication of V .

Examples.

- (i) For any vector space V over \mathbb{K} , V is a subspace of V .
- (ii) $W = \{0\}$ is a subspace of V ; it is called zero subspace.
- (iii) Take $V = M_n(\mathbb{R})$ and $W =$ The set of all $n \times n$ symmetric matrices.
 W is a subspace of $M_n(\mathbb{R})$.
- (iv) Take $V = M_n(\mathbb{C})$ and $W =$ The set of all $n \times n$ self-adjoint matrices.
 Then W is a subspace of $M_n(\mathbb{C})$.
- (v) Take $V = \mathbb{K}[x]$ and $W = \mathbb{K}_n[x]$. Then
 $\mathbb{K}_n[x]$ is a subspace of $\mathbb{K}[x]$.
- (vi) Take $V = M_n(\mathbb{C})$ and $W =$ The set of all $n \times n$ lower triangular matrices.
 W is a subspace of $M_n(\mathbb{C})$.

Theorem.

A non-empty subset W of V is a subspace of V iff
for every $v, w \in W$ and $c \in K$, $cv + w \in W$.

Theorem

Let V be a vector space over K . Then arbitrary intersection of subspaces of V is a subspace of V .

Proof.

Let $W = \bigcap_{\alpha} W_{\alpha}$, W_{α} 's are subspaces of V .

Clearly $0 \in W_{\alpha}, \forall \alpha \Rightarrow 0 \in W. \therefore W \neq \emptyset$.

Let $u, v \in W$ and $c \in K$. Then

$$u \in W_{\alpha}, v \in W_{\alpha}, \forall \alpha$$

Since W_{α} 's are subspaces of V ,

$$cu + v \in W_{\alpha}, \text{ for every } \alpha$$

$$\Rightarrow cu + v \in W.$$

$\therefore W$ is a subspace of V

Definition:

Let S be a subset of a vector space V over K .

Then the intersection of all subspaces of V containing S is called the subspace generated by S . It is denoted by $\text{gen}(S)$.

Properties.

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(i) $\text{gen}(\emptyset) = \{0\}$.

(ii) If S is a non-empty set, then
 $\text{span}(S) = \text{gen}(S)$

(iii) If S is a subspace, then $\text{span}(S) = S$

(iv) $\text{span}(S)$ is the smallest subspace containing S .

Sum of subsets in V .

Let S_1, S_2, \dots, S_k be subsets of V . Then the set $S_1 + S_2 + \dots + S_k$ is defined as

$$S_1 + S_2 + \dots + S_k := \{v_1 + v_2 + \dots + v_k : v_j \in S_j, j = 1, 2, \dots, k\}$$

Lemma

If W_1, W_2, \dots, W_k are subspaces of V , then

$W_1 + W_2 + \dots + W_k$ is a subspace of V .

Proof.

Since $0 \in W_j, j = \overline{1, k}$, $0 \in W_1 + W_2 + \dots + W_k$.

$$\therefore W_1 + W_2 + \dots + W_k \neq \emptyset.$$

Let $u, v \in W_1 + W_2 + \dots + W_k$ and $c \in \mathbb{R}$. Then

$$\begin{aligned} u &= w_1 + w_2 + \dots + w_k \\ v &= w'_1 + w'_2 + \dots + w'_k \end{aligned}, \quad w_j, w'_j \in W_j, j = \overline{1, k}$$

Now

$$cu + v = (cw_1 + w'_1) + \dots + (cw_k + w'_k) \in W_1 + \dots + W_k$$

($\because W_k$'s are subspaces)

$\therefore W_1 + W_2 + \dots + W_k$ is a subspace of V

Determinants.

Let A be an $n \times n$ matrix over K . A matrix which is obtained from A by deleting one column and row is called a minor of a matrix A . We denote M^{ij} is the minor of the matrix by deleting i^{th} row and j^{th} column of A .

The determinant of the matrix A is defined by the recurrence relation

$$\begin{aligned} \det A &:= \sum_{j=1}^n (-1)^{i+j} A_{ij} \det(M^{ij}) \quad (\text{Expansion using row}) \\ &= \sum_{i=1}^n (-1)^{i+j} A_{ij} \det(M^{ij}) \quad (\text{Expansion using column}) \end{aligned}$$

When $A = (a)_{1 \times 1}$, $\det A = a$. The terms $(-1)^{i+j} \det(M^{ij})$ are called cofactors.

Properties.

- (i) $\det \mathbf{0} = 0$; $\det I = 1$
- (ii) $\det A^t = \det A$
- (iii) $\det(cA) = c^n \det A$, $c \in K$
- (iv) $\det(AB) = \det A \cdot \det B$
- (v) $\det A = 0$ if two rows are identical
- (vi) $\det(e_{\text{swap}}(A)) = -\det A$
- (vii) A is invertible iff $\det A \neq 0$.

Definition

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Let A be an $m \times n$ matrix over K . Then the subspace spanned by the rows of the matrix A is called the row space of A and it is denoted by $\text{rowspace}(A)$.

Similarly we can define column space of A .

Properties,

- (i) The dimension of $\text{rowspace}(A)$ is equal to the rank of the matrix A .
- (ii) The non-zero rows of a row-reduced echelon matrix of A is a basis for $\text{rowspace}(A)$.
- (iii) $\text{rank}(A) =$ the size (order) of the highest non-vanishing minor of the matrix A .
- (iv) If A is row-equivalent to B , then $\text{rowspace}(A) = \text{rowspace}(B)$

