

# SALONI MALVIYA

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## EDUCATION

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| <b>University of Michigan</b> - Ann Arbor, MI<br><i>Master of Science in Aerospace Engineering</i><br>Coursework: Spacecraft Technology, Linear Systems Theory, Navigation and Guidance of Aerospace Vehicle | Aug 2024 - May 2026<br>GPA: 3.92/4.0 |
| <b>Vellore Institute of Technology</b> - Bhopal, India<br><i>B. Tech Aerospace Engineering</i>   | Sep 2020 - Aug 2024                  |

## SKILLS

**Coding and Simulation:** C++, Java, MySQL, MATLAB, Simulink, Simscape

**CAD and Analysis:** Ansys Fluent, CREO, AutoCAD, SolidWorks, Catia, Inventor, MSC Adams, Xfoil, QBlade

## WORK EXPERIENCE

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| <b>Indian Space Research Organisation (ISRO)</b> - Ahmedabad, India<br><i>Intern at Space Applications Centre</i> | Jul 2023 - May 2024 |
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- Engineered a **compliant monolithic gripper** for space applications to reduce manufacturing cost and overall weight while withstanding launch loads.
- Employed topology optimization and compliant mechanism design; established kinematic feasibility with **MSC ADAMS** and conducted static and modal (achieving a natural frequency of **174 Hz**) analysis using **Ansys** and **CREO**.
- Achieved **20% reduction in weight** and manufacturing **cost** and validated its feasibility through **2D drawings** and a **3D-printed physical prototype**.

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| <b>Defence Research and Development Organisation (DRDO)</b> - Jodhpur, India<br><i>Intern at Defence Laboratory Jodhpur</i> | Jun 2023 - Jul 2023 |
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- Inspected a high-voltage module for internal defects using non-destructive technique.
- Conducted **CT scans** and analyzed images using **VGStudio MAX** and **GE Phoenix CT** software
- Provided comprehensive internal visualization that enabled precise defect identification and identified critical defects that led to a **25% enhancement in module reliability**.

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| <b>Space Technology and Aeronautical Rocketry (STAR) Lab</b> - Surat, India<br><i>System Engineering Intern</i> | Jan 2023 - Feb 2023 |
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- Designed and modeled a triangular **Static Test Pad** in **Fusion 360** to securely mount solid rocket motors.
- Validated **structural integrity** through static simulations, achieving **safety factors >3.3**, and optimized the design for manufacturability and sensor integration.
- Built a custom **Data Acquisition System**, integrating load cells, amplifiers, and A/D converters using **Arduino**, **Proteus**, and **Eagle**, enabling real-time thrust measurement and sensor data analysis via a custom PCB.

## PROJECT EXPERIENCE

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| <b>Identification &amp; Characterization Expedition for Debris Tracking</b> - Ann Arbor, MI | Sep 2024 - Apr 2025 |
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- Developed a **space-based SAR system** capable of detecting and characterizing over 200 unique RSOs per day.
- Led communication trade studies and prepared the mission's communication architecture using STK analysis and detailed link budget calculations. Achieved a **50% reduction** in downlink access times and a **30% improvement** in link budget margin.

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| <b>Model Reference Adaptive Control for Spacecraft Attitude Tracking</b> – Ann Arbor, MI | Jan 2025 - Apr 2025 |
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- Designed and simulated an MRAC system in **MATLAB** for spacecraft attitude control, outperforming PID and LQR under inertia uncertainties.
- Improved performance with **60% faster settling time** and **>95% reduction** in steady-state error, demonstrating robustness and stability.

## RESEARCH EXPERIENCE

- Malviya, S., Sharma, A., Arora, H. and Gk, P., 2024, July. Design and Development of Underactuated Soft Robotic Gripper for Space Applications. In 2024 IEEE Space, Aerospace and Defence Conference (SPACE) (pp. 700-704). IEEE.*
- MALVIYA, S. and SAH, S.K., A refined shear deformation theory for natural frequency analysis of power law based functionally graded sandwich plate. Materials Research Proceedings, 49.*